Université Lille 1 - Sciences et Technologies Innovimax Sarl
Institut National de Recherche en Informatique et en Automatique Centre de Recherche en Informatique, Signal et Automatique de Lille


## ThÈSE

présentée en première version en vue d'obtenir le grade de Docteur par l'Université de Lille 1 en spécialité Informatique
par
Tom Sebastian

## Evaluation of XPath Queries on XML Streams with Networks of Early Nested Word Automata

Thèse soutenue le 17/06/2016 devant le jury composé de :

| Carlo Zaniolo | University of California | Rapporteur |
| :--- | :--- | :--- |
| Anca Muscholl | Université Bordeaux | Rapporteur |
| Kim NGuyen | Université Paris-Sud | Examinateur |
| Remi Gilleron | Université Lille 3 | Président du Jury |
| Joachim Niehren | INRIA | Directeur |


#### Abstract

The eXtended Markup Language (XmL) provides a format for representing data trees, which is standardized by the W3C and largely used today for exchanging information between all kinds of computer programs. The main application areas of XmL are document processing (DосВоок), Web information representation (Html), and NoSql databases with nested relations. The main task for Xml processing are the problems to query and transform data trees. For solving these tasks, the W3C has developed the languages Xslt, XQuery, and XProc. As a common core, they rely on XPath for querying data trees for nodes, strings, functions, or sequences thereof.

The challenge that we tackle in this thesis is the problem of how to answer XPath queries on XmL streams with low latency, full coverage, high time efficiency, and low memory costs. This requires to overcome the following difficulties: 1. Earliest query answering is computationally untractable, so that one cannot hope to always reach optimal latency and memory consumption. 2. No previous streaming algorithm was able to deal with all navigational XPATH queries while also supporting comparisons of data values, aggregates, and higher-order functions. 3. In contrast to in-memory XPath engines, where document projection with respect to a given XPath query is highly relevant for time efficiency, it was unclear how to project away irrelevant parts of XmL streams.

In this thesis we first propose to approximate earliest query answering for navigational XPath queries by compilation to early nested word automata. It turns out that this yields quasi-optimal results in most practical cases, leading to almost optimal latency and memory consumption. Second, we contribute a formal semantics of XPath 3.0. It is obtained by mapping XPath to the new query language $\lambda \mathrm{XP}$ that we introduce. This language has the advantage to be based on first principles, so that it can be considered as a core language for XPath processing. We then show how to compile $\lambda \mathrm{XP}$ queries to networks of early nested word automata, and develop streaming algorithms for the latter. Thereby we obtain a streaming algorithm that indeed covers all of XPath 3.0. Third, we develop an algorithm for projecting XmL streams with respect to the query defined by an early nested word automaton. Thereby we are able to make our streaming algorithms highly time efficient. We have implemented all our algorithms with the objective to obtain an industrially applicable streaming tool, and tested them on the usual benchmarks. It turns out that our algorithms outperform all previous approaches in time efficiency, coverage, and latency.


## Acknowledgments

First of all, I want to express my gratitude to my doctoral advisor Joachim Niehren. You have introduced me to many different topics that we covered in my thesis and I appreciate all that I could learn. It has always been a pleasure to work with you! To me you have been more than just a great teacher and supervisor. Thank you for having been on my side with the various problems that we lived through during my thesis. Thank you that you cared so much for me. It was a great time. I will miss it!

I want to thank Carlo Zaniolo and Anca Muscholl for their great examination and review of this thesis. I like to thank Kim Nguyen and Remi Gilleron who took part in the jury of my defense, and Iovka Benova and Sławek Staworko for proof reading parts of my thesis. Thanks also to Mohamed Zergaoui, who always had trust in me and who financed this thesis.

I was gifted with a very pleasant work environment with handsome colleagues. I have been very fortunate with Denis, who implemented a great deal of the software tool that we have developed during my PhD. He was always helpful and I could enjoy many interesting discussions with him on code and algorithms. In addition, I especially appreciated the presence of Iovka, Antoine, Pavel, and Momar.

Huge thanks I dedicate to my family. Especially my lovely parents have supported me in so many ways throughout my thesis. I cannot thank you enough! Also I could not have wished for a better brother. Thanks Ron also for equipping me with the newest of technology. "Meine Mama" :)

I am so grateful for my best friends. Eric: thank you so much for being such a good friend for so many years, thanks for putting so much effort into our friendship, for the sports, the competitiveness, and for your kindness. Frank: "hey hey hey" :) thank you also for being such a great friend for all this time, especially for being so charismatic; you have the talent to put a smile onto anybody's face :) Olaaaa: I "love" you :) I am so happy to have met you. You are the best! Bisousss. Sławek: I enjoy every time when we meet. Thanks for your marvelous hospitality and all the times that we spend together.

Eglantine, my little flower, thank you for being so sweet and to have come into my life and heart. "Eggy Spaghetti $\mathrm{P}^{* * *} \mathrm{t}$ " ;)

Last but not least, I want to acknowledge the great Snooker times with Mathias, the evenings with Gwenael and Anne-Sophie, the cooking by Guillaume and the Risotto of Michele, the dish washing with Wassim, and finally all great times that I shared with my flat mates Manon, Sandra, Vincent, and Alexandra.

## Contents

1 Introduction ..... 1
1.1 Xml Processing based on XPath ..... 2
1.1.1 Schema Validation ..... 2
1.1.2 Query-based Transformation ..... 4
1.1.3 XPath ..... 5
1.1.4 Regular Extension of XPath ..... 8
1.1.5 In Memory Evaluation ..... 8
1.1.6 Streaming Evaluation ..... 9
1.2 Open Problems ..... 12
1.2.1 Low Coverage ..... 12
1.2.2 Low Latency ..... 13
1.2.3 Low Time Efficiency ..... 13
1.2.4 Lack of Formal Semantics ..... 13
1.3 Contributions ..... 14
1.3.1 Formal Semantics of XPath 3.0 in $\lambda$ XP ..... 14
1.3.2 Early Query Answering by Early Nwas ..... 14
1.3.3 Networks of Early Nwas ..... 15
1.3.4 Projection for Nwas ..... 15
1.3.5 Implementation and Experiments ..... 16
1.4 Organization ..... 16
1.5 Publications ..... 17
2 Preliminaries ..... 19
2.1 Data Trees ..... 19
2.1.1 Definition ..... 20
2.1.2 Logical Structure ..... 21
2.1.3 Finite State Abstractions ..... 22
2.1.4 Json Trees ..... 23
2.2 Nested Words ..... 24
2.2.1 Definition ..... 24
2.2.2 Linearization of Data Trees ..... 24
2.3 Xml Data Trees ..... 25
2.3.1 Xml Data Model ..... 25
2.3.2 Xml Data Model Specifics ..... 26
2.3.3 Mapping to Nested Words and Back to Xml Documents ..... 28
2.4 Nested Word Automata ..... 29
2.4.1 Definition ..... 29
2.4.2 Runs of Nested Words ..... 30
2.4.3 Runs on Marked Trees ..... 31
2.4.4 Determinization of NWAs ..... 32
2.5 Recursive Functions ..... 34
2.5.1 Partial Orders and Fixed Points ..... 34
2.5.2 Lambda and Letrec Notation ..... 35
I A Formal Semantics of XPath 3.0 ..... 39
3 Navigational XPath 3.0 ..... 41
3.1 Overview ..... 41
3.2 Grammar ..... 42
3.2.1 EbNF ..... 42
3.2.2 Expressions ..... 43
3.2.3 Parse Tree ..... 44
3.3 Path Expressions ..... 45
3.3.1 Forward and Backward ..... 45
3.3.2 Label Tests ..... 46
3.3.3 Kind Tests ..... 46
3.3.4 Relative, Absolute, and Abbreviated Expressions ..... 46
3.3.5 Filters ..... 47
3.3.6 Compositions ..... 47
4 Types and Values ..... 49
4.1 Sequence Type Expressions ..... 50
4.2 Basic Types ..... 51
4.2.1 Atomic Types ..... 51
4.2.2 Union Types ..... 51
4.2.3 Node Types ..... 51
4.2.4 Function Types ..... 53
4.3 Sequence Types ..... 53
4.4 Subtyping ..... 54
4.4.1 Item Types ..... 54
4.4.2 Sequence Types ..... 54
4.5 Dynamic Type Checking ..... 54
5 Full XPath 3.0 ..... 57
5.1 Grammar ..... 58
5.1.1 Basic Expressions ..... 58
5.1.2 Navigational Expressions ..... 59
5.1.3 Postfix Expressions ..... 59
5.1.4 Terminal Expressions ..... 60
5.1.5 Parse Tree ..... 61
5.2 Values ..... 62
5.2.1 Strings and Numbers ..... 62
5.2.2 Booleans ..... 62
5.2.3 Functions ..... 63
5.2.4 Sequences ..... 63
5.2.5 Conversions ..... 65
5.3 Positions ..... 65
5.4 Navigation ..... 66
5.4.1 Path Expressions ..... 66
5.4.2 Map Operator ..... 66
5.5 First-Order Connectives ..... 67
5.5.1 Arithmetics ..... 67
5.6 Data Comparisons ..... 67
5.6.1 Atomic ..... 68
5.6.2 Nodes ..... 68
5.6.3 Sequences ..... 68
5.7 Ordered Sets ..... 68
5.7.1 Duplicate-free Sequences ..... 69
5.7.2 Computing Sets when possible ..... 69
5.8 Error Handling ..... 70
5.8.1 Kinds of Errors ..... 70
5.8.2 Try and Catch Expressions ..... 70
5.9 Documents ..... 71
5.10 Regular Extension of XPath 3.0 ..... 71
5.11 XPathMark Benchmark ..... 72
$6 \lambda \mathbf{X P}$ ..... 75
6.1 Types and Values ..... 76
6.1.1 Typing Parameters ..... 76
6.1.2 Atomic Types ..... 76
6.1.3 Types ..... 77
6.1.4 Subtyping ..... 77
6.1.5 Equality Types ..... 78
6.1.6 Admissible Types ..... 79
$6.2 \quad \lambda \mathrm{XP}$ Queries ..... 79
6.2.1 Philosophy of Sets and Functions ..... 79
6.2.2 Constants ..... 80
6.2.3 Syntax ..... 81
6.2.4 Positive Contexts ..... 82
6.2.5 Type System ..... 82
6.2.6 Library Functions ..... 83
6.2.7 Recursive Functions ..... 85
6.2.8 Regular Axes ..... 85
6.2.9 Datalog ..... 86
6.2.10 Data Comparisons ..... 87
6.3 Semantics ..... 87
6.3.1 Complete Partial Orders ..... 87
6.3.2 Denotational Semantics ..... 90
6.3.3 Well-definedness ..... 91
6.3.4 Correctness ..... 92
6.4 Safety Restrictions ..... 93
7 XPath to $\lambda \mathbf{X P}$ ..... 95
7.1 Instantiation of $\lambda \mathrm{XP}$ ..... 95
7.2 Library functions ..... 96
7.2.1 Access to Node Labels ..... 96
7.2.2 Lists of Nodes ..... 97
7.2.3 String Data Value of Nodes ..... 97
7.2.4 Atomization of Sequences ..... 98
7.2.5 Numerics ..... 99
7.2.6 Booleans ..... 99
7.2.7 Strings ..... 100
7.2.8 EQNames ..... 100
7.2.9 Positions ..... 101
7.2.10 Roots and Input Documents ..... 102
7.3 Compiling the XPath 3.0 Grammar to $\lambda$ XP ..... 102
7.3.1 Navigational XPATH Expressions ..... 102
7.3.2 Arbitrary XPath Expressions ..... 106
7.3.3 Ordering Mode of XQuery ..... 109
II Early Query Answering for Navigational XPath ..... 113
8 Early Nested Word Automata ..... 115
8.1 Introduction ..... 116
8.2 Automata Queries ..... 117
8.2.1 Tuple Selection ..... 118
8.2.2 Monadic Queries ..... 118
8.2.3 Queries by Automata ..... 118
8.2.4 Earliest Query Answering ..... 121
8.3 Early Nested Word Automata ..... 121
8.4 FxP ..... 122
8.5 Compiler from FXP to Early Nested Word Automata ..... 124
8.5.1 ENWA Descriptors ..... 124
8.5.2 When Variables Must be Bound ..... 125
8.5.3 Construction of ENWA Descriptors ..... 126
8.5.4 Construction of the ENWA descriptor $D_{F}(\mathcal{E})$ ..... 127
8.5.5 Correctness ..... 131
8.5.6 Size of Automata Descriptors ..... 132
8.5.7 Time to Compute Automata Descriptors ..... 134
8.6 Early Query Answering ..... 137
8.6.1 On-the-fly Instantiation and Determinization ..... 137
8.6.2 Streaming Algorithm for Deterministic ENWAs ..... 138
8.6.3 Adding Stack-and-State Sharing ..... 139
8.7 QuiXPath tool ..... 143
8.7.1 Implementation, Tools, and Applications ..... 143
8.7.2 Benchmarks ..... 143
8.7.3 Performance Comparison ..... 144
8.7.4 Performance Analysis ..... 146
8.7.5 Detailed Analysis ..... 149
9 Projection ..... 153
9.1 Introduction ..... 153
9.2 A Nested Word Automaton ..... 154
9.3 Projection NWAs ..... 155
9.3.1 Projected Nested Words ..... 155
9.3.2 Projection Nested Word Automata ..... 156
9.3.3 Examples of PNwas and Runs ..... 158
9.3.4 Evaluation of Projection Nwas ..... 159
9.4 Irrelevant Labels and Prefixes of Nested Words ..... 160
9.5 Projection from Nwas to PNwas ..... 162
9.6 Node Selection ..... 164
9.7 Experiments ..... 166
III Query Evaluation Algorithms for Full XPath ..... 169
10 In-Memory Evaluation of $\lambda$ XP Queries ..... 173
10.1 Simplification of $\lambda$ XP Queries ..... 173
10.1.1 Simple Queries ..... 174
10.1.2 Decomposition into Networks of Navigational Queries ..... 174
10.1.3 Backward Axes Elimination ..... 175
10.2 Evaluation Algorithm ..... 176
10.2.1 Specification ..... 176
10.2.2 Implementation ..... 184
10.2.3 Examples ..... 184
11 Streaming Evaluation of $\lambda$ XP Queries ..... 187
11.1 Streaming Evaluators ..... 187
11.1.1 Restrictions ..... 188
11.1.2 Linearizing a Sequence of Trees ..... 190
11.1.3 Updates ..... 190
11.1.4 Extended Types ..... 192
11.1.5 Open Values ..... 192
11.1.6 Registrations ..... 193
11.1.7 Program and Query Evaluators ..... 195
11.1.8 Running Evaluators over Streams ..... 196
11.2 Evaluators ..... 198
11.2.1 Generic Functions ..... 198
11.2.2 Inductive Construction of Evaluators ..... 201
11.3 Examples ..... 244
11.3.1 Navigational Queries ..... 244
11.3.2 A Network of Queries ..... 246
11.4 Tuple Sharing ..... 247
11.5 Experiments ..... 249
12 Conclusion and Outlook ..... 251
A XPathMark Benchmark ..... 253
A. 1 Downward Queries ..... 253
A. 2 Axis Queries ..... 254
A. 3 Comparison Queries ..... 254
A. 4 Aggregation Queries ..... 255
A. 5 Position Queries ..... 255
A. 6 Closure Queries ..... 256
B XPath to $\lambda$ XP Compiler ..... 259
B. 1 Basic Expressions ..... 261
B.1.1 XPath expressions ..... 261
B.1.2 Nonterminals to define inline function expressions ..... 261
B.1.3 Sequence constructions ..... 261
B.1.4 Single expressions ..... 261
B.1.5 Sequence decompositions ..... 261
B.1.6 Let expressions ..... 262
B.1.7 Quantified expressions ..... 262
B.1.8 First-Order expressions ..... 263
B.1.9 Comparisons ..... 264
B.1.10 Concatenation of strings ..... 266
B.1.11 Range expressions ..... 267
B.1.12 Arithmetic Expressions ..... 267
B.1.13 Ordered Sets ..... 268
B.1.14 Type checks and casts ..... 269
B.1.15 Unary Expressions ..... 270
B.1.16 Value expressions ..... 270
B.1.17 Comparison operators ..... 271
B.1.18 Simple Map expressions ..... 271
B. 2 Navigational Expressions ..... 272
B.2.1 Absolute path expressions ..... 272
B.2.2 Relative path expressions ..... 272
B.2.3 Steps ..... 272
B.2.4 Axis steps and Filters ..... 273
B.2.5 Axis Steps ..... 274
B.2.6 Node Tests, Name Tests, and Wildcards ..... 275
B. 3 Postfix expressions ..... 276
B.3.1 Postfix expressions ..... 276
B.3.2 Argument Lists and Predicates ..... 276
B.3.3 Primary expressions ..... 276
B.3.4 Literals ..... 276
B.3.5 Variables ..... 277
B.3.6 Parenthesized expressions and the empty list ..... 277
B.3.7 Context Item, Position, and Size ..... 277
B.3.8 Function Calls ..... 277
B.3.9 Functions ..... 278
B.3.10 Simple Types ..... 279
B. 4 Sequence Type Expressions ..... 279
B.4.1 Top level Sequence Type Matching ..... 279
B.4.2 Item types ..... 280
B.4.3 Atomic and union types ..... 280
B.4.4 Kind Tests ..... 280
B.4.5 Node and Type Names ..... 283
B.4.6 Function Tests ..... 284
B.4.7 EQNames ..... 284
B. 5 Terminal Expressions ..... 284
Bibliography ..... 287

## Chapter 1

## Introduction

## Contents

1.1 Xml Processing based on XPath ..... 2
1.1.1 Schema Validation ..... 2
1.1.2 Query-based Transformation ..... 4
1.1.3 XPatH ..... 5
1.1.4 Regular Extension of XPath ..... 8
1.1.5 In Memory Evaluation ..... 8
1.1.6 Streaming Evaluation ..... 9
1.2 Open Problems ..... 12
1.2.1 Low Coverage ..... 12
1.2.2 Low Latency ..... 13
1.2.3 Low Time Efficiency ..... 13
1.2.4 Lack of Formal Semantics. ..... 13
1.3 Contributions ..... 14
1.3.1 Formal Semantics of XPath 3.0 in $\lambda \mathrm{XP}$ ..... 14
1.3.2 Early Query Answering by Early Nwas ..... 14
1.3.3 Networks of Early Nwas ..... 15
1.3.4 Projection for Nwas ..... 15
1.3.5 Implementation and Experiments ..... 16
1.4 Organization ..... 16
1.5 Publications ..... 17

The eXtended Markup Language (XmL) provides a format for general information representation [Bray 2008], which is standardized by the World Wide Web Consortium (W3C) and largely used today for exchanging information between all kinds of application. Essentially, the Xml format provides a concrete syntax for describing data trees, i.e., finite unranked trees whose nodes are labeled by data values.

There are three communities that joined their forces within the W3C for creating XmL that correspond to the following application areas: document processing as with DocBook [Walsh 2010a] or Sgml [Goldfarb 1986], Web information representation as with HTML [Pemberton 2002, Hickson 2014], and NoSQL databases with nested relations [Meier 2000, Grün 1983, Bloom 2001], where NoSqL stands

```
<twitter>
    <tweet><id>2</id><user>984</user><mess>@PPeter @Marctotheus My
        washing machine just broke down :(</mess></tweet>
    <tweet><id>4</id><user>349</user><reply>2</reply><mess>
        @IthinkThat I advise you to buy a Miele one. Those run forever
        </mess></tweet>
    <tweet><id>6</id><user>984</user><reply>4</reply><mess>@PPeter
        Thx, I will definitely check them out.</mess></tweet>
</twitter>
```

Figure 1.1: An Xml document.
for "not only SQL" [Beyer 2011, Robinson 2015]. Xml was a success story in the first two domains, with biggest success for the usage of input and output format for all kinds of computer programs, so that it can be avoided to write any ad-hoc parsers.

Xml had fewer success with NoSqL databases and the development of Web services, for which a new format of data trees was developed, called the Java Script Object Notation (Json) [Crockford 2001], which despite of its name is independent of the programming language of Web browsers Java Script [Eich 2015]. The data trees of Json can be seen as nested key-value stores, i.e. as unranked unordered trees, in which each edge is annotated by a data value. Furthermore, a key constraint must be satisfied, stating that no two edges outgoing from the same node carry the same data value. The development of recent kinds of NoSQL databases relies on the Json format rather than on XmL, since focussing on distributed query answering algorithms [Friedgut 2004, Atserias 2013, Ngo 2013, Beame 2014, Beame 2013] in contrast to previous XmL databases. The data trees underlying Json and Xml are not that different and can be converted to the other data tree, respectively.

### 1.1 Xml Processing based on XPath

The main task for XmL processing are the problems to validate, query and transform data trees. An example is the data tree of Figure 1.2 that models a collection of tweets that reply to each other, i.e. it models the Xml document in Figure 1.1.

### 1.1.1 Schema Validation

Validation of XmL documents means to verify their conformance against a given schema. For instance, for the data tree of Figure 1.2 one would like to verify the existence of mess-child of a tweet-descendant that contains a non-empty data value, as with XPath filter
[//tweet/mess[not(. = "")]].


Figure 1.2: A data tree representing the XmL document of Figure 1.1.

One would also want to check that every assigned data value of an id node of a tweet is unique. This can be done with the following XPath query that uses function distinct-values that returns the input sequence of id values, but with duplicates removed:

```
count(//tweet/id) = count(distinct-values(//tweet/id/text()))
```

There are several standard schema languages performing validation. The W3C started with Dtds [Bray 2008] and then moved to more powerful Xml Schema [Thompson 2004]. For instance, the syntax of XHTML is defined by a Xml Schema, and also the syntax of DocBook, or the syntax of MathXml for representing mathematical formulas. The document community supported Relax NG [van der Vlist 2003], which was standardized by ISO. For instance, the syntax of the system biology markup language SbmL is defined in Relax NG, while it was previously defined in Xml Schema.

More recently, Schematron [Jelliffe 2006] was developed for an alternative validation approach, where schemas are expressed by XPath filters. This has the advantage that errors can be localized more easily, so that error messages can be more informative. An example is the following XPath filter that verifies that all tweet-labeled descendants have an id, a mess, and a user-labeled child. A corresponding Schematron program would output an error message for every missing id, mess, or user-child of a tweet descendant, and vice versa could report that a particular child exist.

```
[not(//tweet[not(id) or not(mess) or not(user)])]
```

The expressiveness of these schema languages was studied in numerous research papers [Martens 2006b, Martens 2006a]. It was shown that when ignoring data comparisons, DTDs describe vertically local languages of unranked trees, while Xml schemas describe top-down and left-to right deterministic languages of unranked trees, so that they can be validated in streaming mode. The expressiveness
of Schematron, when restricted to XPath filters without advanced concepts (see Section 1.1.3) is restricted to first-order logic, while Relax NG supports general tree automata, and thus monadic second-order logic [Thatcher 1968, Comon 2007, Gottlob 2002].

### 1.1.2 Query-based Transformation

For solving the query-based transformation tasks, the W3C has developed the transformation languages Xslt [Clark 1999a], XQuery [Boag 2007], and XProc [Walsh 2010b]. As a common core, they rely on XPATH [Clark 1999b] for querying data trees for nodes, strings, functions, or sequences thereof. In XQUERY, transformations can then be expressed, similar to SQL data bases, by FLWOR expressions (for, let, where, order by, and return) as in XQuERY

```
for $x in doc("twitter.xml")//tweet
where contains($x/mess,"washing machine")
order by $x/id
return $x/following-sibling::tweet[reply = $x/id]
```

which returns a list of all tweet-nodes that reply to some tweet whose message contains "washing machine". The core of XQUERY studied in [Benedikt 2009] exactly captures the class of first-order definable transformations.

XsLT transformations are expressed via stylesheets that declare a set of transformation rules that are based on XPath expressions. The core of Xslt can be defined by navigational macro tree transducers, where the navigation is defined by XPath queries [Maneth 2005]. For example the following Xslt program produces HTML code that displays a table of all tweet ids and their messages.

```
<xsl:stylesheet version="1.0"
xmlns:xsl="http://www.w3.org/1999/XSL/Transform">
<xsl:template match="/">
    <html><body>
        <h2>Tweet Collection</h2>
        <table border="1"><th>ID</th><th>Message</th>
            <xsl:for-each select="twitter/tweet">
                <tr><td><xsl:value-of select="id" /></td>
                    <td><xsl:value-of select="mess" /></td></tr>
            </xsl:for-each>
        </table>
    </body></html>
</xsl:template>
</xsl:stylesheet>
```

As shown by Maneth and Engelfriet [Engelfriet 2000], macro tree transducers with bounded copying capture the class of all MSO-definable transformations. This
remains true, when adding XPath queries for navigation, as long as these XPath queries remain first-order definable.

XProc is an Xml pipeline language whose programs allow to compose several processing tasks and transformations.

### 1.1.3 XPath

XPath [Clark 1999b] is a language standardized by the W3C for defining node selection queries in data trees. The selection conditions may rely on XPath filters that we encountered already in the section on Xml schemas.

XPath was designed to be a core language hosted by all other XmL processing languages of the W3C, and in particular for defining transformations of data trees based on node selection queries with Xslt, XQuery, and XProc. Currently, there are three W3C recommended versions of XPath [Clark 1999b, Berglund 2010, Robie 2014a] with version numbers 1.0, 2.0, and 3.0. The syntax got extended with each version in order to increase the expressiveness as we will discuss below, while the semantics basically remained unchanged except for the handling of errors and exceptions, and for changes in the type system. Furthermore, the current XPath 3.0 language is given two possible semantics, the ordered semantics used in Xslt transformations and standardized in the W3C document about XPATH 3.0 and the unordered semantics that is used by XQuery as stated in the W3C document on XQuery 3.0 [Robie 2014c]. The difference between these two semantics is that sets are either treated as unordered collections or as sequences in the order of their elements.

This difference is often crucial when it comes to stream processing, since when imposing an order on sets, the latency and buffering needs may increase dramatically. For instance, if one wants to select all tweets with a reply on a twitter stream, but the first tweet does not have any reply, then one must wait until the last tweet arrives, before one can be sure that the first tweet is not selected. In an ordered mode, one needs to output the selected tweets in their order, so the output of all other answers has to wait on the decision for the first tweet, and thus until the very end.

The core of XPATH is a navigational logical language that provides path queries for node selection in Xml data trees [Gottlob 2002, Gottlob 2003]. For instance, the following XPath query selects all message nodes of tweets, that do not have an empty data value:
//tweet/mess[not(. = "")].

Navigational queries may navigate in a data tree moving along the tree relations such as child, descendant, parent, ancestor, following sibling, preceding sibling, following, preceding, etc. They may also test whether the label or data value of a node is equal to some constant.

One of the motivations of the design of XPath was that it should support all first-order connectives, as usual with database queries. This should also hold for its navigational core which is a variable free language in the style of modal and
temporal logics [Arenas 2007]. We already encountered negation in the previous XPath example. Filters of a node express existential properties, stating that some node can be reached when navigating over some path, and multiple filters express conjunctions. Based on negation, universal properties can be expressed by existential properties, and disjunctions by conjunctions. Also existential and universal quantifications exist within the language. For instance, filter

```
some $a in //a satisfies $a/b
```

asks whether there exists an a descendant that has a b child.
Marx and de Rijke [Marx 2004b] showed that the filters of the navigational core of XPATH 1.0 can be mapped to first-order logic formulas with at most 2 variables per subexpression. The variables that are counted here are not only the free variables - of which we need one for node selection and none for filters - but also the free variables of the subexpressions, which may be globally bound. It is well-known, however, that the two variable fragment is not complete for first-order logic of trees. A counter example is the query

$$
a / b^{*} / c
$$

which selects all $c$ nodes $x$ with an $a$-ancestor $y$ such that all intermediate nodes $z$ on the path from $y$ to $x$ are labeled by $b$. Here, three variables are needed, $x, y$, and $z$. Since using recursion based on the Kleene-star, this query is not supported by the syntax of XPATH (in any version), and even worse, it cannot be expressed in the navigational core of XPath 1.0.

This incompleteness problem of XPATH was solved starting with version 2.0 [Berglund 2010], which added the missing expressiveness by adding operator except for path complementation. There the missing query can be expressed as follows ${ }^{1}$ :
/a//c except /a//*[not(fn:local-name(.) = "b")]//c.

As a consequence the navigational core of XPATH became first-order complete, since 3 variables are known to be enough for expressing arbitrary first-order properties of trees [Marx 2004a].

Besides the navigation core, XPATH also permits to select, compare, and aggregate data values in data trees, and to apply all kinds of functions to them, including the usual arithmetic functions and string operations. For first-order logics of data trees with comparisons of data values, however, the 3 variable fragment is no more sufficient. Therefore XPath 2.0 did also add variables to the language. Query

```
for $t in //tweet return following-sibling::tweet[reply = $t/id],
```

for example, returns all tweets that reply to some start tweet, i.e. with the XQUERY unordered semantics. It binds to variable $\$ \mathrm{t}$ progressively all tweet descendants, and returns all following-sibling tweet nodes whose reply child is equal to the id


Figure 1.3: Graph of first-order query for XPATH query for $\$ \mathrm{t}$ in //tweet return following-sibling::tweet[reply = \$t/id].
child of the node at $\$ \mathrm{t}$. A corresponding first-order formula requires at least 4 variables as in query $\{\$ \mathrm{t}, \mid \exists \$ \mathrm{t}, \$ \mathrm{i}, \$ \mathrm{r}: \Phi(\$ \mathrm{t}, \mathbf{\$ t}, \$ \mathrm{i}, \$ \mathrm{r}), \Phi$ presented in Figure 1.3$\}$.

XPath 3.0 comprises a new type system that contains a large domain of data types that are based on sequences. Sequences are ordered shallow lists, that are not nested, whose single element instances are identified with the element itself, making XPath 3.0 an expression language for processing sequences. Query

```
for $x in (1, 2, 3) return $x + 4
```

returns sequence (5, 6, 7), for example. The conversion of data types is also supported within XPATH, for example, it provides conversion function fn:boolean that converts numbers, strings, and sequences of nodes to a boolean, allowing for richer test expressions for conditionals and filters, as in query

```
if ("abc") then fn:true() else fn:false()
```

that returns true, since fn : boolean ("abc") $=$ true. Furthermore, XPATH can also express aggregation queries and supports higher-order functions, such that even first-order logic is not enough!

Functions have become first-class citizens in XPATH 3.0 and they may be of higher order. They can be defined inline within expressions as in query

```
function($a as xs:double, $b as xs:double) as xs:double {$a * $b}
```

that returns the product function, or functions can be returned by partial function applications, such as
fn:concat("a", ?, "c")
which returns the anonymous function $\lambda y . f n: \operatorname{concat("a",~} y$, "c") that accepts one argument.

[^0]
### 1.1.4 Regular Extension of XPath

Extensions of XPath by a Kleene-star operator for recursive path composition were proposed by many research papers [ten Cate 2007, Groz 2012, Parys 2011]. Recursive path queries are already interesting for navigational XPath queries such as $a / b^{*} / c$. These can be expressed otherwise by using path complementation (as available since XPath 2.0). But this kind of encoding does not work in general. For instance one cannot express $a /(b / b)^{*} / c$ in XPath. Furthermore, the encoding of conditional regular axis, which have the form $\mathrm{b}[\mathrm{F}]^{*}$ where F is some filter, by using complementation is cumbersome, and spoils the combined linear time complexity for query answering.

In XPath 3.0 the Kleene-star operator is not supported syntactically, but it can be expressed in the general case by using recursive functions as we will explain later on. Nevertheless we will consider in this thesis an extension of XPath 3.0 with the Kleene-star operator that we call regular XPath 3.0. The addition of the Kleenestar operator will mainly serve us for simplifying the presentation of recursive path queries in examples, and can be eliminated without problems by using recursive functions.

Recursive path queries are particularly relevant when combined with variables and comparisons of data values (data joins). For instance, we can use a regular XPath 3.0 query to select dialogs in a Twitter stream:

```
//tweet[fn:contains(mess, "washing machine")]
    /(let $y := . return following-sibling::tweet[reply = $y/id])*
```

The query navigates to tweet-labeled nodes whose message mess contains "washing machine", and from there it navigates recursively to following-sibling tweets that reply to it. It thereby select the nodes of Figure 1.4 that are marked in bold. For the second tweet with id " 2 ", the dialog query reports the tweet messages of repeated replies, finding tweets with ids " 4 ", " 5 ", and " 6 ".

### 1.1.5 In Memory Evaluation

Evaluation algorithms for XPath queries receive an XPath query $Q$ and an XmL document $D$ as an input, and compute the set of query answers $Q(D)$. Two kinds of evaluators should be distinguished: those who store the whole XmL document as a data tree in main memory in a preprocessing phase where all kinds of indexes can be computed, and those which read the Xml document as a stream in an incremental left-to-right once-only manner.

The complexity of in-memory evaluation algorithms for XPATH fragments found much interest in database theory. For navigational XPath queries without variables from the core of XPath, there exist evaluation algorithms that require combined linear time in the worst case, i.e. time in $O(|Q| \cdot|D|)$ [Gottlob 2005]. When adding comparisons of data values, query answering remains in polynomial time $O\left(|Q|^{3}\right.$. $|D|)$, see Theorem 1.1 in [Bojańczyk 2011], which is even linear in the size of the

$m_{1}=$ I bought me a new pair of asics. And off I go.
$m_{2}=@$ PPeter @Marctotheus My washing machine just broke down :(
$m_{3}=$ @loosingg That's awesome ;)
$m_{4}=@$ IthinkThat I advise you to buy a Miele one. Those run forever
$m_{5}=@$ IthinkThat Oh, but it's not like I can do anything about it.
$m_{6}=@$ PPeter Thx, I will definitely check them out.
Figure 1.4: A Twitter stream containing a dialog.
database. When recursive paths are also permitted, the worst-case complexity increases slightly to $O\left(|Q|^{3} \cdot|D| \cdot \log |D|\right)$. In contrast to these theoretical algorithms, the algorithm from Saxon may run in exponential time in the size of the database even for navigational queries. The problem may arise for queries where the number of alternations between forwards and backwards axis is not bounded, as illustrated by example in [Parys 2011].

The weakness of all these theoretical algorithms is that they traverse the whole database $D$ even for queries $Q$ that require to inspect only the local environment of a given tree node. This important problem can be approached in some algorithms by adding data tree projection as proposed in [Marian 2003, Maneth 2010]. The idea is to discover irrelevant parts of the database during query answering, and to avoid inspecting them as if they were pruned away. Indeed, the projection algorithm for XQuery from [Marian 2003] is used in Saxon [Kay 2004], the most used Xml processing tool for XQuery and Xslt as of today. Good projection algorithms for Xslt are missing though. While not available in Saxon, there exist good projection algorithms for large navigational fragments of XРАтн [Maneth 2010, Arroyuelo 2015] based on tree automata techniques with highly efficient implementations based on clever indexing.

### 1.1.6 Streaming Evaluation

When one wants to select dialogs in Twitter streams in real time, one cannot wait until the end of the stream arrives. Instead one would like to query it as stream of complex events - having a nesting structure - in real time and in an incremental manner. This requires to buffer all tweets of the dialog, since replies to any of these tweets may arrive with arbitrary delay. This is in contrast to sliding window techniques for monitoring continuous streams, which will buffer only a bounded
number of subsequent events on the stream [Barbieri 2010, Phuoc 2011].
The task of online dialog selection in Twitter streams is a special case of complex event processing (CEP) [Brenna 2009, Wu 2006, Mozafari 2012], which is equally relevant for the analysis of stock markets, Rss feeds, and social network posts. In the case of dialog selection, CEP can be reduced to querying XmL streams, i.e., linearizations of data trees in Xml format. As argued by [Mozafari 2012], this also holds for the other CEP tasks mentioned above.

The problem to answer XPath queries on Xml streams has been studied for more than a decade [Gupta 2003, Fernández 2007, Olteanu 2007, Schmidt 2007, Benedikt 2007, Madhusudan 2009, Kay 2010, Gauwin 2011a, Mozafari 2012]. The main motivation here was to deal with huge documents which do not fit into main memory, or large documents (say 40 gigabytes) for which the time to create an in-memory representation would impose a too long delay.

Low Latency. Suppose that we want to select all tweets that have a reply on a Twitter stream, while we assume the unordered mode for the output set. The natural idea to do so works as follows. Any new tweet that arrives on the stream is an alive candidate, of which one does not know yet whether it will become an answer. Therefore it must be buffered until the decision can be taken. Furthermore, whenever a newly arriving tweet is a reply to a previous one in the buffer, then this buffered tweet is a candidate that can be safely selected. In this case it can be output and removed from the buffer.

More generally, the idea for answering queries on XmL streams is to buffer all alive candidates, until one can decide whether they answer the query or not for all continuations of the stream. An algorithm that buffers only alive candidates is called earliest. Any algorithm performing earliest query answering (EQA) must output query answers with lowest latency and discard failed candidates at the earliest time point. Unfortunately, it turns out that EQA is not feasible in polynomial time for XPath queries [Benedikt 2008b], as first shown by adapting counter examples from online verification [Kupferman 2001]. A second hardness argument follows from that deciding aliveness is more difficult than XPATH satisfiability [Gauwin 2011a], which is CoNP-hard even for small fragments of XPath [Benedikt 2008a].

The situation is different for queries defined by deterministic nested word automata (NwAs) [Alur 2004, Alur 2009], for which earliest query answering is feasible in cubic time in the size of the automaton [Madhusudan 2009, Gauwin 2009b]. This can be applied to navigational XPATH queries by compilation to NwAs [Gauwin 2011a], but this does not lead to an efficient streaming algorithm. The first problem is that cubic time per event is too much in practice. The second problem is that the compiler from XPath to Nwas relies on nondeterminism for descendant and following axes, and that the determinization of NwAs often raises huge blow-ups in practice (in contrast to finite automata).

Since EQA is not feasible, existing streaming algorithms for XPATH evaluation either approximate EQA or restrict the problem to 0-delay queries. Approximations
are done by Spex's, which compiles navigational XPath queries to transducer networks [Olteanu 2007], but also by Saxon's streaming Xslt engine [Kay 2010], and Gcx [Schmidt 2007] which implements a fragment of XQuery.

The recent XSeq tool [Mozafari 2012], in contrast, restricts XPath queries by ruling out complex filters all over. In this way, node selection can always be decided with 0-delay [Gauwin 2011b] once having read the attributes of the node (which follow its opening event). Such queries are called begin-tag determined [Benedikt 2007] if not relying on attributes.

Low Memory. A principle question is how much memory one may want to allow for the streaming processing. Given that a stream can be read only once, from left to right, one has to buffer parts of the stream that will be needed later on again. The main objective may be to minimize the size of the buffer as with EQA, given that streams may be huge or even infinite (in the case of Twitter).

Ideally, one would like to grant only constant memory, and thus be independent of the size of the stream. But this allows hardly any query to be evaluated in streaming mode. First of all, streaming algorithms for data trees typically have a stack whose depth is equal to the depth of the tree, so if the depth of the tree is not bounded, the memory will not be bounded. In practice, however, the depth of the tree may become large but rarely huge, so that the stack fits into the main memory. The second problem is about the size of the buffer which may grow linearly with the size of the document, for instance for the query that selects all tweets with a reply on a Twitter stream, where no tweet has a reply.

Besides the dependence on the depth of the XmL tree and the number of candidates that have to be stored, many interesting queries require to buffer data content of the Xml document. For instance, if one wants to verify that no two tweets have the same Id, one needs to store the Ids of all tweets. If the Twitter stream is large but not huge then it may as well happen that the set of all Ids fits into main memory while the whole stream does not.

Time efficiency. Time efficiency is of paramount importance for XPath query answering on XML streams in practice. When the query is fixed, only constant time should be needed for each event, so that the overall time is linear in size of the stream. The typical case where this may fail even for navigational queries without variables, is when the number of buffered candidates grows with the size of the stream. In this case, one must avoid inspecting all the candidates in the buffer at any event.

When measuring the time efficiency, it is important to separate the pure parsing time from the time for answering queries. The reason is that one usually has to answer a collection of XPath queries - stemming from an Xslt or XQuery program - at the same time. The parsing time may be shared between all these XPath queries while the time for answering the query cannot be shared. Furthermore, the parsing-free time for answering a single XPATH query is often dominated by the
parsing time, so that one may quickly take wrong conclusions when not separating these two time measures.

It is also interesting to compare the time requirements of streaming and inmemory algorithms. Both algorithms have to parse the Xml document. While inmemory algorithms may compute some indexes during preprocessing, this cannot be done for streaming algorithms. Besides, the parsing-free time of a streaming algorithm should correspond to the time needed by an in-memory algorithm after preprocessing, except for the benefits of using indexes. The advantage of streaming algorithms may be a lower latency. In applications such as streaming validation, this may help to avoid reading the whole document, and thus spare parts of the parsing time and of the preprocessing time. Generally, when only a few queries have to be answered on the same document, streaming evaluators tend to be more efficient than in-memory evaluators, since the cost of computing the indexes does often not get amortized when answering few queries only.

### 1.2 Open Problems

From the practical perspective the main open problem is that there is no streaming algorithm for XPATH 3.0 with high coverage, low latency, high time efficiency, and low memory consumption. The question is whether such an algorithm may exist, given that EQA is computationally hard.

### 1.2.1 Low Coverage

The coverage of existing tools for navigational XPATH is quite limited and the support of non-navigational concepts is even worse, in particular the support for variables, comparisons of data values, sequences, arithmetics, string operations, aggregations, and higher-order functions.

For instance, the GcX system is the only system that allows to evaluate XPATH queries in streaming that perform some data comparisons, but in order to obtain this, the supported navigational aspects are minimalized. The navigational aspects are also strongly restricted in XSEQ, given that only 0-delay queries are supported, where the selection of a node can be decided after having read its opening tag and its attributes.

When looking into the usual XPathMark benchmark [Franceschet 2005] the best coverage is reached by Olteanu's Spex [Olteanu 2007] with $22 \%$ of the use cases. The time efficiency of Spex, however, is only average, for instance compared to Gcx [Schmidt 2007] which covers $19 \%$ and which often runs in time close to the parsing time for a single query. Given that Saxon is mostly interested in Xslt and XQUERY evaluation, the support for the navigational aspects XPATH remains limited, leading to $6 \%$ of coverage for the XPATHMARK benchmark.

### 1.2.2 Low Latency

Since EQA is computationally hard, one cannot hope for algorithms with minimal latency. For this reason, some approaches including the XSEQ system are restricted to 0-delay queries, in order to avoid buffer management all over [Mozafari 2012, Benedikt 2008b]. Other approaches such as Spex do not impose delay restrictions, but have only low coverage since not supporting data joins, aggregation, higherorder functions, and recursion.

A good approximation of EQA is also essential to ensure low memory consumption. For this it is necessary to decide at a close to optimal time point whether a candidate is safe for selection or rejection for a given query. The earlier candidates can be selected or rejected, the lower will be the latency and memory consumption.

### 1.2.3 Low Time Efficiency

There are numerous reasons that limit the time efficiency of the existing streaming algorithms, many of which depend on the algorithmic approach that is chosen. One typical problem is to deal with queries with variables for tuple selection. In this case, the number of candidate tuples may even grow exponentially in the arity of the tuples. In the case of monadic node selection queries, the number of candidates is at most linear in the size of the stream. This may still raise time costs if all candidates are re-inspected at any event, typically for deciding whether they are still alive or already safe for selection or rejection. If the number of candidates grows linearly in the size of the stream, the overall running time will become quadratic, which is not feasible for large streams.

Another general problem is the lack of projection algorithms for streaming XPath query evaluation. This is an important problem, given that projection is essential for the performance of in-memory evaluators. So the question is how to obtain good projection algorithms for stream processing, by which to reduce the parsing-free query answering time.

### 1.2.4 Lack of Formal Semantics.

Similarly to all other W3C standards XPath has no formal semantics. The problem is that the standardization documents contain only informal descriptions of some hundreds of pages often specified on an abstraction level close to implementation. For example the XPath 3.0 grammar [Robie 2014b] already contains more than one hundred nonterminal symbols and there are hundreds of functions and operators [Kay 2014]. As a result, those definitions cannot serve as a basis for a formal analysis and moreover they are difficult to understand.

So the challenge is whether one cannot have a formal core language of XPATH that is based on first principles, to which all the different versions of XPATH can be mapped by following their specification in the standards. Defining such a core language seems also unavoidable if one wants to obtain large coverage streaming implementations.

### 1.3 Contributions

Our main contributions is a collection of algorithms that allow to evaluate full XPath 3.0 queries on Xml streams with low latency and with high time efficiency in practice.

### 1.3.1 Formal Semantics of XPath 3.0 in $\lambda$ XP

We introduce $\lambda \mathrm{XP}$, a typed first-order logical language for querying data trees based on first principles, supporting path navigation, higher-order functions, recursion, aggregates, tuples, lists, strings, and numbers.

To the best of our knowledge, the language $\lambda \mathrm{XP}$ is different to previous higherorder query languages [Benedikt 2015], in that $\lambda$ XP relies on a mode systems which permits to distinguish logical subformulas for which solutions must be searched, and functional subformulas that can be evaluated deterministically such as functional programs.

The purpose of $\lambda \mathrm{XP}$ in this thesis is to serve as a core language for implementing evaluators for XPath 3.0. Therefore, we show how to compile all of XPath 3.0 to $\lambda \mathrm{XP}$ with one minor exception. The compiler can be understood as a compact formalization of what is described informally in the specification of XPATH 3.0. Even though formal, we believe that some of the details of the XPATH 3.0 specification by the W3C are easier to understand through our compiler to $\lambda \mathrm{XP}$.

### 1.3.2 Early Query Answering by Early Nwas

Queries in the navigational fragment of $\lambda$ XP can be compiled to nested work automata (NwAs) as shown in [Gauwin 2009b], under the assumption that there are no backwards axis.

NwAs are the natural kind of pushdown machines for processing nested words such as XmL streams [Alur 2004]. They can be determinized in contrast to standard pushdown automata, basically since they have the same expressiveness as tree automata. Furthermore, EQA for queries defined by deterministic NWAs can be done in cubic time per event [Gauwin 2009b, Madhusudan 2009]. This is an interesting result, but since the resulting algorithm always requires cubic time in practice, this is by far too slow. Furthermore, determinism is assumed, which must be obtained by static determinization, which may lead to an exponential explosion - which does arise for many practically relevant queries - and even before the cubic time algorithm is applied.

We propose an approximation of EQA for navigational $\lambda$ XP queries, which does not require static determinization. For this we introduce so called early Nwas, which besides final states have selection and rejection states. Whenever a selection (rejection) state is reached, any continuation of the nested word will be accepted (rejected). We then show how to introduce appropriate selection and rejection states when compiling navigational $\lambda$ XP queries to early Nwas. What we obtain is an approximation of EQA, since it may still be the case that some candidate is safe for
selection even though the early Nwa is not in a selection state. But deciding whether an early NwA is in a selection state is much easier that deciding the aliveness of candidates, since the latter depends on its stack and its state. Indeed, the approximation is indeed exact for all positive navigational XPATH queries without valid or unsatisfiable subfilters as shown in [Lick 2013].

Our streaming algorithm for navigational $\lambda$ XP queries runs the corresponding early Nwa for all possible candidates, while performing on-the-fly determinization. A candidate is created and buffered only if it does not go into a selection or rejection state. A candidate from the buffer is output when the state of the candidate is a selection state, and discarded when it is a selection or rejection state.

In order to avoid inspecting all candidates at all events, we propose a stack and state sharing algorithm. The idea is that we can share the computation of any two candidates in the same state, so that the running time does not depend on the number of buffered candidates, but only on the number of states of the deterministic Nwa created by on-the-fly determinization. Our streaming algorithm with stack-and-state sharing for answering queries by early Nwas is original and nontrivial, and enables tight upper bounds for time and space complexity that we prove.

### 1.3.3 Networks of Early Nwas

We present a streaming evaluator for all $\lambda$ XP queries and thereby for all of XPath 3.0. The basic idea is that a formula of $\lambda \mathrm{XP}$ can be decomposed into a network of navigational $\lambda$ XP formulas with only forwards axis, each of which can be compiled to an early Nwa. Therefore, it remains to show how to evaluate networks of early Nwas in a streaming manner.

### 1.3.4 Projection for Nwas

We initiate the development of projection algorithms for processing XmL streams, and in particular for Nwas.

Our idea is that a projected nested word should contain jump symbols . $i$. for projected factors, where the integer $i$ stands for the excess of the factor, i.e., the difference between the number of opening and closing tags. We propose projection nested word automata (PNwas), a kind of mixed pushdown and counting automata, that input projected nested words which besides others contain integers as letters. Conversely, a projection of a nested word with respect to a given NwA can be computed by any corresponding PNwa. We then lift Nwa projection to the evaluation of navigational XPath queries on XmL streams. It turns out that the parsing-free time for our query answering algorithm for navigational XPATH queries reduces by a factor of 4 on average on the XPAthMARK benchmark.

### 1.3.5 Implementation and Experiments

We have implemented our algorithms for navigational XPATH queries and tested and compared them using the usual XPathMark benchmark. Considering only the navigational fragment of XPATH, we improve on all other tools in coverage with $37 \%$ of the XPathMark benchmark (the previous best is Spex with $22 \%$ ). We also outperform all of them in time efficiency with the exception of Gcx, which runs slightly quicker on few queries, and slightly slower on others.

### 1.4 Organization

The thesis starts with Chapter 2 on preliminaries that discusses data trees and their linearization into nested words. It continues on XML data trees that model the treestructure of the XmL data model, and it finishes with Nested Word Automata, that allow to process linearizations of such data trees. This thesis is organized into three main parts.

Part one on "A Formal Semantics of XPath 3.0" describes how the semantics of XPath can be described formally by $\lambda \mathrm{XP}$ expressions. It is split into the following five chapters. Chapter 3 on Navigational XPath describes the navigational XPath 3.0 fragment, Chapter 4 explains the types and values of XPath 3.0, while Chapter 5 presents full XPath 3.0. Various XPath expressions are explained abstractly, while not going into details of the XPath specification. Next, in Chapter 6 we introduce the $\lambda \mathrm{XP}$ language that allows to query data trees and supports higherorder functions and recursion. Then we present a compiler from XPATH to $\lambda$ XP in Chapter 7.

Part two on "Early Query Answering for Navigational XPATH" describes how XPath can be evaluated on Xml streams using Early Nested Word Automata, and how it is speed up by introducing projection thereof. Chapter 8 on Early Nested Word Automata compiles a forward navigational fragment of $\lambda \mathrm{XP}$ to early nested word automata which are run on XmL streams. We present a stack-andstate sharing algorithm that reduces the processing time per event to be linear in the number of states and stack symbols of the early nested word automata and we present and compare the efficiency of our streaming tool that implements the presented algorithms. In Chapter 9 we develop projection algorithms for nested word automata. For this we compile nested word automata into projection nested word automata that we introduce. These are used to produce the projected nested word on which it runs. We finish by an experimental section that shows the speedup that we gain with respect to the early query answering algorithm of Chapter 8.

Part three on "Query Evaluation Algorithms for Full XPATH" presents algorithms for evaluating $\lambda \mathrm{XP}$ formulas on data trees in-memory and in streaming. Chapter 10 presents in-memory evaluators of $\lambda \mathrm{XP}$ queries that rely on the mode system of $\lambda \mathrm{XP}$, which splits the logical and programming parts of $\lambda \mathrm{XP}$ queries. Chapter 11 turns the in-memory evaluator into a streaming evaluation algorithm. It runs early nested word automata for navigational $\lambda$ XP queries, while decomposing
general $\lambda \mathrm{XP}$ queries into a network of navigational queries.
We have added the following two appendices. Appendix A lists the full query collection of the XPathMark benchmark, which we use in our experiments. Appendix B gives a complete translation of the compiler from XPath 3.0 to $\lambda \mathrm{XP}$ expressions that follows the ordered semantics of XsLT.

### 1.5 Publications

A quick sketch of our results of Early Nested Word Automata for XPath Query Answering on Xml streams in Chapter 8 was published in the CIAA'2013 conference [Debarbieux 2013]. We published these results with full proofs and extended experiments in the Theoretical Computer Science Journal [Debarbieux 2015]. Our projection algorithms in Chapter 9 were published in the SOFSEM'2016 conference [Sebastian 2016].

## Preliminaries

## Contents

2.1 Data Trees ..... 19
2.1.1 Definition ..... 20
2.1.2 Logical Structure ..... 21
2.1.3 Finite State Abstractions ..... 22
2.1.4 Json Trees ..... 23
2.2 Nested Words ..... 24
2.2.1 Definition ..... 24
2.2.2 Linearization of Data Trees ..... 24
2.3 Xml Data Trees ..... 25
2.3.1 Xml Data Model ..... 25
2.3.2 Xml Data Model Specifics ..... 26
2.3.3 Mapping to Nested Words and Back to Xml Documents ..... 28
2.4 Nested Word Automata ..... 29
2.4.1 Definition ..... 29
2.4.2 Runs of Nested Words ..... 30
2.4.3 Runs on Marked Trees ..... 31
2.4.4 Determinization of NWAs ..... 32
2.5 Recursive Functions ..... 34
2.5.1 Partial Orders and Fixed Points ..... 34
2.5.2 Lambda and Letrec Notation ..... 35

We introduce basic notations needed throughout the chapters. We start by data trees and nested words. Then we discuss how the XPath data model can be modeled using data trees, and show what Xml streams are. Finally we introduce Nested Word Automata.

### 2.1 Data Trees

Data trees in this thesis will be unranked ordered finite rooted trees in which any node is labeled by a tuple of data values. In addition, any node will also be labeled by a tag from a finite alphabet.


Figure 2.1: A sample of a data tree: $t_{2.1} \in \mathcal{T}_{\text {XML }_{\text {types }}^{\prime}, \mathrm{UtF8} *}$.

### 2.1.1 Definition

We fix a finite ranked alphabet $\Sigma$ with arity function ar : $\Sigma \rightarrow \mathbb{N}$. Elements in $\Sigma$ are called node tags and ranged over by $\sigma$. We will sometimes write $\sigma^{(k)}$ to denote that $\operatorname{ar}(\sigma)=k$ for some $\sigma \in \Sigma$. Furthermore we let $\Delta$ be a finite set, whose elements will be called characters of data values or internal letters and ranged over by $c$.

We next define data trees with parameters $\Delta$ and $\Sigma$. A data value is a string over $\Delta$, and ranged over by $w$, i.e., $w \in \Delta^{*}$. The set of node labels $\mathcal{A}$ is defined as follows:

$$
\mathcal{A}=\bigcup_{\sigma^{(k)} \in \Sigma}\{\sigma\} \times \underbrace{\Delta^{*} \times \ldots \times \Delta^{*}}_{k}
$$

The elements of $\mathcal{A}$ will be ranged over by $a$. The set $\mathcal{T}$ of data trees $t$ over $\Sigma$ and $\Delta$ is the least set that contains all tuples $a\left(t_{1}, \ldots, t_{n}\right)$ where $a \in \mathcal{A}$ and $t_{1}, \ldots, t_{n} \in \mathcal{T}$. In other words, the set of data trees satisfies the following abstract syntax:

$$
t \in \mathcal{T}::=a\left(t_{1}, \ldots, t_{n}\right) \quad \text { where } a \in \mathcal{A}, n \geq 0, \text { and } t_{1}, \ldots, t_{n} \in \mathcal{T}
$$

We will sometimes write $\mathcal{T}_{\Sigma, \Delta}$ instead of $\mathcal{T}$ when we want to specify the signatures explicitly.

A data tree can be drawn as a graph in the obvious manner. An example motivated from the XmL data model is the data tree $t_{2.1}$ given in Figure 2.1. Here, $\Delta=$ UTF8 is the UTF-8 character set and $\Sigma=\mathrm{XmL}_{\text {types }}^{\prime}=\left\{d o c^{(0)}, e l^{(1)}\right.$, att $\left.^{(2)}, t x^{(1)}\right\}$ contains some of the Xml types. For element nodes the data value contains the XmL tag, for text nodes the text content, and for attribute nodes the attribute name and its attribute string-value.

### 2.1.2 Logical Structure

Let $k=\max (\{\operatorname{ar}(\sigma) \mid \sigma \in \Sigma\})$. For data trees, we define a logical structure with the following relational symbols:

$$
\begin{aligned}
& \left\{c h, c h^{+}, n s, n s^{+}, \text {par, par }{ }^{+}, p s, p s^{+}, f o, p c, f u t\right\} \cup \\
& \left\{\text { tag }_{\sigma} \mid \sigma \in \Sigma\right\} \cup\left\{d v_{i} \mid 1 \leq i \leq k\right\} \cup \\
& \{\text { equals }\}
\end{aligned}
$$

The domain of the structure of a data tree $t$ will be the union of the set of the nodes of its graph together with the infinitely many data values in $\Delta^{*}$. Here we consider the graph abstractly, in that nodes are identified by their Dewey address, i.e., by the word of natural numbers that addresses them when starting at the root. The root node of $t$ is identified with the empty word $\varepsilon$, and the $i$-th child of a node $\pi$ of $t$ with $\pi \cdot i$.

More formally, the set of nodes of a data tree is defined recursively for all trees $a\left(t_{1}, \ldots, t_{n}\right)$ by:

$$
\operatorname{Nodes}\left(a\left(t_{1}, \ldots, t_{n}\right)\right)=\{\varepsilon\} \cup\left\{i \cdot \pi \mid 1 \leq i \leq n, \pi \in \operatorname{Nodes}\left(t_{i}\right)\right\}
$$

Another possible identification of nodes would be to simply enumerate them by a consecutive numbering in pre-order for example. The relation symbols are interpreted as binary relations on this domain as follows: The binary relation $c h^{t}$ relates a node to its children, the binary relation $n s^{t}$ relates a node to its next sibling to the right.

$$
\begin{aligned}
c h^{t} & =\{(\pi, \pi \cdot i) \mid \pi \cdot i \in \operatorname{Nodes}(t)\} \\
n s^{t} & =\{(\pi \cdot i, \pi \cdot i+1) \mid \pi \cdot i, \pi \cdot i+1 \in \operatorname{Nodes}(t)\}
\end{aligned}
$$

The parent relation par $^{t}=\left(c h^{t}\right)^{-1}$ relates a node to its parent, and the previous sibling relation $p s^{t}=\left(n s^{t}\right)^{-1}$ relates a node to its previous sibling. Descendant relation $\left(c h^{+}\right)^{t}$, following-sibling relation $\left(n s^{+}\right)^{t}$, ancestor relation $\left(p a r^{+}\right)^{t}$, and the preceding-sibling relation $\left(\mathrm{ps}^{+}\right)^{t}$ are the transitive closure of the child, next-sibling, parent, and previous-sibling relation, respectively: $\left(c h^{+}\right)^{t}=\left(c h^{t}\right)^{+},\left(n s^{+}\right)^{t}=$ $\left(n s^{t}\right)^{+},\left(p a r^{+}\right)^{t}=\left(p a r^{t}\right)^{+}=\left(\left(c h^{+}\right)^{t}\right)^{-1}$, and $\left(p s^{+}\right)^{t}=\left(p s^{t}\right)^{+}=\left(\left(n s^{+}\right)^{t}\right)^{-1}$. For any relation $A$, by $A^{*}$ we denote the reflexive closure of $A^{+}$. The following relation $f o^{t}=\left(\text { par }^{t}\right)^{*} \circ\left(n s^{t}\right)^{+} \circ\left(c h^{t}\right)^{*}$ relates a node to all its following nodes, the preceding relation $p c^{t}=\left(p a r^{t}\right)^{*} \circ\left(p s^{t}\right)^{+} \circ\left(c h^{t}\right)^{*}$ relates a node to its preceding nodes, and last but not least the future relation $f u t^{t}=\left(c h^{t}\right)^{*} \vee f o^{t}$ relates a node to all its future nodes.

The label of a node $\pi \in \operatorname{Nodes}(t)$ is denoted by $\operatorname{lab}_{t}(\pi) \in \mathcal{A}$; it can be defined recursively for all $t=a\left(t_{1}, \ldots, t_{n}\right)$ and $i \pi \in \operatorname{Nodes}(t)$ as follows:

$$
\begin{aligned}
& l a b_{t}(\varepsilon)=a \\
& \operatorname{lab}_{t}(i \pi)=\operatorname{lab_{t_{i}}}(\pi)
\end{aligned}
$$

$t a g_{\sigma}$ are unary relations that are interpreted as the set $t a g_{\sigma}^{t}$ of all nodes that are tagged by $\sigma$. For all $1 \leq i \leq k$ the functions $d v_{i}^{t}$ map a node to the $i$-th data value of its label, i.e. $d v_{i}^{t}(\pi)=w_{i}$ whenever $l a b^{t}(\pi)=\sigma^{(m)}\left(w_{1}, \ldots, w_{m}\right)$.

In order to test equalities among data values, we add function equals ${ }^{t}$ that maps any two data values $w_{1}$ and $w_{2}$ to the boolean of whether $w_{1}$ is equal to $w_{2}$, i.e. equals ${ }^{t}\left(w_{1}, w_{2}\right)=\left(w_{1}=w_{2}\right)$. This operator is what we minimally wanted to have. It allows already to express the XPath join filter [author [child: :text() = "Abiteboul"]] in the first-order logic of this relational structure, assuming that $d v_{1}$ for element nodes returns the XmL tag, and assuming that $d v_{2}$ for text nodes returns its data content:

$$
\begin{aligned}
& \exists r .\left(\neg \exists . \operatorname{ch}(y, r) \wedge \operatorname{tag}_{e l}(r) \wedge e q u a l s\left(d v_{1}(r), \text { author }\right) \wedge\right. \\
& \left.\exists x .\left(\operatorname{ch}(r, x) \wedge \operatorname{tag}_{t x}(x) \wedge e q u a l s\left(d v_{2}(x), \text { Abiteboul }\right)\right)\right)
\end{aligned}
$$

But indeed our structure is incomplete in that its domain does not contain numerical values, nor functions, and in that no arithmetic operations and others are supported.

### 2.1.3 Finite State Abstractions

For applying finite state technology, it is often necessary to abstract information about data values, of which there are infinitely many, into finite state information. For instance, the set of Xml tags is infinite, but it can be abstracted into a finite set for a given query, for which only finitely many XmL tags are relevant.

More generally, we often want to relabel data trees. This can be done when given a relabeling function $\alpha: \mathcal{A} \rightarrow \mathcal{A}^{\prime}$ for some other alphabet $\mathcal{A}^{\prime}=\bigcup_{\sigma^{(k)} \in \Sigma^{\prime}} \sigma \times$ $\left(\Delta^{\prime *}\right)^{k}$. The relabeling of a data tree over $\Sigma$ and $\Delta$ is then defined, such that for all $a\left(t_{1}, \ldots, t_{n}\right) \in \mathcal{T}_{\mathcal{A}}$ :

$$
\operatorname{rel}_{\alpha}(t)=\alpha(a)\left(\operatorname{rel}_{\alpha}\left(t_{1}\right), \ldots, \operatorname{rel}_{\alpha}\left(t_{n}\right)\right)
$$

The relabeled data tree $\operatorname{rel}_{\alpha}(t)$ then belongs to $\mathcal{T}_{\mathcal{A}^{\prime}}$. For instance, if one wants to query the data tree in $t_{2.1} \in \mathcal{T}_{\text {XML }_{\text {types }}^{\prime}, \mathrm{UTF8}}$ in Figure 2.1 by a query that concerns only author-elements and data content, then we can use the following relabeling function $\alpha$ for abstracting the other information away.

$$
\alpha\left(\sigma^{(k)}\left(w_{1}, \ldots, w_{k}\right)\right)= \begin{cases}a^{a u t h o r} r^{(0)} & \text { if } \sigma=e l^{(1)} \text { and } w_{1}=\text { author } \\ t x^{(1)}\left(w_{1}\right) & \text { if } \sigma=t x^{(1)} \\ d o c^{(0)} & \text { if } \sigma=d o c^{(0)} \\ a t t^{(0)} & \text { if } \sigma=a t t^{(2)} \\ e l^{(0)} & \text { if } \sigma=e l^{(1)} \text { and } w_{1} \neq \text { author }\end{cases}
$$

Let $\mathrm{XmL}_{\text {types }}^{\prime \prime}=\left\{d o c^{(0)}, e l^{(0)}, a t t^{(0)}, t x^{(1)}\right\}$. Then we have $\Sigma^{\prime}=\operatorname{XML}_{\text {types }}^{\prime \prime} \cup\left\{a u t h o r^{(0)}\right\}$ and $\Delta^{\prime}=$ UTF8. The relabeling lifted to data trees rel ${ }_{\alpha}$ maps the data tree $t_{2.1}$ in Figure 2.1 to the unary data tree in Figure 2.2.

Another useful relabeling that preserves all information while abstracting general data trees to data trees where nodes have at most one data value, is abstraction $r e l_{\text {concat }}$ that concatenates the data values, if more than one present, using a special separation symbol $\diamond$ :

$$
\operatorname{concat}\left(\sigma^{(k)}\left(w_{1}, \ldots, w_{k}\right)\right)= \begin{cases}\sigma^{(1)}\left(w_{1} \diamond \ldots \diamond w_{k}\right) & \text { if } k \geq 1 \\ \sigma^{(0)} & \text { else }\end{cases}
$$



Figure 2.2: The abstracted data tree $\operatorname{rel}_{\alpha}\left(t_{2.1}\right) \in \mathcal{T}_{\text {XmLt }_{\text {types }}^{\prime \prime}} \cup\left\{\right.$ author ${ }^{(0)\}, U \text { UTF8 }}$ where only author tags and text values are preserved.

### 2.1.4 Json Trees

The Json format [Crockford 2001] contains objects and arrays, which in turn are made up of values. Values are either strings, numbers, objects, arrays, booleans, or null. Objects are unordered sets of key/value pairs where no two pairs contain the same key, and arrays are ordered lists of values. Keys are given by strings. We give a sample Json document that describes a person in Figure 2.3. We display objects in curly brackets, arrays in square brackets, strings in quotes, and for numbers and booleans we just state the respective value.

Data trees that underly Json have signature

$$
\Sigma=\left\{\text { obj }^{0}, \text { arr }^{0}, \text { str }^{1}, \text { numb }^{1}, \text { bool }^{1}, \text { null }^{0}\right\} .
$$

A Json data tree is given in Figure 2.4. However the logical structure of Json data trees is slightly different than for general data trees in that relations $n s, n s^{+}, p s$, $p s^{+}, f o, p c$, and fut are not defined on children of obj-labeled nodes, since Json objects are unordered sets. Furthermore since keys must be unique in Json, we also must impose this constraint on data values of children of obj-labeled nodes.

We next discuss how Json data trees and data trees as in Xml can be identified with each other. Starting from a data tree as in XmL, we have two possibilities to encode it into a Json data tree: We can either pack each child of a node into a new "array"-node with label arr while preserving the order of the children. Or we first annotate each node by its position, i.e. the $i$-th child of a node is annotated by $i$, and then we pack the children of a node into a new "object"-node instead of an "array"-node, with a str-labeled child with the annotation of nodes as data value. Conversely, a Json data tree can be encoded into an Xml data tree by ordering children of $o b j$-labeled nodes according to their data value. This shows that data trees in XML or respectively in Json are very similar.

```
{
    "name": "PPeter",
    "addr": { "street": "Hell 2",
                            "city": "Heaven" },
    "age": 31,
    "phone numbers": [
        { "type": "home",
            "number": "1234567" },
        { "type": "work",
            "number":"7654321" }
    ],
    "isMale": true,
    "email": null
}
```

Figure 2.3: A Json document.

### 2.2 Nested Words

### 2.2.1 Definition

A nested word [Alur 2009] is a word over three disjoint alphabets $O, C$, and $\Delta$, with opening tags $\langle o\rangle \in O$, closing tags $\langle/ c\rangle \in C$, and internal letters in $\Delta$. Complete nested words are nested words that are more restricted in that they are wellbalanced, corresponding opening and closing tags must have the same label, and initial opening tags cannot be closed before the end. The positions of nested words are called events, of which there are three kinds: opening, closing, and internal. Whenever $O$ and $C$ have the same set of labels $\Sigma$ within opening and closing parenthesis, we permit ourselves to define only $\Sigma$, instead of $O=\{\langle a\rangle \mid a \in \Sigma\}$ and $C=\{\langle/ a\rangle \mid a \in \Sigma\}$.

The following nested word is a word over signatures $\Sigma=\{l, b, a, t\}$ and $\Delta=$ $\{A, b, i, t, e, o, u, l, D, a\}$ :

$$
\langle l\rangle\langle b\rangle\langle a\rangle \text { Abiteboul }\langle/ a\rangle\langle t\rangle \operatorname{Data}\langle/ t\rangle\langle/ b\rangle\langle/ l\rangle
$$

Sometimes information from the past may want to be stored within the label of tags of a nested word. For example, we could annotate each opening and closing event by its number as in

$$
\langle(l, 1)\rangle\langle(b, 2)\rangle\langle(a, 3)\rangle \text { Abiteboul }\langle/(a, 4)\rangle\langle(t, 5)\rangle \text { Data }\langle/(t, 6)\rangle\langle/(b, 7)\rangle\langle/(l, 8)\rangle
$$

### 2.2.2 Linearization of Data Trees

We show how to linearize unary data trees into nested words. While data trees in general have arity $k \geq 1$, we can always abstract them to signatures whose maximal arity is 1 via abstraction $r e l_{\text {concat }}$ of before.


Figure 2.4: A Json data tree representing the Json document of Figure 2.3.

In order to linearize unary data trees over $\Sigma$ and $\Delta$ into nested words, we need to fix the following three functions:

$$
o p: \mathcal{A} \rightarrow O, \quad \text { int }: \mathcal{A} \rightarrow \Delta^{*}, \quad \text { and } \quad c l: \mathcal{A} \rightarrow C
$$

If not stated otherwise, functions $o p$ and $c l$ will map the finite part $\sigma$ of node labels to corresponding opening and closing tags, while function int will map to the data value $w$ or $\varepsilon$ if absent:

$$
o p(a)=\langle\sigma\rangle, \quad \operatorname{int}(a)=\left\{\begin{array}{ll}
w & \text { if } a=\sigma^{(1)}(w) \\
\varepsilon & \text { if } a=\sigma^{(0)}
\end{array}, \quad \text { and } \quad \operatorname{cl}(a)=\langle/ \sigma\rangle\right.
$$

Once we have fixed functions $o p$, int, and $c l$ we can linearize any data tree $t=$ $a\left(t_{1}, \ldots, t_{n}\right)$ into the following nested word $\operatorname{lin}(t)$ :

$$
\operatorname{lin}\left(a\left(t_{1}, \ldots, t_{n}\right)\right)=o p(a) \cdot \operatorname{int}(a) \cdot \operatorname{lin}\left(t_{1}\right) \cdot \ldots \cdot \operatorname{lin}\left(t_{n}\right) \cdot \operatorname{cl}(a)
$$

### 2.3 Xml Data Trees

The logical structure of an XML document is known as the data model, which provides a tree representation of the XmL document.

### 2.3.1 Xml Data Model

When referring to the Xml Data model, we mean the informally described tree representation of the data model specification ${ }^{1}$ for XPATH 3.0, XQUERY 3.0, and Xslt 3.0. We formalize it in the following by means of XmL data trees.

[^1]The data model contains six ${ }^{2}$ types of nodes, where in parenthesis we give their abbreviation used throughout this thesis: document (doc), element (el), attribute (att), text (tx), comment (com), processing-instruction (pi).

We model the tree-structure of the XmL data model via data trees, while moving node properties as data to node labels, and moving node type information to

$$
\Sigma=\mathrm{XML}_{\text {types }}=\left\{d o c^{(3)}, e l^{(6)}, a t t^{(5)}, t x^{(1)}, c o m^{(1)}, p i^{(3)}\right\} .
$$

In Figure 2.5 we give a grammar of data trees obtained by the XmL data model together with their node properties. In gray we depict node properties that are not directly relevant when posing XPATH queries by the grammar of XPATH 3.0 [Robie 2014b] but they become relevant when looking at respective XPATH 3.0 functions ${ }^{3}$ (for properties base-uri, document-uri, is-id, and is-idref) or for DTD processing tasks (unparsed-entities). Node property node-name contains the name of an element or attribute node, that consists of a namespace prefix and a local name. Property target holds the name of a processing-instruction, values for attribute nodes are stored in string-value, and property content contains the data of text, comment, and processing-instruction nodes. Finally, properties nilled and schema-type are needed for schema validation. nilled indicates that an element node should be accepted as valid when it has no content. Property schema-type is an XML schema type, which is string "xs:untyped" for elements and "xs:untypedAtomic" for attributes in the absence of schema.

XmL data trees, i.e. trees obtained from XmL documents according to the XML data model, thereby satisfy the following restrictions: The root is the only node whose type is document. All nodes of type attribute, text, comment, and processinginstruction are leafs. Only element nodes have attribute nodes as children, which must precede all its other children. These restrictions are most relevant for early query answering for XPATH. For instance, for the query title [@lang='eng'], any element title-labeled node can be rejected, once the first non-attribute child was read, and there was no lang attribute with string-value eng before.

An example of an XmL document is given in Figure 2.6 and its corresponding Xml data tree is the one in Figure 2.1. It stores the XmL type, but only a subset of the data values from the XmL datamodel: no data values for document nodes, node-name for element and attribute nodes, the attribute value for attribute nodes, and the data content for text nodes.

### 2.3.2 Xml Data Model Specifics

Document order. The so-called document order is a total order among all accessible nodes: The root node is the first node. Children and descendants of nodes

[^2]Grammar:

$$
\begin{aligned}
& d o c \rightarrow(e l+p i+c o m+t x)^{*} \\
& e l \rightarrow \text { att }(e l+p i+c o m+t x)^{*} \\
& \text { att } \rightarrow \text { none } \\
& t x \rightarrow \text { none } \\
& \text { com } \rightarrow \text { none } \\
& p i \rightarrow \text { none }
\end{aligned}
$$

Node labels:

```
\(d o c\) (base-uri, unparsed-entities, document-uri)
\(e l(\) base-uri, node-name, schema-type, nilled, is-id, is-idrefs)
att(string-value, node-name, schema-type, is-id, is-idrefs)
\(t x\) (content)
com(content)
\(p i(\) base-uri, target, content)
```

Figure 2.5: Grammar and node labels by XmL data model abstracted data trees.

```
<library>
    <book id="bk231">
        <author>Abiteboul</author>
        <title>Data</title>
    </book>
</library>
```

Figure 2.6: An Xml document.
occur after the respective node, while they occur before following siblings to the right. Attribute nodes if present follow immediately their element parent nodes. The relative order of attribute nodes is implementation-dependent, in that an implementation may chose the order, but it does not change during the processing of a query or transformation.

String-values. The data model defined the string-value of attribute nodes to be the value of the attribute, while the string-value for document and element nodes is the concatenation of its text nodes descendants in document order. Notice that this value can be derived for document and element nodes, for which reason we do not store it as data value in XML data trees.

Children of element nodes. The Xml data model describes that children of element nodes may exclusively be element, processing-instruction, comments, and text nodes, while attributes, and document nodes can never appear as a child of an element node. Even though that the attributes of an element are not considered to be children, the element is considered to be the parent of these attribute nodes

```
\(\langle d o c\rangle\)
    \(\langle e l\rangle l i b r a r y\)
        〈el>book
            \(\langle a t t\rangle i d \diamond b k 231\langle/ a t t\rangle\)
            〈el>author
                    \(\langle t x\rangle\) Abiteboul \(\langle/ t x\rangle\)
            \(\langle/ e l\rangle\)
            \(\langle e l\rangle t i t l e\)
                \(\langle t x\rangle\) Data \(\langle/ t x\rangle\)
            \(\langle/ e l\rangle\)
        〈/el>
    \(\langle/ e l\rangle\)
\(\langle/ d o c\rangle\)
```

Figure 2．7：The nested word obtained from the Xml data tree in Figure 2．1．
however．
Data trees by the Xml data model have a different definition of the child relation， where attribute nodes are children of element nodes that precede any other children． Therefore when answering XPATH queries on such data trees，one has to be careful， that the child axes are translated correctly，as to come in Section 7．3．

## 2．3．3 Mapping to Nested Words and Back to Xml Documents

From an Xml data tree we can produce a nested word by the linearization of data trees as in Section 2．2．2．This requires abstraction to maximal unary signature Xml data trees obtained by concatenation of data values using a special separation symbol．Such nested words can be interpreted as Xslt programs．The nested word obtained from the XmL data tree in Figure 2.1 is given in Figure 2．7．In turn it can be interpreted as a representation of the Xslt program in Figure 2．8．Indeed，this Xslt program evaluates to the original Xml document in Figure 2．6．

We summarize the correlations Xml documents，data trees，and nested words via the bijections depicted in Figure 2．9．It allows to identify the nested word for some Xml document $D$ by

$$
n w(D)=\operatorname{lin}\left(r e l_{\text {concat }}(\text { data-model }(D))\right) .
$$

Furthermore $n w(D)$ allows to retrieve the XmL documents $D$ again by interpreting the nested word as an Xslt program that creates $D$ ：

Lemma 1．For all Xml documents $D$ it holds that：

$$
D=\operatorname{evaluate}(\operatorname{asXSLT}(n w(D)))
$$

The notion of nested words thus formally captures the essence of an XmL doc－ ument，while ignoring the syntactic details of the XmL standard．While all our

```
<xsl:document>
    <xsl:element name="library">
        <xsl:element name="book">
            <xsl:attribute name="id">bk231</xsl:attribute>
            <xsl:element name="author">
                <xsl:text>Abiteboul</xsl:text>
            </xsl:element>
            <xsl:element name="title">
                    <xsl:text>Data</xsl:text>
            </xsl:element>
        </xsl:element>
    </xsl:element>
</xsl:document>
```

Figure 2.8: The Xslt program represented by the nested word in Figure 2.7: it evaluates to the original XmL document in Figure 2.6.
practical tools will process concrete XmL documents, our algorithms can assume that these come as nested words.

### 2.4 Nested Word Automata

Our finite state technology for processing words will be nested word automata [Alur 2009].

### 2.4.1 Definition

A nested word automaton (NWA) is a pushdown automaton that runs on nested words and suffixes. The usage of the pushdown of an NwA is restricted: a single symbol is pushed at opening tags, a single symbol is popped at closing tags, and the pushdown remains unchanged when processing internal letters. More formally:

Definition 1. A nested word automaton is a tuple $A=\left(O, C, \Delta, Q, Q_{I}, Q_{F}, \Gamma, R\right)$ where $O, C$, and $\Delta$ are the finite alphabets of nested words, $Q$ a finite set of states with subsets $Q_{I}, Q_{F} \subseteq Q$ of initial and final states, $\Gamma$ a finite set of stack symbols, and $R$ is a set of transition rules of the following three types, where $q, q^{\prime} \in Q$, $\langle o\rangle \in O,\langle/ c\rangle \in C$, and $d \in \Delta$ :
(open) $q \xrightarrow{\langle o\rangle: \gamma} q^{\prime}$ can be applied in state $q$, when reading the opening parenthesis o. In this case, $\gamma$ is pushed onto the stack and the state is changed to $q^{\prime}$.
(close) $q \xrightarrow{\langle/ c\rangle: \gamma} q^{\prime}$ can be applied in state $q$ when reading the closing parenthesis $c$ with $\gamma$ on top of the stack. Then, $\gamma$ is popped and the state is changed to $q^{\prime}$.


Figure 2.9: XmL documents $D$ as $n w(D)=\operatorname{lin}\left(r e l_{\text {concat }}(\right.$ data-model $\left.(D))\right)$, and back $D=$ evaluate $\left(\operatorname{asXSLT}\left(\operatorname{lin}\left(\right.\right.\right.$ rel $_{\text {concat }}($ data-model $\left.\left.\left.(D))\right)\right)\right)$.
(internal) $q \xrightarrow{d} q^{\prime}$ can be applied in state $q$ when reading the internal letter $d$. One then moves to state $q^{\prime}$.

An NwA is called deterministic or a dNWA if it is deterministic as a pushdown automaton. In contrast to more general pushdown automata, NwAs can always be determinized [Alur 2009], essentially, since they have the same expressiveness as bottom-up tree automata.

### 2.4.2 Runs of Nested Words

A configuration of an NwA is a state-stack pair in $Q \times \Gamma^{*}$. Let $S \in \Gamma^{n}$ be a stack of depth $n \geq 0$ and $s$ be a suffix of a complete nested word over $O, C$, and $\Delta$, which has excess $-n$. An $S$-run on $s$ must start in a configuration with stack $S$ and some initial state, and then rewrite this configuration on all events of the suffix according to some of the rules in $R$. An $S$-run on a suffix is called successful if it continues until the end while reaching some final state. Note that the stack will always be empty at the end of suffixes, given that the depth of $S$ had the same absolute value as the excess of the suffix and given the restriction on pushdowns of NwAs (often called "visible"). The language $\mathcal{L}_{S}(A)$ of an NwA $A$ is the set of all suffixes over $O, C$, and and $\Delta$ that permit a successful $S$-run by $A$.

An example of a run of the NwA in Figure 2.10 on a suffix of a complete nested word is depicted in Figure 2.11 with start stack $S=\alpha$. The automaton tests whether the suffix of the nested word as a tree satisfies the XPath filter [descendant: : a [descendant: :b]]. When opening an a-node in its initial state $q_{0}$ the Nwa guesses that it matches the a-descendant of the XPATH query, it pushes $\alpha$ onto the stack and moves to state $q_{1}$. From there it waits until the guess of the b-descendant in the query, where it moves into final state $q_{3}$, where it stays until the end.


Figure 2.10: An NwA where $\Sigma=\{a, b\}$ and $\Delta=\emptyset$.


Figure 2.11: A run of the NwA of Figure 2.10 on a suffix of a nested word.


Figure 2.12: The run of Figure 2.11 as a nested word.

Furthermore the runs of nested words can be identified with nested words themselves. In Figure 2.12 we show the run of Figure 2.11 as a nested word. However, corresponding opening and closing tags are labeled differently: For example opening tag $\left\langle\left(a, \alpha, q_{2}\right)\right\rangle$ does not have the same label as its corresponding closing tag $\left\langle/\left(a, \alpha, q_{3}\right)\right\rangle$. Such nested words are still linearizations of trees, but with functions $o p\left(\left(a, \alpha, q, q^{\prime}\right)\right)=\langle(a, \alpha, q)\rangle$ and $c l\left(\left(a, \alpha, q, q^{\prime}\right)\right)=\left\langle/\left(a, \alpha, q^{\prime}\right)\right\rangle$. Since runs of NWAs are nested words, as a consequence, NwAs can be composed.

### 2.4.3 Runs on Marked Trees

A marked data tree is a pair $(t, \pi)$ consisting of a data tree $t$ and a node $\pi \in \operatorname{Nodes}(t)$, called the mark. Marked unary data tree $(t, \pi)$ can be linearized into the nested word, which is the suffix of the complete nested word by the linearization of $t$ starting at the opening event of $\pi$. More formally, we define for any data tree $t=a\left(t_{1}, \ldots, t_{n}\right)$ that contains node $\pi$ a tree suffix $\operatorname{suff}(t, \pi)$ as follows:

$$
\begin{aligned}
& \operatorname{suff}\left(a\left(t_{1}, \ldots, t_{n}\right), \varepsilon\right)=\operatorname{lin}\left(a\left(t_{1}, \ldots, t_{n}\right)\right) \\
& \operatorname{suff}\left(a\left(t_{1}, \ldots, t_{n}\right), i \pi\right)=\operatorname{suff}\left(t_{i}, \pi\right) \cdot \operatorname{lin}\left(t_{i+1}\right) \cdot \ldots \cdot \operatorname{lin}\left(t_{n}\right) \cdot \operatorname{cl}(a)
\end{aligned}
$$

The marked node of a tree suffix is the marked node of the underlying marked data tree. Tree suffixes are complete nested words if and only if the marked node is the root. More generally, tree suffixes lack the opening events for all ancestors of the marked node.


Figure 2.13: NWA for XPATH filter [author [child::text() [1] = "Abiteboul"]] with shortcuts $\Sigma=$ XML $_{\text {types }}^{\prime \prime} \cup\left\{\right.$ author $\left.^{(0)}\right\}, \neg t x=\Sigma \backslash\{t x\}$, and $\Delta=\mathrm{UTF} 8$.

An example for a marked data tree is given in Figure 2.14, where the authornode is chosen as the marked node, and thereby underlined. The Nwa in Figure 2.13 answers the XPath filter [author[child::text()[1] = "Abiteboul"]] and thereby accepts all tree suffixes suff $(t, \pi)$ for a marked data tree $(t, \pi)$ of trees $t$ obtained from Xml documents and a marked author-node $\pi$, whose first text node's data content is equal to "Abiteboul". A successful run over the marked data tree is given in Figure 2.14 with start stack $S=\alpha \alpha \alpha$.

### 2.4.4 Determinization of NWAs

In the following we give a direct determinization procedure for nested word automata over alphabets $\Sigma$ and $\Delta$. These are more restricted nested word automata in that the alphabets $O$ for opening and $C$ for closing parenthesis coincide to $\Sigma=O=C$. It is possible to determinize Nwas in the general case. However the determinization becomes more complicated and moreover the more general case is not needed for our algorithms.

An NwA $A=\left(\Sigma, \Delta, Q, Q_{I}, Q_{F}, \Gamma, R\right)$ is deterministic if $Q_{I}$ contains at most one state, and for any $q \in Q, a \in \Sigma$, and $a^{\prime} \in \Delta$ there is at most one pair $\left(\gamma, q^{\prime}\right)$ with $q \xrightarrow{\langle\rangle: \%} q^{\prime} \in R$, for any $\gamma \in \Gamma$ there exists at most $q^{\prime}$ such that $q \xrightarrow{\langle\mid a\rangle: \gamma} q^{\prime} \in R$, and there exists at most one $q^{\prime}$ such that $q \xrightarrow{a^{\prime}} q^{\prime} \in R$.

Clearly, any dNwa permits at most one run per tree. The difficulty is to deal with competing opening rules $q \xrightarrow{\langle a\rangle: \gamma_{1}} q_{1}$ and $q \xrightarrow{\langle a\rangle: \gamma_{1}} q_{2}$. Essentially, the choice is delayed until closing time. The states and stack symbols of the determinization of $A$ are sets of such pairs of states $\left(q, q^{\prime}\right) \in Q^{2}$, with the intuitive meaning that the sequence of children of the current node can be evaluated to $q^{\prime}$ when starting in $q$.

The three inference rules below define its transitions.

$$
\frac{\bar{Q}^{\prime}=\left\{\left(q_{3}, q_{3}\right) \mid\left(q_{1}, q_{2}\right) \in \bar{Q}, q_{2} \xrightarrow{\langle a\rangle: \gamma} q_{3} \in R\right\}}{\bar{Q} \xrightarrow{\langle a\rangle: \bar{Q}} \bar{Q}^{\prime}}
$$

At opening time the current set $\bar{Q}$ is pushed onto the stack and the evaluation of the sequence of the children of the current node is started in all pairs $\left(q_{3}, q_{3}\right)$, for


Figure 2.14: A successful run of the Nwa of Figure 2.13 on the tree suffix of abstracted data tree from Figure 2.2 where the author-node is chosen as the mark. Here the start stack is equal $S=\alpha \alpha \alpha$ containing stack symbol $\alpha$ for every ancestors of the marked node.
which $q_{3}$ can be reached by some transition of $A$.

$$
\begin{aligned}
& \bar{Q}^{\prime \prime}=\left\{\left(q_{1}, q_{5}\right) \left\lvert\, \begin{array}{l}
\left(q_{3}, q_{4}\right) \in \bar{Q},\left(q_{1}, q_{2}\right) \in \bar{Q}^{\prime}, \\
q_{2} \xrightarrow{\langle a\rangle: \gamma} q_{3}, q_{4} \xrightarrow{\langle/ a): \gamma} q_{5} \in R
\end{array}\right.\right\} \\
& \bar{Q} \xrightarrow{\langle/ a\rangle: \bar{Q}^{\prime}} \bar{Q}^{\prime \prime}
\end{aligned}
$$

At closing time, if one of the left siblings of the $a$-node could be evaluated to $\left(q_{1}, q_{2}\right)$ and the sequence of children of the $a$-node to ( $q_{3}, q_{4}$ ) then one can evaluate the sequence of left siblings including the $a$-subtree to ( $q_{1}, q_{5}$ ), if $q_{2}$ can be opened to $q_{3}$ with the same stack symbol $\gamma$ that allows to close $q_{4}$ to $q_{5}$.

$$
\frac{\bar{Q}^{\prime}=\left\{\left(q_{1}, q_{3}\right) \mid\left(q_{1}, q_{2}\right) \in \bar{Q}, q_{2} \xrightarrow{a} q_{3} \in R\right\}}{\bar{Q} \xrightarrow{a} \bar{Q}^{\prime}}
$$

The internal rule allows to only update the current state in the second component of all pairs of $\bar{Q}$.

The only initial state of the determinization of $A$ is $\left\{(q, q) \mid q \in Q_{I}\right\}$. A state $\bar{Q}$ of the determinization of $A$ is final if it contains some pair $\left(q, q^{\prime}\right)$ with $q \in Q_{I}$ and $q^{\prime} \in Q_{F}$.

In the worst case, the determinized automaton has $2^{|Q|^{2}}$ states. In experiments, we also observed huge size explosions in the average case. For example, for the XPath query //a[following-sibling: :b[.//c][./d]]/e we obtain an Nwa with 38 states and 7719 transitions. We were not able to construct the corresponding
dNwA even if restricted to accessible states only. The main limiting factor was memory. For the mentioned query we stopped the construction shortly, after having reached 5000 states with more than 20 million transitions, and swapping to the disk. Therefore, we will mostly rely on on-the-fly determinization.

### 2.5 Recursive Functions

The semantics of definitions of recursive functions is usually based on fixed points on complete partial orders. We first recall the Kleene fixpoint theorem that extracts the conditions under which such fixpoints exist, and then introduce lambda notion for recursive functions based on this fixed point theorem.

### 2.5.1 Partial Orders and Fixed Points.

A partial order on a set $D$ is a binary relation $\sqsubset$ on $D$ which is irreflexive, antisymmetric, and transitive. For any partial order let $\sqsubseteq$ be the reflexive closure of $\sqsubset$.

Definition 2. We call a partial order complete or equivalently a CPO if for any ascending chain $v_{1} \sqsubseteq v_{2} \sqsubseteq \ldots$ of $D$ has least upper bound $\sqcup\left\{v_{i} \mid i \in \mathbb{N}\right\} \in D$.

We call a function $f: D \rightarrow D$ monotone if for all $v_{1}, v_{2} \in D$ :

$$
v_{1} \sqsubseteq v_{2} \Rightarrow f\left(v_{1}\right) \sqsubseteq f\left(v_{2}\right)
$$

We call $f$ Scott-continuous if every ascending chain $v_{1} \sqsubseteq v_{2} \sqsubseteq v_{3} \ldots$ of elements in $D$ has an upper bound such that:

$$
f\left(\sqcup\left\{v_{n} \mid n \in \mathbb{N}\right\}\right)=\sqcup f\left(\left\{v_{n} \mid n \in \mathbb{N}\right\}\right) .
$$

We recall that any Scott-continuous function is monotone. A fixed point of $f$ is an element $v$ of $D$ such that $f(d)=d$.

Theorem 1 (Kleene fixed-point theorem).
Let $(D, \sqsubset)$ be a complete partially ordered set with least element $\perp$ and $f: D \rightarrow D$ a Scott-continuous function. Then $f$ has a least fixed point $l f p_{f}=\sqcup\left\{f^{n}(\perp) \mid n \in \mathbb{N}\right\}$.

Proof. Since $\perp$ is the least element in $D$, we have that $\perp \sqsubseteq f(\perp)$. Since $f$ is monotone, we have that $f^{n}(\perp) \sqsubseteq f^{n+1}(\perp)$ for all $n \geq 0$. The chain has a supremum since $(D, \sqsubset)$ is complete, so $l f p_{f}=\sqcup\left\{f^{n}(\perp) \mid n \in \mathbb{N}\right\}$ is well defined. It follows that $l f p_{f}$ is a fixed point of $f$ since $f$ is Scott continuous (and thus monotone):

$$
f\left(l f p_{f}\right)=f\left(\sqcup\left\{f^{n}(\perp) \mid n \in \mathbb{N}\right\}\right)=\sqcup\left\{f^{n+1}(\perp) \mid n \in \mathbb{N}\right\}=l f p_{f}
$$

Again from monotonicity it follows that $l f p_{f}$ is smaller than any other fixed point of $f$.

### 2.5.2 Lambda and Letrec Notation

We next introduce $\Lambda$ notation for total functions, which is situated on the meta-level of mathematics, rather than on the formal language level such as $\lambda$-terms.

Definition 3. Let $D, D^{\prime}$ be sets and $f(v) \in D^{\prime}$ for any $v \in D$. Then we write

$$
\Lambda v \in D . f(v)
$$

for the total function $\{(v, f(v)) \mid v \in D\}$.
We next introduce Letrec notation for recursive functions, by which we explain how recursive functions can be defined by least fixed points and can be computed functional programs.

Here we will have to deal with partial functions $g \subseteq D \times D^{\prime}$, which form a CPO with the inclusion ordering. Its least element is the empty partial function $\emptyset$.

Definition 4. Let $f=\left(f_{1}, \ldots, f_{n}\right)$ be a tuple of total function such that $f_{i}$ returns for any input tuple $v=\left(v_{1}, \ldots, v_{n}\right)$ of partial functions $v_{i} \subseteq D_{i} \times D_{i}^{\prime}$ an output tuple $f(v)=\left(f_{1}(v), \ldots, f_{n}(v)\right)$ of partial functions $f_{i}(v) \subseteq D_{i} \times D_{i}^{\prime}$. If $f$ is Scottcontinuous on the CPO:

$$
\left(D_{1} \times D_{1}^{\prime}\right) \times \ldots \times\left(D_{n} \times D_{n}^{\prime}\right)
$$

then we write:

$$
\text { Letrec } v_{1}=f_{1}(v) \ldots v_{n}=f_{n}(v) \text { in } v
$$

for the least fixed point of the operator f, which exists by Kleene's fixed point theorem (Theorem 1) and has the following form, since the tuple of empty partial relations is the least element of the above CPO:

$$
\sqcup\left\{f^{n}(\emptyset, \ldots, \emptyset) \mid n \in \mathbb{N}\right\} .
$$

Furthermore, if there is a function $g$ which can be applied to all elements of the above CPO then we extend the Letrec notation as follows:

$$
\begin{aligned}
& \text { Letrec } v_{1}=f_{1}(v) \ldots v_{n}=f_{n}(v) \text { in } g(v) \\
& \quad={ }_{d f} g\left(\text { Letrec } v_{1}=f_{1}(v) \ldots v_{n}=f_{n}(v) \text { in } v\right)
\end{aligned}
$$

Proposition 1. Let $f=\left(f_{1}, \ldots, f_{n}\right)$ be a tuple of functions as above and $\left(F_{1}, \ldots, F_{n}\right)$ a tuple of functional programs such that $F_{i}$ computes $f_{i}$. Then for any $1 \leq i \leq n$, there exists an functional program that computes the function in the $i$-th component of $v=\left(v_{1}, \ldots, v_{n}\right)$ where:

$$
\text { Letrec } v_{1}=f_{1}(v) \ldots v_{n}=f_{n}(v) \text { in } v
$$

Proof. Let lfp be the least fixed point. The idea is to unfold the definitions of the functions $f_{i}$ as far as needed. This can be done by the following recursively defined functional program:

```
\(l f p=\)
    fun \((j)\)
        fun \((v)\)
                case \(j\)
                        of 1 then \(F_{1}(l f p 1, \ldots, l f p n)(v)\)
                            of \(n\) then \(F_{n}(l f p 1, \ldots\), lfp \(n)(v)\)
in \(\operatorname{lfp}(i)\)
```

We next illustrate the proof of the proposition for the functional program computing the following two mutual recursive functions:

## Letrec

$$
\begin{aligned}
& \quad v_{1}=\Lambda v \in \mathbb{N} . v_{2} v-1 \\
& v_{2}=\Lambda u \in \mathbb{N} \text {. if } u=0 \text { then } 1 \text { else } v_{1} u \\
& \text { in } v_{2} 3
\end{aligned}
$$

Here we use the functions $f_{1}$ and $f_{2}$ such that for all $v_{1}, v_{2}$ :

$$
\begin{aligned}
& f_{1}\left(v_{1}, v_{2}\right)=\Lambda v \in \mathbb{N} . v_{2} v-1 \\
& f_{2}\left(v_{1}, v_{2}\right)=\Lambda u \in \mathbb{N} \text {. if } u=0 \text { then } 1 \text { else } v_{1} u
\end{aligned}
$$

The proof of Proposition 1 yields the following functional program for computing the components of Letrec $v_{1}=f_{1}\left(v_{1}, v_{2}\right) v_{2}=f_{2}\left(v_{1}, v_{2}\right)$ in $\left(v_{1}, v_{2}\right)$ :

```
    \(l f p=\) fun \(j\).
    fun \(v\).
        case \(j\)
            of 1 then lfp \(2 v-1\)
            of 2 then if \(v=0\) then 1 else lfp \(1 v\)
```

When applied to the second function with argument 2, we obtain

$$
\begin{aligned}
\text { lfp } 23 & =\text { if } 3=0 \text { then } 1 \text { else lfp } 13 \\
& =\text { lfp } 13 \\
& =\text { lfp } 23-1 \\
& =\text { lfp } 22 \\
& =\text { if } 2=0 \text { then } 1 \text { else } l f p 12 \\
& =\text { lfp } 12 \\
& =\text { lfp } 22-1 \\
& =\text { lfp } 21 \\
& =\text { if } 1=0 \text { then } 1 \text { else } l f p 11
\end{aligned}
$$

$$
\begin{aligned}
& =l f p 11 \\
& =\text { lfp } 21-1 \\
& =\text { lfp } 20 \\
& =\text { if } 0=0 \text { then } 1 \text { else } l f p 10 \\
& =1
\end{aligned}
$$

## Part I

## A Formal Semantics of XPath 3.0

## Chapter 3

## Navigational XPath 3.0

## Contents

3.1 Overview . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 41
3.2 Grammar . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 42
3.2.1 EbNF . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 42
3.2.2 Expressions . . . . . . . . . . . . . . . . . . . . . . . . . . . . 43
3.2.3 Parse Tree . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 44
3.3 Path Expressions . . . . . . . . . . . . . . . . . . . . . . . . . . 45
3.3.1 Forward and Backward . . . . . . . . . . . . . . . . . . . . . 45
3.3.2 Label Tests . . . . . . . . . . . . . . . . . . . . . . . . . . . . 46
3.3.3 Kind Tests . . . . . . . . . . . . . . . . . . . . . . . . . . . . 46
3.3.4 Relative, Absolute, and Abbreviated Expressions . . . . . . . 46
3.3.5 Filters . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 47
3.3.6 Compositions . . . . . . . . . . . . . . . . . . . . . . . . . . . 47

In this chapter, we distinguish the navigational XPath 3.0 fragment that we call Navigational XPath for short.

### 3.1 Overview

The XPath queries that we present in the following apply to XmL data trees that satisfy the XmL data model that we discussed in Section 2.3.1. Navigational queries select sets of nodes of XmL data trees that are stored in a sequence. The default semantics claims that nodes are to be sorted into document order, while an arbitrary implementation dependent order can be chosen within the unordered semantics of XQuery.

While we explain in detail in Chapter 4 the types and values of XPath 3.0, for this chapter it suffices to understand sequences as a flat ordered list that contains items which can either be a node, an atomic value, or a function. However, the result of path expressions by navigational queries are always sequences of nodes, while filters evaluate to a boolean or a sequence of nodes which is to be tested for non-emptiness.

Navigational XPath is obtained by restricting the grammar of XPath 3.0 [Robie 2014b]. Whenever a rule (X) of the grammar is restricted, the remaining
rules is given the name ( $\mathrm{X}^{\prime}$ ). The restricted grammar that we present in the next section allows for navigation in XML data trees by forward and backward axis, with relative and absolute expressions, filters, and compositions of paths. For example, a navigational XPATH query is

```
descendant::a[child::b]/parent::c
```

that selects the c-labeled parent of a-descendants that have a b-child. This query contains filters and path compositions of single forward and backward paths. Furthermore, navigational queries allow for more complex tests on node labels and types, such as in query

$$
\text { child }:: p: a / \text { child }:: \text { text }()
$$

that selects all text children of type $t x$, below an a-labeled child of the root with namespace prefix p. However, any data value comparisons, arithmetics, function application are excluded by navigational XPATH.

### 3.2 Grammar

We give the grammar of navigational XPath that we obtain from the grammar of XPath 3.0 [Robie 2014b] via some minor modifications. We leave out certain rules in order to disallow certain expressions. For the same reason we change slightly some grammar rules, for example, rule (1) becomes rule ( $1^{\prime}$ ). Finally we add three rules for negation (rule (Neg)) and boolean values true (rule (True)) and false (rule (False)). Note that these exist in XPath 3.0 as built-in functions fn:not, fn:true, and $f n: f a l s e$, but here we add them to the grammar, since no other functions are needed.

### 3.2.1 Ebnf

The grammar of navigational XPath is given in Extended Backus-Naur Form (EbNF). There all nonterminals have a name that starts with a capital letter, while terminal symbols are the strings within double quotes. We refer to the specification ${ }^{1}$ for more details about the EBNF and describe only a few patterns $P$ in the following. A pattern P appears in the right-hand side of a grammar rule, that is either a terminal, a nonterminal, or which consist of the more complex patterns, where $P$ and $P^{\prime}$ are sub-patterns:

- (P) matches P,
- P? matches P or nothing,
- P P' matches P followed by P' ("space" pattern),
- P | P' matches P or P' ("or" pattern),

[^3]- P - P' matches all strings that match $P$, but not $P^{\prime}$,
- P+ matches one or more occurrences of P,and
- P* matches zero or more occurrences of P ("star" pattern)

For example, nonterminal RelativePathExpr has EBNF rule
RelativePathExpr ::= StepExpr (("/" | "//") StepExpr)*
which uses "space", "or", and "star" patterns. Since a "space" pattern matches the pattern before the space followed by the pattern after the space and since "star" patterns match zero ore more occurrences, any string by RelativePathExpr is the concatenation of a string by StepExpr followed by zero or more strings by StepExpr that are separated by characters "/" or "//".

### 3.2.2 Expressions

The grammar starts with path expressions.

| (1') | XPath | : : = OrExpr |
| :---: | :---: | :---: |
| (16) | OrExpr | : := AndExpr ( "or" AndExpr )* |
| (17') | AndExpr | ::= NegationExpr ( "and" NegationExpr )* |
| (Neg) | NegationExpr | ::= TrueExpr \| "not(" TrueExpr ")" |
| (True) | TrueExpr | :: F FalseExpr \| "true" |
| (False) | FalseExpr | ::= PathExpr \| "false" |
| (35) | PathExpr | $\begin{aligned} ::= & (" / " \text { RelativePathExpr?) \| ("//" } \\ & \text { RelativePathExpr) \| RelativePathExpr } \end{aligned}$ |
| (36') | RelativePathExpr | ::=AxisStep (("/" \| "//") AxisStep)* |
| (38) | AxisStep | ```::= (ReverseStep \| ForwardStep) PredicateList``` |
| (39) | ForwardStep | ::= (ForwardAxis NodeTest) \| AbbrevForwardStep |
| (40) | ForwardAxis | ::= ("child" "::") \| ("descendant" "::") | <br> ("attribute" "::") \| ("self" "::") | <br> ("descendant-or-self" "::") \| <br> ("following-sibling" "::") \| <br> ("following" "::") \| ("namespace" "::") |
| (41) | AbbrevForwardSt | := "@"? NodeTest |
| (42) | ReverseStep | ::= (ReverseAxis NodeTest) \| AbbrevReverseStep |
| (43) | ReverseAxis | ```::= ("parent" "::") \| ("ancestor" "::") | ("preceding-sibling" "::") | ("preceding" "::") | ("ancestor-or-self" "::")``` |
| (44) | AbbrevReverseStep | : : = ". ." |
| (50) | PredicateList | : := Predicate* |
| (51') | Predicate | ::= "[" OrExpr "]" |

Path expression may reference node test expressions that verify node labels and kinds.

| (45) | NodeTest | ::= KindTest \| NameTest |
| :---: | :---: | :---: |
| (46) | NameTest | ::= EQName \| Wildcard |
| (47) | Wildcard | $\begin{aligned} ::= & " * "\|(N C N a m e ~ ": " ~ " * ") ~\| ~ \\ & (" * " ~ ": " \text { NCName) \| } \end{aligned}$ |
|  |  | (BracedURILiteral "*") |
| (71') | KindTest | ::= DocumentTest \| ElementTest |
|  |  | AttributeTest \| PITest | CommentTest |
|  |  | TextTest \| AnyKindTest |
| (72) | AnyKindTest | : : = "node" "(" ") " |
| (73') | DocumentTest | :: = "document-node" "(" ElementTest? ")" |
| (74) | TextTest | : : = "text" "(" ")" |
| (75) | CommentTest | : := "comment" "(" ")" |
| (77) | PITest | ::= "processing-instruction" "(" |
|  |  | (NCName \| StringLiteral)? ")" |
| (78) | AttributeTest | $\begin{aligned} ::= & \text { "attribute" "(" (AttribNameOrWildcard } \\ & (", " \text { TypeName)?)? ")" } \end{aligned}$ |
| (79) | AttribNameOrWildcard | :: AttributeName \| "*" |
| (82) | ElementTest | $\begin{aligned} ::= & \text { "element" "(" (ElementNameOrWildcard } \\ & \text { (", " TypeName "?"?)?)? ")" } \end{aligned}$ |
| (83) | ElementNameOrWildcard | d::= ElementName \| "*" |

Node label tests reference names.

| (86) | AttributeName | : : = EQName |
| :---: | :---: | :---: |
| (87) | ElementName | : : = EQName |
| (89) | TypeName | : : = EQName |
| (94) | EQName | ::= QName \| URIQualifiedName |
| (99) | URIQualifiedN | ::= BracedURILiteral NCName |
| (100) | BracedURILiter | : : = "Q" "\{" [^\{\}]* "\}" |
| (104) | QName | ```::= [http://www.w3.org/TR/REC-xml-names /#NT-QName]``` |
| (105) | NCName | $\begin{aligned} ::= & {[h t t p: / / \text { www.w3.org/TR/REC-xml-names }} \\ & / \# N T-N C N a m e] \end{aligned}$ |

### 3.2.3 Parse Tree

An example is the parse tree of XPATH query descendant: :tweet in Figure 3.1. This parse tree is obtained starting with nonterminal XPath. From there the only choice is nonterminal OrExpr. Since the query does not contain the keyword or, the star pattern of nonterminal OrExpr matched zero occurrences. So one expends into nonterminal AndExpr, and so on.


Figure 3.1: The parse tree of XPATH query descendant: :tweet.

### 3.3 Path Expressions

Path expressions access nodes of XmL data trees. Navigation within an XmL data tree is supported via axes by nonterminal AxisStep (38). They are single path steps that perform navigation via forward and backward axis to some node which is tested for its label, kind, and against a list of filters. These path steps can then be composed.

### 3.3.1 Forward and Backward

Single path steps use either a forward or a backward axis. Forward axes contain future nodes of the start node, i.e. those nodes that are related to the start node via future relation fut. In the grammar production below such an axis is child with proceeding colons ": :", to which a test on the target node follows.

```
(40) ForwardAxis::= ("child" "::") | ("descendant" "::") |
    ("attribute" "::") | ("self" "::") |
    ("descendant-or-self" "::") |
    ("following-sibling" "::") |
    ("following" "::") | ("namespace" "::")
```

Backward axes contain all other nodes, i.e. those related to the start node via relation $p c$.
(43) ReverseAxis::= ("parent" "::") | ("ancestor" "::") |
("preceding-sibling" "::") | ("preceding" "::") |
("ancestor-or-self" "::")

### 3.3.2 Label Tests

Label tests inspect the node-name property of element and attribute nodes, that is stored as data value. It represents a QName, which is made up of a namespace prefix and a local part (the actual label). NameTests by nonterminal NameTest (46), allow to test either the namespace prefix, the local part, or both of the nodes label.

An example is query

```
descendant::a
```

that selects all a-labeled descendants of the start node, while query

```
descendant::xml:*
```

selects all descendants nodes, whose namespace prefix is equal to xml .

### 3.3.3 Kind Tests

Any node can be tested for its kind, i.e. the XmL type, that is also stored in node labels of XmL data trees. Kinds test are the document node, element, attribute, processing-instruction, comment, and text node tests, or may be the AnyKindTest node() the matches any node kind.

$$
\begin{aligned}
\left(71^{\prime}\right) \text { KindTest }::= & \text { DocumentTest | ElementTest | AttributeTest | } \\
& \text { PITest | CommentTest | TextTest | AnyKindTest }
\end{aligned}
$$

For example, query

```
child::text()
```

selects all children of type $t x$. One can also test whether descendant of some node are element nodes whose label is "a" as in query

```
descendant::element(a)
```

which is equivalent to descendant: : a.

### 3.3.4 Relative, Absolute, and Abbreviated Expressions

Path expressions can be relative such that they are evaluated from some node as we have seen with queries descendant: : a and child::text(). Otherwise they are absolute and thereby evaluated from the root of the tree. In XPATH absolute expressions have "/" or "//" prepended to them, as in query /descendant: : a that selects all a-descendants of the root node.

Most often XPath queries use the abbreviation "/" for the child axis, and also when the axis name is omitted for a path step, the child axis is the default one:

$$
\mathrm{a} / \mathrm{b}=\text { child::a/child::b }
$$

An occurrence of the abbreviation "//" in XPATH queries which is not at the beginning of a path expression is an abbreviation for /descendant-or-self::node()/, as in query
/a//b = /a/descendant-or-self::node()/b.

### 3.3.5 Filters

Filters a.k.a predicates in XPATH are test expressions given in square brackets. For some node they can test whether it is related to certain other nodes. The following query, for example, retains all book- labeled descendant nodes for which the filter becomes true

```
//book[not(child::title)]
```

It selects all book-descendants of the root, that do not have a title-labeled child node. Therefore, filters determine which elements of an input sequence are kept and which are not.

In general a filter expression $P\left[P^{\prime}\right]$ is evaluated as follows. $P$ evaluates to a sequence of items, and not necessarily to a sequence of nodes only. For every item in the sequence by $P$ the filter $P^{\prime}$ is evaluated. If the filter evaluates to true, the item is retained. Note that filters in the original XPATH grammar [Robie 2014b] allow to evaluate to an integer as well. In that case the item is retained if the integer is equal to the position of the item in the sequence, as with query child: :author [2] that selects the second author-child.

### 3.3.6 Compositions

Single path steps with optional filters can be composed using XPATH's path operator "/". For all a-children that have a b-child, for example, as in query

```
/child::a[child::b]/child::c
```

the expression child: : c is evaluated, resulting in the selection of all c-nodes below a-children of the root that have a b-child.

In general, expressions P in path compositions $\mathrm{P} / \mathrm{P}$ ' must evaluate to a sequence on nodes. Expression $P^{\prime}$ is evaluated for every node in that sequence and result sequences are appended. In the original rule of the XPATH 3.0 grammar of [Robie 2014b] path compositions, as by nonterminal RelativePathExpr (36) single path steps may also return numbers and strings, and not only nodes. The specification of the path operator "/" states that the result sequences by $P$ ' are either sequences of non-nodes, or they are sequences of nodes of which duplicates are removed, and which are returned in document order. The removal of duplicates is performed in order to obtain a set of nodes. Otherwise with tree $a(a(a(b)))$ one would select the common b-descendant several times as with query

```
/descendant::a/descendant::b
```

which selects all b-descendants which has some a-ancestor of the root.

Chapter 4

## Types and Values

## Contents

4.1 Sequence Type Expressions ..... 50
4.2 Basic Types ..... 51
4.2.1 Atomic Types ..... 51
4.2.2 Union Types ..... 51
4.2.3 Node Types ..... 51
4.2.4 Function Types ..... 53
4.3 Sequence Types ..... 53
4.4 Subtyping ..... 54
4.4.1 Item Types ..... 54
4.4.2 Sequence Types ..... 54
4.5 Dynamic Type Checking ..... 54

This chapter explains the types and values of XPath 3.0 that are based on sequences: There are atomic types, node types, and function types. Respective values are atomic values, such as integers, nodes of XmL data trees, and functions. These values are called items. Then there are sequence types, whose values are sequences, which are ordered list that are made up of items and not nested. Therefore a list of pairs $((1$, "one"), (2, "two"), (3, "three")), for example, would have to be encoded into sequence ( 1 , "one", 2 , "two", 3 , "three"), where every two items make up for a pair.

Type checking is static and dynamic. Statically one verifies whether there is no syntax error in the query, whether the declared functions parameters do not have the same name, or whether predefined prefixes such as xml are not declared elsewhere. Otherwise type checking is mostly dynamic, while there exist dynamic type-conditionals, such as instance of, that verify whether a sequence has an expected type or not. Variables in XPath are statically typed depending on their context, functions are annotated with input and output types, while items in general may have several types because of subtyping. For all these reasons, sequence types have a concrete syntax specified by the grammar of XPath 3.0.

### 4.1 Sequence Type Expressions

Sequence type expressions are derived from nonterminal SequenceType (67). They are expressions, but also types in the XPath 3.0 language, as we will discuss.

| (67) SequenceType | $\begin{aligned} ::= & (\text { "empty-sequence" "(" ")") \| } \\ & \text { (ItemType OccurrenceIndicator?) } \end{aligned}$ |
| :---: | :---: |
| (68) OccurrenceIndicator | ::= "?" \| "*" | "+" |
| (69) ItemType | ```::= KindTest \| ("item" "(" ")") | FunctionTest | AtomicOrUnionType | ParenthesizedItemType``` |
| (70) AtomicOrUnionType | : : = EQName |
| (71) KindTest | ```::= DocumentTest \| ElementTest | AttributeTest | SchemaElementTest | SchemaAttributeTest | PITest | CommentTest | TextTest |``` |
|  | NamespaceNodeTest \| AnyKindTest |
| (72) AnyKindTest | :: = "node" "(" ")" |
| (73) DocumentTest | ```::= "document-node" "(" (ElementTest \| SchemaElementTest)? ")"``` |
| (74) TextTest | :: "text" "(" ")" |
| (75) CommentTest | ::= "comment" "(" ")" |
| (76) NamespaceNodeTest | ::= "namespace-node" "(" ")" |
| (77) PITest | ::= "processing-instruction" "(" <br> (NCName \| StringLiteral)? ")" |
| (78) AttributeTest | $\begin{aligned} ::= & \text { "attribute" "(" (AttribNameOrWildcard } \\ & (", " \text { TypeName)?)? ")" } \end{aligned}$ |
| (79) AttribNameOrWildcard | ::=AttributeName \| "*" |
| (80) SchemaAttributeTest | $\begin{aligned} ::= & \text { "schema-attribute" "(" } \\ & \text { AttributeDeclaration ")" } \end{aligned}$ |
| (81) AttributeDeclaration | : := AttributeName |
| (82) ElementTest | $\begin{aligned} ::= & \text { "element" "(" (ElementNameOrWildcard } \\ & \text { (", " TypeName "?"?)?)? ")" } \end{aligned}$ |
| (83) ElementNameOrWildcard | d::= ElementName \| "*" |
| (84) SchemaElementTest | $\begin{aligned} ::= & \text { "schema-element" "(" } \\ & \text { ElementDeclaration ")" } \end{aligned}$ |
| (85) ElementDeclaration | : : = ElementName |
| (86) AttributeName | : : = EQName |
| (87) ElementName | : : = EQName |
| (88) SimpleTypeName | : := TypeName |
| (89) TypeName | : : = EQName |
| (90) FunctionTest | ::= AnyFunctionTest \| TypedFunctionTest |
| (91) AnyFunctionTest | ::= "function" "(" "*" ")" |
| (92) TypedFunctionTest | ::= "function" "(" (SequenceType |

```
                                    ("," SequenceType)*)? ")" "as"
SequenceType
(93) ParenthesizedItemType::= "(" ItemType ")"
(94) EQName ::= QName | URIQualifiedName
```


### 4.2 Basic Types

Basic types in XPath 3.0 are item types. It is a type that is derived by the EbNF rule ItemType (69). Their values are called items. Basically every item is either an atomic value, a node, or a function.

```
(69) ItemType::= KindTest | ("item" "(" ")") |
    FunctionTest | AtomicOrUnionType |
    ParenthesizedItemType
```

The item type item() is the most general item type: any item has type item(). Any item has the type ParenthesizedItemType (93) if and only if the item has the type that is in parenthesis.

### 4.2.1 Atomic Types

The XPath 3.0 data model accommodates of up to 50 different atomic types that are derived by nonterminal AtomicOrUnionType (70) and that we present in Figure 4.1.

For example, strings such as "abc" are of type xs:string, numbers 56 may represent integers of type xs:integer, 56E3 is a representation of a double of type xs:double, booleans are of type xs:boolean, and names math:sin represent an element of type QName that contain some local part (sin) and optionally some namespace prefix (math). For these types XPath 3.0 functions are provided that manipulate their values, such as $\mathrm{fn}: \mathrm{abs}$, fn:floor, math:exp, and math:sin for numeric values, fn : concat, fn :normalize-space, and fn :contains for string values, and fn:prefix-from-QName and fn:local-name-from-QName for QNames.

### 4.2.2 Union Types

There exist union types as well in XPath 3.0. They are also derived by nonterminal AtomicOrUnionType (70) and denote the union of the denotation of two item types.

### 4.2.3 Node Types

The node types are derived by nonterminal KindTest (71).

[^4]

Figure 4.1: Excerpt of the XPath Data Model 3.0 specification about atomic types and their subtype relations.

Amongst the node types there are types document-node(), element(), attribute(), text(), comment(), and processing-instruction() which denote nodes of the respective kind, while node() denotes all nodes of all node kinds. Furthermore there are node types by nonterminal ElementTest (82), for example, that may also specify the label of an element node. For example, type element (a) denotes the
set of element nodes whose label is a. For nodes there exist built-in functions, such as fn:name, fn:local-name, fn:path, fn:innermost, and fn:outermost to name a few.

### 4.2.4 Function Types

Function types are produced by nonterminal FunctionTest (90). Type function (*) , for example, denotes any function. Function types may also contain the types of their signature, such as type

```
function(xs:integer, xs:integer) as xs:integer
```

which denotes all two-parameter functions of signature xs:integer $\times$ xs:integer $\rightarrow$ xs:integer. Built-in functions are provided, such as math:sin which return the sine of its argument. Note that functions may be of higher order, i.e. return a function as its result or take a function as one of its arguments, such as built-in functions fn:for-each and fn:fold-left. The signature of these functions however use sequence types, as we discuss next.

### 4.3 Sequence Types

Sequence types are build from item types. They optionally use one of the occurrence indicators "?", "*", or " + ". Sequence types denote sequences that are ordered lists of items that are not nested. Furthermore a singleton sequence, i.e. a sequence containing exactly one item, is equivalent to the item it carries, for example, the double 56E3 $=(56 \mathrm{E} 3)$.

```
(67) SequenceType ::= ("empty-sequence" "(" ")") |
    (ItemType OccurrenceIndicator?)
(68) OccurrenceIndicator::= "?" | "*" | "+"
```

There is the empty sequence type empty-sequence() which denotes the empty list. A sequence type that is an item type (no occurrence indicator is present) denotes any one-item sequence of an item that denoted by the item type. For example, the item type xs:integer is also a sequence type: xs:integer as an item type denotes the set of integers, while xs: integer as a sequence type denotes the set of one-item lists of integers. This is since singleton sequences are identified to the item they carry, making every item of XPATH 3.0 a sequence.

An occurrence operator indicates the number of items in the sequence: "?" indicates zero or one items, "*" indicates zero or more items, and " + " stands for one or more items. A sequence type that is build from an item type with an occurrence operator "?", "*", or " + " denotes a list whose number of elements fits the occurrence operator, and whose elements are items of the respective item type.

For example the sequence type
xs:integer+
denotes a sequence of one or more integers, such as sequence

$$
(1,2,3) .
$$

### 4.4 Subtyping

XPATH 3.0 defines a subtype relation amongst item types and sequence types. The subtype relation of XPath is first defined for item types and then lifted to sequence types. We refer to the specification ${ }^{1}$ of a complete description of the subtype relation and mention only a few here.

### 4.4.1 Item Types

Any node, function, or atomic type is a subtype of the general item type item(). Any function type is a subtype of the general function type function(*), and any node type is a subtype of node(). For atomic types there are the subtypes indicated by arrows in Figure 4.1, for example

```
xs:integer is a subtype of xs:decimal.
```


### 4.4.2 Sequence Types

The subtype relation for item types is extended to a subtype relation on sequence types. This has to take into account all possible combinations of occurrence operators. For example, the sequence type $T$ ? for some item type $T$, is a subtype of sequence type $\mathrm{T}^{\prime} *$ for some other item type $\mathrm{T}^{\prime}$, if T is a subtype of $\mathrm{T}^{\prime}$, e.g.

```
xs:integer? is a subtype of xs:decimal*
```

Note that the occurrence indicators may not exclude themselves, for example, a sequence type with occurrence indicator " + " cannot be a subtype of a sequence type with occurrence indicator "?", since the occurrence "?" does not match more than one item, and since " + " does not match zero items. Note that the empty sequence type "()" is a subtype of all sequence types with indicators "?" and "*", but not a subtype for those with " + " or without an indicator.

### 4.5 Dynamic Type Checking

Dynamic type checking is referred to in the XPath 3.0 specification as Sequence Type Matching ${ }^{2}$. Given some value it tests whether its type is derived from an expected sequence type.

[^5]Function derives-from that is stated in the specification mainly describes the transitivity of the subtype relation. It can be defined as follows: Let $\mathrm{T}, \mathrm{T}^{\prime}$, and $\mathrm{T}^{\prime \prime}$ be item types. Then $T$ derives from itself. $T$ derives from $T^{\prime}$, if $T$ is a subtype of $T^{\prime}$. $T$ derives from union type $T^{\prime} \cup T^{\prime \prime}$ if either $T=T^{\prime}$ or $T=T^{\prime \prime}$. Finally $T$ derives from $\mathrm{T}^{\prime \prime}$ if T derives from some $\mathrm{T}^{\prime}$, which in turn derives from $\mathrm{T}^{\prime \prime}$.

This allows to check whether a type matches some value, as follows. An item types $T$ simply matches some value $v$, if the type of $v$ is derived from $T$ with respect to the above function derives-from. For sequences it can be defined as follows: the empty sequence type matches the empty sequence. An item type without an occurrence indicator matches a sequence if it contains just one item that is matched by the item type. An item type with an occurrence indicator matches a sequence if the number of elements in the sequence match the occurrence indicator and if the item type matches every item in the sequence.

Chapter 5

## Full XPath 3.0

## Contents

5.1 Grammar ..... 58
5.1.1 Basic Expressions ..... 58
5.1.2 Navigational Expressions ..... 59
5.1.3 Postfix Expressions ..... 59
5.1.4 Terminal Expressions ..... 60
5.1.5 Parse Tree ..... 61
5.2 Values ..... 62
5.2.1 Strings and Numbers ..... 62
5.2.2 Booleans ..... 62
5.2.3 Functions ..... 63
5.2.4 Sequences ..... 63
5.2.5 Conversions ..... 65
5.3 Positions ..... 65
5.4 Navigation ..... 66
5.4.1 Path Expressions ..... 66
5.4.2 Map Operator ..... 66
5.5 First-Order Connectives ..... 67
5.5.1 Arithmetics ..... 67
5.6 Data Comparisons ..... 67
5.6.1 Atomic ..... 68
5.6.2 Nodes ..... 68
5.6.3 Sequences ..... 68
5.7 Ordered Sets ..... 68
5.7.1 Duplicate-free Sequences ..... 69
5.7.2 Computing Sets when possible ..... 69
5.8 Error Handling ..... 70
5.8.1 Kinds of Errors ..... 70
5.8.2 Try and Catch Expressions ..... 70
5.9 Documents ..... 71
5.10 Regular Extension of XPath 3.0 ..... 71
5.11 XPathMark Benchmark ..... 72

In this chapter we present most of the expressions allowed in XPATH 3.0.

### 5.1 Grammar

### 5.1.1 Basic Expressions

(1) XPath ::= Expr
(2) ParamList ::= Param ("," Param)*
(3) Param ::= "\$" EQName TypeDeclaration?
(4) FunctionBody ::= EnclosedExpr
(5) EnclosedExpr ::= "\{" Expr "\}"
(6) Expr ::= ExprSingle ("," ExprSingle)*
(7) ExprSingle ::= ForExpr | LetExpr | QuantifiedExpr |
IfExpr | OrExpr
(8) ForExpr ::=SimpleForClause "return" ExprSingle
(9) SimpleForClause ::= "for" SimpleForBinding
("," SimpleForBinding)*
(10) SimpleForBinding $::=$ "\$" VarName "in" ExprSingle
(11) LetExpr : := SimpleLetClause "return" ExprSingle
(12) SimpleLetClause ::= "let" SimpleLetBinding
("," SimpleLetBinding)*
(13) SimpleLetBinding $::=$ "\$" VarName ":=" ExprSingle
(14) QuantifiedExpr ::= ("some" | "every") "\$" VarName "in"
ExprSingle ("," "\$" VarName "in"
ExprSingle)* "satisfies" ExprSingle
(15) IfExpr : := "if" "(" Expr ")" "then" ExprSingle
"else" ExprSingle
(16) OrExpr $::=$ AndExpr ( "or" AndExpr )*
(17) AndExpr ::= ComparisonExpr ( "and" ComparisonExpr )*
(18) ComparisonExpr $::=$ StringConcatExpr ( (ValueComp |
GeneralComp | NodeComp)
StringConcatExpr )?
(19) StringConcatExpr : := RangeExpr ( "\||" RangeExpr )*
(20) RangeExpr : :=AdditiveExpr ( "to" AdditiveExpr )?
(21) AdditiveExpr $::=$ MultiplicativeExpr ( ("+" | "-")
MultiplicativeExpr )*
(22) MultiplicativeExpr ::= UnionExpr ( ("*" | "div" | "idiv" |
"mod") UnionExpr )*
(23) UnionExpr : := IntersectExceptExpr ( ("union" | "|")
IntersectExceptExpr )*
(24) IntersectExceptExpr ::= InstanceofExpr ( ("intersect" |
"except") InstanceofExpr )*
(25) InstanceofExpr ::= TreatExpr ( "instance" "of"
SequenceType )?
(26) TreatExpr ::= CastableExpr ( "treat" "as"
SequenceType )?

| (27) CastableExpr | $::=$ CastExpr ( "castable" "as" SingleType )? |
| :--- | :--- |
| (28) CastExpr | $::=$ UnaryExpr ( "cast" "as" SingleType )? |
| (29) UnaryExpr | $::=("-" \mid ~ "+") *$ ValueExpr |
| (30) ValueExpr | $::=$ SimpleMapExpr |
| (31) GeneralComp | $::=$ "=" \| "!=" | "<" | "<=" | ">" | ">=" |
| (32) ValueComp | $::=$ "eq" \| "ne" | "lt" | "le" | "gt" | "ge" |
| (33) NodeComp | $::=$ "is" \| "<<" | ">>" |
| (34) SimpleMapExpr | $::=$ PathExpr ("!" PathExpr)* |

### 5.1.2 Navigational Expressions

(35) PathExpr : := ("/" RelativePathExpr?) | ("//" RelativePathExpr) | RelativePathExpr
(36) RelativePathExpr ::= StepExpr (("/" | "//") StepExpr)*
(37) StepExpr ::= PostfixExpr | AxisStep
(38) AxisStep ::= (ReverseStep | ForwardStep)

PredicateList
(39) ForwardStep ::= (ForwardAxis NodeTest) | AbbrevForwardStep
(40) ForwardAxis ::= ("child" "::") | ("descendant" "::") |
("attribute" "::") | ("self" "::") |
("descendant-or-self" "::") |
("following-sibling" "::")
("following" "::") | ("namespace" "::")
(41) AbbrevForwardStep::= "@"? NodeTest
(42) ReverseStep ::= (ReverseAxis NodeTest) | AbbrevReverseStep
(43) ReverseAxis ::= ("parent" "::") | ("ancestor" "::") |
("preceding-sibling" "::")
("preceding" "::") |
("ancestor-or-self" "::")
(44) AbbrevReverseStep ::= ".."
(45) NodeTest ::= KindTest | NameTest
(46) NameTest ::= EQName | Wildcard
(47) Wildcard ::= "*" | (NCName ":" "*") |
("*" ":" NCName) |
(BracedURILiteral "*")

### 5.1.3 Postfix Expressions

(48) PostfixExpr
(49) ArgumentList
(50) PredicateList
::= PrimaryExpr (Predicate | ArgumentList)*
::= "(" (Argument ("," Argument)*)? ")"
::= Predicate*
(51) Predicate
(52) PrimaryExpr
(53) Literal
(54) NumericLiteral
::= IntegerLiteral | DecimalLiteral | DoubleLiteral
(55) VarRef
::= "\$" VarName
(56) VarName
: := EQName
(57) ParenthesizedExpr
::= "(" Expr? ")"
(58) ContextItemExpr ::= "."
(59) FunctionCall
::= EQName ArgumentList
(60) Argument
::= ExprSingle | ArgumentPlaceholder
(61) ArgumentPlaceholder::= "?"
(62) FunctionItemExpr ::= NamedFunctionRef | InlineFunctionExpr
(63) NamedFunctionRef ::= EQName "\#" IntegerLiteral
(64) InlineFunctionExpr : := "function" "(" ParamList? ")" ("as"

SequenceType)? FunctionBody
(65) SingleType ::= SimpleTypeName "?"?
(66) TypeDeclaration ::= "as" SequenceType

### 5.1.4 Terminal Expressions

(95) IntegerLiteral ::= Digits
(96) DecimalLiteral ::= ("." Digits) | (Digits "." [0-9]*)
(97) DoubleLiteral ::= (("." Digits) | (Digits ("." [0-9]*)?)) [eE] [+-]? Digits
(98) StringLiteral ::= ('"' (EscapeQuot | [^"])* '"') | (")" (EscapeApos | [^)])* ")")
(99) URIQualifiedName::= BracedURILiteral NCName
(100) BracedURILiteral::= "Q" "\{" [^\{\}]* "\}"
(101) EscapeQuot : := '"",
(102) EscapeApos $::=$ "),"
(103) Comment $\quad:=$ "(:" (CommentContents | Comment)* ":)"
(104) QName : := [http://www.w3.org/TR/REC-xml-names /\#NT-QName]
(105) NCName $::=$ [http://www.w3.org/TR/REC-xml-names /\#NT-NCName]
(106) Char $::=$ [http://www.w3.org/TR/REC-xml\#NT-Char]
(107) Digits $::=$ [0-9]+
(108) CommentContents : := (Char+ - (Char* ('(:' | ':)') Char*))


Figure 5.1: The parse tree of XPAth query descendant: :tweet.

### 5.1.5 Parse Tree

We present the parse tree of XPath query descendant::tweet for the XPath 3.0 grammar in Figure 5.1. This is the parse tree using the original XPath 3.0 grammar, in contrast to the parse tree of Figure 3.1 for the same query, but for the navigational XPath grammar given in Section 3.2.2.

### 5.2 Values

### 5.2.1 Strings and Numbers

There are literal expressions, created by nonterminal Literal (53), which are expressions that either return a string or a numeric value. They are syntactic representations of a string or a numeric value.

A numeric expression without ".", "e", or " E " is an integer of type xs:integer. It is of type xs:decimal if it only has the dot ".", and otherwise it is a value of type xs:double. For example, expression 84 is a decimal value of type xs:decimal. They can also be constructed using constructor functions that specify the atomic type. For example, xs:integer (84) creates an integer value of type xs:integer. Furthermore, we would like to mention xs:float ("NaN") that returns special floatingpoint value "Not a Number", and xs:double("INF") that return a special value for "positive infinity".

String expressions are surrounded by double quotes and denote the string of characters within the quotes. For example expression "8.4" denotes a string containing the characters " 8 ", ".", and "4". Strings can be concatenated via the string concatenation expression by StringConcatExpr (19) that uses symbol "||" to denote the concat function fn : concat. For example, query "8." || "4" returns string "8.4".

### 5.2.2 Booleans

The boolean values true and false are returned by XPATH 3.0 functions fn:true and fn : false, respectively. Boolean values in XPATH 3.0 are computed by conditionals, logical connectives, filters, quantifications, and comparisons. However also other data types than booleans are permitted as test expressions, such as node sequences, strings, and numeric values. For example, query

```
if //a then //b else ()
```

evaluates to the sequence of b-descendants, if there is an a-descendant, and otherwise it evaluates to the empty sequence.

How to evaluate to boolean values in general is defined in XPATh by the effective boolean value, which is computed by function $f n$ : boolean. This function is computed implicitly for all expressions requiring boolean values. The above example is therefore equivalent to

```
if fn:boolean(//a) then //b else ()
```

For node sequences, functions fn : boolean returns true, if the sequence contains at least one node. For string types, the function returns true, if the value is not the empty string. For numeric values that are not equal to 0 and not the constant $N a N$ (not a number), true is returned and for boolean values the value itself is returned.

### 5.2.3 Functions

Function expressions. Functions can be referenced using EQNames, such as built-in function math: sin. The whole list of built-in functions is given in [Kay 2014].

Functions may be also referenced by an expression name\#arity that uniquely identifies a function via its name and arity such as concat\#2, which returns the concat function with two arguments.

Functions can also be defined inline within the XPATH expression, such as

```
function($a as xs:double, $b as xs:double) as xs:double {$a * $b},
```

that returns a function with two arguments of type xs:double computing their product. Inline function expressions specify the sequence types of the parameters of the function, the sequence type of the result, and the body of the function (the part within the curly brackets). If a sequence type is not declared, the default type is item()*.

Last but not least in XPATH 3.0 there are function call expressions that identify a function via an EQName, and which is called with a list of arguments. If some of the arguments are argument placeholder expressions ?, it is considered to be a partial function application that returns a function that is obtained via currying. For example the partial function application $f n: c o n c a t(" a ", ~ ?, ~ " c ") ~ r e s u l t s ~ i n ~$ function $\lambda y . f n:$ concat("a", $y, ~ " c ")$.

Atomization and Coercion. The evaluation of a function requires to convert the value of its arguments to their expected type, which is specified by the function conversion rules ${ }^{1}$. If one of its arguments types is a function type, then function coercion is applied to each function of the argument sequence, see next paragraph. Otherwise the expected argument type is a sequence type of non-function items. Atomization is applied to every item in that sequence, resulting in a sequence of atomic values. Those values are then converted to the expected non-function item type, if possible.

The specification defines function coercion ${ }^{2}$, which converts a function that is passed as argument to another function, in order to delay the checking of argument and return types until the invocation of the function. The function is converted into a new function that has the expected function type. When the new function is invoked, function conversion rules are applied to the function arguments, with which the original function is called. This result is finally converted to the expected result type of the function, applying once more the function conversion rules.

### 5.2.4 Sequences

Construction. The empty sequence is constructed with query (). In general sequences are constructed using the comma as in (( (2)), (3.0, "4"), ()) which is subject to sequence flattening.

[^6]Flattening. Sequences are not nested, in that a sequence can not appear as an element of another sequence. When combining sequences and items, an implicit flattening occurs, e.g.
(((2)), (3.0, "4"), ()),
where () is the empty sequence, is flattened to the sequence
(2, 3.0, "4").

Decomposition. Sequence are decomposed via for expressions by nonterminal ForExpr (8), such as

```
for $x in (1, 33, 555) return ($x + 100, $x)
```

which evaluates to sequence ( $101,1,133,33,655,555$ ). The expression following the return keyword is evaluated for every item $\$ \mathrm{x}$ in the sequence by the expression before the return keyword and in that order. Result sequences are appended. Moreover, functions that operate on sequences exist as built-in functions, such as fn:head, fn:tail, fn:remove, and reverse.

Atomization. The evaluation of arithmetic expressions and comparison expressions, relies on atomization, which atomizes a sequence of atomic values, nodes, and functions, to obtain a sequence of atomic values only. This is computed by function $f n$ : data, which retains atomic values, raises an error when encountering functions, and which computes the typed value of node items. The typed value is the data content of text, comment, and processing-instruction nodes, which corresponds to the attribute value for attribute nodes, and to the concatenation of data content of text node descendants for document and element nodes. For attribute and element nodes the result string is then cast to the schema-type stored as data value property of attribute and elements nodes.

For example, if the value of the argument to function fn : data is already atomic, as in query $\mathrm{fn}:(12.5)$, then the atomic value is returned. Otherwise for the small document "<a>Hello <b>there</b>.</a>" query

```
fn:data(//a)
```

returns the untyped atomic value "Hello there.": The function gets a list of a-nodes. Since nodes are not atomic, the nodes are atomized to their typed value.

Type Checking. An example XPath 3.0 query that performs sequence type matching directly is expression $P$ instance of $P^{\prime}$ which returns true whenever the type of the result by $P$ matches the type by P'. For example

$$
(1,2,3) \text { instance of xs:integer+ }
$$

evaluates to true.

### 5.2.5 Conversions

XPath 3.0 provides cast expressions that allow to cast values to a specific type, for which the specification gives a vast list of conversion rules ${ }^{3}$ that we will not discuss in any detail. An example is the following cast expression that casts value 2 as a double value:

```
2 cast as xs:double
```

For the purpose of comparing values using comparison expressions, see Section 5.6, one may require to find the least common type of two types, to which respective values are converted. For example the least common type of an xs:integer and a xs:float value is xs:float.

### 5.3 Positions

XPath makes vastly use of positions, which is the facility to test filters and to evaluate path expressions according to some position in a sequence. It means to reason about an item in a list, its position, and the size of the list. This information has to be accessible when looking at just one item in the sequence, thus one would require lists of tuples with this information when implementing it. However this is not supported directly within XPath 3.0, since sequences are flat.

For path expression using the path operator in expressions $\mathrm{P} / \mathrm{P}$ ', or the simple map operator (see Section 5.4.2) in expressions P! $\mathrm{P}^{\prime}$, or when testing predicates $\left.\mathrm{P}^{[\mathrm{P}}{ }^{\prime}\right]$, XPath defines a dynamic context for the evaluation of sub-expressions P', which contains information about the evaluation of P : The context item, referred to by XPath expression ".", is the item which is currently being processed, whose initial value is to be set by an implementation. For path expressions and filters, the context item for $P^{\prime}$ ' is the item of sequence $P$ that is currently being processed. The context position, referred to by function fn : position(), is the position of the context item within the sequence. Finally the context size is the number of items in the sequence, and referred to by function fn:last().

For example consider query

$$
(1 \text { to } 30)[. \bmod 3 \text { eq } 0],
$$

where 1 to 30 is a range expression that evaluates to the sequence of consecutive integers 1 until 30. Each of those integers eventually becomes the context item, for which the filter . mode 3 eq 0 evaluates to true if and only if it is dividable by 3. The result sequence is therefore $3,6,9, \ldots, 27,30$. The context size for the filter is 30 and the context item happens to be the context position. A query referring to context position and size is
//a[fn:position()=fn:last()] = //a[fn:last()]

[^7]which returns the last a-node in document order: The number of a-nodes in the sequence is $\mathrm{fn}: l \mathrm{last}()$, while the positions of the a-nodes range from 1 until $f n$ :last () such that the equality becomes true only for the last a-node. Last but not least, we mention a query that uses the path operator /, and which returns a sequence of consecutive integers: one for every a-node, starting with 1 :

```
//a/fn:position()
```


### 5.4 Navigation

### 5.4.1 Path Expressions

Path expressions are produced by nonterminal PathExpr (35), which we discussed in detail in Chapter 3. Path expressions according to the full XPath 3.0 grammar may also be postfix expressions, i.e. expressions by nonterminal PostfixExpr (48), that produce literal expressions, variable reference expressions, function calls, and function expressions.

### 5.4.2 Map Operator

One of the new features of XPATH 3.0 are expressions by nonterminal SimpleMapExpr (34) that use the mapping operator "!", which in contrast to the path operator operates on sequences of items, not only on sequences of nodes or non-node. It does not perform duplicate elimination, but only appends sequences by $P$ ' in the order of items of the sequence by $P$ for mapping expressions $P!P$ '. For example, query

$$
(1,3,5)!(.+10)
$$

returns the sequence $(11,13,15)$ : Subexpression (. + 10) is evaluated for every item in $(1,3,5)$ where the context item "." takes value 1, 3, and 5. Its result sequence therefore contains items 11, 13, and 15 in that order. However when XPath 3.0 is used in host language XQuery 3.0, whose ordering mode is set to unordered, then the result sequence may be returned in an implement-dependent order, see also Section 5.7.2.

Interestingly, the path expressions P/P' that use the path operator "/" can be expressed by the mapping operator which uses operations on sets of nodes:

```
P/P' =
    let $R:= P!P' return
    if (every $r in $R satisfies $r instance of node()) then
        ($R union ())
    else if (every $r in $R satisfies not($r instance of node())) then
        $R
    else error()
```

First, expression $P!P^{\prime}$ is evaluated. Then the result sequence is analyzed for whether only nodes are contained. If so, the union operator union is applied to the result
sequence with the empty one: Duplicates are eliminated (see Section 5.7.1). Otherwise if there exist an item in the sequence that is not a node, all items must be non-nodes and the sequence is returned, otherwise an error is thrown.

### 5.5 First-Order Connectives

XPath 3.0 provides first-order logic constructs, such as the logical connectives: conjunctions, disjunctions, negation, and quantifications.

Logical connectives like function fn :not and disjunction or perform implicit calls to fn : boolean for their operands as in the following query. The function computes the effective boolean value as discussed in Sectionchap3:sec:booleanvalues.

```
//book[fn:not(title) or fn:not(author)]
```

that selects all book-nodes, which either have no title or no author.
XPATH provides existential quantification some $\$ \mathrm{y}$ in P satisfies $\mathrm{P}^{\prime}$ that evaluate to true, if the effective boolean value of at least one evaluation of $\mathrm{P}^{\prime}$ with variable $\$ y$ bound to an element of the sequence by $P$ is true. The quantification every $\$ y$ in $P$ satisfies $P$ ' requires function $f n$ :boolean to become true for all evaluations of $P^{\prime}$ as in query

```
every $y in (1, "b", fn:true()) satisfies $y
```

which evaluates to true, since the fn : boolean(1) $=$ true, fn : boolean("b") = true and since the boolean constant fn:true() evaluates to true.

### 5.5.1 Arithmetics

Arithmetic operators are provided for addition " + ", subtraction "-", multiplication "*", division "div" and "idiv", modulus "mod", and for unary expressions "+" and "-".

Arithmetic expressions $P$ op $P^{\prime}$ are evaluated as follows, where op is one of the mentioned arithmetic operators. $P$ and $P^{\prime}$ are evaluated to sequences, that undergo atomization. Then when the sequences contain exactly one atomic value, whose types are of valid combination ${ }^{4}$ for operator op, then the result is computed. Certain errors are raised if some of the mentioned condition for the computation of the arithmetic expressions are not met, or from division by 0 for example. The division of -3 div 2 for example returns a decimal value of -1.5 , while the integer division -3 idiv 2 returns integer -1 .

### 5.6 Data Comparisons

Two values can be compared using one of XPATH 3.0 comparison expressions: value comparisons, node comparisons, and sequence comparisons.

[^8]
### 5.6.1 Atomic

Atomic value comparison expressions, a.k.a. value comparisons in XPAth, use comparison operators "eq" (equals), "ne" (not equals), "lt" (less than), "le" (less than or equals), "gt" (greater than), and "ge" (greater than or equals). These expressions are evaluated similar to arithmetic expressions, in that sequences of the operators are atomized, and in that they should contain only a single item. The resulting two values, however, are first converted to their least common type before they are compared, assuming that they are valid combinations. An example is XPath query

```
//book[pages lt 200]
```

which selects all book-descendants of less than 200 pages.

### 5.6.2 Nodes

Node comparison expressions use operator "is", which checks node identity, and operators "<<" and ">>", which checks whether a node appears before or after another node in document order, respectively. No atomization occurs, but sequences must evaluate to single-node sequences. Query

```
//book[isbn="34668966"] is /library/book[title="Data"]
```

returns true, if the book-descendant with isbn-number "34668966" is the same node as a certain book-node, whose title is "Data".

### 5.6.3 Sequences

For sequence comparisons, a.k.a. general comparisons in XPath, two sequences are being joined together in order to find respective elements that compare to true with respect to the sequence comparison operators " $=$ " (equals), " $!=$ " (not equals), "<" (less than), "<=" (less than or equals), ">" (greater than), and ">=" (greater than or equals). Atomization is applied to each operand of the comparison to obtain sequences of atomic values. In essence the result of the comparison is true, if there exists a value from the first sequence and another value from the second one, such that they compare to true with respect to the comparison operator. Behind the scene a variety of type conversion are carried out in order to obtain comparable types for the atomic values that are being compared. For example query

```
//book[author = "Abiteboul"]
```

selects all book-descendant, who have an author-child whose concatenation of data content of its text node descendants is equal to "Abiteboul".

### 5.7 Ordered Sets

The concept of sets or sets of nodes is present in XPath 1.0. There the type node-set is used, which is considered to be an unordered collection of nodes without
duplicates. However when serializing or enumerating a set of items or a set of nodes, one always needs to fix an order. Therefore in XPath 3.0 the concept of ordered sets moved forward. It is represented as a sequence without duplicates.

### 5.7.1 Duplicate-free Sequences

The selection of nodes via navigation, as discussed in Section 3.3, produces a sequence of nodes without duplicates, that if not specified otherwise (see below in Section 5.7.2), is sorted in document order.

Also basic operations on sets of nodes are provided: unions, intersections, and complements. They take two sequences of nodes and compute the union, intersection, and set difference, respectively. All operators eliminate duplicates and subsequently sort the nodes in document order, computing thus an ordered set of nodes. For example XPath query

```
//a//c intersect //b//c
```

selects all c-nodes that are descendants of both an a-descendant and a b-descendant of the root. Query //a//c union //b//c selects all c-nodes that are descendants of either an a - or a b-descendant of the root. Last but not least query //a//c except //b//c selects all c-nodes that are descendants of a-descendants of the root, but which are no descendants of b-root descendants.

Furthermore there is a function fn:distinct-values which returns an ordered set. It takes a sequence of items and returns a new duplicate-free sequence that removes all but one of a set of values that are equal to one another. The sequence may be returned in an implementation dependent order. We note that this function heavily depends on the implementation of XPATH's equality operator eq.

### 5.7.2 Computing Sets when possible

For efficiency reasons one is interested in returning sequences in an arbitrary implementation dependent order. This can be obtained within XPath 3.0 by applying fn:unordered. However it relaxes the ordering only for the sequence that is its immediate operand. For query

```
fn:unordered(for $y in (1, 2, 3) return $y + 10)
```

any permutation of $(11,12,13)$ is an admissible answer. However the sequences are still concatenated in the order of sequence (1, 2, 3), and this cannot be undone by applying function fn : unordered to the concatenation.

Within the host language of XQUERY the order in which sequences are produced can be relaxed in XPATH 3.0 expressions according to the ordering mode of XQuery. This "order indifference" in XQuery expressions was already discussed in [Grust 2007] and exploited in a purely algebraic fashion.

XQUERY defines the ordering mode $\in\{$ ordered, unordered\}, which has the two values ordered and unordered that affect the order in which sequences of
expressions and all nested expressions thereof are returned. XQuery expressions ordered $\{P\}$ and unordered $\{P\}$ determine the ordering mode of expressions $P$ and its subexpressions. The ordering mode affects path expressions, node-set operations, for expressions, and allows freedom even with position functions (Section 5.3) that depend on the order of items in a sequence. For example the XQuery

```
unordered{//a/b//c}
```

would not have to sort the a-descendants found by subexpression //a into document order, before applying the path operator / to find b-children and c-descendants thereof.

### 5.8 Error Handling

### 5.8.1 Kinds of Errors

Errors may be raised in XPath 3.0 during static analysis or during the evaluation of the query. Errors raised during the static analysis phase, that are no type errors, are called static errors as with query

## 30div 5

which results in a syntax error. Type errors occur when some type does not match another expected type. They may occur during static analysis or during the evaluation phase. Finally, dynamic errors are mostly those errors that are detected during the evaluation phase. Consider XPath query
(5 div \$y) + xs:decimal (\$z)
which may result in a dynamic error, when $\$ \mathrm{y}$ evaluates to 0 or when $\$ \mathrm{z}$ evaluates to string "abc", for example. An implementation however may choose which of the two errors is raised by the additive expression and if some operand of some expression raises an error, then it may always decide to evaluate the other operands as well in order to detect whether errors occur there as well.

### 5.8.2 Try and Catch Expressions

Try and catch expressions do not exist in XPath 3.0 as built-in constructs, although they exist in XQuery 3.0. However, they exist in XPath 3.0 implicitly. There is an expression in XPath that tests whether a given value is castable into a certain type:
"The expression E castable as T returns true if the result of evaluating $E$ can be successfully cast into the target type $T$ by using a cast expression; otherwise it returns false."

The castable-as expression thus performs a real cast (Section 5.2.5), and it catches any dynamic errors that it may throw.

### 5.9 Documents

XPath 3.0 provides a collection of functions that access input documents and external resources, and other functions that allow to create XmL data trees on the fly.

There is function $f n$ :doc that identifies an XmL data tree within a sequence of available documents using a string that contains a URI and it returns its root node, which is a document node. The query

```
fn:doc("library.xml")/library//books
```

selects all book-descendants of library-children of the root within the XmL data tree that is associated with URI "library.xml".

Access to external resources, for example a text file, is granted by function fn:unparsed-text that takes a string that contains a URI as argument and optionally an encoding and that returns a string that represents the content of the file associated with the URI. An example query that checks whether a string is contained in a text file is:

```
fn:contains(fn:unparsed-text(passwords.txt),"#$df&@Wdf")
```

Last but not least we mention function fn : collection that returns a sequence of nodes of XmL data trees. The function associates the URI "http://example.org" in query

```
fn:collection("http://example.org")//people
```

with a collection of nodes.

### 5.10 Regular Extension of XPath 3.0

By Regular XPath 3.0 we mean an extension of XPath 3.0 with regular axis $\mathrm{P}^{*}$, which repeats steps for some path expression $P$. This is a pure syntactic extension, since regular axis can be expressed by recursive functions in XPATH 3.0 as we show below. Syntactically it can be integrated into the grammar of XPATH 3.0 by adding a pattern "(" RelativePathExpr ")*" to nonterminal PathExpr (35), obtaining
(35') PathExpr::= ("/" RelativePathExpr?) | ("//" RelativePathExpr) |
RelativePathExpr | "(" RelativePathExpr ")*"
Its semantics can be understood as follows. The context item, i.e. the item at which $\mathrm{P}^{*}$ is evaluated, must be a node, and P must always evaluate to a sequence of nodes. Then $\mathrm{P}^{*}$ evaluates to a sequence of nodes, which contains the context item and which contains recursively all nodes that an evaluation of $P$ yields from a node that is contained in the sequence by $\mathrm{P}^{*}$.

However, the extension with regular axis to the grammar is not necessary, although we keep it for simplicity, since regular axis $P^{*}$ can be expressed in XPATH

```
\(\mathrm{P}^{*}={ }_{\mathrm{df}}\)
let \$closureP :=
        function(\$nodes as node()*,
                                \$closure as function(node()*,function()) as node()*)
            \{let \$newnodes := \$nodes union (\$nodes/P)
            return if fn:exists(\$newnodes except \$nodes) then
                        \$closure(\$newnodes, \$closure)
                        else
                        \$newnodes
            \},
    \$regaxis :=
        function(\$nodes as node()*) as node()*
            \{\$closureP(\$nodes,\$closureP) \}
return \$regaxis(.)
```

Figure 5.2: Regular axis $\mathrm{P}^{*}$ by let expressions and recursive function definitions.
3.0 already as we show in Figure 5.2 using let expressions and recursive function definitions. There the outer let expression defines two variables \$closureP and \$regaxis, which are assigned to (unnamed) functions. Variable \$regaxis is assigned to a function that takes one argument, which is a list of nodes. It is invoked with the context node ".", meaning the list containing only the context node. It then invokes variable \$closureP, which is assigned a function with two parameters: the first being a list of nodes and the second parameter is function \$closure also with two parameters. The function proceeds by computing the union with all nodes reached from nodes in \$nodes by path expression $P$, obtaining possibly a bigger set of nodes in \$newnodes. If the new set of nodes is the same as the start set of nodes in \$nodes, then it is returned, otherwise the function goes into recursion with the new set of nodes in \$newnodes.

For example, consider the XmL data tree that represents a collection of tweets by Twitter in Figure 1.4, where each tweet-node has children id, reply, mess, and user. Then the regular XPath query

```
(let $y := . return following-sibling::tweet[reply = $y/id])*
```

when started at the second tweet-node, selects recursively all tweet-followingsibling nodes that reply to it. They are marked in bold in the Figure 1.4.

### 5.11 XPathMark Benchmark

A common XPath benchmark is the XPathMark benchmark ${ }^{5}$ which is the revised version in contrast to the benchmark of the original paper [Franceschet 2005]. It

[^9]contains queries about XMARK documents that contain a table of bids and a table of bidders. Some of the queries are parameterized by an integer $i \geq 1$, so that these queries can be scaled in size. Notice that the XPathMark bechmark was designed to test XPath 1.0 queries only, which are valid XPath 3.0 queries however. We give an overview in the following about the types of queries in the benchmark, while we refer to Appendix A for the full benchmark query collection, of which we test only a subset in our experiments.

The benchmark contains six categories A-F of queries: downward (A), axis (B), comparison (C), aggregation (D), position (E), and closure queries (F). Downward queries in the benchmark use child and descendant axes, such as query

## A3: /site/closed_auctions/closed_auction//keyword

or they contain filters with conjunctions or disjunctions, such

## A7: /site/people/person[phone or homepage]/name

The axis queries in the benchmark use in addition to the downward axes, also backward axes, attribute axes and other forward axes. Some of the queries are parametric, such as

$$
\text { B12(i): //item(/@id/. . })^{i} / \text { name }
$$

The comparison queries in the benchmark perform mostly data joins, such as query

C2:

```
/site/open_auctions/open_auction[bidder/increase = current]
/interval
```

The benchmark contains various aggregation queries that allow to count items, or to sum up values:

```
D3: /site/open_auctions/open_auction
[sum(bidder/increase) > 10 * initial]/interval
```

Positional queries of the benchmark contains positions as in query

## E3: //keyword/ancestor: llistitem[1]/text/keyword

Finally, there are some queries, that use some closure function, that repeatedly perform axes steps, similar to regular axes.

## Chapter 6

## $\lambda \mathbf{X P}$

## Contents

6.1 Types and Values . . . . . . . . . . . . . . . . . . . . . . . . . 76
6.1.1 Typing Parameters . . . . . . . . . . . . . . . . . . . . . . . . 76
6.1.2 Atomic Types . . . . . . . . . . . . . . . . . . . . . . . . . . . 76
6.1.3 Types . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 77
6.1.4 Subtyping . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 77
6.1.5 Equality Types . . . . . . . . . . . . . . . . . . . . . . . . . . 78
6.1.6 Admissible Types . . . . . . . . . . . . . . . . . . . . . . . . . 79
6.2 $\lambda$ XP Queries . . . . . . . . . . . . . . . . . . . . . . . . . . . . 79
6.2.1 Philosophy of Sets and Functions . . . . . . . . . . . . . . . . 79
6.2.2 Constants . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 80
6.2.3 Syntax . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 81
6.2.4 Positive Contexts . . . . . . . . . . . . . . . . . . . . . . . . . 82
6.2.5 Type System . . . . . . . . . . . . . . . . . . . . . . . . . . . 82
6.2.6 Library Functions . . . . . . . . . . . . . . . . . . . . . . . . 83
6.2.7 Recursive Functions . . . . . . . . . . . . . . . . . . . . . . . 85
6.2.8 Regular Axes . . . . . . . . . . . . . . . . . . . . . . . . . . . 85
6.2.9 Datalog . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 86
6.2.10 Data Comparisons . . . . . . . . . . . . . . . . . . . . . . . . 87
6.3 Semantics . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 87
6.3.1 Complete Partial Orders . . . . . . . . . . . . . . . . . . . . . 87
6.3.2 Denotational Semantics . . . . . . . . . . . . . . . . . . . . . 90
6.3.3 Well-definedness . . . . . . . . . . . . . . . . . . . . . . . . . 91
6.3.4 Correctness . . . . . . . . . . . . . . . . . . . . . . . . . . . . 92
6.4 Safety Restrictions . . . . . . . . . . . . . . . . . . . . . . . . . 93

In this chapter we introduce $\lambda \mathrm{XP}$, a typed first-order logical language that can query data trees. The language contains constructs for path navigation and supports higher-order functions and recursion. It relies on a mode system that distinguishes logical subformulas for which solutions must be searched allowing for efficient implementations. $\lambda \mathrm{XP}$ is then used as a core language for implementing evaluators for XPath 3.0 in the next chapter.

### 6.1 Types and Values

We define a typed language for values including tree nodes, tuples, sets, lists, and higher-order types with unions.

### 6.1.1 Typing Parameters

The type language is parameterized by a set of atomic types, their subtyping relationships and their interpretation.

Definition 5. The type parameters for sequences of data trees are a tuple $\mathcal{A}$ with the following components:

- $\Sigma$ is a finite ranked set, the node constructors of the data trees.
- $\Delta$ is a finite set, the alphabet of the data values of the data trees.
- $D$ is a set of elements,
- $\mathcal{T}_{\text {atom }}$ is a finite set whose elements are the atomic types to be interpreted over $D \uplus \operatorname{nodes}(s)$ for any sequence $s$ of data trees. They must contain:

$$
\{\text { node }, \text { char, string, none, int, float, bool, lab }\} \subseteq \mathcal{T}_{\text {atom }}
$$

- For any sequence $s$ of data trees and any atomic type $T \in \mathcal{T}_{\text {atom }}$, there is a domain of elements inhibiting this type $\llbracket T \rrbracket_{s} \subseteq D \uplus$ nodes $(s)$.
- For any sequence s of data trees, $\leq_{D}$ is a partial order on $D$ which is total when restricted to elements of equality types $\mathcal{T}_{\text {eq }}$ defined below.


### 6.1.2 Atomic Types

The set of atomic types must contain the type node for nodes of trees in the sequence, the type char of string characters in $\Delta$, the type string of strings over $\Delta$, the empty type none, the two numeric types int for integers and float for floats, the Boolean type bool, and the type lab of node constructors in $\Sigma$. These types have the following domains for any sequence of trees $s \in\left(\mathcal{T}_{\Sigma, \Delta}\right)^{*}$ :

$$
\begin{aligned}
& \llbracket \text { node } \rrbracket_{s}=\operatorname{nodes}(s) \\
& \llbracket \text { char } \rrbracket_{s}=\Delta \\
& \llbracket \text { string } \rrbracket_{s}=\Delta^{*} \\
& \llbracket \text { none } \rrbracket_{s}=\emptyset \\
& \llbracket \text { int } \rrbracket_{s}=\text { Int } \\
& \llbracket \text { float } \rrbracket_{s}=\text { Float } \\
& \llbracket \text { bool } \rrbracket_{s}=\text { Bool } \\
& \llbracket \text { lab } \rrbracket_{s}=\Sigma
\end{aligned}
$$

We assume that nodes of $s$ are identified by values that are different from all others, even though one may think of node identifiers as numbers. On atomic types we define a subtype relation $\preceq_{\text {atom }}$ semantically so that for all $T_{1}, T_{2} \in \mathcal{T}_{\text {atom }}$ :

$$
T_{1} \preceq_{\text {atom }} T_{2} \text { iff } \forall s . \llbracket T_{1} \rrbracket_{s} \subseteq \llbracket T_{2} \rrbracket_{s}
$$

In particular, we have int $\preceq_{\text {atom }}$ float and none $\preceq_{\text {atom }} T$ for all $T \in \mathcal{T}_{\text {atom }}$. Furthermore, since we assumed that node identifiers are different from all other values, we have node cannot be subtype or supertype of any of other atomic type enumerated above. However, there may be some other atomic types, say for instance node $_{\sigma}$ for all nodes labeled by $\sigma \in \Sigma$ and this type is a subtype of node.

### 6.1.3 Types

A type is a term build from atomic types according to the following abstract syntax:

$$
T::=A\left|T_{1} \times \ldots \times T_{n}\right|[T]|\{T\}| T_{1} \cup T_{2} \mid T_{1} \rightarrow T_{2}
$$

Besides atomic types $A \in \mathcal{T}_{\text {atom }}$, there are types for $n$-tuples $T_{1} \times \ldots \times T_{n}$, lists [ $T$ ], sets $\{T\}$, unions $T_{1} \cup T_{2}$, and functions $T_{1} \rightarrow T_{2}$, where $T, T_{1}, T_{2}$ are types again. The tuple type were $n=0$ is denoted by unit. We can also define the type of numerals:

$$
\text { num }={ }_{\text {def }} \text { int } \cup \text { float }
$$

To any type $T$ and sequence $s$ of trees we assign a value $\llbracket T \rrbracket_{s}$ by extending the definition for atomic types as follows:

$$
\begin{aligned}
& \llbracket T_{1} \times \ldots \times T_{n} \rrbracket_{s}=\llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s} \\
& \llbracket\{T\} \rrbracket_{s}=\left\{S \mid S \subseteq \llbracket T \rrbracket_{s} \text { finite }\right\} \\
& \llbracket[T] \rrbracket_{s}=\left(\llbracket T \rrbracket_{s}{ }^{*}\right. \\
& \llbracket T_{1} \cup T_{2} \rrbracket_{s}=\llbracket T_{1} \rrbracket_{s} \cup \llbracket T_{2} \rrbracket_{s} \\
& \llbracket T_{1} \rightarrow T_{2} \rrbracket_{s}=\llbracket T_{1} \rrbracket_{s} \rightarrow\left(\llbracket T_{2} \rrbracket_{s} \cup\{\perp\}\right)
\end{aligned}
$$

Note that the type string denotes the set of all character strings in $\Delta^{*}$, while the denotations of num and float are both the set of floats, since int $\preceq$ float.

The function type $T_{1} \rightarrow T_{2}$ is interpreted as the set of all partial functions $\llbracket T_{1} \rrbracket_{s} \rightarrow\left(\llbracket T_{2} \rrbracket_{s} \cup\{\perp\}\right)$. The symbol $\perp$ is returned for all the values of $\llbracket T_{1} \rrbracket_{s}$ where the function is undefined. This is needed, for instance, to treat division by zero in a proper manner, but also for the treatment of non-termination of function evaluation.

### 6.1.4 Subtyping

We extend the subtype relation $\preceq_{\text {atom }}$ to a subtype relation on types $\preceq$ by means of the rules in Figure 6.1. We next note that subtyping entails set inclusion on the denotations of the types.

Lemma 2. If $T_{1} \preceq T_{2}$ then $\llbracket T_{1} \rrbracket_{s} \subseteq \llbracket T_{2} \rrbracket_{s}$.
Proof. By induction of judgements of $T_{1} \preceq T_{2}$. In the base case of $T_{1} \preceq{ }_{\text {atom }} T_{2}$ it holds by semantic definition of $\preceq_{\text {atom }}$.

$$
\begin{aligned}
& \frac{T_{1} \preceq{ }_{\text {atom }} T_{2}}{T_{1} \preceq T_{2}} \quad \frac{\text { true }}{\text { none } \preceq T} \quad \frac{\forall 1 \leq i \leq n: T_{i} \preceq T_{i}^{\prime}}{T_{1} \times \ldots \times T_{n} \preceq T_{1}^{\prime} \times \ldots \times T_{n}^{\prime}} \\
& \begin{array}{c}
1 \leq i \leq n \quad T_{i} \preceq T_{i}^{\prime} \cup T_{i}^{\prime \prime} \\
\hline T_{1} \times \ldots \times T_{n} \preceq \cup\left(T_{1} \times \ldots \times T_{i}^{\prime} \times \ldots \times T_{n}\right) \\
\left(T_{1} \times \ldots \times T_{i}^{\prime \prime} \times \ldots \times T_{n}\right)
\end{array} \\
& \frac{T_{1} \preceq T_{2}}{\left[T_{1}\right] \preceq\left[T_{2}\right]} \quad \frac{T_{1} \preceq T_{2}}{\left\{T_{1}\right\} \preceq\left\{T_{2}\right\}} \quad \frac{\text { true }}{T_{1} \preceq T_{1} \cup T_{2}} \quad \frac{T_{1} \preceq T}{T_{1} \cup T_{2} \preceq T} \\
& \frac{T_{1} \preceq T_{2}}{T_{1} \cup T_{2} \preceq T_{2}} \quad \frac{T_{1}^{\prime} \preceq T_{1} T_{2} \preceq T_{2}^{\prime}}{T_{1} \rightarrow T_{2} \preceq T_{1}^{\prime} \rightarrow T_{2}^{\prime}}
\end{aligned}
$$

Figure 6.1: Subtyping.

### 6.1.5 Equality Types

For defining the semantics of our language, we will distinguish types whose elements can be compared for equality and ordered totally from the others. In particular, it is not clear how to test functions for equality, so we rule we exclude function type from the set of equality types.

Definition 6. The set $\mathcal{T}_{\text {eq }}$ of equality types is the least set that contains all atomic types, and for all equality types $T, T_{1}, \ldots, T_{n} \in \mathcal{T}_{\text {eq }}$, the tuple type $T_{1} \times \ldots \times T_{n}$, the list type $[T]$, and the union type $T_{1} \cup T_{2}$.

We assume that the partial order $\leq_{D}$ is total on all elements of equality types, i.e, on $D^{e q}=\cup_{T \in \mathcal{T}_{e q}} \llbracket T \rrbracket_{s}$. Thereby we obtain an equality relation on all elements of equality types:

$$
=_{e q}=\left(D^{e q} \times D^{e q}\right) \cap \leq_{D} \cap \geq_{D}
$$

In practice the order $\leq_{D}$ is obtained as follows. We can assume that the values of atomic types are totally ordered, so this order will be subsumed by $\leq_{D}$. The order for comparing tuples $\leq_{T_{1} \times \ldots \times T_{n}}$ is the lexicographic order on $\llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s}$. The order for lists is the lexicographic order on $\left(\llbracket T \rrbracket_{s}\right)^{*}$. Furthermore, we can have atomic types except strings before tuples and lists, while strings are to be identified with lists of characters.

We next show that subtypes of equality types are equality types too.
Lemma 3. Subtypes of equality types are equality types.
Proof. By induction of judgements $T_{1} \preceq T_{2}$. Atomic subtypes are equality types by definition. For subtypes of types of $n$-tuples, the lemma hold by induction, and similarly for subtypes of list types. Subtypes $T_{1}$ or $T_{2}$ of union type $T_{1} \cup T_{2} \in \mathcal{T}_{\text {eq }}$ are equality types by definition. For subtyping rule $\frac{T_{1} \preceq T}{T_{1} \cup T_{2} \preceq T}$ T $\preceq$ T follows by induction that $T_{1}$ and $T_{2}$ are equality type, since $T_{1} \preceq T$ and $T_{2} \preceq T$ for equality type $T$. It follows that subtype $T_{1} \cup T_{2}$ of $T$ is an equality type by definition. For rule $\frac{T_{1} \preceq T_{2}}{T_{1} \cup T_{2} \preceq T_{2}}$ it follows by induction that $T_{1}$ is an equality type since $T_{1} \preceq T_{2}$
for equality type $T_{2}$. By definition also $T_{1} \cup T_{2}$ is an equality type. Function and set types are ruled out, since we assume equality types.

### 6.1.6 Admissible Types

Definition 7. A type is admissible if for any of its subterms $\{T\}$ the type $T$ is an equality type.

Lemma 4. Subtypes of admissible types are admissible.
Proof. By induction of judgements $T_{1} \preceq T_{2}$ it follows for all subtyping rules, except rule $\frac{T_{1} \preceq T_{2}}{\left\{T_{1}\right\} \preceq\left\{T_{2}\right\}}$, that the inferred subtype is admissible, according to the definition of admissibility. For rule $\frac{T_{1} \preceq T_{2}}{\left\{T_{1}\right\} \preceq\left\{T_{2}\right\}}$, we know that for admissible type $\left\{T_{2}\right\}$ the type $T_{2}$ is an equality type. By Lemma 3 the subtype $T_{1}$ of $T_{2}$ is an equality type. By definition we have that subtype $\left\{T_{1}\right\}$ of $\left\{T_{2}\right\}$ is an admissible.

Therefore, we restrict ourselves to admissible types, for which the elements of sets have an equality type. This is particularly relevant for implementing finite sets, as for instance by ordered lists, so that one can remove duplicates efficiently.

Lemma 5. For any two equality types $T_{1}, T_{2}$, the restrictions of $\leq_{T_{1}}$ and $\leq_{T_{2}}$ to $\llbracket T_{1} \rrbracket_{s} \cap \llbracket T_{2} \rrbracket_{s}$ coincide.

As a consequence, if $T_{1} \preceq T_{2}$ then $\llbracket T_{1} \rrbracket_{s} \subseteq \llbracket T_{2} \rrbracket_{s}$ by Lemma 2 , so that $\leq_{T_{1}}$ is the restriction of $\leq_{T_{2}}$ to $\llbracket T_{1} \rrbracket_{s}$.

Proof. The orders $\leq_{T_{1}}$ and $\leq_{T_{2}}$ are contained within $\leq \tau_{e q}$ and are thereby noncontradicting.

## 6.2 $\lambda$ XP Queries

We present $\lambda \mathrm{XP}$ a hybrid logic that combines navigation with standard programming language constructs.

### 6.2.1 Philosophy of Sets and Functions

Sets and functions can be seen as relations which may contain infinitely many elements. We are not only interested in finite sets, since we may also want to define sets of strings and not only sets of nodes.

Therefore, one must clarify what it means that an algorithm returns a set or a function. A set will be given by an algorithm that enumerates the elements of the set. This algorithm can then be used to evaluate membership expression $x \in E$, where all possible bindings of $x$ to some value of $E$ must be generated. A function $f$ of type $T \rightarrow T^{\prime}$ will be given by an algorithm that inputs an argument $v$ of the function and returns the value of $f(v)$.

It should be noticed that sets are considered as generators, while functions are considered as applications. Therefore, it will not be possible to encode sets by their characteristic functions in the well-moded subset of our language, to which the evaluator will be restricted.

### 6.2.2 Constants

The language $\lambda \mathrm{XP}$ is parameterized by a set of typed constants $\mathcal{C}$ onst that are listed in Figure 6.2. The type of $c \in \mathcal{C}$ onst is denoted by Type $(c)$. The semantics of a constant $c$ of type $T$ with respect to a sequence of trees $s$ with node $\pi$ is value $\llbracket c \rrbracket_{s, \pi} \in \llbracket T \rrbracket_{s}$ that is defined in Figure 6.3.

In order to convert a list into a set or vise versa, we need to impose a total order on the elements, in which the conversion is carried out. The order is most relevant for converting a finite set into a list in a deterministic manner. Which precise order to chose is irrelevant in such cases. And whenever a concrete order is expected, it can be obtained by applying a sort function to the list obtained from the set. The ordering chosen for the conversions may be implementation dependent. This happens for instance, when converting a set to a list, where the elements of the set are produced in streaming manner. One then wants to apply the conversion to the elements of the set in the order in which they arrive on the stream. Sorting these elements in some other order would require to buffer the whole set, which may block real time progress in a streaming setting or require high memory consumption.

The current node which changes during evaluation of various axes can always be accessed by applying function cur to the unit, i.e. to the empty tuple () which has type none: the call will return the node $\pi$ of the current environment.

Furthermore, we give in the following one of many possible implementations of constant listconcat that concatenates lists of type $T$ to obtain a single list of type $T$ : This implementation models lists, as open lists $L^{o p}$ of type $T$ that are lists $L$ with a future element •, for example, $v_{1}:: \ldots:: v_{n}:: \bullet$, where $v_{i} \in \llbracket T \rrbracket_{s}$. Then listconcat can be implemented as follows.

```
listconcat \((L)={ }_{\mathrm{df}}\) let \(O=\) open-list.new() in open-list.toList(listconcat \(\left.{ }^{\prime}(L, O)\right)\)
```

where

$$
\begin{aligned}
& \text { open-list.new }=_{\mathrm{df}} \text { let } F=\text { future.new }() \text { in }(F, F), \\
& \text { open-list.toList }(O)={ }_{\mathrm{df}} \text { let }(O L, F)=O, b=\text { future.bind }(F, \text { nil }) \text { in } O L, \\
& \text { listconcat }^{\prime}(L, O)=\text { case } L \text { of nil then return } O \\
& \quad \text { } \begin{array}{c}
\text { } \text { ase } L \text { of } H: L^{\prime} \text { then return } \\
\quad \text { listconcat }^{\prime}\left(L^{\prime}, \text { open-list.extend }(O, H)\right)
\end{array}
\end{aligned}
$$

| Constants | Type |
| :---: | :---: |
| 1,2,3, $\ldots$, max_int | int $\preceq$ num |
| -1E4, 1.23, -0, 0, ... max_float | float $\preceq$ num |
| $c \in \Delta$ | char |
| $w \in \Delta^{*}$ | string |
| true, false | bool |
| ,,$+- \times, \div$ idiv, mod | $\bigcup \quad T \times T \rightarrow T$ |
| $\not \mathcal{F}_{T},=_{T},>_{T},<_{T}, \geq_{T}, \leq_{T}$ | $T \times T \rightarrow$ bool |
| $T$ is equality type |  |
| nil | [none] |
| $\emptyset$ | \{none\} |
| cur | unit $\rightarrow$ node |
| set2list $_{T}$ | $\{T\} \rightarrow[T]$ |
| list $^{\text {sett }}$ T | $[T] \rightarrow\{T\}$ |
| $\epsilon_{T}$ | $T \times\{T\} \rightarrow$ bool |
| labtype | node $\rightarrow$ lab |
| labvalues | node $\rightarrow \cup_{\sigma^{(k)} \in \Sigma}$ String $^{k}$ |
| type $_{T, T^{\prime}}$ | $T \times T^{\prime} \rightarrow$ bool |
| cast $_{T, T^{\prime}}$ | $T \rightarrow T^{\prime}$ |
| root | string $\rightarrow$ node |
| roots | string $\rightarrow$ [node] |
| listconcat | $[[T]] \rightarrow[T]$ |

Figure 6.2: Constants.

$$
\begin{aligned}
& \text { open-list.extend }(O, H)={ }_{\mathrm{df}} \text { case } H \text { of nil then return } O \\
& \text { case } H \text { of } X:: H^{\prime} \text { then } \\
& \text { let } F^{\prime}=\text { future.new }(), \\
& (O L, F)=O, \\
& b=\text { future.bind }\left(F, X:: F^{\prime}\right) \\
& \text { in }\left(O L, F^{\prime}\right)
\end{aligned}
$$

### 6.2.3 Syntax

The abstract syntax of $\lambda \mathrm{XP}$ formulas is given in Figure 6.4. It is parameterized by some alphabet $\Sigma$, and alphabet $\Delta$, the set of constants $\mathcal{C}$ onst, a set of variables $\mathcal{V}$, a set of axes $A$, and a set of label properties $\mathcal{L}$. A label property $L \in \mathcal{L}$ verifies a property for some label in $\Sigma$, i.e. $L: \Sigma \rightarrow \mathbb{B}$. For some sequence of data trees $s$ the label properties $L \in \mathcal{L}$ are used in unary relation symbols and interpreted as the set $L^{s}$ of nodes of $s$ whose label satisfy $L$.

The navigational fragment $F$ of $\lambda \mathrm{XP}$ are formulas composed of axes, label properties, node tests, conjunction, disjunction, and negation only:

$$
F::=A(F)|L| i s_{x}\left|F_{1} \wedge F_{2}\right| F_{1} \vee F_{2} \mid \neg F
$$

$$
\begin{aligned}
& \llbracket i \rrbracket_{s, \pi}=i \\
& \llbracket o \rrbracket_{s, \pi}=\bigcup_{T \preceq \text { num }}\left(o^{\llbracket T \rrbracket_{s}}\right)^{\perp} \\
& \llbracket o_{T} \rrbracket_{s, \pi}=\left(o^{\llbracket T \rrbracket_{s}}\right)^{\perp} \\
& \llbracket n i l \rrbracket_{s, \pi}=\text { empty list } \\
& \llbracket \emptyset \rrbracket_{s, \pi}=\text { empty set } \\
& \llbracket \text { set } 2 l i s t \rrbracket_{s, \pi}=\left(\text { set } 2 l i s t t^{\llbracket T \rrbracket_{s}}\right)^{\perp} \\
& \llbracket l i s t 2 s e t \rrbracket_{\rrbracket_{s, \pi}}=\left(\text { list } 2 \text { set }{ }^{\llbracket T \rrbracket_{s}}\right)^{\perp} \\
& \llbracket c u r \rrbracket_{s, \pi}=\{(-, \pi)\} \\
& \llbracket \epsilon_{T} \rrbracket_{s, \pi}=\left(\in^{\left.\llbracket T \rrbracket_{s}\right)^{\perp}}\right. \\
& \llbracket \text { labtype } \rrbracket_{s, \pi}=(\text { labtype })^{\perp} \\
& \text { 【labvalues } \rrbracket_{s, \pi}=(\text { labvalues })^{\perp} \\
& \llbracket \text { type }_{T, T^{\prime}} \rrbracket_{s, \pi}=\left(\text { type }^{\llbracket T \rrbracket_{s}, \llbracket T^{\prime} \rrbracket_{s}}\right)^{\perp} \\
& \llbracket \text { cast }_{T, T^{\prime}} \rrbracket_{s, \pi}=\left(\text { cast }^{\llbracket T \rrbracket_{s},\left[T^{\prime} \rrbracket_{s}\right)^{\perp}}\right. \\
& \llbracket r o o t \rrbracket_{s, \pi}=(\text { root })^{\perp} \\
& \llbracket \text { roots } \rrbracket_{s, \pi}=(\text { roots })^{\perp} \\
& \llbracket \text { listconcat } \rrbracket_{s, \pi}=\left(\text { listconcat }^{\left\lfloor T \rrbracket_{s}\right.}\right)^{\perp}
\end{aligned}
$$

if $\operatorname{Type}(i)=$ num $\cup$ char $\cup$ string $\cup$ bool
if $\operatorname{TYPE}(o)=\bigcup_{T \preceq \text { num }} T \times T \rightarrow T$
if $\operatorname{TYPE}(o)=T \times T \rightarrow$ bool
set to list conversion
list to set conversion
always returns the current node
set membership
node label types
node label data values
checks whether for $v: T$ also $v: T^{\prime}$
casts from $T$ to $T^{\prime}$
root nodes by strings
list of root nodes by strings
concatenation of lists

Figure 6.3: Semantic of constants from Figure 6.2.

When furthermore only forward axes child, descendant, and following-sibling are used, i.e. $A=\left\{c h, c h^{+}, n s^{+}\right\}$, then formulas belong to the forward navigational fragment of $\lambda \mathrm{XP}$, called Fxp.

Besides conjunction, disjunction, and negation $\lambda \mathrm{XP}$ contains also constants $c$, variables $x$, existential quantification, and goto constructs at $\left(E_{1}, E_{2}\right)$. Standard programming language constructs that $\lambda \mathrm{XP}$ inherits are conditionals and the creation and decomposition of tuples, sets, and lists. $\lambda \mathrm{XP}$ can define recursive higher-order functions, for which it contains a recursive let-construct. Notice that all expressions bound to variables must be monotone, see next section, since otherwise we can not ensure the termination of recursively defined functions. Finally $\lambda$ XP contains expressions for function applications and definitions. $\lambda$ XP contains try and catch expression for exception handling, which we do not consider in our formal analysis.

### 6.2.4 Positive Contexts

In order to decide whether an expression with recursive let definitions is valid or not, we introduce positive contexts of expressions and positive functions: We define positive contexts and positive functions in Figure 6.5.

### 6.2.5 Type System

The typing rules of $\lambda \mathrm{XP}$ are explained in Figure 6.6. The type of constants $c$ and variables $x$ is denoted by $\operatorname{TyPE}(c)$ and $\operatorname{TyPE}(x)$, respectively. Most of the typing

$$
\begin{aligned}
& E::=E_{1} \wedge E_{2}\left|E_{1} \vee E_{2}\right| \neg E|c| x \mid \exists x . E \quad \text { first-order logic } \\
& |A(E)| L \mid \boldsymbol{a t}\left(E_{1}, E_{2}\right) \\
& \text { | if } E_{1} \text { then } E_{2} \text { else } E_{3} \\
& \mid \quad \text { letrec } x_{1}=E_{1}, \ldots, x_{n}=E_{n} \text { in } E \\
& \text { navigation } \\
& \text { conditionals } \\
& \text { where all } x_{i} \text { occur in positive contexts in } E_{1}, \ldots, E_{n} \\
& \text { and all } E_{i} \text { have function types } \\
& \left|\left(E_{1}, \ldots, E_{n}\right)\right| \operatorname{match} E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2} \text { tuples where } n \neq 1 \\
& \mid\{x \mid E\} \quad \text { sets } \\
& \left|\quad E_{1}:: E_{2}\right| \operatorname{match} E_{1} \text { with } x:: y \text { then } E_{2} \text { else } E_{3} \text { lists } \\
& \text { | } E_{1} E_{2} \mid \lambda x . E \quad \text { functions } \\
& \text { |ry } E_{1} \boldsymbol{\operatorname { c a t c h }}(x) E_{2} \mid \text { raise } E \quad \text { exceptions }
\end{aligned}
$$

Figure 6.4: Abstract syntax of $\lambda \mathrm{XP}$ formula $E$, where $c \in \mathcal{C}$ onst is a constant, $x \in \mathcal{V}$ a variable, $L \in \mathcal{L}$ a label predicate, and $A$ a set of axes.
rules are standard. Notice that we require explicit type annotations on function definition, since otherwise this type cannot always be inferred. Notice also that for recursive let definitions we require that all variables are function types.

### 6.2.6 Library Functions

A common shortcut for the test whether the value of a variable is equal to the current node is

$$
i s_{x}={ }_{\mathrm{df}} x=\operatorname{cur}() .
$$

Another shortcut is the simple non-recursive let that is reduced to function application:

$$
\text { let } x=E \text { in } E^{\prime}={ }_{\mathrm{df}}\left(\lambda x \cdot E^{\prime}\right)(E)
$$

In Figure 6.7, we define sets of tuples and functions that input tuples. Note also, that one can always add or remove parenthesis in $(E)$, so this expression is equivalent to $E$; there are no 1-tuples in the language.

In Figure 6.8, we define the usual notion for sets, including enumerations for finite sets, unions, and maps, and for-loops for their aggregation. Finally, we can convert sets into lists, based on an implementation dependent order on the elements of the set.

Data joins are defined in Figure 6.9. They are reduced to existential quantifiers, conjunctions, and data comparisons. The usual list functions map, foldL, and append are defined in Figure 6.10.

```
C::= [.] | C^E | E\wedgeC | C\veeE | E\veeC
    | \epsilonT (E,C) | \existsx.C | A(C) | at(E,C) | at(C,E)
    | if E then C else E' | if E then E' else C
    letrec }\mp@subsup{x}{1}{}=\mp@subsup{E}{1}{},\ldots,\mp@subsup{x}{n}{}=\mp@subsup{E}{n}{}\mathrm{ in C
                where all }\mp@subsup{x}{i}{}\mathrm{ occur in positive contexts in }\mp@subsup{E}{1}{},\ldots,\mp@subsup{E}{n}{
                and all E}\mp@subsup{E}{i}{}\mathrm{ have function types
    match C with ( }\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{})\mathrm{ in E
        where all }\mp@subsup{x}{i}{}\mathrm{ occur in positive contexts in E
    match E with ( }\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{})\mathrm{ in C
        {x|C}
        C:: E| E :: C
        match C with x :: y then E else E E
            where x and y occur in positive contexts in E
        match E with }x::y\mathrm{ then }C\mathrm{ else E }\mp@subsup{E}{}{\prime
        match E with }x::y\mathrm{ then }\mp@subsup{E}{}{\prime}\mathrm{ else C
        PC where P is a positive function
P ::= \lambdax.E where x occurs only only in positive contexts of E
        c where \llbracketc\rrbracket \ is Scott continuous for all s such as +,*,\ldots
    | letrec }\mp@subsup{x}{1}{}=\mp@subsup{E}{1}{},\ldots,\mp@subsup{x}{n}{}=\mp@subsup{E}{n}{}\mathrm{ in }\mp@subsup{x}{j}{
                where all }\mp@subsup{x}{i}{}\mathrm{ occur in positive contexts in }\mp@subsup{E}{1}{},\ldots,\mp@subsup{E}{n}{
                and }\mp@subsup{E}{j}{}\mathrm{ is some positive function }\mp@subsup{P}{}{\prime}\mathrm{ and 1}\leqj\leq
```

Figure 6.5: Positive contexts $C$ and positive function $P$ in $\lambda$ XP formulas.

$$
\begin{aligned}
& \frac{E_{i}: \text { bool }}{E_{1} \wedge E_{2}: \text { bool }} \quad \frac{E_{i}: \text { bool }}{E_{1} \vee E_{2}: \text { bool }} \quad \frac{E: \text { bool }}{\neg E: \text { bool }} \quad \frac{\operatorname{TyPE}(c)=T}{c: T} \\
& \frac{\operatorname{Type}(x)=T}{x: T} \quad \frac{x: T E: \text { bool }}{\exists x . E: \text { bool }} \\
& \frac{E: \text { bool }}{A(E): \text { bool }} \frac{\text { true }}{L: \text { bool }} \frac{E_{1}: \text { node } E_{2}: T}{\text { at }\left(E_{1}, E_{2}\right): T} \\
& \begin{array}{l}
E_{1}: \text { bool } E_{2}: T \quad E_{3}: T \\
\hline \text { if } E_{1} \text { then } E_{2} \text { else } E_{3}: T
\end{array} \\
& \begin{array}{r}
x_{1}: T_{1} \ldots \\
\ldots
\end{array} x_{n}: T_{n} \quad E_{1}: T_{1} \ldots \quad E_{n}: T_{n} \quad E: T \quad T_{1}, \ldots, T_{n} \text { function types }{ }^{\text {letrec } x_{1}=E_{1}, \ldots, x_{n}=E_{n} \text { in } E: T} \\
& \frac{E_{1}: T_{1} \ldots E_{n}: T_{n}}{\left(E_{1}, \ldots, E_{n}\right): T_{1} \times \ldots \times T_{n}} \\
& \frac{E_{1}: T_{1} \ldots E_{n}: T_{n} \quad E_{1}: T_{1} \times \ldots \times T_{n} \quad E_{2}: T}{\operatorname{match} E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2}: T} \\
& \frac{x: T \quad T \in \mathcal{T}_{\text {eq }} E: \text { bool }}{\{x \mid E\}:\{T\}} \\
& \frac{E_{1}: T_{1} \quad E_{2}:\left[T_{2}\right]}{E_{1}:: E_{2}:\left[T_{1} \cup T_{2}\right]} \quad \frac{E_{1}:[T] \quad E_{2}, E_{3}: T^{\prime}}{\text { match } E_{1} \text { with } x:: y \text { then } E_{2} \text { else } E_{3}: T^{\prime}} \\
& \frac{E_{1}: T_{1} \rightarrow T_{2} \quad E_{2}: T_{1}}{E_{1} E_{2}: T_{2}} \quad \frac{x: T_{1} \quad E: T_{2} \quad \lambda x: T_{1} \rightarrow T_{2}}{\lambda x \cdot E: T_{1} \rightarrow T_{2}} \\
& \frac{E: T \quad T \preceq T^{\prime} \quad T^{\prime} \text { admissible }}{E: T^{\prime}}
\end{aligned}
$$

Figure 6.6: Typing rules.

### 6.2.7 Recursive Functions

We can define recursive functions such as the faculty function as done usually in functional programming:

$$
f a c={ }_{\mathrm{df}} \text { letrec } f=\lambda y \text {. if } y=0 \text { then } 1 \text { else } y \cdot f(y-1) \text { in } f
$$

This definition relies on the laziness of conditionals. For instance, when computing $f(0)$ then in the second branch of the conditional there is the expression $f(-1)$, which is undefined and evaluates to $\perp$. But this second branch will not be evaluated since the test of the conditional $y=0$ is satisfied in this case.

### 6.2.8 Regular Axes

We would like to notice that within $\lambda \mathrm{XP}$ we can express regular axis $E^{*}$ where $E:\{$ node $\}$, which recursively navigates from the current node to one of the nodes selected by $E$ :

$$
\begin{gathered}
E^{*}={ }_{\mathrm{dff}} \text { letrec } O=\lambda X . \text { let } X^{\prime}=X \cup\{y \mid \exists x . x \in X \wedge y \in \operatorname{at}(x, E)\} \\
\quad \text { in if } X=X^{\prime} \text { then } X^{\prime} \text { else } O\left(X^{\prime}\right)
\end{gathered}
$$

$$
\begin{aligned}
& (E)=_{\mathrm{df}} E \\
& \left\{\left(x_{1}, \ldots, x_{n}\right) \mid E\right\}=_{\mathrm{df}}\left\{x \mid \exists x_{1} \ldots \exists x_{n} \cdot x=\left(x_{1} \ldots, x_{n}\right) \wedge E\right\} \\
& \lambda\left(x_{1}, \ldots, x_{n}\right) . E==_{\mathrm{df}} \lambda z . \text { match } z \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E
\end{aligned}
$$

Figure 6.7: Tuples where $n \neq 1$.

$$
\begin{aligned}
& \{e\}={ }_{\mathrm{df}}\{x \mid x=e\} \\
& E_{1} \cup E_{2}={ }_{\mathrm{df}}\left\{x \mid x \in E_{1} \vee x \in E_{2}\right\} \\
& E_{1} \cap E_{2}={ }_{\mathrm{df}}\left\{x \mid x \in E_{1} \wedge x \in E_{2}\right\} \\
& E_{1} \backslash E_{2}={ }_{\mathrm{df}}\left\{x \mid x \in E_{1} \wedge \neg\left(x \in E_{2}\right)\right\} \\
& \text { map-set }={ }_{\mathrm{df}} \lambda f \lambda x . \operatorname{list} 2 \operatorname{set}(\operatorname{map}(f, \operatorname{set} 2 \operatorname{list}(x))) \\
& \text { foldL-set }={ }_{\mathrm{df}} \lambda f . \lambda x . \lambda y . \operatorname{list} 2 \operatorname{set}(\text { foldL }(\operatorname{set} 2 l i s t(y), x, f))
\end{aligned}
$$

Figure 6.8: Sets.

Notice, that the recursive definition of regular axes and the one for datalog as we show below, has a terminating condition. When one of these computed sets during some recursion does not grow anymore, meaning that it is the same with respect to the previous recursion, then one stops and the final set is computed. Notice also that a similar definition for recursion functions, as in the previous section, does not work. One could imagine to compute the graph of all arguments and values of the function, but since it may not be finite, one cannot test for equality.

### 6.2.9 Datalog

We can express save Datalog programs by considering predicates as sets of tuples. For instance consider the following datalog program defining the accessibility relation of a graph with edge relation e.

$$
\begin{aligned}
& p(x, z):-e(x, z) . \\
& p(x, z):-p(x, y), p(y, z) .
\end{aligned}
$$

With recursive functions, such recursive set definitions can be expressed as follows:
letrec $f=\lambda p^{\prime}$. let $p=p^{\prime} \cup\left\{(x, z) \mid e(x, z) \vee \exists y .(x, y) \in p^{\prime} \wedge(y, z) \in p^{\prime}\right\}$

$$
\text { in if } p=p^{\prime} \text { then } p \text { else } f(p)
$$

in $f(\emptyset)$

$$
\exists \bowtie\left(E_{1}, E_{2}\right)={ }_{\mathrm{df}} \exists y_{1} \cdot \exists y_{2} \cdot y_{1} \in E_{1} \wedge y_{2} \in E_{2} \wedge y_{1} \bowtie y_{2}
$$

Figure 6.9: Data comparison where $\bowtie \in\{\neq,=,>,<, \geq, \leq\}$.

$$
\begin{aligned}
& m a p={ }_{\mathrm{df}} \text { letrec } m a p^{\prime}=\lambda f \lambda x \text {. match } x \text { with } z:: x^{\prime} \text { then } \\
& f(z):: m a p^{\prime} f x^{\prime} \text { else nil in } m a p^{\prime} \\
& \text { fold } L={ }_{\mathrm{df}} \text { letrec } \text { foldL } L^{\prime}=\lambda f . \lambda x . \lambda y \text {. match } y \text { with } z:: y^{\prime} \text { then } \\
& \text { foldL } L^{\prime} f f(x, z) y^{\prime} \text { else } x \text { in fold } L^{\prime} \\
& \text { fold } R={ }_{\mathrm{df}} \text { letrec fold } R^{\prime}=\lambda f . \lambda x . \lambda y \text {. match } y \text { with } z:: y^{\prime} \text { then } \\
& f\left(z, f o l d R^{\prime} f x y^{\prime}\right) \text { else } x \text { in } f o l d R^{\prime} \\
& \text { append }={ }_{\mathrm{df}} \text { letrec append }{ }^{\prime}=\lambda(x, y) \cdot \text { match } x \text { with } z:: x^{\prime} \text { then } \\
& z:: \text { append }^{\prime}\left(x^{\prime}, y\right) \text { else } y \text { in append }{ }^{\prime}
\end{aligned}
$$

Figure 6.10: Lists.

### 6.2.10 Data Comparisons

Consider the following example that makes references to two different input trees in $s=t_{1}, t_{2}$, where $x_{1}=\operatorname{root}\left(t_{1}\right)$ and $x_{2}=\operatorname{root}\left(t_{2}\right)$ :

$$
\begin{align*}
& \operatorname{at}\left(x_{1},\left\{x \mid \operatorname{ch}+\left(\text { tweet } \wedge i s_{x}\right.\right.\right. \\
& \wedge \exists=\left(\operatorname{fn}: \operatorname{data}\left(\operatorname{set} 2 l i s t\left(\left\{x^{\prime} \mid \operatorname{ch}\left(\text { user_name } \wedge i s_{x^{\prime}}\right)\right\}\right)\right)\right.  \tag{1}\\
& \quad \text { at }\left(x_{2}, \mathrm{fn}: \operatorname{data}( \right. \\
& \left.\left.\left.\left.\left.\left.\quad \operatorname{set} 2 l i s t\left(\left\{x^{\prime} \mid c h^{+}\left(\text {students } \wedge \operatorname{ch}\left(\text { name } \wedge i s_{x^{\prime}}\right)\right)\right\}\right)\right)\right)\right)\right)\right\}\right)
\end{align*}
$$

It selects the set of tweet-descendant nodes in $t_{1}$, that have a user_name-child whose typed value is equal to the typed value of name-children of student-descendants of $t_{2}$. It is a join query between $t_{1}$ and $t_{2}$, where at-formulas are used to jump between the two trees. It corresponds to XPATH query $\$ x_{1} / /$ tweet [user_name $=\$ x_{2} / /$ students/name]. The typed values are obtained via atomization that we discussed in Section 5.2.4, while we refer to Section 7.2.4 for an $\lambda$ XP expression defining fn:data.

### 6.3 Semantics

We next define a denotational semantics for $\lambda$ XP queries. Since $\lambda$ XP permits recursive definitions, we will base the semantics least fixed points, whose existence is ensured by Kleene's fixed point theorem.

### 6.3.1 Complete Partial Orders

For any $s$, we will turn the set of all $s$-values into a CPO, so that Kleene's fixed point theorem can be applied.

$$
\begin{array}{r}
\begin{array}{c}
\perp \sqsubset v \\
v, v^{\prime} \in \llbracket T \rrbracket_{S} \quad T \text { set type } \\
v \subsetneq v^{\prime} \Rightarrow v \sqsubset v^{\prime}
\end{array} \frac{v, v^{\prime} \in \llbracket T \rrbracket_{s} \quad T \text { function type }}{v \subsetneq v^{\prime} \Rightarrow v^{\perp} \sqsubset v^{\prime \perp}}
\end{array}
$$

Figure 6.11: Partial order $\sqsubset$ on $s$-values, valid for all $v, v^{\prime} \in V_{s} \backslash\{\perp\}$.

The main difficulty that we have to deal with here is that of program errors or nontermination in our denotational semantics. As usual, we will represent these by the special symbol $\perp$, and add $\perp$ to the $s$-values in an appropriate manner.

For all types $T$ except for function types, we define the domain of the CPO by adding $\perp$ to the $s$-values of type $T$ :

$$
\llbracket T \rrbracket_{s}^{\perp}=\llbracket T \rrbracket_{s} \cup\{\perp\}
$$

For function types $T \rightarrow T^{\prime}$, we will define the CPOs by lifting functions to undefined inputs: A partial function $f: \llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s} \rightarrow \llbracket T \rrbracket_{s}^{\perp}$ is lifted to a total function $f^{\perp}: \llbracket T_{1} \rrbracket_{s}^{\perp} \times \ldots \times \llbracket T_{n} \rrbracket_{s}^{\perp} \rightarrow \llbracket T \rrbracket_{s}^{\perp}$ such that for all $v_{1} \in \llbracket T_{1} \rrbracket_{s}^{\perp}, \ldots, v_{n} \in \llbracket T_{n} \rrbracket_{s}^{\perp}:$

$$
f^{\perp}\left(v_{1}, \ldots, v_{n}\right)= \begin{cases}f\left(v_{1}, \ldots, v_{n}\right) & \text { if } v_{1}, \ldots, v_{n} \neq \perp \\ \perp & \text { otherwise. }\end{cases}
$$

We define the following domains for function types:

$$
\llbracket T \rightarrow T^{\prime} \rrbracket_{s}^{\perp}=\left\{f^{\perp} \mid f \in \llbracket T \rightarrow T^{\prime} \rrbracket_{s}\right\} \cup\{\perp\}
$$

Notice that we distinguish the empty partial functions $f_{\emptyset}: T \rightarrow T^{\prime}$ from $\perp$.
For any sequence $s$ we now define a partial order $\sqsubset$ on the set of all lifted $s$ values $V_{s}=\cup_{T}$ type $\llbracket T \rrbracket_{s}^{\perp}$. This is the least partial order that satisfies the axioms in Figure 6.11.

According to the first rule, $\perp$ is the least element of $V_{s}$ with respect to $\sqsubset$. For Booleans we assume that false $\sqsubset$ true. Sets do increase if an element is added, and similar for functions. Tuples increase if one of their components increases.

Since false $\sqsubset$ true it follows that $\wedge^{\text {bool }}$ and $\vee^{\text {bool }}$ are monotone functions while $\neg^{\text {bool }}$ is not monotone. Since sets increase when adding elements, it follows that set union is a monotone function, while set complement is not. The membership functions $\Lambda v^{\prime} . v \in v^{\prime}$ is monotone for any $v$, while non-membership $\Lambda v^{\prime} . v \notin v^{\prime}$ is not.

Proposition 2. For any function $f: \llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s} \rightarrow \llbracket T \rrbracket_{s}^{\perp}$ and any $1 \leq j \leq n$, if $f$ is monotone in its $j$-th argument then the function $f^{\perp}$ is monotone in its $j^{\prime}$ 'th argument too..

Proof. We consider two members of $\llbracket T_{1} \rrbracket_{s}^{\perp} \times \ldots \times \llbracket T_{n} \rrbracket_{s}^{\perp}, v=\left(v_{1}, \ldots, v_{n}\right)$ and $v^{\prime}=\left(v_{1}, \ldots, v_{j-1}, v_{j}^{\prime}, v_{j+1}, \ldots, v_{n}\right)$ such that $v_{j} \sqsubset v_{j}^{\prime}$. We have to show that $f^{\perp}(v) \sqsubseteq$ $f^{\perp}\left(v^{\prime}\right)$. If there exists $1 \leq i \leq n$ such that $v_{i}=\perp$, then $f^{\perp}(v)=\perp \sqsubseteq f^{\perp}\left(v^{\prime}\right)$.

Otherwise, $v_{i} \neq \perp$ for all $1 \leq i \leq n$ and also $v_{j}^{\prime} \neq \perp$. Hence for all $1 \leq i \leq n$, $v_{i} \sqsubset v_{i}^{\prime}$ in the CPO $\llbracket T_{i} \rrbracket_{s}$ ordered by the restriction of $\sqsubset$. The monotonicity of $f$ then yields $f^{\perp}(v)=f(v) \sqsubseteq f\left(v^{\prime}\right)=f^{\perp}\left(v^{\prime}\right)$.

We will show next that the ordering $\sqsubset$ preserves the "top-level structure" of $s$-values different from the error: it increases only some leaves containing functions or Booleans, or adds some elements to the sets.

Definition 8. An ordered top-level structure is a term with n-constructors from

$$
\left\{\text { set }^{\left(n^{\prime}\right)} \mid n^{\prime} \in \mathbb{N}_{0} \cup\{\infty\}\right\} \cup\left\{\text { tuple }^{(n)}, \text { list }^{(n)} \mid n \in \mathbb{N}_{0}\right\}
$$

and constants from $\cup_{T \in \mathcal{T}_{\text {atom }}} \llbracket T \rrbracket_{s} \cup \cup_{T, T^{\prime} \text { types }} \llbracket T \rightarrow T^{\prime} \rrbracket_{S}$.
To any value of $V_{s} \backslash\{\perp\}$ we can assign a set of ordered top-level structures, by fixing for each set an order on the elements.

Lemma 6. For any $s$ and any values $v, v^{\prime} \in V_{s}$, if $v \sqsubseteq v^{\prime}$ then either $v=\perp$ or there exist ordered top-level structures $t$ of $v$ and $t^{\prime}$ of $v^{\prime}$ such that for all nodes $\pi$ of $t$ and $n \geq 0$ :

1. if $t[\pi]=$ set $^{(n)}$ then $t^{\prime}[\pi]=$ set $^{(m)}$ for some $n \leq m$,
2. if $t[\pi]=t^{\prime}[\pi]$,
3. if $t[\pi]=$ false and $t^{\prime}[\pi]=$ true,
4. if $t[\pi]=\tilde{v}^{\perp}$ and $t\left[\pi^{\prime}\right]=\tilde{v}^{\prime \perp}$ are functions such that $\tilde{v} \subseteq \tilde{v}^{\prime}$.

Proof. By structural induction on derivations of $v \sqsubseteq v^{\prime}$.
Proposition 3. For any s, the partial order $\sqsubset$ on s-values is a complete partial order (CPO).

Proof. We need to show that any increasing nonempty chain $v_{1} \sqsubseteq \ldots v_{i} \sqsubseteq \ldots$ has a least upper bound. The chain may be of finite or infinite length.

Only the elements in the prefix of a prefix of the chain may be equal to $\perp$, since only the first rule concerns $\perp$. In this case, the least upper bound of the same chain but without the $\perp$-prefix is a least upper bound for the complete chain too. Therefore, we can assume that $\perp$ does not occur in the chain. The only chains containing an atom must be constantly equal to this atom, so it is the least upper bound. Therefore, it is sufficient to consider chains without values of atomic types or $\perp$.

Now suppose that all $v_{i}$ are either tuples, sets, lists, or functions. According to Lemma 6, there exist ordered top-level structures $t_{i}$ of $v_{i}$, such that the nodes sets of $t_{i}$ are increasing as well as the labels of the same nodes.

Let $t$ be the ordered top-level structure with nodes $(t)=\cup_{i} \operatorname{nodes}\left(t_{i}\right)$, such that for every node $\pi$ of some $t_{i}$, the label of $t$ is $t[\pi]=\sqcup_{j \geq i} t_{i}[\pi]$. In the case where $t_{i}[\pi]=\operatorname{set}^{\left(n_{i}\right)}$ for some $n_{i}$, we set $\sqcup_{j \geq i} t_{i}[\pi]=\sqcup_{j \geq i} \operatorname{set}^{\left(n_{i}\right)}=\operatorname{set}^{\text {sup }_{j \geq i} n_{j}}$. Note that
$\sup _{j \geq i} n_{j}$ may be equal to $\infty$. The only other possibility applies to leaf nodes $\pi$, where all $t_{i}[\pi]$ are some functions $f_{i}^{\perp}$ where $f_{i} \in \llbracket T \rrbracket_{s}$. In this case, $\sqcup_{i} t_{i}[\pi]=\left(\cup_{i} f_{i}\right)^{\perp}$. The unique value $v$ that admits $t$ as ordered top-level structure is the least upper bound of the chain of $v_{i}$ 's.

It follows from Proposition 3 that the partial order $\sqsubset$ restricted to $V_{s} \backslash\{\perp\}$ forms a CPO as well.

Proposition 4. For any function $f: \llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s} \rightarrow \llbracket T \rrbracket_{s}^{\perp}$ that is Scottcontinuous in all arguments, the function $f^{\perp}$ is also Scott-continuous in all arguments.

Proof. We fix a sequence of values $v_{1}, \ldots, v_{n} \in V_{s}$ and $1 \leq i \leq n$. We define a function $g$ by:

$$
g(v)=f\left(v_{1}, \ldots, v_{i-1}, v, v_{i+1}, \ldots, v_{n}\right)
$$

for all $v \in V_{s}$. By assumption, $g$ is Scott-continuous, i.e., for any increasing nonempty chain $v_{1}^{\prime} \sqsubseteq \ldots \sqsubseteq v_{i}^{\prime} \sqsubseteq \ldots$ in $V_{s} \backslash\{\perp\}$ it holds that $\sqcup_{i} g\left(v_{i}^{\prime}\right)=g\left(\sqcup_{i} v_{i}^{\prime}\right)$. We have to show that $g^{\perp}$ is Scott-continuous too. So let $v_{1}^{\prime} \sqsubseteq \ldots \sqsubseteq v_{i}^{\prime} \sqsubseteq \ldots$ be an increasing chain in $V_{s}$. If $v_{i}^{\prime}=\perp$ for all $i$ we have $\sqcup_{i} g^{\perp}\left(v_{i}^{\prime}\right)=\sqcup_{i} g^{\perp}(\perp)=\sqcup_{i} \perp=$ $\perp=g^{\perp}\left(\sqcup_{i} v_{i}^{\prime}\right)$.

Otherwise, we can remove the maximal prefix of $\perp$-values from the chain, and obtain an increasing nonempty chain in $V_{s} \backslash\{\perp\}$. Let $m$ be the first index of this chain. We then have $\sqcup_{i \geq m} g\left(v_{i}^{\prime}\right)=g\left(\sqcup_{i \geq m} v_{i}^{\prime}\right)$ since $g$ is Scott-continuous. Furthermore, $\sqcup_{i} g^{\perp}\left(v_{i}^{\prime}\right)=\sqcup_{i \geq m} g^{\perp}\left(v_{i}^{\prime}\right)$ and $\sqcup_{i} v_{i}^{\prime}=\sqcup_{i \geq m} v_{i}^{\prime}$. Hence $\sqcup_{i} g^{\perp}\left(v_{i}^{\prime}\right)=g^{\perp}\left(\sqcup_{i} v_{i}^{\prime}\right)$ as required.

### 6.3.2 Denotational Semantics

In Figure 6.12 and Figure 6.13 we define the denotational semantics $\llbracket E \rrbracket_{s, \pi, \mu}$ of an $\lambda$ XP formula $E$ with respect to a sequence of data trees $s$, a node $\pi \in \operatorname{nodes}(s)$ of one of these data trees, and a possibly partial variable assignment $\mu$ from variables to $s$-values. We define the consistent union of two variable assignments $\mu$ and $\mu^{\prime}$ by $\mu \uplus \mu^{\prime}=\mu \cup \mu^{\prime}$ if this union is a functional relation and leave it undefined otherwise. We also write $\mu \uplus x / \perp$ instead of $\mu$ if $x$ is undefined in $\mu$. This is a slight abuse of notation, in that $\mu$ is a functional relation with $\mu \subseteq V \times V_{s} \backslash\{\perp\}$ rather than a total function with codomain $V_{s}$.

Furthermore, during the computation of a set $\llbracket E \rrbracket_{s, \pi, \mu}$ where $E:\{T\}$, the order in which the elements of the set are discovered will depend on $s, \pi$ and $\mu$. In order to obtain a deterministic semantics, we will fix the required orders as parameters of the semantics. As parameters of the denotational semantics, we assume for any equality type $T \in \mathcal{T}_{\text {eq }}$, expression $E:\{T\}$, trees $s$ with node $\pi$, and variable assignment $\mu$ into $s$ a total order $\leq_{E, T, s, \pi, \mu}$ on the elements of $\llbracket E \rrbracket_{s, \pi, \mu}$. This order can be freely chosen by the implementation.
$\llbracket E_{1} \wedge E_{2} \rrbracket_{s, \pi, \mu}=\llbracket E_{1} \rrbracket_{s, \pi, \mu} \wedge^{\text {Bool }}{ }^{\perp} \llbracket E_{2} \rrbracket_{s, \pi, \mu}$
$\llbracket E_{1} \vee E_{2} \rrbracket_{s, \pi, \mu}=\llbracket E_{1} \rrbracket_{s, \pi, \mu} \vee^{\text {Bool }} \llbracket E_{2} \rrbracket_{s, \pi, \mu}$
$\llbracket \neg E \rrbracket_{s, \pi, \mu}=\neg^{\text {Bool }}{ }^{\perp} \llbracket E \rrbracket_{s, \pi, \mu}$
$\llbracket c \rrbracket_{s, \pi, \mu}=\llbracket c \rrbracket_{s, \pi}$
$\llbracket x \rrbracket_{s, \pi, \mu}=\mu(x) \quad$ may be undefined if $x \notin \operatorname{dom}(\mu)$
$\llbracket \exists x . E \rrbracket_{s, \pi, \mu}= \begin{cases}\text { true } & \text { if exists } v \in \llbracket \operatorname{TYPE}(x) \rrbracket \text { such that } \llbracket E \rrbracket_{s, \pi, \mu \uplus[x / v]}=\text { true } \\ \text { false } & \text { if all } v \in \llbracket \operatorname{TYPE}(x) \rrbracket \text { satisfy } \llbracket E \rrbracket_{s, \pi, \mu \uplus[x / v]}=\text { false } \\ \perp & \text { otherwise }\end{cases}$
$\llbracket A(E) \rrbracket_{s, \pi, \mu}=\left(\exists \pi^{\prime} \in \operatorname{nodes}(s) . A^{s}\left(\pi, \pi^{\prime}\right) \wedge^{\text {Bool }}{ }^{\perp} \llbracket E \rrbracket_{s, \pi^{\prime}, \mu}=\right.$ true $)$
$\llbracket L \rrbracket_{s, \pi, \mu}=\left(\pi \in L^{s}\right)$
$\llbracket \operatorname{at}\left(E_{1}, E_{2}\right) \rrbracket_{s, \pi, \mu}=\left(\Lambda \pi \in \operatorname{nodes}(s) . \llbracket E_{2} \rrbracket_{s, \pi, \mu}\right)^{\perp}\left(\llbracket E_{1} \rrbracket_{s, \pi, \mu}\right)$
$\llbracket$ if $E_{1}$ then $E_{2}$ else $E_{3} \rrbracket_{s, \pi, \mu}= \begin{cases}\llbracket E_{2} \rrbracket_{s, \pi, \mu} & \text { if } \llbracket E_{1} \rrbracket_{s, \pi, \mu}=\text { true } \\ \llbracket E_{3} \rrbracket_{s, \pi, \mu} & \text { if } \llbracket E_{1} \rrbracket_{s, \pi, \mu}=\text { false } \\ \perp & \text { if } \llbracket E_{1} \rrbracket_{s, \pi, \mu}=\perp\end{cases}$
$\llbracket \operatorname{letrec} x_{1}=E_{1}, \ldots, x_{n}=E_{n}$ in $E \rrbracket_{s, \pi, \mu}=$
Letrec $v_{1}=\llbracket E_{1} \rrbracket_{s, \pi, \mu^{\prime}}, \ldots, v_{n}=\llbracket E_{n} \rrbracket_{s, \pi, \mu^{\prime}}$ in $\llbracket E \rrbracket_{s, \pi, \mu^{\prime}}$
where $\mu^{\prime}=\mu \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]$

Figure 6.12: Part 1 of denotational semantics of $\lambda \mathrm{XP}$, where $s$ is a sequence of data trees, $\pi \in \operatorname{nodes}(s)$, and $\mu$ to $s$-values is a well-typed variable assignment.

### 6.3.3 Well-definedness

For instance, one can verify with this definition that the mutual recursive definition:

$$
\text { letrec } g=\lambda z \cdot f(z), f=\lambda y .27 \text { in } g(0)
$$

evaluates to 27. The fixed point operator for the two equations will start with $(\emptyset, \emptyset)$, then produce $(\emptyset, \Lambda v .27)$ and finally converge to $(\Lambda v .27, \Lambda v .27)$. Note that the semantics must use tuples with increasing components to obtain the correct evaluation.

The following proposition states that the semantics of letrec expressions is always well-defined.

Proposition 5. Let $x_{1}: T_{1}, \ldots, x_{n}: T_{n}$ be variables of function types, $s$ be $a$ sequence of trees, $\pi \in \operatorname{nodes}(s)$ and $\mu$ a variable assignment to s-values. Let $D=$ $\llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s}$ and $\sqsubseteq_{D}$ be the least partial order on $D$ satisfying for any two elements $\left(v_{1}, \ldots, v_{n}\right) \in D$ and $\left(v_{1}^{\prime}, \ldots, v_{n}^{\prime}\right) \in D$ :

$$
\frac{v_{1} \sqsubseteq v_{1}^{\prime} \quad \ldots \quad v_{n} \sqsubseteq v_{n}^{\prime}}{\left(v_{1}, \ldots, v_{n}\right) \sqsubseteq_{D}\left(v_{1}^{\prime}, \ldots, v_{n}^{\prime}\right)}
$$

Let $\sqsubset_{D}$ be the irreflexive restriction of $\sqsubseteq_{D}$. Then $\left(D, \sqsubset_{D}\right)$ is a CPO with least element $(\emptyset, \ldots, \emptyset)$.

$$
\begin{aligned}
& \llbracket\left(E_{1}, \ldots, E_{n}\right) \rrbracket_{s, \pi, \mu}=\quad \text { where } E_{1}: T_{1}, \ldots, E_{n}: T_{n} \\
& \left(\Lambda v_{1} \in \llbracket T_{1} \rrbracket_{s}, \ldots, v_{n} \in \llbracket T_{n} \rrbracket_{s} .\left(v_{1}, \ldots, v_{n}\right)\right)^{\perp}\left(\llbracket E_{1} \rrbracket_{s, \pi, \mu}, \ldots, \llbracket E_{n} \rrbracket_{s, \pi, \mu}\right) \\
& \llbracket \text { match } E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2} \rrbracket_{s, \pi, \mu}= \\
& \begin{cases}\llbracket E_{2} \rrbracket_{s, \pi, \mu \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]} & \text { if } \llbracket E_{1} \rrbracket_{s, \pi, \mu}=\left(v_{1}, \ldots, v_{n}\right) \\
\perp & \text { otherwise }\end{cases} \\
& \llbracket\{x \mid E\} \rrbracket_{s, \pi, \mu}= \begin{cases}\left\{v \in \llbracket \operatorname{TYPE}(x) \rrbracket_{s} \mid \llbracket E \rrbracket_{s, \pi, \mu \uplus[x / v]}\right\} & \text { if for all } v \in \llbracket \operatorname{TYPE}(x) \rrbracket_{s}: \\
\perp & \left.\begin{array}{ll} 
& \text { otherwise }
\end{array}\right)\end{cases} \\
& \llbracket E:: E^{\prime} \rrbracket_{s, \pi, \mu}=\left(\Lambda v \in \llbracket T \rrbracket_{s}, v^{\prime} \in \llbracket[T] \rrbracket_{s} . v:: v^{\prime}\right)^{\perp}\left(\llbracket E \rrbracket_{s, \pi, \mu}, \llbracket E^{\prime} \rrbracket_{s, \pi, \mu}\right) \text { where } E: T \\
& \llbracket \text { match } E_{1} \text { with } x:: y \text { then } E_{2} \text { else } E_{3} \rrbracket_{s, \pi, \mu}= \\
& \begin{cases}\llbracket E_{2} \rrbracket_{s, \pi, \mu \uplus\left[x / v, y / v^{\prime}\right]} & \text { if } \llbracket E_{1} \rrbracket_{s, \pi, \mu}=v:: v^{\prime} \\
\llbracket E_{3} \rrbracket_{s, \pi, \mu} & \text { if } \llbracket E_{1} \rrbracket_{s, \pi, \mu}=\text { nil } \\
\perp & \text { otherwise }\end{cases} \\
& \llbracket E_{1} E_{2} \rrbracket_{s, \pi, \mu}= \begin{cases}f\left(\llbracket E_{2} \rrbracket_{s, \pi, \mu}\right) & \text { if } f=\llbracket E_{1} \rrbracket_{s, \pi, \mu} \neq \perp \\
\perp & \text { otherwise }\end{cases} \\
& \llbracket \lambda x \cdot E \rrbracket_{s, \pi, \mu}=\left(\Lambda v \in \llbracket \operatorname{TYPE}(x) \rrbracket_{s} . \llbracket E \rrbracket_{s, \pi, \mu \uplus[x / v]}\right)^{\perp}
\end{aligned}
$$

Figure 6.13: Part 2 of denotational semantics of $\lambda \mathrm{XP}$, where $s$ is a sequence of data trees, $\pi \in \operatorname{nodes}(s)$, and $\mu$ to $s$-values is a well-typed variable assignment.

Proof. Proposition 3 show that the set $V_{s}$ of all $s$-values is a CPO with least element $\perp$. It follows from Lemma 6 that all restrictions $\left(\llbracket T_{i} \rrbracket_{s}, \sqsubset_{\mid \llbracket T_{i} \rrbracket_{s} \times \llbracket T_{i} \rrbracket_{s}}\right.$ ) are CPO's too, whose least element is $\emptyset$. As a consequence, $\left(D, \sqsubset_{D}\right)$ is a CPO too whose least element is $(\emptyset, \ldots, \emptyset)$.

### 6.3.4 Correctness

Proposition 6. Let $s$ be a sequence of trees, $\pi \in \operatorname{nodes}(s)$, and $\mu$ a variable assignment to s-values. Let $\lambda x$.E be a positive function. Then the function described by its denotation

$$
\left(\Lambda v \in \llbracket \operatorname{TYPE}(x) \rrbracket_{s} \cdot \llbracket E \rrbracket_{s, \pi, \mu \uplus[x / v]}\right)^{\perp}
$$

is Scott-continuous.
Proposition 7. Let $s$ be a sequence of trees, $\pi \in \operatorname{nodes}(s)$, and $\mu$ a variable assignment to $s$-values. Let letrec $x_{1}=E_{1}, \ldots, x_{n}=E_{n}$ in $E$ be a recursive let expression, where all $x_{i}$ occur in positive contexts in $E_{1}, \ldots, E_{n}$ and all $E_{i}$ are positive functions. Then the function

$$
\Lambda v \in \llbracket T_{1} \rrbracket_{s} \times \ldots \times \llbracket T_{n} \rrbracket_{s} \cdot\left(\llbracket E_{1} \rrbracket_{s, \pi, \mu \uplus \nu(v)}, \ldots, \llbracket E_{n} \rrbracket_{s, \pi, \mu \uplus \nu(v)}\right)
$$

is Scott-continuous on the CPO of Proposition 5, where $\nu=\Lambda\left(v_{1}, \ldots, v_{n}\right) .\left[x_{1} / v_{1}\right] \uplus$ $\cdots \uplus\left[x_{n} / v_{n}\right]$ and for all $1 \leq i \leq n$ : $\operatorname{TYPE}\left(x_{i}\right)=T_{i}$.

$$
\begin{aligned}
& \frac{E \triangleright V \rightarrow V^{\prime}}{E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}} \quad \begin{array}{l}
E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime} \\
E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}
\end{array} \\
& \frac{E_{1} \triangleright V \rightarrow V^{\prime}}{E_{1} \wedge E_{2} \triangleright V \rightarrow V \uplus V^{\prime} \cup V^{\prime} \rightarrow V^{\prime \prime}} \frac{\text { true }}{c \triangleright \emptyset \rightarrow \emptyset} \frac{\text { true }}{x \triangleright\{x\} \rightarrow \emptyset} \\
& \begin{array}{c}
E_{1} \triangleright V \rightarrow V^{\prime} \quad E_{2} \triangleright V \rightarrow V^{\prime} \\
E_{1} \vee E_{2} \triangleright V \rightarrow V^{\prime}
\end{array} \frac{E \triangleright V \rightarrow V^{\prime} \cup\{x\} \quad x \notin V^{\prime}}{\exists x . E \triangleright V \rightarrow V^{\prime}} \frac{E \triangleright V \rightarrow \emptyset}{\neg E \triangleright V \rightarrow \emptyset} \\
& \frac{E \triangleright V \rightarrow V^{\prime}}{A(E) \triangleright V \rightarrow V^{\prime}} \frac{E \triangleright V \rightarrow V^{\prime} \mathrm{E} \text { is navigational }}{\neg E \triangleright V \rightarrow V^{\prime}} \frac{E_{1} \triangleright V \rightarrow \emptyset E_{2} \triangleright V \rightarrow V^{\prime}}{\mathbf{a t}\left(E_{1}, E_{2}\right) \triangleright V \rightarrow V^{\prime}} \\
& \begin{array}{c}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow V^{\prime} \quad E_{3} \triangleright V \rightarrow V^{\prime} \\
\text { if } E_{1} \text { then } E_{2} \text { else } E_{3} \triangleright V \rightarrow V^{\prime}
\end{array} \\
& \frac{\forall 1 \leq i \leq n . E_{i} \triangleright V \uplus\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow \emptyset \quad E \triangleright V \uplus\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime}}{\text { letrec } x_{1}=E_{1}, \ldots, x_{n}=E_{n} \text { in } E \triangleright V \rightarrow V^{\prime}} \\
& \frac{\forall 1 \leq i \leq n . E_{i} \triangleright V \rightarrow \emptyset}{\left(E_{1}, \ldots, E_{n}\right) \triangleright V \rightarrow \emptyset} \quad \frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \uplus\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime}}{\text { match } E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2} \triangleright V \rightarrow V^{\prime}} \\
& \begin{array}{c}
E \triangleright V \rightarrow\{x\} \\
\{x \mid E\} \triangleright V \rightarrow \emptyset
\end{array} \\
& \begin{array}{c}
E_{1} \triangleright V \rightarrow \emptyset E_{2} \triangleright V \rightarrow \emptyset \\
E_{1}:: E_{2} \triangleright V \rightarrow \emptyset
\end{array} \frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \uplus\{x, y\} \rightarrow V^{\prime} \quad E_{3} \triangleright V \rightarrow V^{\prime}}{\text { match } E_{1} \text { with } x:: y \text { then } E_{2} \text { else } E_{3} \triangleright V \rightarrow V^{\prime}} \\
& \frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow \emptyset}{E_{1} E_{2} \triangleright V \rightarrow \emptyset} \frac{E \triangleright V \uplus\{x\} \rightarrow \emptyset \quad x \notin V}{\lambda x . E \triangleright V \rightarrow \emptyset} \\
& \frac{E \triangleright V \rightarrow \emptyset}{x=E \triangleright V \rightarrow\{x\}} \quad \frac{E \triangleright V \rightarrow \emptyset}{x \in E \triangleright V \rightarrow\{x\}}
\end{aligned}
$$

Figure 6.14: Mode judgements for well-typed $\lambda \mathrm{XP}$ formulas.

### 6.4 Safety Restrictions

Let $E$ be a $\lambda$ XP formula. A mode of $E$ is a pair of variable subsets $V \rightarrow V^{\prime}$ of input variables $V \subseteq \mathcal{V}$ whose values are known before evaluation of $E$, and output variables $V^{\prime} \subseteq \mathcal{V}$ whose values will be produced during the evaluation of $E$. We write $E \triangleright V \rightarrow V^{\prime}$ to say that $E$ has mode $V \rightarrow V^{\prime}$. Let $f V(E)$ be the set of free variables in $E$. We say that $E$ is well-moded, if $V^{\prime}$ contains all free variables of $E$, except those variables in $V$, i.e. $f V(E) \backslash V \subseteq V^{\prime}$.

Well-moded $\lambda$ XP formulas allow for efficient evaluation. Problems arise with existential quantification $\exists x$. $E$, where one would have to test $E$ enumerating all possible values of $\operatorname{Type}(x)$, and also in set constructions $\{x \mid E\}$ with the test of $E$. To avoid this we have designed a mode system for $\lambda$ XP in Figure 6.14 that guarantees well-modedness, such that well-moded $\lambda$ XP formulas can be efficiently evaluated.

For existential quantifications for example, we have mode rule:

$$
\frac{E \triangleright V \rightarrow V^{\prime} \cup\{x\} \quad x \notin V^{\prime}}{\exists x . E \triangleright V \rightarrow V^{\prime}}
$$

It says that $\exists x$.E is well-moded with input variables $V$ and output variables $V^{\prime}$,

$$
\left\{x_{1}, x_{2}\right\} \rightarrow \emptyset x_{1}
$$

Figure 6.15: Mode-tree of query $Q_{1}^{\prime}$ from Section 10.1.1 with expanded shortcuts, and where $E_{1}=\mathrm{fn}: \operatorname{data}\left(\operatorname{set2list}\left(\left\{x^{\prime} \mid \mathbf{a t}\left(y, \operatorname{ch}\left(\right.\right.\right.\right.\right.$ user_name $\left.\left.\left.\left.\left.\wedge i s_{x^{\prime}}\right)\right)\right\}\right)\right)$ and $E_{2}=$ fn: $\operatorname{data}\left(\operatorname{set2list}\left(\left\{x^{\prime} \mid \boldsymbol{a t}\left(x_{2}, \operatorname{ch}{ }^{+}\left(\right.\right.\right.\right.\right.$students $\wedge c h\left(\right.$ name $\left.\left.\left.\left.\left.\left.\wedge i s_{x^{\prime}}\right)\right)\right)\right\}\right)\right)$.
if expression $E$ has mode $E \triangleright V \rightarrow V^{\prime} \cup\{x\}$ producing values for variables $x$. An evaluation of $\exists x$. $E$ then does not have to guess all possible values for $x$, but evaluates $E$ to generate a finite set of possible values for $x$.

For query $Q_{1}^{\prime}$ of Section 10.1 .1 we give the mode-tree in Figure 6.15, i.e. where all terms in $Q_{1}^{\prime}$ are annotated by a mode, following the mode system. Notice that the mode system allows $\lambda$ XP to be differently well-moded, which is due to the two rules for submodes.

Note that for regular axis queries $E^{*}$, the mode system rules out $E$ with mode $E \triangleright V \rightarrow V^{\prime}$ where $V^{\prime} \neq \emptyset . E$ may contain free variables however, but then their values must be produced outside of $E^{*}$, e.g. when being used within another formula. This follows from the rule on lambda abstraction, but also from the rule on disjunctions.

## Chapter 7

## XPath to $\lambda \mathbf{X P}$

## Contents

7.1 Instantiation of $\lambda$ XP . . . . . . . . . . . . . . . . . . . . . . . 95
7.2 Library functions . . . . . . . . . . . . . . . . . . . . . . . . . . 96
7.2.1 Access to Node Labels . . . . . . . . . . . . . . . . . . . . . . 96
7.2.2 Lists of Nodes . . . . . . . . . . . . . . . . . . . . . . . . . . 97
7.2.3 String Data Value of Nodes . . . . . . . . . . . . . . . . . . . 97
7.2.4 Atomization of Sequences . . . . . . . . . . . . . . . . . . . . 98
7.2.5 Numerics . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 99
7.2.6 Booleans . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 99
7.2.7 Strings . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 100
7.2.8 EQNames . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 100
7.2.9 Positions . . . . . . . . . . . . . . . . . . . . . . . . . . . . . 101
7.2.10 Roots and Input Documents . . . . . . . . . . . . . . . . . . 102
7.3 Compiling the XPath 3.0 Grammar to $\lambda$ XP . . . . . . . . . 102
7.3.1 Navigational XPath Expressions . . . . . . . . . . . . . . . . 102
7.3.2 Arbitrary XPath Expressions . . . . . . . . . . . . . . . . . . 106
7.3.3 Ordering Mode of XQuery . . . . . . . . . . . . . . . . . . . 109

In this chapter we first define library functions that are required by the compiler from XPATH 3.0 expressions to $\lambda$ XP terms that we present in a second step.

### 7.1 Instantiation of $\lambda \mathrm{XP}$

For the mapping from XPATH expressions to $\lambda$ XP formulas, we instantiate $\lambda \mathrm{XP}$ with parameters $\Sigma$ and $\Delta$ for signatures, axes $A$, (label properties $\mathcal{L}$ ), constants $\mathcal{C o n s t}$, and parameter $\mathcal{A}\left(\mathcal{T}_{\text {atom }}, D, \llbracket . \rrbracket ., \leq\right.$. $\left.\preceq_{\text {atom }}\right)$ for atomic types.

The signatures are defined as discussed in Section 2.3.1:

$$
\begin{aligned}
& \Sigma=\mathrm{XML}_{\text {types }} \\
& \Delta=\mathrm{UTF}^{2}
\end{aligned}
$$

We allow the following axes:

$$
A=\left\{c h, c h^{+}, n s^{+}, p a r, p a r^{+}, p s^{+}\right\} .
$$

We define $\mathcal{C}$ onst to contain all constants that we define in Section 6.2.2, where we assume that arithmetic and comparison functions are defined as described by the specification for arithmetics and comparisons ${ }^{1}$, and where the cast function is defined as presented in the specification ${ }^{2}$. We assume a function sort of type $[T] \rightarrow[T]$ for any equality type $T \in \mathcal{T}_{\text {eq }}$ that may implement any of the known sorting algorithms. Also by $N a N$ we denote the double value of type xs:double that stands for not a number. Values true and false are booleans contained in Bool $\subseteq D$. Furthermore we add all XPATH 3.0 built-in functions to $\mathcal{C}$ onst, which can be mapped to $\lambda$ XP expressions. In Section 7.2 we only presented the translation of a small subset of the XPATh 3.0 functions to $\lambda$ XP.

The parameter $\mathcal{A}$ for atomic types is defined as follows. The structure $s$ is a sequence of data trees that are potentially available using XPath 3.0 functions fn:doc, fn:unparsed-text, and fn:collections. Function root from our constants then return for some the URI that specifies a document the root node of the respective data tree, and similarly function roots takes a collection URI for a collection of documents and returns a sequence of root nodes of respective data trees. Note that we model text files as data trees with a doc-root node, that has a single child of type $t x$, whose data values contains the content of the text file. $\mathcal{T}_{\text {atom }}$ is the finite set of atomic types that contains all atomic XmL types of Figure 4.1. The domain $D$ contains all nodes of $s$ and all atomic values of the XmL Schema Part 2 specification ${ }^{3}$, i.e. the denotation of atomic types as discussed in Section 4.2.1. The denotation $\llbracket . \rrbracket_{s}$ maps the atomic types of $\mathcal{T}_{\text {atom }}$ to corresponding atomic values of $D \cup \operatorname{nodes}(s)$. The subtype relation for atomic types was discussed in Section 4.4. Finally the order for atomic XmL types is defined in section "Operator Mapping" ${ }^{4}$ of the XPath 3.0 specification.

### 7.2 Library functions

In this section we define library functions to translate XPath 3.0 expressions and functions. See also Section 6.2 .6 for library functions of $\lambda$ XP expressions, such as functions map, foldL, and append, that are not purely related to the XPATH 3.0 specification.

### 7.2.1 Access to Node Labels

In Figure 7.1 we present functions that operate on the label of nodes of XmL data trees. They use functions labtype and labvalues of Figure 6.2 that are defined according to the XmL node labels and thereby return the node type and node data values, respectively.

[^10]Function $l a b_{\text {name }}$ returns the value of node property "node-name" for element and attribute nodes. It verifies with function labtype whether its argument node is an element or an attribute node, and matches its data values according to function labvalues against a 6 - or a 5 -tuple, respectively, and returns its "node-name" property, which is stored at the second component. Function lab name is defined only for element and attribute nodes, such that it raises an error for other node types. Notice that the value returned is a string that represents a QName, which is always composed of a namespace prefix and a local name that are separated by a colon ":".

Similar function lab schema-type returns the value of node property "schema-type" for element and attribute nodes. The default values for property "schema-type" in the absence of schema for elements is xs:untyped and for attributes it is xs:untypedAtomic. Function $l a b_{\text {nilled }}$ returns the value of node property "nilled" for element nodes, which is either string "true" or "false". Function lab target returns the value of node property "target" for processing-instruction nodes. Function lab data returns the value of node property "content" for text, comment, and processing-instruction nodes, and function $l a b_{\text {value }}$ returns the value of node property "string-value" for attribute nodes.

### 7.2.2 Lists of Nodes

The following functions transforms a list of nodes into a set of nodes, and it throws an error, if a non-node is encountered in the list
nodelist2set $=_{\mathrm{df}}$

```
letrec nodelist2set' \(=\)
    \(\lambda z\). match \(z\) with \(x:: y\) then
        if type \(_{\text {TYPE }(x) \text {,node }}(x)\) then \(\{x\} \cup\) nodelist2set \(^{\prime}(y)\) else raise error
        else \(\emptyset\)
    in nodelist2set'
```


### 7.2.3 String Data Value of Nodes

The string-value of a node, which according to the specification is the concatenation of the string values of all its text-node descendants for element nodes, can be compiled into the $\lambda \mathrm{XP}$ in Figure 7.2.

The fn : string ${ }^{5}$ function returns the string-value of nodes, while its casts atomic values to string type xs:string.
【fn:string $=_{\text {df }}$
$\lambda z$.match $z$ with $x:: y$ then
if type $\operatorname{TYPE}(x)$,node $(x)$ then string_value $(x)$
else if type TYPE $(x)$, xs:anyAtomicType $(x)$ then cast $_{\text {TYPE }(x), \text { string }}(x)$
else raise error
else ""

[^11]$l a b_{\text {name }}={ }_{\text {df }}$
$\lambda x$. if labtype $(x)=e l$ then match $\operatorname{labvalues(x)}$ with $\left(x_{1}, \ldots, x_{6}\right)$ in $x_{2}$
else if $\operatorname{labtype}(x)=$ att then match labvalues $(x)$ with $\left(x_{1}, \ldots, x_{5}\right)$ in $x_{2}$ else raise error
la $_{\text {schema-type }}={ }_{\mathrm{df}}$
$\lambda x$. if labtype $(x)=e l$ then match $\operatorname{labvalues(x)}$ with $\left(x_{1}, \ldots, x_{6}\right)$ in $x_{3}$ else if labtype $(x)=$ att then match labvalues $(x)$ with $\left(x_{1}, \ldots, x_{5}\right)$ in $x_{3}$ else raise error
$l a b_{\text {nilled }}=\mathrm{df}$
$\lambda x$. if labtype $(x)=e l$ then match labvalues $(x)$ with $\left(x_{1}, \ldots, x_{6}\right)$ in $x_{4}$ else raise error
lab $_{\text {target }}=\mathrm{df}$
$\lambda x$. if labtype $(x)=p i$ then match $\operatorname{labvalues}(x)$ with $\left(x_{1}, \ldots, x_{3}\right)$ in $x_{2}$
else raise error
$l a b_{d a t a}={ }_{d f}$
$\lambda x$. if labtype $(x)=t x$ then match labvalues $(x)$ with $\left(x_{1}\right)$ in $x_{1}$
else if labtype $(x)=\operatorname{com}$ then match $\operatorname{labvalues}(x)$ with $\left(x_{1}\right)$ in $x_{1}$
else if labtype $(x)=p i$ then match $\operatorname{labvalues}(x)$ with $\left(x_{1}, x_{2}, x_{3}\right)$ in $x_{3}$
else raise error
$l a b_{\text {value }}={ }_{\mathrm{df}}$
$\lambda x$. if labtype $(x)=$ att then match labvalues $(x)$ with $\left(x_{1}, \ldots, x_{5}\right)$ in $x_{1}$
else raise error

Figure 7.1: Access to Node Labels.

### 7.2.4 Atomization of Sequences

The typed-value of a node can be computed via its string-value:
typed_value $=$ df
$\lambda x$. if type ${ }_{\operatorname{TYPE}(x) \text {,textnode }}(x) \vee$ type $_{\operatorname{TYPE}(x) \text {,commentnode }}(x)$
$\checkmark$ type $_{\text {TYPE }}(x)$,pinode $(x)$ then
$l a b_{d a t a}(x)$
else
cast $_{\text {string }, T Y P E}\left(\right.$ lab $\left._{\text {schema-type }}(x)\right)($ string_value $(x))$
Function fn : $\mathrm{data}^{6}$ that computes the atomization of a sequence, as discussed in Section 5.2.4.
$\llbracket \mathrm{fn}:$ data】 $=_{\mathrm{df}}$

[^12]```
string_value \(=_{\text {df }}\)
    letrec string_value \(^{\prime}=\)
    \(\lambda x\). if type TYPE \((x)\),textnode \((x) \vee\) type \(_{\operatorname{TYPE}(x) \text {,commentnode }}(x)\)
            \(\checkmark\) type \(_{\text {TYPE }}(x)\),pinode \((x)\) then
            \(l a b_{\text {data }}(x)\)
        else if type \({ }_{\operatorname{TYPE}(x), \text { attribute }}(x)\)
            lab \(_{\text {value }}(x)\)
        else if type \(\mathrm{TYPE}(x)\),elementnode \((x)\)
            \(\vee\) type \(_{\text {TYPE }}(x)\),documentnode \((x)\) then
            listconcat
                (map string_value \({ }^{\prime}\)
                sort (set2list (
                    \(\left.\left.\left.\left\{x^{\prime} \mid \boldsymbol{a t}\left(x, c h^{+}\left(i s_{x^{\prime}} \wedge \operatorname{labtype}\left(x^{\prime}\right)=t x\right)\right)\right\}\right)\right)\right)\)
in string_value \({ }^{\prime}\)
```

Figure 7．2：Function string＿value that computes strings of nodes．

```
\(\lambda z . m a p\left(\lambda z^{\prime}\right.\).if type \(_{\text {TyPE }\left(z^{\prime}\right), \text { xs:anyAtomicType }}\left(z^{\prime}\right)\) then \(z^{\prime}\)
        else if type \({\operatorname{TYPE}\left(z^{\prime}\right), \text { node }}\left(z^{\prime}\right)\) then typed_value \(\left(z^{\prime}\right)\) else raise error) \(z\)
```


## 7．2．5 Numerics

Function $f n$ ：number ${ }^{7}$ accepts singleton lists only whose element is cast into a double of type xs：double．Otherwise the function returns the double value $N a N$ ．
$\llbracket f n:$ number $\rrbracket=_{d f}$
$\lambda z$ ．match $z$ with $x:: y$ then
if $y=$ nil then $\operatorname{try} \operatorname{cast}_{T Y P E(x), \mathbf{x s}: \text { double }}(x) \boldsymbol{\operatorname { c a t c h }}(e) N a N$ else $N a N$ else $N a N$

Function fn ：count ${ }^{8}$ counts the number of elements in a sequence or list．
$\llbracket$ fn：count】 $={ }_{\mathrm{df}}$
letrec count $=$
$\lambda z$ ．match $z$ with $x:: y$ then $1+\operatorname{count}(y)$ else 0
in count

## 7．2．6 Booleans

Function fn ：boolean ${ }^{9}$ computes the effective boolean value that we discussed in Section 5．5．
【fn：boolean】 $={ }_{d f}$

[^13]```
\(\lambda z\). match \(z\) with \(x:: y\) then
        if type TYPE \((x)\),node \((x)\) then
        true
        else if \(y=\) nil then
        if type TYPE \((x)\),bool \((x)\) then \(x\)
        else if type \(\operatorname{TYPE}(x)\), string \((x) \vee\) type \(_{\text {TYPE }(x), \mathbf{x s}: \text { anyURI }}(x)\)
                \(\checkmark\) type \(_{\operatorname{TYPE}(x), \mathbf{x s}: \text { untypedAtomic }}(x)\) then \(\neg(x=" ")\)
        else if type \({ }_{\text {TYPE }(x), \text { num }}(x)\) then
            if \(x=0 \vee x=N a N\) then false else true
        else raise error (err:FORG0006)
        else raise error (err:FORG0006)
    else false
```

In the following we translate boolean functions $f n$ :true, $f n: f a l s e$, and $f n: n o t$.
$\llbracket f n$ :true $\rrbracket={ }_{\mathrm{df}}$
true
$\llbracket f n: f a l s e \rrbracket={ }_{d f}$
false
$\llbracket \mathrm{fn}: \operatorname{not} \rrbracket={ }_{\mathrm{df}}$
$\lambda z . \neg \llbracket \mathrm{fn}$ : boolean $\rrbracket(z)$

### 7.2.7 Strings

Function fn : concat ${ }^{10}$, for example, concatenates strings. It takes a list of atomic values, casts them to xs : string values, and concatenates the stings, treating them as lists of characters.

$$
\begin{aligned}
& \llbracket \mathrm{fn}: \text { concat } \rrbracket={ }_{\mathrm{df}} \\
& \quad \lambda\left(z_{1}, \ldots, z_{n}\right) . \text { listconcat }\left(\operatorname{map}\left(\text { cast }_{\mathrm{xs}: \text { anyAtomicType,string }}, z_{1}:: \ldots:: z_{n}:: \text { nil }\right)\right)
\end{aligned}
$$

Other functions on strings ${ }^{11}$ like $f n$ :contains and $f n$ :normalize-space can be implemented straightforwardly, by decomposition of lists of characters. Function fn: contains can be implemented by some function contains that tests whether a certain string contains another one, while fn: normalize-space removes from a string leading and trailing whitespace and reduces sequences of whitespace within the string to a single space character.

### 7.2.8 EQNames

EQNames are produced by nonterminal EQName (94) and are either QNames (104) or URIQualifiedNames (99). Their values are to be identified with lists of char-

[^14]acters, similar to strings.
QNames contain a local name (the actual label), and a namespace prefix. To have access to the individual parts, functions fn:local-name-from-QName and fn:prefix-from-QName exist. Namespace prefix and local name in QNames are separated by a colon ":", which makes it easy to implemented with an $\lambda \mathrm{XP}$ expression that treats QNames as lists of characters.

URIQualifiedNames contain a namespace URI and a local name, of which the namespace URI is put in curly brackets which follows the local name. Similarly to before, we can think of functions withinBrackets and afterBrackets that return the namespace URI and local name. Also since we need to compare namespace prefixes to namespace URIs we assume a function prefix can returns the corresponding namespace prefix for some namespace Uri.

The following function testEQName tests for some node $z$ whether the data value of its property node-name (which represents a QName) matches EQName $z^{\prime}$ (which is either a QName or a URIQualifiedName).

```
testEQName = df
```

$\lambda\left(z, z^{\prime}\right)$.
if type ${\text { TYPE }\left(z^{\prime}\right), \text { xs:QName }}\left(z^{\prime}\right)$ then if contains $\left(z^{\prime}\right.$, ":") then
lab $_{\text {name }}(z)=z^{\prime}$
else $\llbracket$ fn:local-name-from-QName $\rrbracket\left(l a b_{\text {name }}(z)\right)=z^{\prime}$
else $\quad / /$ type $_{\text {TYPE }\left(z^{\prime}\right), \text { xs:URIQualifiedName }}\left(z^{\prime}\right)=$ true
$\llbracket \mathrm{fn}: l \mathrm{local}-$ name-from-QName $\rrbracket\left(\operatorname{lab} b_{\text {name }}(z)\right)=\operatorname{afterBrackets}\left(z^{\prime}\right) \wedge$
【fn:prefix-from-QName】 $\left(\right.$ lab $\left.{ }_{\text {name }}(z)\right)=\operatorname{prefix}\left(\right.$ withinBrackets $\left.\left(z^{\prime}\right)\right)$

### 7.2.9 Positions

The addPositionAndSize function takes a list of elements and creates a new list with the same elements, but with information about the position of the element in the list and the size of the list. The result list stores triples that contain the original element, its index in the list, and the size of the list. E.g. addPositionAndSize("a" :: "b" :: nil) = ("a", 1, 2) :: ("b", 2, 2) :: nil. addPositionAndSize $=_{\mathrm{df}}$
$\lambda z$. letrec $a d d$-index $=\lambda\left(x_{1}, x_{2}, x_{3}\right)$.
match $x_{1}$ with $x:: y$ then
$\left(x, x_{2}\right)::$ add-index $\left(y, x_{2}+1, x_{3}\right)$
else nil
in add-index $(z, 1, \llbracket \mathrm{fn}:$ count $\rrbracket(z))$
Function addReversePositionAndSize similarly computes a list of triples, but stores reverse indices for elements. E.g. addReversePositionAndSize("a" :: "b" :: $n i l)=(" \mathrm{a} ", 2,2)::(" \mathrm{~b} ", 1,2)::$ nil.
addReversePositionAndSize $={ }_{\mathrm{df}}$

```
\(\lambda z\). letrec addReverseIndex \(=\lambda\left(x_{1}, x_{2}, x_{3}\right)\).
        match \(x_{1}\) with \(x:: y\) then
        \(\left(x, x_{2}\right)::\) addReverseIndex \(\left(y, x_{2}-1, x_{3}\right)\)
        else nil
    in addReverseIndex \((z, \llbracket \mathrm{fn}:\) count \(\rrbracket(z)+1, \llbracket \mathrm{fn}:\) count \(\rrbracket(z))\)
```


### 7.2.10 Roots and Input Documents

The $\mathrm{fn}:$ root $^{12}$ function returns the root node of the data tree to which its argument node $\$ \mathrm{z}$ belongs: $\llbracket \mathrm{fn}:$ root $(\$ \mathrm{z}) \rrbracket=\llbracket(\$ \mathrm{z} /$ ancestor-or-self::node()) [1] $\rrbracket$.

In order to have access to input source documents we have added function root in $\lambda \mathrm{XP}$, for the translation of function $\mathrm{fn}:$ doc, which given an Uri that represents a document, returns the root of the respective data tree:

```
|n:doc\rrbracket = df
    root
```

Similar we have a function roots in $\lambda \mathrm{XP}$ that mimics function fn :collection of XPath 3.0, returning a list of root nodes of data trees for a collection Uri:

```
|n:collection\rrbracket= df
    roots
```


### 7.3 Compiling the XPath 3.0 Grammar to $\lambda$ XP

In this section we present the translation of a subset of XPath 3.0 expressions to $\lambda$ XP expressions, while we refer to Appendix B for a complete translation of XPath 3.0 to $\lambda$ XP that follows the ordered semantics of Xslt. We start by the translation of navigational XPAth 3.0 expressions relating to Chapter 3. Next we show how queries with positions with respect to Section 5.3 are translated. Finally, we present how ordering constraints can be relaxed within the unordered semantics of XQuery, while otherwise we assume the standard ordered semantics of Xslt.

### 7.3.1 Navigational XPath Expressions

We present a translation for navigational XPath 3.0 expressions, which we discussed in Chapter 3. The translation applies only for instances of XPath 3.0 expressions P by the original XPath grammar [Robie 2014b], i.e. those in Section 5.1.2, but only if query P can also be produced by the grammar of the navigational XPath 3.0 fragment given in Section 3.2.2.

The translation of a navigational XPath expression $P$ that is an instance of nonterminal N produces a boolean $\lambda \mathrm{XP}$ expression $E$. The translation is parameterized by some given boolean $\lambda$ XP formula $F$ of properties to be verified at nodes

[^15]that $P$ navigates to, such as node label tests that we translate before the translation of axes steps. For the translation of navigational expressions we write
$$
(\mathrm{N}(\mathrm{P}))^{F}=E
$$

The translation is initialized with $F=$ true such that the result of $(\mathrm{N}(\mathrm{P}))^{\text {true }}$ is a boolean $\lambda \mathrm{XP}$ formula that is satisfied by some data tree of which the XmL document that it models satisfies the XPATH filter [P]. Otherwise $F$ is set to $i s_{x}$ such that the result of $(N(P))^{i s_{x}}$ is satisfied by some data tree, if the value for variable $x$ is amongst the nodes that XPath query P selects. The nodes selected by expressions P then correspond to $\lambda \mathrm{XP}$ expression

$$
\left\{x \mid(N(P))^{i s_{x}}\right\}
$$

We refer to the next section for an integration of the translation for navigational XPath queries, that we present in the following, into a translation for arbitrary XPath expressions.

Path Compositions. We start by the translation of expressions by nonterminal
(36) RelativePathExpr::= StepExpr (("/" | "//") StepExpr)*
for the case that the expression uses the path operator "/":
$\left(\text { RelativePathExpr }\left(\text { StepExpr }(\mathrm{P}) / \operatorname{StepExpr}\left(\mathrm{P}^{\prime}\right)\right)\right)^{F}={ }_{\mathrm{df}}$
$(\text { StepExpr }(P))^{(S t e p E x p r}\left(P^{\prime}\right) D^{F}$
The idea is that formula $F$ is to be tested at nodes selected by StepExpr ( P )/StepExpr ( $\mathrm{P}^{\prime}$ ), so it reduces to translation $\left(\operatorname{StepExpr}\left(\mathrm{P}^{\prime}\right)\right)^{F}$, which is to be tested at nodes selected by StepExpr ( P ). Navigational expressions by nonterminal

```
(37) StepExpr::= PostfixExpr | AxisStep
```

are expressions by nonterminal AxisStep (38).

Filters. Expressions by nonterminal
(38) AxisStep::= (ReverseStep | ForwardStep) PredicateList
require a translation of a forward or backward path step $P$, which is an instance of nonterminal ReverseStep or ForwardStep, respectively, together with a list of filters $\mathrm{P}_{i}$ (by nonterminal PredicatesList) which are instances of nonterminal Expr.
$\left(\operatorname{AxisStep}\left(\mathrm{P}\left[\operatorname{Expr}\left(\mathrm{P}_{1}\right)\right] \ldots\left[\operatorname{Expr}\left(\mathrm{P}_{n}\right)\right]\right)\right)^{F}={ }_{\mathrm{df}}$
$(\mathrm{P})^{F \wedge\left(\operatorname{Expr}\left(\mathrm{P}_{1}\right)\right)^{\text {true }} \wedge \ldots \wedge\left(\operatorname{Expr}\left(\mathrm{P}_{n}\right)\right)^{\text {true }}}$
The idea is that $F$ and all filters require evaluation at nodes by P .

Single Forward Path Steps.
(39) ForwardStep::= (ForwardAxis NodeTest) | AbbrevForwardStep

For nonterminal ForwardStep we are not interested in nonterminal AbbrevForwardStep, since considering only non-abbreviated XPATH queries.
(ForwardStep(ForwardAxis(P) NodeTest(P')) $)^{F}={ }_{\mathrm{df}}$
$(\text { ForwardAxis (P) })^{F \wedge\left(\text { NodeTest ( } \mathrm{P}^{\prime}\right) D^{t r u e}}$
$F$, together with the nodes label and kind tests by NodeTest ( $\mathrm{P}^{\prime}$ ) are tested at nodes by P .

Then we can translate the following expressions by nonterminal ForwardAxis(40) as follows, where att is a label property that accepts all labels of attribute nodes.

```
(40) ForwardAxis::= ("child" "::") | ("descendant" "::") |
    ("attribute" "::") | ("self" "::") |
    ("descendant-or-self" "::") |
    ("following-sibling" "::") |
    ("following" "::") | ("namespace" "::")
```

$(\text { ForwardAxis(child: :) })^{F}={ }_{\mathrm{df}}$
$\operatorname{ch}(F \wedge \neg a t t)$
$(\text { ForwardAxis (descendant: :) })^{F}={ }_{\mathrm{df}}$
$c h^{+}(F \wedge \neg a t t)$
(ForwardAxis(attribute::) $)^{F}={ }_{\mathrm{df}}$
$\operatorname{ch}(F \wedge a t t)$
(ForwardAxis(self::)) $)^{F}={ }_{\mathrm{df}}$
F
$(\text { ForwardAxis(descendant-or-self::) })^{F}={ }_{d f}$
$c h^{*}(F \wedge \neg a t t)$
$(\text { ForwardAxis(following-sibling: :) })^{F}={ }_{\mathrm{df}}$
$n s^{+}(F \wedge \neg a t t)$
(ForwardAxis (following: :) $)^{F}={ }_{\mathrm{df}}$
$\operatorname{par}^{*}\left(n s^{+}\left(c h^{*}(F \wedge \neg a t t)\right)\right)$
(ForwardAxis(namespace: :) $)^{F}={ }_{\mathrm{df}}$
raise error
(41) AbbrevForwardStep::= "@"? NodeTest

We do not consider abbreviated XPATH queries.

Single Backward Path Steps. Concerned are the following three nonterminals, whose translation works similar to the translation of single forward path steps.

```
(42) ReverseStep ::= (ReverseAxis NodeTest) | AbbrevReverseStep
(43) ReverseAxis ::= ("parent" "::") | ("ancestor" "::") |
    ("preceding-sibling" "::") |
    ("preceding" "::") |
    ("ancestor-or-self" "::")
(44) AbbrevReverseStep::= ".."
```

(ReverseStep(ReverseAxis(P) NodeTest( $\mathrm{P}^{\prime}$ )) $)^{F}={ }_{\mathrm{df}}$
$(\text { ReverseAxis }(\mathrm{P}))^{F \wedge\left(\text { NodeTest }\left(\mathrm{P}^{\prime}\right)\right)^{\text {true }}}$
$\left(\right.$ ReverseAxis $(\text { parent::) })^{F}={ }_{\mathrm{df}}$
$\operatorname{par}(F \wedge \neg a t t)$
(ReverseAxis(ancestor::) $)^{F}={ }_{\mathrm{df}}$
$\operatorname{par}^{+}(F \wedge \neg a t t)$
$(\text { ReverseAxis(preceding-sibling::) })^{F}={ }_{\mathrm{df}}$
$p s^{+}(F \wedge a t t)$
(ReverseAxis(preceding::) $)^{F}={ }_{\mathrm{df}}$
$\operatorname{par}^{*}\left(p s^{+}\left(c h^{*}(F \wedge \neg a t t)\right)\right)$
(ReverseAxis(ancestor-or-self::) $)^{F}={ }_{\mathrm{df}}$
$\operatorname{par}^{+}(F \wedge \neg a t t)$
Node Labels and Kinds. Labels and kinds of nodes are verified by nonterminal

> (45) NodeTest ::= KindTest | NameTest

They will be translated to label properties $L$, which are satisfied by all nodes whose label satisfied $L$.

An expression by nonterminal NameTest (46)
(46) NameTest::= EQName | Wildcard
(94) EQName : : = QName | URIQualifiedName
is a QName by nonterminal QName (104), for example, which is either a local name P or a composition $\mathrm{P}^{\prime}: \mathrm{P}$ of a namespace prefix $\mathrm{P}^{\prime}$ and a local name P . We thereby obtain
$(\text { QName (P) })^{\text {true }}={ }_{\mathrm{df}}$
$P$
(QName $\left.\left(\mathrm{P}^{\prime}: P\right)\right)^{\text {true }}={ }_{\mathrm{df}}$
$P \wedge P^{\prime}$
where we identify the result $P$ of the translation with the label property that holds for all nodes whose local name is P , and label property $P^{\prime}$ holds for all nodes whose namespace prefix is $\mathrm{P}^{\prime}$.

We will not discuss in detail expressions by Wildcard (47). Furthermore, we only give a few expressions that check node kinds, as derived by nonterminal KindTest (71): Expressions attribute(), element(), and text() are satisfied by attribute, element, and text nodes, respectively. We translate these test expressions to corresponding label properties:

```
\((\text { AttributeTest(attribute())) })^{\text {true }}={ }_{\mathrm{df}}\)
    att
(ElementTest(element())) \({ }^{\text {true }}={ }_{\mathrm{df}}\)
    el
\((\text { TextTest (text ())) })^{\text {true }}={ }_{\mathrm{df}}\)
    \(t x\)
```

First-Order Connectives. The boolean connectives and and or by nonterminals

```
(16) OrExpr ::= AndExpr ( "or" AndExpr )*
(17) AndExpr::= ComparisonExpr ( "and" ComparisonExpr )*
```

and the XPath 3.0 functions fn :true, false, and fn : not, that may appear in filters of navigational XPATH queries are translated straightforwardly as follows.
(OrExpr (AndExpr $(\mathrm{P})$ or AndExpr $\left.\left(\mathrm{P}^{\prime}\right)\right) D^{\text {true }}={ }_{\mathrm{df}}$
$(\text { AndExpr }(\mathrm{P}))^{\text {true }} \vee\left(\operatorname{AndExpr}\left(\mathrm{P}^{\prime}\right)\right)^{\text {true }}$
(AndExpr (ComparisonExpr (P) and ComparisonExpr ( $\mathrm{P}^{\prime}$ )) ) true $={ }_{\mathrm{df}}$
(ComparisonExpr $(\mathrm{P}))^{\text {true }} \wedge\left(\text { ComparisonExpr }\left(\mathrm{P}^{\prime}\right)\right)^{\text {true }}$
$(\mathrm{fn} \text { : true() })^{\text {true }}={ }_{\mathrm{df}}$
true
(fn:false()) $)^{\text {true }}={ }_{\mathrm{df}}$
false
$(\mathrm{fn}: \operatorname{not}(\operatorname{Expr}(\mathrm{P})))^{\text {true }}={ }_{\mathrm{df}}$
$\neg(\operatorname{Expr}(\mathrm{P}))^{\text {true }}$
Example. We present an example for the previously mentioned XPath query descendant::a/child::b that applies the presented translation rules:

$$
\begin{aligned}
& \text { (descendant::a/child:: } \mathrm{b})^{i s_{x}}=\left(\text { descendant::a) }{ }^{(\operatorname{child}:: \mathrm{b})^{i s x}}\right. \\
& =\left(\text { descendant: : } \|^{(\text {child }: ~: b)^{i s}} \wedge(\mathrm{a})^{\text {true }}\right. \\
& =c h^{+}\left((\text {child }:: \mathrm{b})^{i s_{x}} \wedge(\mathrm{a})^{t r u e} \wedge \neg a t t\right) \\
& =c h^{+}\left((\text {child }:: \mathrm{b})^{i s_{x}} \wedge a \wedge \neg a t t\right) \\
& =c h^{+}\left((\text {child }::)^{i s_{x} \wedge(\mathrm{~b})^{\text {true }}} \wedge a \wedge \neg a t t\right) \\
& =\operatorname{ch}^{+}\left(\operatorname{ch}\left(i s_{x} \wedge(\mathrm{~b})^{\text {true }} \wedge \neg a t t\right) \wedge a \wedge \neg a t t\right) \\
& =c h^{+}\left(\operatorname{ch}\left(i s_{x} \wedge b \wedge \neg a t t\right) \wedge a \wedge \neg a t t\right)
\end{aligned}
$$

### 7.3.2 Arbitrary XPath Expressions

We discuss how to translate arbitrary XPath expressions to $\lambda$ XP expressions. We translate an instance P of a nonterminal N of the XPath 3.0 grammar to some $\lambda \mathrm{XP}$ expression $E$, and write

$$
\llbracket \mathrm{N}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} E .
$$

The translation is parameterized by three variables $\bar{z}, \hat{z}$, and $\tilde{z}$, which is needed for a correct translation of positional queries. Those variables refer to the context item, context position, and context size, respectively. Before we explain in detail
the treatment of positional queries, we first discuss the integration of the translation for navigational queries that we presented before.

Navigational Expressions. The standard semantics claims that navigational XPath queries return duplicate-free sequences of nodes, which are to be sorted into document order, while the sorting can be relaxed within the unordered semantics of XQuery, as we describe later. We therefore reuse our translation for navigational expressions of before, and wrap it into a set, which we then transform into a list in an arbitrary order via library function set2list, while applying an additional sorting:

$$
\llbracket \mathrm{N}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df} \operatorname{sort}\left(\operatorname{set} 2 \operatorname{list}\left(\left\{x \mid(\mathrm{N}(\mathrm{P}))^{i s_{x}}\right\}\right)\right)
$$

Positional Queries. We discuss in the following how to evaluate filters and path expressions in general. For this let $P$ and $P^{\prime}$ be subexpressions of filters $P\left[P^{\prime}\right]$ and path expressions $P / P^{\prime}$ and $P!P^{\prime}$, while we assume that expressions $P^{\prime}$ are not navigational and thus may contain positions, such as the context item expression ".", or function calls fn :position() or fn :last(), that we discussed in Section 5.3. Those expressions return the context item, position, and size, respectively. We recall, that the context item is the item currently being processed in sequence $P$, the context position is the position of the context item within the sequence, and the context size is the number of items in the processed sequence.

The question is how to translate those filters and path expressions and their subexpressions, since subexpressions $\mathrm{P}^{\prime}$ reference items and positions of items in the result list by P , such that expressions $\mathrm{P}^{\prime}$ cannot be translated without information of the evaluation of $P$. The idea is, that we translate $P^{\prime}$ as a function which requires the items, their positions, and the size of the list by P as input arguments, for which we translate $P$ to a list of such triples, and filters and path expressions to function applications.

Context Item, Position, and Size. We thus translate the context item expression "." by nonterminal ContextItemExpr (58), and function calls fn:position() and fn :last() to variables, whose values will be computed later, during evaluation.

【ContextItemExpr (.) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \bar{z}$
$\llbracket \mathrm{fn}$ : position() $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \hat{z}$
[fn:last() $\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \tilde{z}$
Functions of Items, Position, and Size. Expressions P' of filters and path expressions, that contain context item expressions or functions calls, are translated to functions

$$
\lambda(\bar{z}, \hat{z}, \tilde{z}) \cdot\left[\mathrm{P}^{\prime} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} .\right.
$$

This translation of subexpressions $\mathrm{P}^{\prime}$ to functions allows to compute the filter or path expressions, when applied to triples of items, position, and size.

Lists of Triples of Items, Position, and Size. For items within a list, the information about its position within the list, and the size of the list, must be available directly, when evaluating filters and path expressions. We translate expressions $P$ not to a list of items, but to a list of triples of items, positions, and list-size.

This is done via function addPositionAndSize presented in Section 7.2.9 of our function library. For the evaluation of filters and path expressions as mentioned above, we translate subexpressions P to addPositionAndSize $\left(\llbracket \mathrm{P} \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}\right)$. For example, this function takes the list ("a", "bc", 135) and outputs the list (("a", 1, 3), ("bc", 2, 3), (135, 3, 3)).

Evaluation of Filters. Filters $\mathrm{P}\left[\mathrm{P}^{\prime}\right]$ by nonterminal
(38) AxisStep::= (ReverseStep | ForwardStep) PredicateList,
where $P$ is an instance of nonterminal ReverseStep (42) or ForwardStep (39), and where $\left[\mathrm{P}^{\prime}\right]$ is a filter by nonterminal PredicateList (50), can be translated to function applications:

```
\(\llbracket \mathrm{P}\left[\mathrm{P}^{\prime}\right] \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let eval \(=\lambda z\). match \(z\) with \(x:: y\) then
        match \(x\) with \((c i, c p, c s)\) in
            let filter \(=\) if type \(_{\text {TyPE }(c i), \text { node }}(c i)\) then
                        \(\boldsymbol{a t}\left(c i,\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \mathrm{P}^{\prime} \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\right)\)
                            else
                        \(\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \mathrm{P}^{\prime} \rrbracket z^{i}, z^{p}, z^{s}\right)(c i, c p, c s)\)
            in
            if type TYPE(filter),num \((\) filter \() \wedge\) cast \(_{\operatorname{TYPE}(\text { filter }), \text { int }}(\) filter \()=c p\) then
                ci :: \(\operatorname{eval}(y)\)
            else if 【fn: boolean】(filter) then
                ci :: eval(y)
            else \(\operatorname{eval}(y)\)
        else nil
    in \(\operatorname{eval}\left(\operatorname{addPositionAndSize}\left(\llbracket \mathrm{P} \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}\right)\right)\)
```

For this, we define an evaluation function eval that inputs a list of triples addPositionAndSize $\left(\llbracket \mathrm{P} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$. This function decomposes the list into triples $x$, which are made up of items $c i$, their position $c p$ within the list, and the size $c s$ of the list. Next, the function computes the function application $\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \mathrm{P}^{\prime} \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)$ which is evaluated from $c i$ if $c i$ is a node, and from $\bar{z}$ otherwise. The return value of the evaluation is stored in variable filter. When it is a numerical value, then the item $c i$ is retained, if its position $c p$ is equal to that value. Otherwise the effective boolean value of the value in filter is computed, where $c i$ is retained if it evaluates to true.

Mapping Operator Expressions. Similarly we translate expressions that use the mapping operator "!" as by nonterminal
(34) SimpleMapExpr : := PathExpr ("!" PathExpr)*

```
\(\llbracket \operatorname{SimpleMapExpr}\left(\right.\) PathExpr (P) ! PathExpr \(\left.\left(\mathrm{P}^{\prime}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let apply \(=\lambda z\). match \(z\) with \(x:: y\) then match \(x\) with \((c i, c p, c s)\) in
        if type TYPE \((c i)\),node \((c i)\) then
            \(\operatorname{at}\left(c i,\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \operatorname{PathExpr}\left(\mathrm{P}^{\prime}\right) \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\right):: \operatorname{apply}(y)\)
        else
            \(\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \operatorname{PathExpr}\left(\mathrm{P}^{\prime}\right) \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s):: \operatorname{apply}(y)\)
        else \(n i l\) in
    listconcat apply(addPositionAndSize \(\left.\left(\llbracket \operatorname{PathExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)\)
```

We define a function apply that performs the function applications. It gets as input a list of triples addPositionAndSize $\left(\llbracket \operatorname{PathExpr}(\mathrm{P}) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}\right)$. For each triple the function application is performed evaluating PathExpr $\left(\mathrm{P}^{\prime}\right)$, which returns a list of items. The overall result is thus a list of lists of items. Since sequences in XPath are flat, we flatten this result list by appending the lists that are contained, and we obtain a list of items.

Path Operator Expressions. Expressions that use the path operator "/" as by nonterminal
(36) RelativePathExpr::= StepExpr (("/" | "//") StepExpr)*
can be expressed using the mapping operator "!", see Section 5.4.2.

```
\llbracketRelativePathExpr(P/P')}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{}=\mp@subsup{}{\textrm{df}}{
    |RelativePathExpr(
        let $R:= P!P' return
        if (every $r in $R satisfies $r instance of node()) then
            ($R union ())
        else if (every $r in $R satisfies not($r instance of node()))
            then $R
        else error()}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{
```


### 7.3.3 Ordering Mode of XQuery

If ordering mode of XQUERY is set to ordered, node sequences returned by path expressions, union, intersect, and except expressions, and the fn:id and fn:idref functions are to be sorted into document order. Otherwise the order of these return sequences is implementation-dependent. In the following we use some constant mode which is equal to the sort function sort if the ordering mode of XQuERY is set to ordered, while it is the identity function $i d$, when the ordering mode is set to unordered:

$$
\text { mode }= \begin{cases}\text { sort } & , \text { ordering mode of XQUERY is ordered } \\ i d & , \text { ordering mode of XQUERY is unordered }\end{cases}
$$

Node Selecting Path Expressions. Depending on constant mode the result list of nodes for navigational expressions P is sorted or not:

$$
\llbracket \mathrm{N}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \operatorname{mode}\left(\operatorname{set} 2 l i s t\left(\left\{x \mid\left(\mathrm{N}(\mathrm{P}) D^{i s_{x}}\right\}\right)\right)\right.
$$

Union, Intersect, and Except Expressions. Expressions by nonterminals

```
(23) UnionExpr ::= IntersectExceptExpr ( ("union" | "|")
    IntersectExceptExpr )*
(24) IntersectExceptExpr::= InstanceofExpr ( ("intersect" |
    "except") InstanceofExpr )*
```

use operators union, intersect, and except, which operate on sequences of nodes only, see Section 5.7.1.

Notice that according to the specification, if one of the items in the sequences is not a node, a type error is raised, which we treat with library function nodelist2set.

```
|UnionExpr(IntersectExceptExpr(P1) union ...
    union IntersectExceptExpr (P
    mode(set2list(nodelist2set([IntersectExceptExpr (P
    Unodelist2set([IntersectExceptExpr (P
```

Notice here, that translations $\llbracket$ IntersectExceptExpr $\left(\mathrm{P}_{i}\right) \rrbracket \bar{z}, \hat{z}, \tilde{z}$ produce lists of nodes, which we transform to sets of nodes by function nodelist2set, whose set union is computed, and which afterwards is converted back to a list of nodes in an arbitrary order.

Expressions IntersectExceptExpr where $\mathrm{op}_{i} \in$ \{intersect, except $\}$ for all $1 \leq i \leq n$ translate similarly:
【IntersectExceptExpr (
InstanceofExpr ( $\mathrm{P}_{1}$ ) op 1 InstanceofExpr $\left(\mathrm{P}_{2}\right)$...
InstanceofExpr $\left(\mathrm{P}_{n}\right) \quad \mathrm{op}_{n}$ InstanceofExpr $\left.\left(\mathrm{P}_{n+1}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}^{n \geq 2}$
mode (set2list (
nodelist2set ( $\llbracket$ InstanceofExpr $\left.\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \mathrm{op}_{1}$ nodelist2set $\left(\llbracket \operatorname{Instanceof} \operatorname{Expr}\left(\mathrm{P}_{2}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \mathrm{op}_{2}$
$\left.\left.\ldots \mathrm{op}_{n} \operatorname{nodelist2set}\left(\llbracket \operatorname{InstanceofExpr}\left(\mathrm{P}_{n+1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)\right)$

For Expressions. For expressions for $\$ \mathrm{x}$ in P return $\mathrm{P}^{\prime}$ by nonterminal ForExpr in
(8) ForExpr ::= SimpleForClause "return" ExprSingle
(9) SimpleForClause ::= "for" SimpleForBinding
("," SimpleForBinding)*
(10) SimpleForBinding::= "\$" VarName "in" ExprSingle
concatenate sequences of the return expression $\mathrm{P}^{\prime}$ in the order of the items in the binding sequence $P$ if the ordering mode of XQUERY is set to ordered:

```
|ForExpr(for $VarName(y) in ExprSingle(P)
    return ExprSingle(P'))}\mp@subsup{|}{\overline{z},\hat{z},\tilde{z}}{}=\mp@subsup{}{\textrm{df}}{
    listconcat
```



There we perform a map on list $\llbracket \operatorname{ExprSingle}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ with function $\lambda \llbracket \operatorname{VarName}(\mathrm{y}) \rrbracket_{\bar{z}, \hat{z}} \tilde{z} \cdot[\operatorname{ExprSingle}(\mathrm{P}$ while flattening the result list. For Example, query

```
for $x in (1, 33, 555) return ($x + 100, $x)
```

evaluates to list ( $101,1,133,33,655,555$ ). If the ordering mode were set to $u n$ ordered, then the sequences by the return expression would not need to be concatenated in the order of the items of the binding sequence, but in an arbitrary order. For example, $(655,555,101,1,133,33)$ is an admissible answer. However, the order of the items in the list by any evaluation of the return expression cannot be changed: $(1,33,101,133,555,655)$ is not an admissible answer. In order to profit from this kind of order indifference, we allow the translation to add a call to XPath 3.0 function fn :unordered to the result of the evaluation of the binding sequence, which allows the sequence to be returned in an implement-dependent order, but only if the ordering mode is set to unordered:

```
|ForExpr(for $VarName(y) in ExprSingle(P)
    return ExprSingle(P'))}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{}=\mp@subsup{}{\textrm{df}}{
    listconcat
```



```
            \llbracketfn:unordered\rrbracket([ExprSingle(P) \rrbracketz,\tilde{z},\tilde{z}})\mathrm{ )
```

Notice that function fn : unordered only relaxes the order for its immediate operand, while the ordering mode unordered of XQuery applies to all nested expressions.

## Part II

## Early Query Answering for Navigational XPath

Chapter 8

## Early Nested Word Automata

## Contents

8.1 Introduction ..... 116
8.2 Automata Queries ..... 117
8.2.1 Tuple Selection ..... 118
8.2.2 Monadic Queries ..... 118
8.2.3 Queries by Automata ..... 118
8.2.4 Earliest Query Answering ..... 121
8.3 Early Nested Word Automata ..... 121
8.4 Fxp ..... 122
8.5 Compiler from FXP to Early Nested Word Automata ..... 124
8.5.1 ENWA Descriptors ..... 124
8.5.2 When Variables Must be Bound ..... 125
8.5.3 Construction of ENWA Descriptors ..... 126
8.5.4 Construction of the ENwA descriptor $D_{F}(\mathcal{E})$ ..... 127
8.5.5 Correctness ..... 131
8.5.6 Size of Automata Descriptors ..... 132
8.5.7 Time to Compute Automata Descriptors ..... 134
8.6 Early Query Answering ..... 137
8.6.1 On-the-fly Instantiation and Determinization ..... 137
8.6.2 Streaming Algorithm for Deterministic ENWAs ..... 138
8.6.3 Adding Stack-and-State Sharing ..... 139
8.7 QuiXPath tool ..... 143
8.7.1 Implementation, Tools, and Applications ..... 143
8.7.2 Benchmarks ..... 143
8.7.3 Performance Comparison ..... 144
8.7.4 Performance Analysis ..... 46
8.7.5 Detailed Analysis ..... 149

In this chapter, we propose a new algorithm that approximates earliest query answering for navigational XPATH queries. Our early query answering algorithms is based on early nested word automata that we introduce that are obtained from Fxp, the forward navigational fragment of $\lambda \mathrm{XP}$. We test our algorithms in detail on the usual benchmarks in an experimental section with promising performance.

### 8.1 Introduction

We present an approximation of earliest query answering for navigational XPATH queries. One objective is to improve on previous approximations, in order to support earliest rejection for XPATH queries with negation, such as for instance:

```
//tweet[not(pub/text()='Springer')][contains(text(),'Lille')]
```

When applied to an XmL document for an electronic library, as below, all books published from Springer can be rejected once its publisher was read:

```
<lib>...<book>...<pub> Springer </pub>
    ...<content>...Lille...</content>...</book> . . </lib>
```

SPEX's algorithm on the basis of transducer networks [Olteanu 2007], however, will check for all books from Springer whether they contain the string Lille and detect rejection only when the closing tag </book> is met. This requires unnecessary buffering space.

We provide an approximation of the earliest query answering algorithm for queries defined by NwA [Gauwin 2009b, Madhusudan 2009], while removing the assumption of determinism imposed there. The main idea to gain efficiency is that selection and rejection should depend only on the current state of an NwA but not on its current stack. Therefore, we propose early nested word automata (ENWAs) that are Nwas with two kinds of distinguished states: rejection states and selection states. Selection states are final and must always remain final, so that a nested word can be accepted, once one of its prefixes reaches a selection state. Symmetrically, rejection states can never reach a final state, so that a nested word can be rejected, once all non-blocking runs on a prefix reach a rejection state. We then present a new streaming algorithm for answering ENwA queries in an early manner. The basic idea is to run the ENWA for all possible candidates while determinizing on-the-fly, so that one can see easily whether all non-blocking runs of the nondeterministic automaton reach a rejection state, or whether one of them is selecting. The second idea is to share the stacks and states of runs of buffered candidates in the same state, so that the running time does not depend on the number of buffered candidates, but only on the number of states of the deterministic automaton discovered during the on-the-fly determinization. Our streaming algorithm with stack-and-state sharing for answering ENwAs queries is original and nontrivial. It enables tight upper bounds for time and space complexity that we prove (Theorem 3).

Furthermore, we show how to compile XPATH expressions to small ENwA descriptors defining the same query. These descriptors allow to represent ENWAs with large finite alphabets in a succinct manner, by replacing labels in ENWA rules by label descriptors. The label descriptor $\neg a$, for instance, stands for the set of all finitely many labels different from $a$. The target of our XPATH-compiler are thus ENwA descriptors. For instance, the ENwA descriptors that our XPath compiler obtains for the XPATH expressions $P_{n}=$ child: $: a_{1} /$ child: $: a_{2} / \ldots /$ child: $: a_{n}$ is
of size $O(n)$, while the described ENwA is of size $O\left(n^{2}\right)$. The latter has $n$ states each of which has $n$ transitions, in order to accept children with all possible letters $a_{1}, \ldots, a_{n}$. We will prove a tight time bound for our compiler (Theorem 2). It implies the same bound on the size of the generated ENwA descriptors, and in particular that the eNwa descriptors for any XPath expressions without filters, unions, and with no other axes than child axes (such as $P_{n}$ for instance) can be compiled in time $O(n)$. This improves on the previous compiler to dNwas from [Gauwin 2011a], which required time $O\left(n^{4}\right)$ for $P_{n}$. The main idea of the compiler is to adapt the previous translation to dNWAs, so that it produces descriptors of ENWAs while distinguishing selection and rejection states. We maintain pseudo-completeness (no run can ever block) as an invariant, so that we can compile negations efficiently in the deterministic case. Otherwise, we treat negation based on ENwa determinization after the instantiation of the ENwA descriptors, even though this is costly in theory and often unfeasible in practice. The XPath operators introducing nondeterminism are recursive axes such as descendant, following and following-sibling, disjunctions of filters and unions of paths, and also expressions with child axes such as child::a[following::b] where the subexpression cannot be decided when closing the child. It should also be noticed that the compilation of forward axis requires a more complex treatment of stack symbols during the ENwA construction, which leads to a more tedious correctness statement for our compiler.

We have implementated our algorithms to answer navigational XPATH queries in the QuiXPath system. It improves on all other tools in coverage with $37 \%$ of the XPathMark benchmark (the previous best is Spex with $22 \%$ ), and also outperforms all of them in time efficiency with the exception of Gcx, which runs slightly quicker on few queries, and slightly slower on others. Our approximation of earliest query answering turns out to be tight in practice, in that all supported queries of the XPathMark are treated in an earliest manner. Our algorithms are not earliest on particular XPAth queries with valid or unsatisfiable filters, of which there are two in the XPathMark. Although they are not supported by the algorithms presented in this chapter (since they use recursive axes below a negation), they are supported by our algorithm in Chapter 10, which answer them in a nonearliest manner. It is shown in follow-up work [Lick 2013] that our approximation is also tight in theory, in that it is exact for all positive XPath queries without valid or unsatisfiable subfilters. Note that there is still a gap between the tightness results in practice presented here, and those in the theory of the follow-up paper, in that some of the supported queries of the XPathMark use negation.

### 8.2 Automata Queries

We introduce how nested word automata are used to define node selection queries on Xml data trees. We also introduce what it means to answer node selection queries on data trees in streaming mode in an earliest manner.

### 8.2.1 Tuple Selection

We consider tuple selection queries on marked trees, which select $n$-tuples of nodes of the marked tree.

Definition 9. A tuple selection (forward) query over alphabets $\Sigma$ and $\Delta$ is a function $P^{n}$ that maps all marked trees $(t, \pi)$ over $\Sigma$ and $\Delta$ to some subset $P^{n}(t, \pi)$ of $n$-tuples of nodes $\left(\pi_{1}, \ldots, \pi_{n}\right)$ of $t$ opened later or equal to $\pi$, i.e.,

$$
P^{n}(t, \pi) \subseteq\left\{\left(\pi_{1}, \ldots, \pi_{n}\right) \mid \text { for all } 1 \leq i \leq n . f u t^{t}\left(\pi, \pi_{i}\right)\right\}
$$

These kinds of tuple selection queries cannot select nodes opened before $\pi$. We impose this restriction since we are interested in XPath queries with forward axes only in this chapter. From a streaming perspective, this means that queries of the above type concern only the tree suffix $\operatorname{suff}(t, \pi)$ defined by a marked tree $(t, \pi)$. An example for a binary query is to select all pairs of nodes of $a$-descendant with their $b$-children.

Even though tuple selection queries are needed for answering general XPath queries over Xml streams, see Chapter 10, we consider mostly monadic queries for the ease of presentation.

### 8.2.2 Monadic Queries

Monadic queries $P$ are tuple selection queries that select tuples of size 1:

$$
P(t, \pi) \subseteq\left\{\pi^{\prime} \mid f u t^{t}\left(\pi, \pi^{\prime}\right)\right\}
$$

The XPath query following-sibling::b, for instance, will select the nodes 2 and 3 of the marked tree $(a(b, b, b), 1)$, since the b-node 1 of $a(b, b, b)$ has the next sibling 2 with label $b$, which in turn has the next sibling 3 again labeled by $b$. This is an example of a query that does not make much sense when started at the root of a tree, since the root never has any following sibling. For this reason, we apply queries to marked trees and let the query start at the marked node.

### 8.2.3 Queries by Automata

We will use Nwas to define monadic queries (as usual for showing that tree automata capture monadic second-order (Mso) queries). The idea is that an Nwa should only test whether a candidate node is selected by the query on a given tree suffix, but not generate the candidate by itself. We fix a single variable $x$ for annotation and set the label alphabet of such Nwas to $\left\{a, a^{x} \mid a \in \Sigma\right\}$. Letters $a^{x}$ are called annotated (or "starred" in the terminology of [Madhusudan 2009]) while letters $a$ are not. Then, a unique candidate node is assumed to be annotated on the input tree suffix by some external process. A monadic query $P$ on marked trees can be defined by any Nwa that recognizes the set of variants of $\operatorname{suff}(t, \pi)$, in which the label of a single selected node in $P(t, \pi)$ is annotated by $x$.


Figure 8.1: An example of a data tree for a library, in which the first book-element is marked. The second auth-child of the marked node is annotated by variable $x$.


Figure 8.2: A data tree with finite signature, obtained from the data tree in Figure 8.1 via some relabling function that anonymizes letters not occurring in book[starts-with(title, 'XML')]/auth.

Example. An example for a marked data tree of a library with an annotated label is given in Figure 8.1. There only auth-elements and title-elements carry a data value. The first book-element is chosen as the marked node. The second auth-child of the marked book-element node is annotated by the variable $x$. The XPath query

```
book[starts-with(title,'XML')]/auth
```

selects the annotated node when applied to the marked library (without the annotation), since the marked node is a book-element, whose title starts with "XML" and since the annotated node is an auth-child of the marked node.

Whether the above XPATH query applied to a marked tree can select a given node, can be verified as follows. First we annotate the given node with $x$ as in Figure 8.1, second we anonymize all symbols not occurring in the query by substitution with _, as in Figure 8.2, so that the signatures become finite, and third we run the deterministic NWA in Figure 8.3 on the marked, annotated, and anonymized tree in Figure 8.2.

A successful run on the annotated marked tree from Figure 8.2 is depicted in Figure 8.4. This $S$-run starts at the marked book node, with the start stack $S=\gamma$ containing a single element, since the marked node has a single ancestor.


Figure 8.3: An NwA for XPath query book[starts-with(title, 'XML')]/auth selecting all authors of all books of a library whose title starts with "XML". It can be run on any marked library while starting at its marked node, under the assumption that there is an arbitrary but unique node annotated by $x$. This is a candidate node for which selection is to be verified by the Nwa. The finite signatures, obtained by anonymization of all letters that do not belong to the query to - , are $\Sigma=\left\{a, a^{x} \mid\right.$ $\left.a \in \Sigma^{\prime}\right\}$ where $\Sigma^{\prime}=\{(e l$, book $),(e l$, title $),(e l$, author $),(e l,)$,$\} and \Delta=\left\{L, M, X,,_{-}\right\}$. As shortcuts, we use the sets of transitions $*_{\alpha}=\left\{\langle a\rangle: \alpha,\langle/ a\rangle: \alpha \mid a \in \Sigma^{\prime}\right\} \cup \Delta$ and $*_{\beta}$ defined analogously to $*_{\alpha}$, and the set of tags Non_Title $=\Sigma^{\prime} \backslash\{($ el,title $)\}$.


Figure 8.4: A successful run of the NwA of Figure 8.3 on the annotated library from Figure 8.2, in which the first book element is chosen as the marked node. Here, the stack $S=\gamma$ provides a stack symbol for the unique ancestor of the marked node.

### 8.2.4 Earliest Query Answering

Let $P$ be a query, $(t, \pi)$ a marked tree, $\pi^{\prime}$ a node such that $f u t^{t}\left(\pi, \pi^{\prime}\right)$ is true, and $e$ an event of suff $\left(t, \pi^{\prime}\right)$. We call $\pi^{\prime}$ safe for selection at $e$ if $\pi^{\prime} \in P\left(t^{\prime}, \pi\right)$ for every $t^{\prime}$ being a continuation of $t$ beyond $e$, i.e., such that the prefixes of the linearizations of $t$ and $t^{\prime}$ until event $e$ are equal. We call $\pi^{\prime}$ safe for rejection at $e$ if $\pi \notin P\left(t^{\prime}, \pi\right)$ for every $t^{\prime}$ such that $t^{\prime}$ is a possible continuation of $t$ beyond $e$. We call $\pi$ alive at $e$ if it is neither safe for selection nor rejection at $e$. An earliest query answering (EQA) algorithm outputs selected nodes at the earliest event when they become safe for selection, and discards rejected nodes at the earliest event when they become safe for rejection. Indeed, an EQA algorithm buffers only alive nodes. The problem to decide the aliveness of a node is Exptime-hard for queries defined by Nwas [Gauwin 2009b]. For dNwas it can be reduced to the reachability problem of pushdown machines which is in cubic time [Gauwin 2011a]. This, however, is too much in practice with Nwas of more than 50 states, 50 stack symbols, and $4 * 50^{2}=10.000$ transition rules, so that the time costs are in the order of magnitude of $10.000^{3}=10^{12}$.

### 8.3 Early Nested Word Automata

We will introduce early Nwas for approximating earliest query answering for Nwas with high time efficiency. The idea is to avoid reachability problems of pushdown machines, by enriching Nwas with selection and rejection states ${ }^{1}$, so that aliveness can be approximated by inspecting states, independently of the stack. As we will see in Section 8.5, we can indeed distinguish appropriate selection and rejection states when compiling XPath queries to eNwas descriptors.

A subset $Q^{\prime}$ of states of an Nwa $A$ is called an attractor if any run of $A$ that reaches a state of $Q^{\prime}$ can always be continued and must always stay in a state of $Q^{\prime}$. Whether runs reaching $Q^{\prime}$ can always be continued is not that easy to decide syntactically, since it requires to decide accessibility questions for pushdown automata. In practice, however, we will only consider attractors that consists of a single state, which can loop in itself with all possible transitions.

Definition 10. An early nested word automaton (ENwA) is a triple $E=\left(A, Q_{S}\right.$, $\left.Q_{R}\right)$ where $A$ is an NwA, $Q_{S}$ is an attractor of $A$ of final states called selection states, and $Q_{R}$ an attractor of non-final states called rejection states.

In the example Nwa in Figure 8.3, we can define $Q_{S}=\left\{q_{9}\right\}$ and $Q_{R}=\emptyset$. We could add a sink state to the automaton and to the set of rejection states. Also all selection states can be merged into a single state, and all rejection states can be deleted or merged into a single sink, if one wants to preserve pseudo-completeness (no run can ever block), as needed for efficient complementation in the deterministic case.

[^16]An eNwa defines the same language or query as the underlying Nwa. Let us consider an ENwa $E$ defining a monadic query and a data tree with some annotated node $\pi$. Clearly, whenever some run of $E$ on this annotated tree reaches a selection state then $\pi$ is safe for selection. By definition of attractors, this run can always be continued until the end of the stream while staying in selection states and thus in final states. In analogy, whenever all runs of $E$ reach a rejection state, then $\pi$ is safe for rejection, since none of the many possible runs can ever escape from the rejection states by definition of attractors, so none of them can be successful. For finding the first event, where all runs of $E$ either reach a rejection state or block, it is advantageous to assume that the underlying Nwa is deterministic. In this case, if some run reaches a rejection state or blocks, we can conclude that all of them do, as there is at most one run.

We call an eNwa deterministic if the underlying Nwa is. We next argue that the determinization procedure for Nwas, see Section 2.4.4, can be lifted to ENwas. Let $E=\left(A, Q_{S}, Q_{R}\right)$ be an ENwA and $A^{\prime}$ the determinization of NwA $A$. The states of $A^{\prime}$ are sets of pairs of states of $A^{\prime}$, and not just sets of states of $A$, in contrast to more traditional classes of automata. We define the deterministic ENwA $E^{\prime}=\left(A^{\prime}, Q_{S^{\prime}}, Q_{R}{ }^{\prime}\right)$ such that $Q_{S^{\prime}}$ contains all sets of pairs of states of $A$, such that the second component of some pair belongs to $Q_{S}$, while $Q_{R}{ }^{\prime}$ contains all sets of pairs of states of $A$, for which all pairs have their second component in $Q_{R}$.

Lemma 7. Let $E=\left(A, Q_{S}, Q_{R}\right)$ be an ENwA and $E^{\prime}=\left(A^{\prime}, Q_{S^{\prime}}, Q_{R}{ }^{\prime}\right)$ be the deterministic ENWA obtained from the above determinization procedure. For any event e of the stream of a tree $t$, there exists a run of $E$ going into $Q_{S}$ at event e if and only if there is a run of $E^{\prime}$ going into $Q_{S^{\prime}}$ at $e$. Likewise all runs of $E$ go into $Q_{R}$ at event $e$ iff all runs of $E^{\prime}$ go into $Q_{R}{ }^{\prime}$ at $e$.

This means that eNwa determinization preserves early selection and rejection. Intuitively, the reason is as follows. If we ignore the first components of the state pairs, then the run of automaton $E^{\prime}$ on $t$ always reaches the set of states reached by $E$ on $t$. Hence, whenever some run of $E$ on $t$ goes into a selection state $q$, the unique run of $E^{\prime}$ goes into a set of states that contains $q$ and is thus selecting for $E^{\prime}$. And whenever all runs of $E$ on $t$ reach a rejection state (or block), then the unique run of $E^{\prime}$ on $t$ reaches the set of all these rejection states, which is rejecting for $E^{\prime}$.

### 8.4 Fxp

By Fxp we denote the forward navigational fragment of $\lambda$ XP extended with label formulas, and comparisons to static string data values, whose abstract syntax is given in Figure 8.5. It is parameterized by some alphabet $\Sigma$, an alphabet $\Delta$ for strings, a set of variables $\mathcal{V}$, and a set of label properties $\mathcal{L}$, where a label property $L \in \mathcal{L}$ verifies whether a property holds about some label in $\Sigma$, i.e. $L: \Sigma \rightarrow \mathbb{B}$. Formulas are constructed from the single atomic formula true, the usual boolean

```
Formulas \(\quad F::=\mathrm{F} \wedge \mathrm{F}|\mathrm{F} \vee \mathrm{F}| \neg F \mid\) true \(|A(F)| B(F) \mid O_{w}\)
Forward Axes \(A::=c h\left|c h^{+}\right| n s^{+} \mid f o\)
Label formulas \(B::=i s_{x}|L| B \& B\)
Comparisons \(\quad O::=\) equals \(\mid\) contains \(\mid\) starts-with \(\mid\) ends-with
```

Figure 8.5: Abstract syntax of Fxp where $x \in \mathcal{V}$ is a variable, $L \in \mathcal{L}$ a label predicate on $\Sigma$, and $w \in \Delta^{*}$ a string data value.
operators, forward axes $A$, label formulas $B(F)$, where $B$ imposes a set of label properties $L \in \mathcal{L}$ and a set of variables annotations $x \in \mathcal{V}$, and string comparisons equals $_{w}$, contains $_{w}$, starts-with ${ }_{w}$, and ends-with $w$ where $w \in \Delta^{*}$.

For some data tree $t$ the label properties $L \in \mathcal{L}$ are used as unary relation symbols and interpreted as the set $L^{t}$ of nodes of $t$ whose label satisfies $L$. The unary relations contains ${ }_{w}^{t}$, equals ${ }_{w}^{t}$, starts-with ${ }_{w}^{t}$ and ends-with ${ }_{w}^{t}$ for words $w \in \Delta^{*}$ are satisfied by all nodes $\pi$ of $t$ whose data values satisfy the respective relation to $w$.

Navigational XPath queries are compiled to Fxp formulas as described in Section 7.3.1. The XPATH query book[starts-with(title, 'XML')]/auth, for example, will be compiled to the following Fxp formula with one free variable $x$ :

$$
\text { el\&book } \left.\left.\left.\left(\text { ch }\left(\text { el\&title }\left(\text { starts-with }_{X M L}\right)\right)\right) \wedge \text { ch }\left(\text { el\&author\&is }_{x}\left(\text { true }^{2}\right)\right)\right)\right)\right)
$$

In this example, we rely on the following label properties: the label property el stands for all node labels $(e l, a)$ with $a \in \Sigma$, the label book for all ( $T$, book) where $T$ is one of the XmL types, and similarly title and author test whether a node label has the respective XmL tag. In addition, we use relations symbols ch and starts-with ${ }_{X M L}$ for talking about the corresponding relations of data trees.

We define the conjunction width $w(F)$ as the number of conjunction operators $\wedge$ in $F$. The conjunction width of an Fxp formula will be relevant for the complexity analysis of the automata construction in Section 8.5. Note that conjunctions in label formulas $B \& B^{\prime}$ are not counted. Furthermore, $B(F)$ can be rewritten equivalently with a conjunction $B \wedge F$, but this would increase the conjunction width.

We recall the formal semantics of FXP in Figure 8.6 for a single data tree $t$, while not considering program errors. A formula $F$ is evaluated to a Boolean with respect to a given marked data tree $(t, \pi)$ and a variable assignment $\mu$ that maps all variables of $F$ to nodes of $t$ opened later than $\pi$. The value of a formula $F$ is the Boolean $\llbracket F \rrbracket_{t, \pi, \mu}$ defined in Figure 8.6. As usual we will write $F \models F^{\prime}$ if all models of $F$ are also models of $F^{\prime}$, i.e. if $\llbracket F \rrbracket_{t, \pi, \mu}$ is true then also $\llbracket F^{\prime} \rrbracket_{t, \pi, \mu}$.

Any formula $F$ with one free variable $x$ defines a monadic query $P$ on marked trees such that $P(t, \pi)=\left\{\mu(x) \mid \llbracket F \rrbracket_{t, \pi, \mu}=\right.$ true $\}$. For compiling XPATH expressions to the fragment sketched above, we need only such Fxp formulas. For the general case, as treated in the remainder of this chapter, formulas with $n$ free

$$
\begin{array}{ll}
\llbracket F_{1} \wedge F_{2} \rrbracket_{t, \pi, \mu} \Leftrightarrow \llbracket F_{1} \rrbracket_{t, \pi, \mu} \wedge \llbracket F_{2} \rrbracket_{t, \pi, \mu} & \llbracket B(F) \rrbracket_{t, \pi, \mu} \Leftrightarrow \llbracket B \rrbracket_{t, \pi^{\prime}, \mu} \wedge \llbracket F \rrbracket_{t, \pi^{\prime}, \mu} \\
\llbracket F_{1} \vee F_{2} \rrbracket_{t, \pi, \mu} \Leftrightarrow \llbracket F_{1} \rrbracket_{t, \pi, \mu} \vee \llbracket F_{2} \rrbracket_{t, \pi, \mu} & \llbracket i_{x} \rrbracket_{t, \pi, \mu} \Leftrightarrow \pi=\mu(x) \\
\llbracket \neg F \rrbracket_{t, \pi, \mu} \Leftrightarrow \neg\left[F \rrbracket_{t, \pi, \mu}\right. & \llbracket L \rrbracket_{t, \pi, \mu} \Leftrightarrow \pi \in L^{t} \\
\llbracket t r u \rrbracket_{t, \pi, \mu} \Leftrightarrow \operatorname{true} & \\
\llbracket A(F) \rrbracket_{t, \pi, \mu} \Leftrightarrow \exists \pi_{1} . A^{t}\left(\pi, \pi_{2} \rrbracket_{t, \pi, \mu} \Leftrightarrow \llbracket B_{1} \rrbracket_{t, \pi^{\prime}, \mu} \wedge \llbracket B_{2} \rrbracket_{t, \pi^{\prime}, \mu}\right. \\
& \llbracket F \rrbracket_{t, \pi^{\prime}, \mu}
\end{array} \mathbb{O}_{w} \rrbracket_{t, \pi, \mu} \Leftrightarrow \pi \in O_{w}^{t} .
$$

Figure 8.6: Semantics of Fxp formulas $F$ for an Xml data tree $t$ with node $\pi$ and variable assignment $\mu$ to nodes of $t$.
variables will be essential. Since the general case does not raise any additional difficulties, we will not impose any restriction on the number of variables.

### 8.5 Compiler from FXP to Early Nested Word Automata

We have already seen in the previous examples of Nwas for XPATH expressions ${ }^{2}$ that the number of similar transitions for different labels may become huge. Furthermore, the alphabet of Nwas are exponential in the number of variables, which may become huge in the $n$-ary case. Therefore, we will compile Fxp formulas into compact descriptors of ENwAs, in which labels are replaced by label descriptors.

### 8.5.1 ENWA Descriptors

Let $\mathcal{V}_{0} \subseteq \mathcal{V}$ be a finite set of variables and $\mathcal{L}_{0} \subseteq \mathcal{L}$ a finite set of label predicates over $\Sigma$, for instance those used by some fixed Fxp formula.

A descriptor $D_{l a b}$ for a letter in $\Sigma$ is an expression $E_{1} \& \ldots \& E_{n}$ where all $E_{i}$ belong to $\left\{L, \neg L \mid L \in \mathcal{L}_{0}\right\}$ and $n \geq 0$. We write $D_{\text {lab }}=$ true if $n=0$. We define the denotation $\llbracket D_{l a b} \rrbracket \subseteq \Sigma$ as follows:

$$
\llbracket L \rrbracket=L \quad \text { and } \quad \llbracket \neg L \rrbracket=\Sigma \backslash L \quad \text { and } \quad \llbracket E_{1} \& \ldots \& E_{n} \rrbracket=\llbracket E_{1} \rrbracket \cap \ldots \cap \llbracket E_{n} \rrbracket .
$$

A descriptor $D_{v a r}$ for a subset of $\mathcal{V}_{0}$ is a pair $\left(V, V^{\prime}\right)$ of subsets of $\mathcal{V}_{0}$. Its denotation is defined as follows:

$$
\llbracket\left(V_{1}, V_{2}\right) \rrbracket=\left\{V \mid V_{1} \subseteq V \subseteq\left(\mathcal{V} \backslash V_{2}\right)\right\}
$$

We define the conjunction of two such descriptors $\left(V_{1}, V_{1}^{\prime}\right) \&\left(V_{2}, V_{2}^{\prime}\right)$ as $\left(V_{1} \cup V_{2}, V_{1}^{\prime} \cup\right.$ $\left.V_{2}^{\prime}\right)$. Clearly, $\llbracket\left(V_{1}, V_{1}^{\prime}\right) \&\left(V_{2}, V_{2}^{\prime}\right) \rrbracket$ is equal to $\llbracket\left(V_{1}, V_{1}^{\prime}\right) \rrbracket \cap \llbracket\left(V_{2}, V_{2}^{\prime}\right) \rrbracket$.

A descriptor $D_{\text {tup }}$ for a triple in $\Sigma \times 2^{\mathcal{V}_{0}} \times 2^{\mathcal{V}_{0}}$ is a triple $\left(D_{1}, D_{2}, D_{3}\right)$ consisting of a descriptor $D_{1}$ for a letter in $\Sigma$, and descriptors $D_{2}$ and $D_{3}$ for subsets of $\mathcal{V}_{0}$. The denotation is $\llbracket\left(D_{1}, D_{2}, D_{3}\right) \rrbracket=\llbracket D_{1} \rrbracket \times \llbracket D_{2} \rrbracket \times \llbracket D_{3} \rrbracket$.

[^17]

Figure 8.7: A descriptor of an ENwA for XPATH filter [child:: $a_{1} /$ child:: $a_{2} / \ldots /$ child:: $a_{n}$ ] with selection state sel and rejection state rej (without transitions for texts and other XmL types for simplicity).

A descriptor of an ENwA is an ENwA itself, whose alphabets of opening and closing tags contain descriptors. An ENwA descriptor thus uses opening and closing tags $\langle D\rangle$ and $\langle/ D\rangle$ where $D$ is a descriptor of a label in $\Sigma \times 2^{\nu_{0}} \times 2^{\nu_{0}}$ rather than the label itself. The intuition for why we consider labels in $\Sigma \times 2^{\nu_{0}} \times 2^{\nu_{0}}$ is that we construct automata, who need to check a label in $\Sigma$, an annotation in $2^{\nu_{0}}$, and who needs to check the possibility for annotations in $2^{\nu_{0}}$ of future nodes of the data tree. This will become clearer in the following. The ENwA described is obtained from an ENwA descriptor by instantiating all occurrences of letters $D$ in transition rules by all possible values of $\llbracket D \rrbracket$. We also need similar descriptors for letters in $\Delta$ but omit the details here. Note that it is possible that a rule is described twice by an ENwa descriptor, while the described automaton is still deterministic.

In Figure 8.7, we illustrate the ENwA descriptor for XPath filter [child: : $a_{1}$ $\left./ \ldots / \operatorname{child}:: a_{n}\right]$, i.e., the Fxp expression $\operatorname{ch}\left(e l\left(a_{1}\left(\operatorname{ch}\left(\ldots \operatorname{ch}\left(e l\left(a_{n}\right)\right)\right)\right)\right)\right)$. Here we need conjunctive descriptors such as $a_{i} \& e l$ for expressing simultaneous type and tag restrictions for the same node, and negative descriptors such as $\neg e l$ and $\neg a_{i}$ for handling else cases. Thanks to the latter, the size of this eNwa descriptor is in $O(n)$, even though the size of the described ENwA is in $O\left(n^{2}\right)$, since for each of the $n$ states $q_{i}$ there are $n$ outgoing edges, one for each $a_{i}$.

### 8.5.2 When Variables Must be Bound

Consider the Fxp formula $\operatorname{ch}(x($ true $))$. The linearization of an annotated tree must be immediately rejected if $x$ got assigned to the start node, since then $x$ cannot be assigned to any child of the start node anymore. What is relevant here is which variables must be bound in order to make a subformula true.

Definition 11. Let $F$ be an Fxp formula and $x$ a variable. We say $F$ must bind $x$ if $F \models$ fut $(x)$ and that $F$ cannot bind $x$ if $F \models \neg$ fut $(x)$.

In order to approximate $F \models f u t(x)$ syntactically, as needed for our automata construction to define rejection states, we define the predicate $F \vdash f u t(x)$ as the least binary relation such that:

1. $F_{1} \wedge F_{2} \vdash f u t(x)$ if $F_{1} \vdash f u t(x)$ or $F_{2} \vdash f u t(x)$
2. $F_{1} \vee F_{2} \vdash f u t(x)$ if $F_{1} \vdash f u t(x)$ and $F_{2} \vdash f u t(x)$
3. $A(F) \vdash f u t(x)$ if $F \vdash f u t(x)$
4. $L(F) \vdash f u t(x)$ if $F \vdash f u t(x)$
5. $x(F) \vdash f u t(x)$ is true

Given a formula $F$ one can compute in linear time the set $\{x \in \mathcal{V} \mid F \vdash f u t(x)\}$. The following soundness lemma for syntactic binding is obvious.

Lemma 8. For any Fxp formula $F$ and variable $x: F \vdash f u t(x) \Rightarrow F \models f u t(x)$.
The converse, i.e. completeness, does not hold in general but still in many interesting cases (see [Lick 2013]). The above soundness result will be sufficient to justify the correctness of our automata construction. In cases where completeness fails our ENWA may fail to be earliest.

### 8.5.3 Construction of ENWA Descriptors

Let $\mathcal{V}_{0} \subseteq \mathcal{V}$ be a finite subset of variables. For any tree $t$ and mapping $\alpha: \mathcal{V}_{0} \rightarrow$ nodes $(t)$ we define the annotated tree $t * \alpha$, by replacing in $t$ for any node $\pi$ the label $l$ of $\pi$ by $\left(l, \alpha^{-1}(\pi)\right)$, i.e., by annotating the label of any node by the set of variables that are mapped to it.

Let $F$ be an Fxp formula with variables in $\mathcal{V}_{0}$ and $n \geq 0$. We define the language of tree suffixes of $F$ with marks at tree depth $n$ as follows:

$$
\begin{aligned}
\mathcal{L}_{n}(F):=\{\operatorname{suff}(t * \mu, \pi) \mid & \llbracket F \rrbracket_{t, \pi, \mu} \text { is true, } \pi \text { is a node of } t \text { at depth } n \\
& \left.\mu\left(\mathcal{V}_{0}\right) \subseteq \operatorname{fut}^{t}(\pi), \operatorname{dom}(\mu)=\mathcal{V}_{0}\right\}
\end{aligned}
$$

This language contains all tree suffixes of annotated trees $t * \mu$, such that $F$ evaluates to true for a node $\pi$ of $t$ at depth $n$, and variable assignment $\mu$. For any finite set $\mathcal{E}$ of "external" stack symbols, that will be fixed by the context in which $F$ will be used, we construct an ENWA $E_{F}(\mathcal{E})$, such that for all stacks $S \in \mathcal{E}^{n}$ :

$$
\mathcal{L}_{S}\left(E_{F}(\mathcal{E})\right)=\mathcal{L}_{n}(F)
$$

Note that this equality will hold for all stacks $S$ of height $n$, so that it is independent of the precise content of the stack.

We call a tree suffix $s$ with opening and closing parentheses <l> and </l> where $l \in \Sigma \times 2^{\mathcal{V}_{0}}$ canonical, if each variable of $\mathcal{V}_{0}$ is annotated to exactly one node of $s$. Whether a tree suffix is canonical can be decided by a streaming algorithm, that runs the following deterministic finite word automaton $C$ on the linearization of $s$. The state set of $C$ is $2^{\mathcal{V}_{0}}$, the initial state is $\mathcal{V}_{0}$, and its final state is $\emptyset$. The rules are $V \xrightarrow{\left\langle\left(a, V^{\prime}\right)\right\rangle} V \backslash V^{\prime}$ if $V^{\prime} \subseteq V, V \xrightarrow{\left\langle/\left(a, V^{\prime}\right)\right\rangle} V$, and $V \xrightarrow{w} V$ for $a \in \Sigma, w \in \Delta^{*}$,
and $V, V^{\prime} \in 2^{\mathcal{V}_{0}}$. Note that $C$ gets stuck at the earliest event, when the variable annotation gets in conflict with canonicity.

Given a tree suffix of a marked tree $s=\operatorname{suff}(t * \alpha, \pi)$, let $\operatorname{Can}(t * \alpha, \pi)$ be obtained from $s$ by annotating all events by the subset of variables in $\mathcal{V}_{0}$ that were not bound in the past or at the current event by $\alpha$, so that they can still be bound in the future. More formally $\operatorname{Can}(t * \alpha, \pi)$ is the suffix at node $\pi$ of the tree obtained from $t * \alpha$ by replacing for any node $\pi^{\prime}$ the label $(l, V) \in \Sigma \times 2^{\mathcal{V}_{0}}$ by $\left(l, V, V^{\prime}\right)$, where $V^{\prime}=\left\{v \in \mathcal{V}_{0} \mid \alpha(v) \in\right.$ fut $\left.^{t}\left(\pi^{\prime}\right) \backslash\left\{\pi^{\prime}\right\}\right\}$. Note that corresponding opening and closing events of $\operatorname{Can}(t * \alpha, \pi)$ have the form $\left\langle\left(a, V, V_{1}\right)\right\rangle$ and $\left\langle/\left(a, V, V_{2}\right)\right\rangle$ where $V_{1}$ may be a proper subset of $V_{2}$, so the label of corresponding events need not be the same. Such nested words are still linearizations of trees but with the functions $o p\left(a, V, V_{1}, V_{2}\right)=\left\langle\left(\mathrm{a}, \mathrm{V}, \mathrm{V}_{1}\right)>\right.$ and $c l\left(a, V, V_{1}, V_{2}\right)=</\left(\mathrm{a}, \mathrm{V}, \mathrm{V}_{2}\right)>$.

First we obtain $C a n(s)$ by running the DFA $C$ on the input tree suffix $s$, whose current state will always be the subset of variables in $\mathcal{V}_{0}$ that were not yet bound. Second, on the stream $\operatorname{Can}(s)$, the automaton $E=E_{F}(\mathcal{E})$ will run the ENwA described by $D=D_{F}(\mathcal{E})$ constructed below. Whenever the run of $C$ blocks, the ENwA described by $D$ will go into a rejection state.

### 8.5.4 Construction of the eNwa descriptor $D_{F}(\mathcal{E})$

In order to compile an Fxp formula to the ENwA descriptor $D_{F}(\mathcal{E})$, we follow the same fundamental approach as for compiling tree logics such as Mso into tree automata, as used before in the context of XPath [Gauwin 2009b, Madhusudan 2009]. The most novel part here is the distinction of appropriate selection and rejection states, and the usage of label descriptors. It should also be noticed that our compiler will heavily rely on non-determinism in order to compile formulas with recursive axes such as $c h^{+}(F), n s^{+}(F)$, or $f o(F)$, and disjunctions $F_{1} \vee F_{2}$. However, we will try to preserve determinism of the described ENWA as much as possible, so that we can compile many formulas $\neg F$ without having to determinize the described ENWA for $F$. The compiler will rely on the so-called head $h(D)$, that contains the subset of all opening rules of $D$ that start from an initial state, and the subset of closing rules of $D$ that end in a selection or rejection state with a stack symbol pushed by such an opening rule. Without disjunctions and conjunctions, the heads will always remain of constant size. This is the reason why formulas such as $\operatorname{ch}(a(\operatorname{ch}(\ldots \operatorname{ch}(a) \ldots))$ can be compiled to ENWA descriptors of linear size in linear time. When adding disjunction but no conjunction, the heads are still of amortized constant size, as we will show later on. This is the reason why we will need an amortized size and time analysis.

The construction of $D_{F}(\mathcal{E})$ is by induction on the structure of $F$ as follows.
Case $F=F_{1} \wedge F_{2}$. Let $D_{F_{i}}(\mathcal{E})=\left(A_{i}, Q_{S_{i}}, Q_{R_{i}}\right)$ be the ENWA descriptors for $F_{i}$ where $A_{i}$ has state set $Q_{i}$ and $i \in\{1,2\}$. We define the ENwA descriptor $D=$ $\left(A, Q_{S}, Q_{R}\right)$ such that $A$ is the product of $A_{1}$ and $A_{2}$. We choose $Q_{S}=Q_{S 1} \times Q_{S 2}$, since a node is safe for selection for $F_{1} \wedge F_{2}$ iff it is safe for selection for both $F_{1}$ and $F_{2}$. For rejection states we take $Q_{R}=\left(Q_{R_{1}} \times Q_{2}\right) \cup\left(Q_{1} \times Q_{R_{2}}\right)$, which may lead
to a proper approximation of earliest query answering. Furthermore, note that a large number of conjunctions may lead to an exponential blow-up of the number of states.
Case $F=F_{1} \vee F_{2}$. Let $D_{F_{i}}(\mathcal{E})=\left(A_{i}, Q_{S i}, Q_{R_{i}}\right)$ be the ENwA descriptor for the subexpressions where $A_{i}$ has state set $Q_{i}$ and $i \in\{1,2\}$. We define $D=\left(A, Q_{S}, Q_{R}\right)$ such that $A$ is the union of $A_{1}$ and $A_{2}$, which introduces nondeterminism in contrast to products. Furthermore, we define $Q_{S}=Q_{S_{1}} \cup Q_{S_{2}}$ and $Q_{R}=Q_{R_{1}} \cup Q_{R_{2}}$.
Case $F=\neg F_{1}$. If $D_{1}=D_{F_{1}}(\mathcal{E})$ describes a deterministic ENwA, then we obtain $D$ by flipping selection and rejection states of $D_{1}$. This is correct, since we maintain pseudo-completeness (i.e. no run can ever block [Gauwin 2009a], instead it goes into a rejection state) of the described ENwA as an invariant. There is no approximation here, since a node is safe for selection for $\neg F_{1}$ iff it is safe for rejection for $F_{1}$, and conversely. Otherwise, we first compute the eNwa described by $D$ and determinize it in a first step, which is also free of approximation by Lemma 7, and second apply the previous construction.
Case $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains neither recursive axes nor disjunctions. Since $F_{1}$ neither contains recursive axes nor disjunctions, $D_{1}=D_{F_{1}}(\mathcal{E})$ describes a deterministic eNwa. Furthermore, selection and rejection can be decided no later than when closing the start node. In this case, we can construct $D$ such that it runs $D_{1}$ on all children of the start node, deterministically one by one, until a selection state is reached or the start node was closed. This can be done by adding 2 states and stack symbols to $D_{1}$ only, based on a recomputation trick for the stack symbol pushed at the start node by $D_{1}$ [Gauwin 2009a].

The ENwa described by $D=D(\mathcal{E})$ first reads the opening event of the start node, say $\left\langle\left(a, V^{\prime}, V^{\prime \prime}\right)\right\rangle$ and goes into a rejection state if there exists $x \in V^{\prime}$ such that $F_{1} \vdash f u t(x)$ or if $V^{\prime} \cap V^{\prime \prime} \neq \emptyset$. In the latter case, $C$ will block. Otherwise, $D$ behaves as $D_{1}$ but stacks the Boolean 0 (stating that no previous child was tested successfully) instead of what $D_{1}$ would stack. The missing stack symbol will then be recomputed when closing the root of the child. In order to construct $D$ alike, one needs to iterate over the head of $D_{1}$, but does not have to touch the rest of $D_{1}$. This can be done in time $\left|h\left(D_{1}\right)\right|$. The selection states of $D$ are those of $D_{1}$, while $D$ introduces a new rejection state. Whenever a run of $D_{1}$ goes into a rejection state of $D_{1}$ (which is not a rejection state of $D$ ), then automaton $D$ may stop any further child tests if $x$ occurs in a set of $\gamma$ and $F_{1} \vdash f u t(x)$, in which case $D$ goes into its rejection state. If $D$ reaches the closing event of the start node (that is when the Boolean 0 is popped), then $D$ also goes into the rejection state (this is correct again since $F_{1}$ contains no following axes, so that rejection of $\operatorname{ch}\left(F_{1}\right)$ can be decided there). Therefore, no external stack symbol from $\mathcal{E}$ will ever be read by $D$ (they may appear only after selection or rejection).
Case $F=A\left(F_{1}\right)$ where $A \in\left\{c h^{+}, n s^{+}, f o\right\}$ or $F=c h\left(F_{1}\right)$ where $F_{1}$ contains recursive axes or disjunctions. Let $D_{1}=D_{F_{1}}\left(\mathcal{E} \cup \Gamma_{\text {new }}\right)$ be the ENwa descriptor for $F_{1}$, where $\Gamma_{\text {new }}$ is the set of stack symbols that $D=D_{F}(\mathcal{E})$ introduces. A nondeterministic ENwA is described by $D$, which guesses an $A$-successor of the
start node and runs $D_{1}$ starting there. There is a main run of $D$, which for all non- $A$ successors of the start node goes into a skip state $q_{s k i p}$, and which goes into a state $q$ that generates tests for $F_{1}$ for potential following $A$-successors: For $A=c h$ the main run goes to state $q$ such that the next potential opening event is a child of the start node, and it stays in $q_{\text {skip }}$ for the subtrees of children of the start node. For $A=c h^{+}$the main run goes and stays in state $q$ for all descendants of the start node (no skip state $q_{\text {skip }}$ needed). For $A=n s^{+}$the main run goes to state $q$ for all siblings to the right of start node, and it stays in $q_{\text {skip }}$ for the subtree of the start node and any of the subtrees of its siblings to the right. For $A=f o$ the main run skips the subtree of the start node and after stays in $q$ for the rest of the stream, which is done via closing rules $q \xrightarrow{\langle/(\text { true })\rangle ; \beta} q$ for all $\beta \in \mathcal{E}$. The main run of $D$ starts tests for $F_{1}$ by adding a rule $q \xrightarrow{\langle a\rangle: \alpha} p$ for each initial rule $i \xrightarrow{\langle a\rangle: \alpha} p$ of $D^{\prime}$ with $i \in Q_{I}$ of $D^{\prime}$. This main run will continue until:

- either $x$ occurs in a set of $\gamma$ and $F_{1} \vdash f u t(x)$, in which case $D$ goes into a rejection state, or
- the closing event of the start node of $P$ arrives (for $A=c h$ and $A=c h^{+}$),
- the closing event of the parent of the start node of $P$ arrives (for $A=n s^{+}$),
- the end of the stream arrives (for $A=f o$ ), indicated by a unique top most stack symbol.

Automaton descriptor $D$ inherits its selection and rejection states from $D_{1}$. Note that here it matters again that a candidate can be rejected only if all runs of $D$ on this candidate go into a rejection state.
Case $F=B\left(F_{1}\right)$. Without loss of generality, let $B=L_{1} \& \ldots \& L_{m} \& x_{1} \& \ldots \& x_{n}$ where $n+m \geq 1$ such that $L_{i} \in \mathcal{L}$ and $x_{i} \in \mathcal{V}_{0}$. Let $D_{F_{1}}(\mathcal{E})$ be the ENwA descriptor for $F_{1}$. We build $D$ from $D_{1}$, by restricting all label descriptors of initial rules of $D_{1}$ by $B$ : Descriptors $\left(E_{1} \& \ldots E_{k},\left(V_{1}, V_{2}\right),\left(V_{1}^{\prime}, V_{2}^{\prime}\right)\right)$ are replaced by $\left(E_{1} \& \ldots \& E_{k} \& L_{1} \& \ldots \& L_{m},\left(V_{1} \cup\left\{x_{1}, \ldots, x_{n}\right\}, V_{2}\right),\left(V_{1}^{\prime}, V_{2}^{\prime}\right)\right)$. Furthermore, in order to obtain pseudo-completeness, we add one new rule to $D$ for each conjunct of $B$ and each initial state of $D_{1}$ going into a rejection state of $D_{1}$ : For $1 \leq i \leq m$ the new initial rule has label descriptor $\left(\neg L_{i} \& L_{i+1} \& \ldots \& L_{m},(\emptyset, \emptyset),(\emptyset, \emptyset)\right.$ ), which describe the complement of $L_{1} \& \ldots \& L_{m}$ deterministically. The initial rule for $1 \leq i \leq n$ has label descriptor (true, $\left.\left(\emptyset,\left\{x_{i}\right\}\right),(\emptyset, \emptyset)\right)$ describing all variable subsets that do not contain $x_{i}$. D inherits selection and rejection states from $D_{1}$.
Case $F=O_{w}$. The ENwA descriptor $D$ for $O_{w}$ has to compute the concatenation of all strings of text nodes contained in the subtree of the start node, and has to compare it to $w$ with respect to $O$. This is done by creation of a deterministic finite state automaton $B$ that accepts all strings $w^{\prime}$ such that $\left(w^{\prime}, w\right)$ is in the relation induced by $O$. The idea is that $D$ runs automaton $B$ on all strings of text nodes in the subtree of the start node. $D$ maintains a copy of states of $B$, called copy states. $D$ 's main run $r$ remains in copy states of $B$ whenever not reading strings of text
nodes of the subtree of the start node, while $r$ switches to corresponding states of $B$ at text nodes. The main run starts in the initial copy state of $B$ and stays there until the first text node arrives at which it changes to the initial state of $B$. The string of the text node is consumed by $B$, while reaching some state $q$ which is not necessarily a final state of $B$. At the corresponding closing event of the text node, the main run goes into the corresponding copy state $q_{\text {copy }}$ for $q$ and stays there until the next text node arrives, where $r$ continues as before. The main run continues until the closing event of the start node, where $O_{w}$ can be decided. Whenever $B$ blocks, the main run moves into a rejection state, and whenever a final state of $B$ is reached, it moves into a selection state.
Case $F=$ true. The ENwA descriptor $D$ for true has five plus $2|\mathcal{E}|$ rules with label descriptor $($ true, $(\emptyset, \emptyset),(\emptyset, \emptyset))$ : one opening initial rule to a selection state, opening and closing rules looping in the selection and the rejection state, and $2|\mathcal{E}|$ closing rules to close the stream in the selection and rejection state.

Definition 12. We call an Fxp formula determinization free if it does not contain any disjunction or any axis from $\mathrm{ch}^{+}, n s^{+}$, and fo below a negation.

For the complexity analysis of our compiler, we will need to assume that the input Fxp formula is simple, in that all label subformulas are of one of the following three forms: $B\left(O_{w}\right), B(A(F))$ or $B($ true $)$. We can transform all Fxp formulas into equivalent simple Fxp formulas by applying the rewrite rule $B(F) \rightarrow B($ true $) \wedge F$ everywhere. This procedure, however, would increase the conjunction width, on which the efficiency of our compiler depends. Instead, we will assume that the input formulas is simply labeled in the following sense.

Definition 13. We call an occurrence of an operator in a formula labeled if it has some ancestor, which is a label formula $B$ but without having any axis $A$ in between. We call a formula simply labeled if it does not contain any labeled disjunctions and negations.

Lemma 9. Any simply labeled Fxp formula can be transformed into a simple Fxp formula with the same conjunction width in linear time.

Proof. We apply the following two rewrite rules exhaustively in a bottom-up manner. This can be done in linear time since no subformulas are copied, and it does not affect the number of conjunctions.

$$
\begin{aligned}
B\left(F \wedge F^{\prime}\right) & \rightarrow B(F) \wedge F^{\prime} \\
B\left(B^{\prime}(F)\right) & \rightarrow B \& B^{\prime}(F)
\end{aligned}
$$

Both rules preserve simple labeling, since whenever one of them applies, all unlabeled disjunctions and negations of $F$ and $F^{\prime}$ must be located below some axis. Therefore, they will remain unlabeled. If none of these rules applies any more, the resulting Fxp formula is simple: subformulas $B\left(F \wedge F^{\prime}\right)$ and $B\left(B^{\prime}(F)\right)$ would be rewritten, $B\left(F \vee F^{\prime}\right)$ and $B(\neg(F))$ are excluded since not simply labeled, and all other three possible forms $B($ true $), B(A(F))$ and $B\left(O_{w}\right)$ are simple.

### 8.5.5 Correctness

Proposition 8 (Correctness). Let $\mathcal{E}$ be a set of "external" stack symbols, $n \geq 0$, $S \in \mathcal{E}^{n}, F$ an Fxp formula with variables in a finite set $V \subseteq \mathcal{V}_{0}$, and $D=D_{F}(\mathcal{E})$ be the constructed ENwa. Then

$$
\mathcal{L}_{S}\left(D_{F}(\mathcal{E})\right)=\operatorname{Can}\left(\mathcal{L}_{n}(F)\right)
$$

Proof. The proof is by induction on the structure of Fxp formulas.
Case $F=F_{1} \wedge F_{2}$. Let $D_{1}=D_{F_{1}}(\mathcal{E})$ and $D_{2}=D_{F_{2}}(\mathcal{E})$ be the ENWA for $F_{1}$ and $F_{2}$ respectively. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, then trivially, $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$ and $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{2}\right)\right)$. By induction, for any $i \in\{1,2\}$, some run on $s$ by $D_{i}$ goes into a selection state. Selection states of $D$ are pairs of a selection state of $D_{1}$ and a selection state of $D_{2}$. Hence some run of $D$ on $s$ goes into a selection state as well, such that $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$, then there exist some run on $s$ by $D$ which goes into a selection state. Therefore there exist some run on $s$ by $D_{i}$ going into a selection state of $D_{i}$. By induction it follows that $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{i}\right)\right)$ for $i=\{1,2\}$, and thus $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$.
Case $F=F_{1} \vee F_{2}$. Let $D_{1}=D_{F_{1}}(\mathcal{E})$ and $D_{2}=D_{F_{2}}(\mathcal{E})$ be the ENwA for $F_{1}$ and $F_{2}$ respectively. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, then there exist $i \in\{1,2\}$ such that $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{i}\right)\right)$. By induction, some run on $s$ by $D_{i}$ goes into a selection state. Since all selection states of $D_{i}$ are selection states of $D$ it follows that some run of $D$ on $s$ goes into a selection state, and $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$, then there exist some run on $s$ by $D$ which goes into a selection state. Hence there exist $i \in\{1,2\}$ such that some run on $s$ by $D_{i}$ goes into a selection state. By induction it follows that $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{i}\right)\right)$, and hence $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$.
Case $F=\neg F_{1}$. Let $D_{1}=D_{F_{1}}(\mathcal{E})$ be the ENwa for $F_{1}$. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, then $s \notin \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$. By induction, all runs on $s$ by $D_{1}$ go into a rejection state. By Lemma 7 the unique run of the determinization of $D_{1}$ on $s$ goes into a rejection state. Since $D$ flips selection with rejection states the unique run of $D$ on $s$ goes into a selection state, and thus $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$, then the unique run on $s$ by $D$ goes into a selection state. Hence the unique run by $D_{1}$ on $s$ goes into a rejection state. By induction it follows that $s \notin \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$, so that $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$.
Case $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains neither recursive axes nor disjunctions. Let $D_{1}=D_{F_{1}}(\mathcal{E})$ be the ENwA for $F_{1}$. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, then there exist a suffix $s^{\prime}$ of $s$ with $s^{\prime} \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right.$ ), while starting with the opening event of some child of the start node of $s$. By induction, as $D_{1}$ is deterministic the unique run on $s^{\prime}$ by $D_{1}$ goes into a selection state. By construction the unique run of $D$ goes into the same selection state on $s$. Hence $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$, then the unique run on $s$ by $D$ goes into a selection state. As $D$ runs $D_{1}$ on all children of the start node of $s$, and as $D$ goes into a selection state whenever $D_{1}$ does, it follows that the unique run of $D_{1}$ goes into a selection state for some suffix $s^{\prime}$ of $s$, that starts with the opening event of some child of the start node of $s$. By induction it follows that $s^{\prime} \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$, so that $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$.

Case $F=A\left(F_{1}\right)$ where $A \in\left\{c h^{+}, n s^{+}, f o\right\}$ or $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains recursive axes or disjunctions. Let $D_{1}=D_{F_{1}}\left(\mathcal{E} \cup \Gamma_{\text {new }}\right)$ be the ENWA for $F_{1}$, where $\Gamma_{\text {new }}$ are stack symbols that $D$ introduces. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, then there exist a suffix $s^{\prime}$ of $s$ with $s^{\prime} \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$, while starting with the opening event of some $A$-successor of the start node of $s$. By induction, some run of $D_{1}$ on $s^{\prime}$ goes into a selection state. By construction some run of $D$ goes into the same selection state on $s$. Thus $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$, then some run on $s$ by $D$ goes into a selection state. As $D$ runs $D_{1}$ on all $A$-successor of the start node of $s$, and as $D$ goes into a selection state whenever $D_{1}$ does, it follows that some run of $D_{1}$ goes into a selection state for some suffix $s^{\prime}$ of $s$, that starts with the opening event of some $A$-successor of the start node of $s$. By induction it follows that $s^{\prime} \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$, and hence $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$.
Case $F=B\left(F_{1}\right)$. Let $D_{1}=D_{F_{1}}(\mathcal{E})$ be the eNwa for $F_{1}$. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, then the label of the start node of $s$ belongs to all label properties $L$ in $B$, while the start node is annotated according to all variable restrictions in $B$, and $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$. By induction, some run $r$ of $D_{1}$ on $s$ goes into a selection state. By construction as $D$ runs $D_{1}$ for some start node, whose label belongs to all label properties $L$ of $B$ and is annotated by all variable restrictions in $B$, the same run $r$ of $D$ goes into the same selection state on $s$. Therefore $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$, then some run $r$ on $s$ by $D$ goes into a selection state only if the label of the start node satisfies all properties or restrictions in $B$. This selection state is a selection state of $D_{1}$, such that the same run $r$ of $D_{1}$ goes into a selection state on $s$. By induction it follows that $s \in \operatorname{Can}\left(\mathcal{L}_{n}\left(F_{1}\right)\right)$, and therefore $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$ according to fulfilled label and annotation restrictions.
Case $F=O_{w}$. Let $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F, V)\right)$, then the start node of $s$ belongs to $O_{w}$. By construction $D$ runs a finite state automaton $B$ (which accepts all string $w^{\prime}$, such that ( $w, w^{\prime}$ ) is in the relation induced by $O$ ) over the concatenation of the text nodes in the subtree of the start node of $s$. As the start node of $s$ belongs to $O_{w}$, $D$ goes into a final state of $B$ for some string of some text node, and thereby into a selection state of $D$. Hence $s \in \mathcal{L}_{S}(D)$. Conversely let $s \in \mathcal{L}_{S}(D)$. Then there is a run on $s$ by $D$ which goes into a selection state, such that the data value of the start node of $s$ must be in relation with $w$ with respect to $O$. Hence the start node of $s$ belongs to $O_{w}$, such that $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F, V)\right)$.
Case $F=$ true. $s \in \operatorname{Can}\left(\mathcal{L}_{n}(F)\right)$, is true for any tree suffix $s$. By construction $D$ moves to a selection state for any start node of $s$. Hence any run of $D$ on any suffix $s$ goes into a selection state, such that $s \in \mathcal{L}_{S}(D)$.

### 8.5.6 Size of Automata Descriptors

Lemma 10 (Size of automaton descriptor). There exists a constant $c^{\prime}$ such that for any Fxp-formula $F$, that is determinization free and simply labeled, and for any finite set $\mathcal{E}$ of external stack symbols: $\left|D_{F}(\mathcal{E})\right| \leq\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{w(F)+1}$.

Proof. By Lemma 9 we can make $F$ simple in a preprocessing step in linear time without changing the conjunction width $w(F)$. For the treatment of recursive axis $c h^{+}, n s^{+}$, and $f 0$, we need nondeterministic automata with multiple initial rules. If we always had a single initial rule, then the proof of the lemma was straightforward. With multiple initial rules, we need an amortized cost analysis. Therefore, we define the amortized size of an ENwA descriptor $D$ by $A S(D)=|D|+\mid$ init $(D) \mid$ where $|D|$ is the size of $D$ and $\operatorname{init}(D)$ the set of initial rules of $D$, i.e. rules that depart an initial state. With the constant $c^{\prime}=7$, we can show for all determinization free Fxp formulas $F$ that:

$$
A S\left(D_{F}(\mathcal{E})\right) \leq\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{w(F)+1}
$$

The lemma will then follow from $\left|D_{F}(\mathcal{E})\right| \leq A S\left(D_{F}(\mathcal{E})\right)$. The proof is by induction on the structure of $F$. Let $D=D_{F}(\mathcal{E})$. Let $\mathcal{E}^{\prime}$ be the extension of $\mathcal{E}$ and $F_{1}$ and possibly $F_{2}$ the subformulas of $F$, such that $D$ was constructed from $D_{1}=D_{F_{1}}\left(\mathcal{E}^{\prime}\right)$ and possibly $D_{2}=D_{F_{2}}\left(\mathcal{E}^{\prime}\right)$. We write $\omega, \omega_{1}$, and $\omega_{2}$ for the respective conjunction widths of $w(F), w\left(F_{1}\right)$, and $w\left(F_{2}\right)$, and $I, I_{1}$ and $I_{2}$ for the number of initial rules of $D, D_{1}$, and respectively $D_{2}$.
Case $F=F_{1} \wedge F_{2}$. The eNwa descriptor $D$ is the product $D_{1}$ and $D_{2}$ where $\mathcal{E}=\mathcal{E}^{\prime}$. Hence $|D|=\left|D_{1}\right|\left|D_{2}\right|$ and $I=I_{1} I_{2}$, so that:

$$
\begin{aligned}
A S(D) & \leq A S\left(D_{1}\right) A S\left(D_{2}\right) \\
& \leq\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}\left(\left|F_{2}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{2}+1} \quad \text { (ind. hypo.) } \\
& \leq\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} \cdot\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{2}+1} \\
& =\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+\omega_{2}+2} \\
& =\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega^{\omega+1}}
\end{aligned}
$$

Case $F=F_{1} \vee F_{2}$. The ENwA descriptor $D$ is the union of the ENwA descriptors $D_{1}$ and $D_{2}$ where $|\mathcal{E}|=|\mathcal{E}|^{\prime}$, so $|D|=\left|D_{1}\right|+\left|D_{2}\right|$ and $I=I_{1}+I_{2}$. It follows that $A S(D)=A S\left(D_{1}\right)+A S\left(D_{2}\right)$ and thus smaller than in the case of conjunction.
Case $F=\neg F_{1}$. Since $F$ is determinization free, $D_{1}$ describes a deterministic automaton, which furthermore can never get stuck, so that we only need to swap rejection and selection states of $D_{1}$ in order to obtain $D$. Hence, by induction hypothesis: $A S(D)=A S\left(D_{1}\right) \leq\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} \leq\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$
Case $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains neither recursive axes nor disjunctions. Since $F_{1}$ contains no nondeterministic constructs, the automaton described by $D_{1}$ will be deterministic. The ENwA described by $D$ will thus run the ENwA described by $D_{1}$ (where $\mathcal{E}=\mathcal{E}^{\prime}$ ) on all children of the marked node, until one of these runs succeeds. The rules of the head of $D_{1}$ are rewritten for recomputing the stack symbols that $D_{1}$ used at the roots of all children of the marked node, but the number of rules is not increased thereby. In addition, $c^{\prime}=7$ new rules were added for the treatment of the marked node. Therefore, $|D|=\left|D_{1}\right|+c^{\prime}$. The size of the head of $D$ is smaller than that of $D_{1}$. Hence, $A S(D) \leq c^{\prime}+A S\left(D_{1}\right) \leq c^{\prime}+\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} \leq$ $\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$.

Case $F=A\left(F_{1}\right)$ where $A \in\left\{c h^{+}, n s^{+}, f o\right\}$ or $F=c h\left(F_{1}\right)$ where $F_{1}$ contains recursive axes or disjunctions. Now $\mathcal{E}^{\prime}$ is obtained by $\mathcal{E}$ by adding at most $c^{\prime}$ new stack symbols. The ENwA descriptor $D$ has a generator state, from which it starts all initial rules $I_{1}$ of $D_{1}$, when being at an $A$-successor of the marked node. For $A=$ fo maximum $|\mathcal{E}|$ rules are added in order to find all following nodes in any future. In addition, $c^{\prime}=7$ new rules were added for the treatment of the main run of $D$. Thus, $|D| \leq\left|D_{1}\right|+I_{1}+c^{\prime}+|\mathcal{E}|$, so that:

$$
\begin{aligned}
A S(D) & =\left|D_{1}\right|+I_{1}+c^{\prime}+|\mathcal{E}| \\
& =A S\left(D_{1}\right)+c^{\prime}+|\mathcal{E}| \\
& \leq\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+c^{\prime}+|\mathcal{E}| \quad \text { (ind. hypo.) } \\
& \leq\left(\left(\left|F_{1}\right|+1\right)\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} \\
& =\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}
\end{aligned}
$$

Case $F=B\left(F_{1}\right)$. Since $F$ is simply labeled, $F_{1}$ has the form $A\left(F_{2}\right)$ or $O_{w}$ or true. Hence, descriptor $D_{1}$ for $F_{1}$ has only one initial state. The size $|D|$ of the ENWA descriptor $D$ is the size of $D_{1}$, plus $|B|$ opening rules to the initial state of $D_{1}$, with which the complement of $B$ is described (for pseudo-completeness). Hence $|D|=\left|D_{1}\right|+|B|$ and the number of initial rules $I$ of $D$ is $I_{1}+|B|$. Therefore $A S(D)=\left|D_{1}\right|+|B|+I=A S\left(D_{1}\right)-I_{1}+|B|+I_{1}+|B| \leq\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+2|B| \leq$ $\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$, since $2 \leq c^{\prime}$ and $|F|=\left|F_{1}\right|+|B|$.
Case $F=O_{w}$. The size of $D$ is the sum of at most $3 \cdot|w|$ many rules for the finite state automaton $B$ (that accepts all strings $w^{\prime}$ such that $\left(w^{\prime}, w\right)$ is in the relation induced by $O), 3 \cdot|w|$ many rules for moving in and out of copy states of $B$ as described above, and at most $c^{\prime}$ many rules for the treatment of $D$ s main run. In addition $D$ needs $2|\mathcal{E}|$ rules to close the stream in selection and rejection states. Hence the size of $D$ is smaller or equal to $6|w|+c^{\prime}+2|\mathcal{E}|$, while the head of $D$ is constant and can be bounded by $c^{\prime}$. As $|F|=|w|$ it follows that $A S(D) \leq$ $\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$.
Case $F=$ true. The size $|D|$ of the ENwA descriptor $D$ for true is 5 and contains $2|\mathcal{E}|$ many rules to close the stream. D's amortized size is thereby smaller than $\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$.

### 8.5.7 Time to Compute Automata Descriptors

Theorem 2 (Compilation time). There exist $c, c^{\prime}>0$ such that for any determinization free and simply labeled Fxp-formula $F$ and any finite set $\mathcal{E}$ of external stack symbols, the time to compute the ENWA descriptor $D_{F}(\mathcal{E})$ is at most $2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{w(F)+1}$.

Proof. We fix a set $\mathcal{E}$ and constants $c_{1}=2, c^{\prime}=7$ and $c=c_{1}+c^{\prime}=9$. We again need an amortized analysis. We define the amortized time of an ENWA descriptor $D=D_{F}(\mathcal{E})$ constructed by our algorithm as follows, where $T(D)$ is the construction
time:

$$
A T(D)=T(D)+|h(D)|+|\mathcal{E}|
$$

The proof is by induction on the structure of Fxp formulas $F$, under the assumption that they are determinization free and simply labeled. Let $F_{1}$ and possibly $F_{2}$ be the arguments of the top-level operator of $F$, and $D_{i}=D_{F_{i}}\left(\mathcal{E}^{\prime}\right)$ be the subautomata from which $D$ was constructed. We will also write $H$ for $|h(D)|, H_{i}$ for $\left|h\left(D_{i}\right)\right|$, and similarly $T$ for $T(D), T_{i}$ for $T\left(D_{i}\right)$.
Case $F=F_{1} \wedge F_{2}$. The time to compute an ENwA descriptor $D=D_{F}(\mathcal{E})$ for the product $F$ is the sum of the times for computing the ENwA descriptors $D_{1}=D_{F_{1}}(\mathcal{E})$ and $D_{2}=D_{F_{2}}(\mathcal{E})$, plus the time to compute ENwA descriptor $D$ for $F$, which can be done in time $c_{1} \cdot\left|D_{1}\right| \cdot\left|D_{2}\right|$. Hence

$$
\begin{array}{rlr}
A T(D)= & T_{1}+T_{2}+c_{1}\left|D_{1}\right|\left|D_{2}\right|+H+|\mathcal{E}| \\
\leq & A T\left(D_{1}\right)+A T\left(D_{2}\right)+c_{1}\left|D_{1}\right|\left|D_{2}\right|+H \\
\leq & A T\left(D_{1}\right)+A T\left(D_{2}\right)+\left(c_{1}+1\right)\left|D_{1}\right|\left|D_{2}\right| \\
\leq & 2 c\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+2 c\left(\left|F_{2}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{2}+1} & \\
& +\left(c_{1}+1\right)\left|D_{1}\right|\left|D_{2}\right| & \\
\leq & 2 c\left(\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+\left(\left|F_{2}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{2}+1}\right. & \left(c_{1}+1 \leq c\right) \\
& \left.+\left|D_{1}\right|\left|D_{2}\right|\right) \\
\leq & 2 c\left(\left(\left|F_{1}\right| \mid\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+\left(\left|F_{2}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{2}+1}\right. & (\text { Lemma 10 }) \\
& \left.+\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}\right)\left(\left|F_{2}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{2}+1} & \\
\leq & 2 c\left(\left(\left|F_{1}\right|+\left|F_{2}\right|\right)\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+\omega_{2}+2}\left(a^{m}+b^{n}+a^{m} b^{n} \leq(a+b)^{m+n}\right) \\
\leq & 2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1} &
\end{array}
$$

Case $F=F_{1} \vee F_{2}$. The time to compute an eNwa descriptor $D$ is the sum of the times to compute $D_{1}$ and $D_{2}$. The size of the head of $D$ is the sum of the head of $D_{1}$ and the head of $D_{2}$. Hence

$$
\begin{aligned}
A T(D) & =T+H+|\mathcal{E}|=T_{1}+T_{2}+H+|\mathcal{E}|= \\
& =A T\left(D_{1}\right)-H_{1}-|\mathcal{E}|+A T\left(D_{2}\right)-H_{2}-|\mathcal{E}|+H+|\mathcal{E}| \\
& \leq A T\left(D_{1}\right)+A T\left(D_{2}\right)
\end{aligned}
$$

and thus smaller than in the case of conjunction.
Case $F=\neg F_{1}$. Since $F$ is determinization free, $D_{1}$ describes a deterministic automaton, which furthermore can never get stuck, so that we only need to swap rejection and selection states of $D_{1}$ in order to obtain $D$. Hence, by induction hypothesis: $A T(D)=A T\left(D_{1}\right) \leq 2 c\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} \leq 2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$
Case $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains neither recursive axes nor disjunctions. Since $F_{1}$ contains no nondeterministic constructs, the automaton described by $D_{1}$ will be deterministic. The time to compute $D$ is the time to compute $D_{1}$ (where $\mathcal{E}=\mathcal{E}^{\prime}$ ), plus the time to rewrite the head of $D_{1}$ for the recomputation of stack symbols pushed at root of the children of the marked node. In addition $D$ takes time $2|\mathcal{E}|$ to delete closing stream rules for the rejection state of $D_{1}$ and to add these to the new rejection state of $D_{1}$, and time at most $c^{\prime}$ to add at most $c^{\prime}$ new
rules for the treatment of the marked node. The head of $D$ contains only 5 rules. Hence

$$
\begin{array}{rlrl}
A T(D) & =A T\left(D_{1}\right)-H_{1}-|\mathcal{E}|+H_{1}+2|\mathcal{E}|+c^{\prime}+H+|\mathcal{E}| & \\
& =A T\left(D_{1}\right)+2|\mathcal{E}|+c^{\prime}+5 & \\
& \leq 2 c\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+2|\mathcal{E}|+c^{\prime}+5 & & \\
& \leq 2 c\left(\left(\left|F_{1}\right|+1\right)\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} & & \\
& =2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1} & &
\end{array}
$$

Case $F=A\left(F_{1}\right)$ where $A \in\left\{c h^{+}, n s^{+}, f o\right\}$ or $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains recursive axes or disjunctions. The time to compute $D$ is the time to compute $D_{1}$ where $\mathcal{E}^{\prime}$ is obtained from $\mathcal{E}$ by adding at most $c^{\prime}$ new stack symbols. Furthermore $D$ needs time to compute $I_{1}$ many rules for starting the test for $F_{1}$ from $D$ s generator state, plus $|\mathcal{E}|$ closing rules to reach all following nodes of the stream for the case that $A=f o$, plus at most $c^{\prime}$ rules for the treatment of the main run. The head $H=H_{1}-I_{1}+2$, as the head of $D$ contains all closing rules of the head of $D_{1}$, but none of the initial rules belonging to the head of $D_{1}$, such that $D$ needs two new initial rules. Therefore $A T(D)=T(D)+h(D)+|\mathcal{E}|=$

$$
\begin{aligned}
A T(D) & =T_{1}+I_{1}+|\mathcal{E}|+c^{\prime}+h(D)+|\mathcal{E}| \\
& =A T\left(D_{1}\right)-H_{1}-|\mathcal{E}|+I_{1}+|\mathcal{E}|+c^{\prime}+H_{1}-I_{1}+2+|\mathcal{E}| \\
& =A T\left(D_{1}\right)+c^{\prime}+2+|\mathcal{E}|
\end{aligned}
$$

and thus smaller than in the case of $F=\operatorname{ch}\left(F_{1}\right)$ where $F_{1}$ contains no nondeterministic constructs.

Case $F=B\left(F_{1}\right)$. Since we assumed that $F$ is simply labeled, it follows that $F_{1}$ is either a comparison $O_{w}$, an axis $A\left(F_{2}\right)$, or true. In all cases, the ENwA descriptor $D_{1}$ for $F_{1}$ has only one initial state, and its head $H_{1}$ is of size at most $c^{\prime}$. Therefore the time $T$ for computing $D$ is the time to compute $D_{1}$, plus the time to intersect label properties and variable restriction in $B$ with the label descriptors of initial rules of $D_{1}$ (of which there are at most $H_{1}$ many), plus the time to add an opening rule for the initial state of $D_{1}$ to some rejection state of $D_{1}$ to describe the complement of $B$. The head of $D$ contains all rules from the head of $D_{1}$, plus $|B|$ rules for the initial state in order to maintain pseudo-completeness. Hence

$$
\begin{array}{rlrl}
A T(D) & =T+H+|\mathcal{E}|=T_{1}+c^{\prime}+|B|+H+|\mathcal{E}| & \\
& =A T\left(D_{1}\right)-H_{1}-|\mathcal{E}|+c^{\prime}+|B|+H_{1}+|B|+|\mathcal{E}| & \\
& =A T\left(D_{1}\right)+c^{\prime}+2|B| & & \\
& \leq 2 c\left(\left|F_{1}\right|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1}+c^{\prime}+2|B| & & \text { (ind. hypo.) } \\
& \leq 2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega_{1}+1} & & |F|=\left|F_{1}\right|+|B|
\end{array}
$$

Case $F=O_{w}$. The time to compute $D$ is the time to compute at most $3 \cdot|w|$ many rules for the finite state automaton $B$ (that accepts all strings $w^{\prime}$ such that $\left(w^{\prime}, w\right)$ is in the relation induced by $O$ ), the time to compute $3 \cdot|w|$ many rules for moving in and out of copy states of $B$ as described above, the time to compute at most $c^{\prime}$
many rules for the treatment of $D$ s main run, plus $2|\mathcal{E}|$ rules to close the stream in selection and rejection states. D's head contains only four rules. With $|F|=|w|$ the amortized time to compute $D$ is therefore at most $6|w|+c^{\prime}+2|\mathcal{E}|+4+|\mathcal{E}| \leq$ $2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$.

Case $F=$ true. The time to compute $D$ is the time to compute the $5+2|\mathcal{E}|$ many rules. The head of $D$ has size 3 (initial rule plus 2 closing rules in for the selection and rejection state). $D$ 's amortized time is therefore $5+2|\mathcal{E}|+3+|\mathcal{E}|=8+3|\mathcal{E}|$, which is smaller than $2 c\left(|F|\left(c^{\prime}+2|\mathcal{E}|\right)\right)^{\omega+1}$.

### 8.6 Early Query Answering

We show how to use ENWA descriptors for evaluating monadic queries on XML streams. The main idea is to generate on the fly all possible answer candidates, and to run the described ENWA on all of them in parallel in a streaming manner. The nondeterminism and the automata descriptors are resolved by on-the-fly instantiation and determinization. We then improve this streaming algorithm in an important manner, so that the stacks and states of the runs of multiple answer candidates in the same state may be shared.

### 8.6.1 On-the-fly Instantiation and Determinization

Let $D$ be a descriptor of an ENwA $E^{\prime}$ that defines a monadic query, i.e., with tag alphabet $\left\{a, a^{x} \mid a \in \Sigma\right\}$ where $x$ is a fixed variable. We are interested in running the determinization $E$ of $E^{\prime}$. This can be done while generating the needed part of $E$ from $D$ on the fly (and thus without ever constructing $E^{\prime}$ ). At any time point, we store the subset of the states and transitions of $E$ that were used before. If a missing transition rule is needed for some state $\left\{\left(q_{1}, q_{1}^{\prime}\right), \ldots,\left(q_{k}, q_{k}^{\prime}\right)\right\}$ of $E$ and some label $l$ then for each $1 \leq i \leq k$ one computes transitions of $D$ from state $q_{i}$ that describe label $l$ (if not already computed once). These transition rules are then used to compute the result state of $E$ by applying the determinization procedure. It should be noticed that each transition of $E$ can be computed in polynomial time (but not in linear time). For example, to compute a missing closing transition of the deterministic automaton by on-the-fly determinization, our algorithm needs time $O\left(|Q|^{4} \cdot|\Sigma|\right)$, where $Q$ are the states of $E^{\prime}$, see Section 2.4.4. Recall also that the states of $E$ are sets of pairs of states of $E^{\prime}$. For efficiency reasons, we will substitute such sets by integers, so that the known transitions of $E$ can be executed as efficiently as if a deterministic ENwA $E^{\prime}$ was given at beforehand. Therefore, we can safely separate the aspects of on-the-fly instantiation and determinization from what follows.

### 8.6.2 Streaming Algorithm for Deterministic ENWAs

We present a streaming algorithm that answers monadic queries defined by a deterministic eNwas $E$ in an early manner. This algorithm can then be lifted to eNwa descriptors by on-the-fly determinization and instantiation, as explained above. We will also assume that the deterministic eNwa $E$ is pseudo-complete, so that it has a unique complete run on any document.

Buffering Possibly Alive Candidates Suppose that we are given a stream containing a nested word of some data tree, and that we want to compute the answers of the query defined by $E$ on this data tree in an early manner. That is, we have to find all nodes of the data tree that can be annotated by $x$, so that $E$ can run successfully on the annotated data tree. At any event $e$ of the stream, our algorithm maintains a finite set of candidates in a so-called buffer. A candidate is a triple that contains a value for $x$, a state of $E$ that is neither a selection nor a rejection state, and a stack of $E$. The value of $x$ can either be a node opened before the current event $e$, or "unknown" which we denote by $\bullet$. At the start event, there exists only a single candidate in the buffer, which is $\left(\bullet, q_{0}, \perp\right)$ where $q_{0}$ is the unique initial state of $E$ and $\perp$ the empty stack. At any later event, there will be at most one candidate containing the $\bullet$

Lazy Candidate Generation New candidates are generated lazily under supervision of the automaton. This can happen at all opening events for which there exists a candidate with the unknown value $\bullet$ (which then is unique). Consider the <a> event of some node $\pi$ and let $(\bullet, q, S)$ be the candidate with the unknown value in the buffer at this event. The algorithm then computes the unique pair $\left(\gamma, q^{\prime}\right)$ such that $q \xrightarrow{\left\langle a^{x}\right\rangle: \gamma} q^{\prime}$ is a transition rule of $E$. If $q^{\prime}$ is a selection state, then $\pi$ is an answer of the query, so we can output $\pi$ directly. If $q^{\prime}$ is a rejection state, then $\pi$ is safe for rejection (since $E$ is deterministic), so we can ignore it. Otherwise, $\pi$ may still be alive, so we add the candidate ( $\pi, q^{\prime}, S \gamma$ ) to the buffer.

Candidate Updates At every event, all candidates in the buffer must be updated except for those that were newly created. First, the algorithm updates the configuration of the candidate by applying the rule of $E$ with the letter of the current event to the configuration of the candidate. If a selection state is reached, the node of the candidate is output and discarded from the buffer. If a rejection state is reached, the candidate is also discarded from the buffer. Otherwise, the node may still be alive, so the candidate is kept in the buffer.

Example We illustrate the basic algorithm in Figure 8.8 on the eNwa from Figure 8.3 and the suffix of the document from Figure 8.2 with the book as start node. Initially the buffer contains a single candidate with the unknown node $\bullet$, that starts in the initial state of the ENwA. According to opening tag 〈library $\rangle$ we launch the open transition and apply state and stack changes. At the opening event of node


Figure 8.8: Evolution of the buffer (a) for the ENwA from Fig. 8.3 when answering the XPATH query book[starts-with(title, 'XML')]/auth on the suffix of the data tree (b) with start node book.

3, i.e., when reading the open tag $\langle$ author $\rangle$ in state $q_{1}$, a new candidate is created. This is possible, since there exists the transition rule $q_{1} \xrightarrow{\left\langle\text { author }^{x}\right\rangle: \beta} q_{3}$ in the ENWA and since $q_{3}$ is neither a rejection nor a selection state. Similarly a new candidate will be created for node 4 at its opening event. Only after having consumed the text value of the title node 5 , a selection state is reached for the candidates with node 3 and 4, such that they can be output and removed from the buffer.

### 8.6.3 Adding Stack-and-State Sharing

For most queries of the XPathMark benchmark, the buffer will contain only 2 candidates at every event, of which one is the candidate with the unknown value -. It may happen though that the number of candidates grows linearly with the size of the document. An example is the XPATH query /child: : a [following: :b] on a document whose root has a large list of only $a$-children. There the processing time will grow quadratically in the size of the document. All candidates (of which there are $O(n)$ for documents of size $n$ ) must be touched for all following events on the stream (also $O(n)$ ). A quadratic processing time is unfeasible even for small documents of some megabytes, so this is a serious limitation.

We next propose a data structure for state and stack sharing, that allows to solve this issue. The idea is to share the work for all candidates in the same state, by letting their stacks evolve in common. Thereby the processing time per event for running the ENWA on all candidates will become linear in the number of states and stack symbols of the ENWA, instead of linear in the number of candidates in the buffer. In addition to this time per event, the algorithm must touch each candidate at most three times, once for creation, output, and deletion. We will use a directed acyclic graph (DAG) with nodes labeled in $\Gamma$ for sharing multiple stacks. For instance a DAG for stacks $\gamma_{1} \gamma_{2} \gamma_{3} \gamma_{4}$ and $\gamma_{1} \gamma_{2}^{\prime} \gamma_{3} \gamma_{4}^{\prime}$ share nodes for stack symbols $\gamma_{1}$ and $\gamma_{3}$, as depicted in Figure 8.9.

In addition, we use a table $B: Q \times \Gamma \rightarrow$ Aggreg relating a state and a root of


Figure 8.9: DAG representing stacks.
the Dag through an aggregation of candidates. Table $B$ aims at storing enough information when sharing at opening events, so that one can undo the sharing properly at closing events. Formally, Aggreg is the least set such that (1) it contains all sets of candidates, and (2) all subsets of $\{(a, \gamma) \mid a \in$ Aggreg, $\gamma \in \Gamma\}$. For instance, the Dag and its associated $B$ table at the <title>-event in Figure 8.8 is illustrated in Figure 8.10. Here we have $B\left(q_{6}, \alpha\right)=\{3,4\}$ and $B\left(q_{2}, \beta\right)=\{\bullet\}$. In this case, the aggregations are just sets of candidate nodes. In general, an aggregation contains information on how to unshare candidates related to a root in the DAG which represents more than one stack. This means one needs more information than just a set of candidates, and for this reason we introduce a nested structure. Let $B\left(q_{i}, \beta_{i}\right)=A_{i}$ for aggregations $A_{i}$ in state $q_{i}$ with stack symbol $\beta_{i}$ on top of the stack, for $1 \leq i \leq k$ (i.e. there are $k$ roots).

At an opening event the automaton may have transitions that lead into the same state $q$ pushing the same stack symbol $\beta$ for some of the states $q_{i}$, for instance $q_{2}$ and $q_{3}$. Since the corresponding aggregations $A_{2}$ and $A_{3}$ originate from different roots in the DAG, we add this information in a new aggregation $A=\left\{\left(A_{2}, \beta_{2}\right),\left(A_{3}, \beta_{3}\right)\right\}$. Consider for instance the situation depicted in Figure 8.11. From the first configuration, we reach the second with the <a>-event. There the candidate 2 is created from the -candidate whose configuration has $\beta$ on top of the stack, goes into state $q^{\prime \prime}$, and pushes $\gamma^{\prime}$. However, there is also the candidate 1 which will go into the same state $q^{\prime \prime}$ while pushing the same stack symbol $\gamma^{\prime}$, but from a configuration with $\beta^{\prime}$ on top of the stack. The pairs $(2, \beta)$ and $\left(1, \beta^{\prime}\right)$ must be stored in the aggregation, so we define $B\left(q^{\prime \prime}, \gamma^{\prime}\right)=\left\{(2, \beta),\left(1, \beta^{\prime}\right)\right\}$.

At closing events for aggregations that contain pairs $\left(A_{i}, \beta_{i}\right)$ of an aggregation $A_{i}$ and a stack symbol $\beta_{i}$, the unsharing is done by relating aggregation $A_{i}$ to the new root $\beta_{i}$ in the DaG, after closing. For instance the closing event </a> is read when moving from the second to the third situation in

Figure 8.11. There we have to undo the sharing. We decompose the aggregate and update the data structure to $B\left(q^{\prime \prime \prime}, \beta\right)=\{2\}, B\left(q^{\prime \prime \prime}, \beta^{\prime}\right)=\{1\}$ and $B(q, \beta)=$ $\{\bullet\}$.

At every time point, $B$ contains each buffered candidate exactly once. Whenever a selection state is reached in the B-table, the candidates in the aggregate of this state will be output and the aggregate will be deleted from the data structure. For rejection states, we only have to discard the aggregate. Note that rejected or selected candidates get deleted entirely from the data structure this way, since no candidate may appear twice in different aggregates, again due to determinism.


Figure 8.10: Buffer of <title>.


Figure 8.11: Data structures for the state sharing algorithm.

Proposition 9 (Time per Event). For every deterministic eNwa E defining a monadic query $P$ and data tree $t$ the time complexity per event of our query answering algorithm with stack-and-state sharing to compute $P(t)$ is in $\mathcal{O}(|Q|)$, where $Q$ is the set of states of $E$.

We can even reduce $|Q|$ to the maximal number of states per event that are assigned to the buffered candidates. This bound is at most 2 for all queries in our practical experiments. In practice, therefore, the runtime should grow linearly in the size of the document, and be independent of the size of the query. This will indeed be confirmed by the experiments in Figure 8.18, which also indicate that the costs for on-the-fly instantiation and determinization are irrelevant in practice.

Proof. We start with the case of opening events. Since $E$ is deterministic there is only one opening transition per state and label. According to the tag alphabet $\left\{a, a^{x} \mid a \in \Sigma\right\}$, the query answering algorithm has therefore two choices for opening transitions for an opening event $a$. Hence at most $2|Q|$ edges to new roots in the Dag may be added. For candidates in table $B$ additional information may have to be stored (which needs only constant time). This happens, when candidates in different states related to different roots in the Dag reach the same state at an opening event. The evolution of the DAG at opening events can therefore be done in time $\mathcal{O}(|Q|)$.

For internal events, the DAG structure is not altered. At most $|Q|$ many state changes occur in table $B$.

We finish with the case of closing events. Closing transitions are applied according to the label of the closing event $e^{\prime}$ and to table $B$, which relates states and roots of the Dag to an aggregation of candidates. At first glance it seems as there could be $|Q||\Gamma|$ (hence quadratically many) possible transitions. Nevertheless the number of possible closing transitions at $e^{\prime}$ is bounded by

1. the number of opening transitions for opening event $e$ that corresponds to $e^{\prime}$ (of which there are maximum $2|Q|$ many), plus
2. those closing transitions for potential candidates that were created between events $e$ and $e^{\prime}$.
(1) is obvious, in that at event $e$ table $B$ contained maximum $2|Q|$ entries to aggregations $C$ of candidates. As $E$ is deterministic at event $e^{\prime}$ there are thus $2|Q|$ many possibilities for these aggregations $C$ to be related with stack symbols on top of the Dag. For (2) let us consider the creation of new candidates between events $e$ and $e^{\prime}$. All these candidates were instantiated from the unique $\bullet$ candidate, such that they share parts of the stack. At the closing event all potentially created candidates therefore are related to the unique stack symbol $\gamma$ in the top of the Dag belonging to the $\bullet$ candidate. These new candidates may be in at most $|Q|$ many different states. Hence with (1) and (2) maximum $3|Q|$ closing transition may be applied. For these only a constant number of operations are needed to unshare the aggregations of candidates. Hence all together the run-time per event is in $\mathcal{O}(|Q|)$.

Theorem 3 (Time and Space). For any deterministic ENwA $E$ with state set $Q$ defining a monadic query $P$ and data tree $t$, the time complexity of our streaming algorithm with stack-and-state sharing to compute $P(t)$ is in $\mathcal{O}(|E|+|Q||t|)$ and its space complexity in $\mathcal{O}(|E|+\operatorname{depth}(t)|Q|+C)$, where $C$ is the maximal number of buffered candidates of $P$ on $t$ at any event.

Proof. By Proposition 9, the run-time per event is linear in the number of states $Q$. With the construction of $E$ we thereby obtain an overall run-time complexity which is in $\mathcal{O}(|E|+|Q||t|)$. Regarding space complexity, we have to keep $E$ in memory all the time. The maximum number of buffered candidates at any event is $C$, while the DAG data-structure uses space in $\operatorname{depth}(t)|Q|$.

As we did in the time analysis, we can reduce $|Q|$ in our space analysis to the maximal number per event of states of the buffered candidates. Therefore, we can replace $|Q|$ by 2 in our practical experiments. So if the depth of the tree is bounded in addition (which is the case in our experiments), the space requirement is determined by the maximal number of buffered candidates per event, and by the size of the automaton. This will indeed be confirmed by our experiments in Figure 8.19.

### 8.7 QuiXPath tool

We present an implementation of our algorithms in the QuiXPath system and analyze its time and space performance experimentally.

### 8.7.1 Implementation, Tools, and Applications

We have implemented QuiXPath, which inherits a library, called Fxp tool, for compiling Fxp formulas to ENwAs. QuiXPATH is a streaming query evaluator for a fragment of XPATH 3.0. The implementation consists of 3 parts. First, a streaming algorithm with stack-and-state sharing for answering eNwA queries, second, a compiler from FXP to ENWAs, and third a compiler from navigational XPath 3.0 to Fxp. All our implementation is done in Java 1.6, while relying on the free XPath parser from Saxon.

In addition to what we presented in this chapter, QuiXPATH supports arithmetics, aggregation, and data comparisons, which is implemented on basis of networks of ENwAs that we discuss in Chapter 10. Furthermore, there is a support for backwards axes, which are eliminated at the cost of forward axes and regular axes. Regular axes $P^{*}$ are supported by QuiXPATH, but only if $P$ has 0-delay. This is enough for most backwards axes in the usual benchmarks. We would also like to notice that conditional regular axes are not sufficient for eliminating general backwards axes, as proven in [Ley 2009].

All our experiments are run on a machine which features an Intel Core i72720 QM processor at $2.20 \mathrm{GHz}, 3.8 \mathrm{~GB}$ of RAM , and an SSD hard drive. The operating system is a 64-bit version of ubuntu 12.04 LTS.

### 8.7.2 Benchmarks

We will analyze the coverage and the time and space performance of QuiXPath, and compare it to other streaming XPath evaluators, such as Spex, Saxon, and Gcx. For this, we need an XPath benchmark collection, see Section 5.11, which consists of a collection of XPATH queries and a collection of documents, so that both of them can be scaled in size.

We mainly use the XPATHMARK benchmark collection ${ }^{3}$ in its revised version (and not the one from the original paper [Franceschet 2005]). These are (parametric) queries about XMARK documents that contain a table of bids and a table of bidders. The size of these documents can be scaled, basically by adding more bids and bidders. Amongst the XPathMark queries from Section 5.11 only queries A1A8, B1-B7, B11(i)-B15(i), and C2 can be answered by some of the available tools (QuiXPath, Spex, Saxon, and Gcx). With $i=1$ these are $39 \%$ of the XPathMark queries only. We added 2 further queries O 1 and O 2 to our collection, which are given in Figure 8.12. These queries do apply to the same XMark documents,

[^18]O1: /site[closed_auctions/closed_auction/type]//item
O2: /site[c or not(c)]//bidder
Figure 8.12: Additional queries for illustrating the buffering behaviour.
but illustrate a different performance behavior since requiring to buffer much more candidates.

It should be noticed that neither Saxon nor Gcx support XPath directly, but through Xslt respectively XQUery programs. Therefore we could not run the queries from the XPathMark directly, but had to embed them in an Xslt or XQuery program. This kind of rewriting is not fully trivial, if one does not want the experiments to be biased by different output modes. For Spex we used their internal output mode "count_results" and for QuiXPath we counted the materialized answer nodes. For Saxon we use a style sheet which counts the number of query answers. For GCX we were not able to count the number of answers without producing them. Therefore, we decided not to produce any output (rather than using their default output mode, which is to print the subtrees of the selected nodes).

There is a further problem when comparing to Gcx, which is that Gcx does not support XmL attributes. Since we did not want to take Gcx out of the race, we had to adapt the benchmark in the case of GCX as follows: in documents, we replaced attributes by elements, and in queries we replaced attribute axes by child axes. These adaptations are not fully neutral. Therefore, we will also compare Gcx and QuiXPath on the same documents and queries in a separate study.

### 8.7.3 Performance Comparison

In Figure 8.13 we compare the different tools for their XPath "conceptual" coverage on the XPathMark benchmark: Gcx [Schmidt 2007], LNFA [Onizuka 2010], Saxon [Kay 2010], Spex [Olteanu 2007], XMLtk [Green 2004], XSeq [Mozafari 2012], and XsQ [Peng 2005]. Only 4 tools were available for testing in practice, but we can still compare the coverage in terms of the concepts that are supported, and also in the percentage of queries that require these features. When presenting such percentages, we restrict ourselves to the XPATHMARK queries with parameter $i=1$. This is an advantage for our competitor tools, since these cannot deal with $n \geq 2$ anyway. Later on, we will also experiment with QuiXPath on queries with larger parameters $i \geq 2$ separately.

Only Gcx is able to deal with some queries with data joins such as C 2 . What is not covered by any of the tools are queries with data positions, full aggregations, and full negation. These features are used by the remaining $63 \%$ of queries of the XPathMark. Spex and QuiXPath cover mostly the same features except for top-level aggregation. Nevertheless, QuiXPath covers $37 \%$ of the XPathMark queries, while Spex can only deal with $22 \%$. The other available tools cover even fewer queries, Gcx has $19 \%$ and Saxon is at $6 \%$.

| Name | QuiXPath | Gcx | LNFA | Saxon | Spex | XMLtk | XSEQ | XSQ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Language | XPath | XQuery | XPath | Xslt | XPath | XPath | XSEQ | XPath |
| Available | yes | yes | no | yes | yes | yes | no | no |
| Coverage of XPathMark | 37\% | 19\% | 18\% | $6 \%$ | 22\% | 5\% | 7\% | 11\% |
| Downward axis | $\sim$ | $\cdots$ | $\sim$ | $*$ | $\sim$ | $\sim$ | $\cdots$ | $\sim$ |
| Complex filters | $*$ | $\checkmark$ | $\checkmark$ | $x$ | $\checkmark$ | $x$ | $x$ | $\checkmark$ |
| Backward axis | - | $x$ | $x$ | $x$ | $\checkmark$ | $x$ | $x$ | $x$ |
| Negation | - | - | $x$ | $x$ | - | $x$ | $x$ | $x$ |
| Top level aggreg. | $\cdots$ | $\checkmark$ | $x$ | $\cdots$ | $x$ | $x$ | $x$ | $\checkmark$ |
| Nested aggreg. | $x$ | $\sim$ | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ |
| Arithmetics | $x$ | $x$ | $x$ | $\cdots$ | $x$ | $x$ | $x$ | $x$ |
| 0-delay reg. axis | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | $\cdots$ | $x$ |
| Regular axis | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ |
| Join | $x$ | $\sim$ | $x$ | $x$ | $x$ | $x$ | $x$ | $x$ |
| Multi inputs | $x$ | $x$ | $x$ | $\sim$ | $x$ | $x$ | $x$ | $x$ |
| supported: $\sim$ |  | partially | pport | - | not sup | orted: | $x$ |  |

Figure 8.13: System features.

The advantage in coverage of QuiXPath over Spex is mostly due to the fact that Spex does not support all queries that are produced by backward axes elimination. Saxon's low coverage for XPath in streaming mode may be motivated by their focus on Xslt. The coverage of Gcx is lowered since it does not support backward axes. While the $37 \%$ coverage of QuiXPath on the XPathMark benchmark is better than all previous tools, a much better result of $95 \%$ is achieved by $\lambda \mathrm{XP}$.

In Figure 8.14, we compare the runtime performance of QuiXPath against Spex, Saxon, and Gcx on the benchmark queries. A negative runtime here means that the query was not supported by the respective tool. The document was fixed to a 1.1GB XMark file. Generally, QuiXPath and Gcx show very good performance, outperforming Saxon and Spex.

The parametric queries B11(i)-B15(i) cannot be treated by neither Spex nor Gcx and also stresses QuiXPath to its limits. The problem comes with backwards axes, which must be rewritten into forward axes ${ }^{4}$, such that the rewritten queries are supported by the query evaluator. Indeed, only QuiXPath is able to execute some of the rewritten queries, as we will discuss in Section 8.7.5.

In Figure 8.15 we give a more detailed comparison of the runtime performance of QuiXPath and Gcx on the same 1.2GB document without attributes with the queries adapted accordingly. It turns out that the parsing of GCX is considerably higher than that of QuiXPath which inherits the parser from Saxon, even though

[^19]

Figure 8.14: Runtime in seconds of QuiXPath, Spex, Saxon, and Gcx for the benchmark queries obtained on a 1.1GB XMark document. Whenever the query was supported, we depict a negative runtime. The runtimes were averaged over three runs, if there were no outliers (outliers were discarded).

Gcx is implemented in C++ and the others in Java. On the other hand side, the overhead of Gcx with respect to the parsing time is lower than that of QuiXPath.

### 8.7.4 Performance Analysis

In order to understand the time efficiency of QuiXPath on the different queries of the benchmark, it is essential to separate the parsing time from the time for pure query evaluation. This is relevant to all languages embedding XPath queries, since there, many XPath queries must be executed at the same time, while the document is parsed only once.

We propose to measure the parsing-free evaluation time $T_{\text {parsefree }}(P, d)$ of a query $P$ on a document $d$ as follows. We launch the query several times in parallel on the document, while parsing the document only once. When scaling the copy number, the parsing time should become irrelevant in the limit. Let $T(P, d, n)$ be the runtime that is needed to evaluate $n$ copies of $P$ in parallel on document $d$, and let $T_{\text {parse }}(d)$ be the parsing time for document $d$. We then define the parsing-free runtime $T_{\text {parsefree }}(P, d)$ of query $P$ on document $d$ as follows:

$$
T_{\text {parsefree }}(P, d)=\lim _{n \rightarrow \infty} \frac{T(P, d, n)-T_{\text {parse }}(d)}{n}
$$

The limit converged quickly for all our benchmark queries. Already for $n=10$ the difference to the previous value was less than 50 ms for a 1.1 GB XMark document. In Figure 8.16 we display the parsing-free evaluation times for all benchmark queries


Figure 8.15: Runtime comparison of Gcx and QuiXPath for Gcx compatible queries on a compatible 1.2GB XMark document.
on the 1.1 GB XMark document, and related it to the overall runtime and to the parsing time.

The result shows that parser works in parallel with the query evaluator. The reason is that the CPU can work in parallel with file accesses to the stream. However, the degree of parallelism remains quite low for QuiXPath. It should also be noticed that we were not able to compute the parsing-free evaluation time for the other tools, so that we do not know whether they exploit more parallelism or not.

Our next objective is to explain the difference in the parsing-free evaluation times for the various queries. The most relevant parameter is the workload of a query on a document, which is the number of pairs of states and non-projected events (see next paragraph), such that some buffered candidate was in this state at the event. Figure 8.17 shows that the workload correlates nicely to the parsing free evaluation time for all queries of our benchmark, except for queries that store big numbers of candidates, whose rejection or selection requires additional time.

The QuiXPath implementation supports 2 kinds of projections (on which the workload depends) while we do not consider the projection algorithms in Chapter 9 that we have added only later in $\lambda$ XP. First, if a query does not depend on text data, all text events are projected away. This is indeed the case for all queries in the benchmark except for query C 2 with data joins (that QuiXPath cannot deal with). The second kind is depth projection for queries that do not use the descendant axis, so that they consider the nodes until a certain depth only. The queries with depth projection are exactly those with the lowest parsing-free evaluation time: A7, A8, B3, B4 (depth projection at depth 4), A6, B1 (depth projection at depth 5), and A1, A4 (depth projection at depth 7). The next best queries are those with 0-delay, since this reduces the workload too: A2, A3, B2, B6, B12(1), B13(1). The next class are queries without projection, but only few buffered candidates A5, B5, B7,


Figure 8.16: Parsing-free time of QuiXPath in relation to the additional runtime for the benchmark queries on the 1.1 GB XMark document.
$\mathrm{B} 11(1), \mathrm{B} 14(1)$, and $\mathrm{B} 15(1)$. The highest parsing-free evaluation time is obtained for the queries O1 and O2, which buffer thousands of candidates for many events, but all of them in the same state.

QuiXPath scales up to large document sizes. Thanks to stack and state sharing, the runtime remains linear in the size of the document as for all benchmark queries in Figure 8.18 on larger documents ranging from 1 GB until 28 GB in size. This even holds for queries such as O 1 and O 2 , where the number of buffered candidates grows linearly. But since all of them are in the same state, the running times remain linear (and not quadratic). For document sizes greater than 17 GB the candidates needed to buffer for query O 2 did not fit into memory, such that no evaluation times could be reported.

Query O2 is the only query from our benchmark collection, where QuiXPath is not earliest. In general QuiXPath is not earliest with the presence of valid respectively unsatisfiable filters (as in the examples showing the hardness of earliest query answering [Gauwin 2011a]). It was also proven in follow-up work [Lick 2013], that our early query answering algorithm is indeed earliest for a large subset of positive XPath queries.


Figure 8.17: Workload compared to parsing-free evaluation time.

### 8.7.5 Detailed Analysis

We provide a detailed analysis of the performance of QuiXPath including measurements of its space consumption in particular.

We start with the analysis for the non-parametric XPATHMARK queries reported in Figure 8.19. The first step is to compile the XPath queries into simple Fxp formulas $F$, while eliminating backwards axes. The size of the formula and its conjunction width becomes apparent only after this precompilation phase. The maximal values are reached for the simple Fxp formula of query A8, with a size of 112 and a conjunction width of 12 . These quite large values are due to backwards axes elimination and the following rewriting into simple Fxp formulas.

The next compilation step is to convert $F$ into a descriptor of the nondeterministic eNwa. The number N of the states of this descriptor remains moderately small with at most 129 states for A8 and also the memory $\mathrm{KB}_{\text {desc }}$ for its storage with at most 1186 KB . The number $D$ of states visited by deterministic ENwA during on-the-fly instantiation and determinization also remains small with at most 127 for A8. The results confirm that the on-the-fly determinization inspects only a very small subset of the state space of the determinized automaton, and that the time required for on-the-fly instantiation and determinization ( $T_{\text {det }}$ ) can be ignored in practice. The memory $\mathrm{KB}_{\text {run }}$ needed for storing the deterministic automaton and the candidate buffer is small for all queries with few candidates with at most 672 KB for A8. It grows however linearly with the number of buffered candidates, as one can observe for queries O1 and O2.

The minimal memory required to evaluate a query in reasonable time is the sum of $\mathrm{KB}_{\text {desc }}+\mathrm{KB}_{\text {run }}+2000 \mathrm{~KB}$, where the 2 MB serve for running the java virtual maschine itself. Our runtime experiments were performed with 3 GB of memory


Figure 8.18: Runtimes of the benchmark queries for large documents.
in order to reduce overheads by repeated garbage collections. Less memory implies larger overheads. For query A1 we conducted a small experiment to estimate these overheads. We restricted the memory to $5,15,30,60$, and 120 MB and obtain as runtimes $14.0,12.7,10.7,10.4$, and 10.1 seconds respectively.

We next analyze the parametric queries B11(i)-B15(i). These contain backwards axes, which must be rewritten into forward axes. QuiXPath can do this, but the sizes of the Fxp formulas obtained by backwards axes elimination may be large, as shown in Figure 8.21. For instance, the formula for B14(4) has size 11804 and conjunction width 912. As a consequence, the corresponding eNwa descriptors will be huge, so that they quickly do no more fit into main memory (for $i \geq 5$ for all B13(i), B14(i), B15(i)), or may not leave enough space for on-the-fly determinization (for B13(4) and B15(4)).

Figure 8.20 shows the runtimes for the parametric queries that can still be evaluated by QuiXPath with 3 GB of memory. It should be noticed that the queries B11(i) are equivalent for all $i \geq 1$, and similarly for B12(i), B13(i), B14(i), and B15(i) respectively. Nevertheless, the sizes of the corresponding Fxp formulas grow with parameter $i$ and also the conjunction width (since our compiler ignores query equivalence). Despite this, our compiler produces the same ENwa descriptor for all B11(i) independently of $i$, and similarly for all B12(i), while the ENwA descriptors for B13(i), B14(i), and B15(i) do grow quickly with $i$. The surprisingly good treatment of the families B11(i) and B12(i) can be explained as follows. The Fxp formulas obtained after backward axes elimination contain conjunctions of the same filter over and over (the filter [./bidder] for B11(i) and the filter [@id] for B12(i)). The automata for such conjunctions are independent of the number of times that the filter is conjoined with itself.

The queries B13(i), B14(i), B15(i) with $i \geq 3$ illustrate that the costs of on-thefly determinization may become relevant for the runtime in extreme cases. Otherwise the runtime should be independent of the size of the ENwA descriptor, as explained earlier. In extreme cases, the deterministic automata have thousands of

|  | A1 | A2 | A3 | A4 | A5 | A6 | A7 | A8 | B1 | B2 | B3 | B4 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\|F\|$ | 25 | 13 | 17 | 31 | 24 | 34 | 37 | 115 | 43 | 41 | 19 | 19 |
| $w(F)$ | 0 | 0 | 0 | 1 | 1 | 2 | 2 | 12 | 0 | 2 | 0 | 0 |
| N | 17 | 9 | 12 | 27 | 17 | 35 | 21 | 129 | 24 | 39 | 13 | 13 |
| $\mathrm{~KB}_{\text {desc }}$ | 201 | 102 | 131 | 237 | 177 | 307 | 212 | 1186 | 276 | 411 | 136 | 141 |
| D | 14 | 10 | 14 | 27 | 23 | 32 | 23 | 127 | 14 | 49 | 16 | 15 |
| $\mathrm{~KB}_{\text {run }}$ | 192 | 232 | 256 | 256 | 224 | 256 | 552 | 672 | 192 | 384 | 192 | 192 |
| $T_{\text {det }}$ | 0.00 | 0.00 | 0.00 | 0.00 | 0.01 | 0.00 | 0.00 | 0.03 | 0.00 | 0.02 | 0.00 | 0.00 |


|  | B 5 | B 6 | B 7 | $\mathrm{~B} 11(1)$ | $\mathrm{B} 12(1)$ | $\mathrm{B} 13(1)$ | $\mathrm{B} 14(1)$ | $\mathrm{B} 15(1)$ | O 1 | O 2 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\|F\|$ | 24 | 103 | 21 | 17 | 16 | 37 | 62 | 69 | 23 | 34 |
| $w(F)$ | 1 | 4 | 1 | 1 | 0 | 2 | 0 | 3 | 1 | 2 |
| N | 13 | 58 | 15 | 12 | 10 | 32 | 33 | 34 | 25 | 18 |
| $\mathrm{~KB}_{\text {desc }}$ | 161 | 571 | 122 | 120 | 99 | 389 | 326 | 372 | 251 | 193 |
| D | 32 | 28 | 20 | 17 | 11 | 28 | 19 | 29 | 25 | 12 |
| $\mathrm{~KB}_{\text {run }}$ | 256 | 320 | 336 | 304 | 256 | 352 | 224 | 288 | 39432 | 112460 |
| $T_{\text {det }}$ | 0.00 | 0.01 | 0.00 | 0.00 | 0.00 | 0.01 | 0.00 | 0.01 | 0.00 | 0.00 |

Figure 8.19: Detailed analysis for XPathMark queries. The queries are compiled to FXP formulas $F$ of size $|F|$ and conjunction width $w(F)$. N is the number of states of the ENWA descriptor constructed for $F$ and $\mathrm{KB}_{\text {desc }}$ the size of the memory needed for its storage. D is the number of states of the deterministic ENwA constructed by on-the-fly instantiation and determinization. $\mathrm{KB}_{\text {run }}$ is the memory required at runtime for storing the deterministic ENWA and the candidate buffer, i.e., the overall memory needed is at least $\mathrm{KB}_{\text {run }}+\mathrm{KB}_{\text {desc }} . T_{\text {det }}$ is the time in seconds needed to compute all D states by on-the-fly instantiation and determinization.
states (D), each of which contains thousands of states of the nondeterministic automaton (N). This is problematic since the determinization time is not linear but highly polynomial: overall it is in time $\mathcal{O}\left(D N^{4}|\Sigma|\right)$. Indeed, the overall time for on-the fly determinization ( $T_{\text {det }}$ ) grows importantly in these cases. Furthermore, the backward axes elimination for $\mathrm{B} 13(\mathrm{i})$, $\mathrm{B} 14(\mathrm{i})$, and $\mathrm{B} 15(\mathrm{i})$ produces Fxp formulas with many disjunctions, so that the candidates admit almost all of the N states of the nondeterministic ENwA. For this reason, the on-the-fly determinization requires high memory costs in these cases (included in $\mathrm{KB}_{\text {run }}$ ), raising out-of-memory errors for B13(4) and B15(4).


Figure 8.20: Runtime for parametric queries B11(i)-B15(i) of the XPathMark queryset on a 1.1 GB XMark document. When for some parameter $i$ no runtime is displayed, then the corresponding ENWA descriptor did not fit into memory (for B14(5)) or it could not be evaluated on-the-fly (for B13(4) and B15(4)).

|  | $\mathrm{B} 13(1)$ | $\mathrm{B} 13(2)$ | $\mathrm{B} 13(3)$ | $\mathrm{B} 14(1)$ | $\mathrm{B} 14(2)$ | $\mathrm{B} 14(3)$ | $\mathrm{B} 14(4)$ | $\mathrm{B} 15(1)$ | $\mathrm{B} 15(2)$ | $\mathrm{B} 15(3)$ |  |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\|F\|$ | 37 | 173 | 863 | 62 | 374 | 2116 | 11804 | 69 | 527 | 4149 |  |
| $w(F)$ | 2 | 10 | 56 | 0 | 16 | 136 | 912 | 3 | 32 | 299 |  |
| N | 32 | 325 | 4273 | 33 | 237 | 1959 | 17611 | 34 | 347 | 4294 |  |
| $\mathrm{~KB}_{\text {desc }}$ | 389 | 4896 | 76514 | 326 | 2560 | 22291 | 230733 | 372 | 4448 | 64 | 098 |
| D | 14 | 120 | 503 | 19 | 29 | 36 | 43 | 29 | 136 | 2625 |  |
| $\mathrm{~KB}_{\text {run }}$ | 352 | 1683 | 32747 | 224 | 384 | 1821 | 16868 | 288 | 1448 | 394 | 780 |
| $T_{\text {det }}$ | 0.01 | 0.76 | 113.02 | 0.00 | 0.02 | 1.13 | 21.05 | 0.00 | 0.54 | 971.88 |  |

Figure 8.21: Detailed analysis for the parametric queries B13(i)-B15(i). The backward axes elimination of QuiXPath infers a Fxp formula $F$ of size $|F|$ and conjunction width $w(F)$ up to 912 ! The Fxp formulas are then compiled into ENwA descriptors with N states, which can be stored in a memory of size $\mathrm{KB}_{\text {desc }}$. On-thefly instantiation and determinization yields a deterministic ENWA of which D states are visited. The memory for storing this deterministic automaton and the canidate buffer is $\mathrm{KB}_{\text {run }} . T_{d e t}$ is the time in seconds needed for on-the-fly instantiation and determinization.

## Chapter 9

## Projection

## Contents

9.1 Introduction . . . . . . . . . . . . . . . . . . . . . . . . . . . . 1539.2 A Nested Word Automaton154
9.3 Projection NWAs ..... 155
9.3.1 Projected Nested Words ..... 155
9.3.2 Projection Nested Word Automata ..... 156
9.3.3 Examples of PNwas and Runs ..... 158
9.3.4 Evaluation of Projection Nwas ..... 159
9.4 Irrelevant Labels and Prefixes of Nested Words ..... 160
9.5 Projection from Nwas to PNwas ..... 162
9.6 Node Selection ..... 164
9.7 Experiments ..... 166

In this chapter we develop projection algorithms for nested word automata. Our algorithms translate nested word automata to projection nested word automata that we introduce. They are a kind of mixed pushdown and counting automata. The projection nested word automata is then evaluated over a stream producing a projected nested word on which it runs. Our experiments show that we gain a speed up of a factor of 4 in parsing-free time with respect to our query answering algorithm for navigational XPATH queries by early nested word automata.

### 9.1 Introduction

Projection is most relevant for efficient Xml processing algorithms, as shown for in-memory evaluators for XQuery in [Marian 2003] and for a fragment of XPath in [Maneth 2010]. The projection algorithm for XQuery runs in Saxon [Kay 2004], today's most used Xml processing tool.

The objective of this chapter is to initiate the development of projection algorithms for processing Xml streams. Given that a single program written in one of the Xml standards XQuery, Xslt, or XProc contains a collection of XPath queries, we are interested in the evaluation of a collection of XPAth queries on a single input stream. The parsing time can be shared between many XPath queries, and thus should be counted seperately. Therefore, we are mainly interested in the
parsing-free time for query evaluation. Note however, that the parsing-free time for a single query is often dominated by the parsing time.

We will restrict ourselves to projection for navigational XPATH queries, since these are fundamental to all others. For instance, in order to check whether the root of a tree has at least $5 a$-children, all other children of the root can be projected. The computation of the projection still requires to read the entire input tree, but the time for this can be shared similarly to the parsing time. As discussed before in Chapter 8, navigational XPAth queries are reduced to running an NwA on all possible answer candidates.

Projection for finite automata is well known [Frisch 2004, Maneth 2010]. It amounts to project away all letters of the input word that do not change the state. Projection for Nwas is more tedious, since such automata have a stack by which they can pass information from opening tags to corresponding closing tags. Therefore, one cannot simply project an opening tag away without taking care of the corresponding closing tag. Our idea is that a projected nested word should contain jump symbols . $\stackrel{i}{ }$. for projected factors, where the integer $i$ stands for the excess of the factor, i.e., the difference between the number of opening and closing tags. We present projection nested word automata (PNWAS), a kind of mixed pushdown and counting automata, that input projected nested words which beside others contain integers as letters. These integers allow the automaton to compute the depth of the current node of the tree at any time, and also the excess of the last jump. Conversely, a projection of a nested word with respect to a given NwA can be computed by any corresponding PNwA. It may be surprising, but it turns out there may exist different PNwas with maximal projection for the same Nwa. Therefore, our projection algorithm has to make its choices.

We then lift Nwa projection to the evaluation of navigational XPath queries on Xml streams. It turns out that the parsing-free time for our query answering algorithm of Chapter 8 is reduced by a factor of 4 on average on the usual XPathMark benchmark.

### 9.2 A Nested Word Automaton

Let $\Sigma$ be a finite alphabet. Let $P_{\Sigma}$ be the set of parenthesis with labels in $\Sigma$, that is the set of opening tags $\langle a\rangle$ and closing tags $\langle/ a\rangle$ where $a \in \Sigma$. We consider complete nested words over $P_{\Sigma}$, such that corresponding opening and closing tags have the same label. Furthermore we omit internal letters $\Delta$ for what follows. As a result XmL data trees and their linearizations contain no data values, which is a strong simplification. However the treatment of data values works orthogonal to the treatment of element nodes, since they can be encoded into elements.

Let us consider the unranked tree in Figure 9.1. The Xml stream obtained by linearizing this unranked tree into a complete nested word is given in Figure 9.2. A deterministic Nwa that accepts the nested word is given in Figure 9.3. It defines the XPath filter [//a/b] which accepts all XmL trees that contain some


Figure 9.1: An unranked tree.


Figure 9.2: The corresponding nested word is an Xml stream.
$a$-descendant with a $b$-child. Rules containing label sets represent sets of rules, one for each label.

### 9.3 Projection NWAs

We next introduce projected nested words. Let $\mathbb{N}_{0}=\mathbb{N} \uplus\{0\}$ be the by 0 extended set of natural numbers, and $\mathbb{Z}$ the set of integers. For any unranked tree, we are interested in the binary node relations child $c h$, descendant $c h^{+}, n$-th grand parents $c h^{-n}$ where $n \in \mathbb{N}$, descendants of $n$-th grand parents $c h^{-n} / c h^{+}$, children of $n$-th grand parents $c h^{-n} / c h$, and stay at self. So let:

$$
\text { Rels }=\left\{c h, c h^{+}, c h^{-n}, c h^{-n} / c h^{+}, c h^{-n} / c h, \text { self } \mid n \in \mathbb{N}\right\} .
$$

### 9.3.1 Projected Nested Words

A projected nested word is a word whose letters are jump symbols . ${ }^{i}$. where $i \in \mathbb{Z}$ and jump targets $p @ r$ where $p \in P_{\Sigma}$ and $r \in$ Rels. We write $P_{\Sigma} \dddot{ }$ for the set of all these letters. We assume that any jump target is proceeded by a jump symbol that indicates the excess of the jump, that is the depth difference in the tree or equivalently, the difference of the numbers of opening and closing tags in the complete nested word. We also assume that projected nested words are well-nested up to jumping.

Two examples for projected nested words are given in Figure 9.4. Both are valid descriptions of the nested word in Figure 9.2: $p w_{1}$ projects to the letters drawn in blue, while $\underline{p w_{2}}$ projects to the letters drawn in green. As we will see,


Figure 9.3: A deterministic Nwa over $\Sigma=\{a, b, c\}$ for XPath filter [//a/b].
$p w_{1}$ : for all $a$-nodes without an $a$-parent and all non- $a$-children of $a$-nodes keep the opening and closing tags, until the opening tag of the first match of $/ / \mathrm{a} / \mathrm{b}$ :

$$
\begin{aligned}
& \langle\mathbf{c}\rangle .{ }^{0} .\langle\mathbf{a}\rangle @ c h^{+} .{ }^{2} .\langle\mathbf{c}\rangle @ c h^{+} .{ }^{0} . \quad\langle/ \mathbf{c}\rangle @ s e l f . .^{2} .\langle\mathbf{c}\rangle @ c h^{-3} / \mathrm{ch}^{+} \\
& .0 .\langle\mathbf{a}\rangle @ c h^{+} .0 .\langle/ \mathbf{a}\rangle @ s e l f .0 .\langle/ \mathbf{c}\rangle @ c h^{-1} .0 .\langle\mathbf{b}\rangle @ c h^{-1} / c h^{+}
\end{aligned}
$$

$p w_{2}$ : for all $a$-nodes and all $b$-children of $a$-nodes keep the opening and closing tags, until the opening tag of the first match of $/ / \mathrm{a} / \mathrm{b}$ :

$$
\begin{aligned}
& .0 .\langle/ a\rangle @ c h^{-1} . \frac{1}{2}\langle\mathbf{a}\rangle @ c h^{-1} / c h^{+} . .0 .\langle/ \mathbf{a}\rangle @ s e l f .-1 .\langle\mathbf{b}\rangle @ c h^{-2} / c h
\end{aligned}
$$

Figure 9.4: Two projected nested words describing the nested word in Figure 9.2.
both projections can be obtained from the Nwa in Figure 9.3. Note that the initial opening tag is always kept for technical reasons. Except of this, both projections are maximal, in that no further tags can be projected away: they just preserve enough information for deciding whether the original nested word satisfies the filter [//a/b]. Nevertheless, none of these two projections is more general than the other. The green projection $p w_{2}$ has the advantage to keep only tags with letters occurring in the XPath filter $[/ / \mathrm{a} / \mathrm{b}]$. The blue projection $p w_{1}$, has the advantage to keep fewer of these tags, but therefore, it also keeps some others.

The blue projection $p w_{1}$ starts with $\langle\mathbf{c}\rangle$, meaning that any matching nested word must start with $\langle c\rangle$. The next factor $.0 .\langle\mathbf{a}\rangle @ c h^{+}$describes a nested word with excess 0 that is followed by $\langle a\rangle$ in descendant position, i.e., by the opening tag of an $a$-child of the root. The next factor ..2. $\langle\mathbf{c}\rangle @ c h^{+}$describes a nested word with excess 2 followed by $\langle c\rangle$ opening a descendant. Then $.0 .\langle/ \mathbf{c}\rangle @$ self requires to jump with excess 0 to the closing tag $\langle/ c\rangle$ of the same node. Next, $.^{-2}\langle\mathbf{c}\rangle @ c h^{-3} / c h^{+}$asks to jump with excess -2 to an opening tag $\langle c\rangle$ of a descendant of a grand-grand-grand-parent, etc.

### 9.3.2 Projection Nested Word Automata

We introduce PNwas as a mixture of a pushdown and a counting automaton, that receive projected nested words as input. The counting serves for updating the depths of nodes when jumping, so that the depth of the current node can always
be deduced from the current stack. Whenever jumping over a projected factor, the excess of this factor is pushed. This is an integer that is popped when trying to close the jump.

Definition 14. $A$ PNwA is a tuple $A=\left(\Sigma, Q, Q_{I}, Q_{F}, \Gamma, R\right)$ like an NwA but with different kinds of transition rules: given $a \in \Sigma, \gamma \in \Gamma$, and $q, q^{\prime} \in Q$, there are rules of the following types in $R$, for changing the state from $q$ to $q^{\prime}$.

Open: $q \xrightarrow{\langle a\rangle \downarrow \gamma} q^{\prime}$ Like for NWAs.
Close: $q \xrightarrow{\langle/ a\rangle \uparrow \gamma} q^{\prime}$. Like for NWAs.
Jump to a child or a descendant: $q \xrightarrow[\forall z \geq 0]{\stackrel{z}{z}\langle a\rangle @ r \downarrow z \downarrow \gamma} q^{\prime}$, where $r \in\left\{c h, c h^{+}\right\}$.
When $r=$ ch then $z$ must be 0, and we jump to the opening tag of an a-child and push first 0 and then $\gamma$ onto the stack. When $r=c h^{+}$then we jump over $z$ descendants to the opening tag of an a-descendant, and push first $z$ and then $\gamma$ onto the stack. For short we denote this transition as $q \xrightarrow{j u(\langle a\rangle, r, \gamma)} q^{\prime}$.

Rejump to another child or descendant: $q \frac{\tilde{z}\langle a\rangle @ c h^{-\left(z^{\prime}+1\right)} / r \uparrow z^{\prime} \downarrow z+z^{\prime} \downarrow \gamma}{\forall z, z^{\prime} . z^{\prime} \geq 0, z+z^{\prime} \geq 0} q^{\prime}$, where $r \in\left\{c h, c h^{+}\right\}$.

While trying to close a jump from some grand parent to some node one can rejump to another opening a-tag of a child or a descendant of the same grand parent. The excess of the jump to the first node $z^{\prime}$ on the stack is updated to the excess of the second node $z+z^{\prime}$. Furthermore, $\gamma$ is pushed. For short, we write this transition as $q \xrightarrow{r e j u(\langle a\rangle, r, \gamma)} q^{\prime}$.
 ing tag of the self $a$-node. In this case, $\gamma$ is popped from the stack.
 a jump, one may jump back to the closing tag of the a-node where the current jump started. The excess of $-z$ is popped from the stack together with the symbol $\gamma$ which was pushed for the non-jumped a-node. For short we write $q \xrightarrow{j u-b a c k(\langle/ a\rangle, \gamma)} q^{\prime}$.

Close last jump step: $q \xrightarrow[\forall z>0]{\langle/ a\rangle \uparrow z \downarrow z-1} q^{\prime}$. When trying to close a jump, one may read a closing a-tag for which the corresponding opening a-tag was jumped, so that no stack symbol was pushed. In this case the excess of the jump on the stack must be updated from $z$ to $z-1$.

A configuration of a PNwA is a pair in $Q \times\left(\Gamma \uplus \mathbb{N}_{0}\right)^{*}$ consisting of a state in $Q$ and a stack in $\left(\Gamma \uplus \mathbb{N}_{0}\right)^{*}$. A run $r$ of a PNwA $A$ on a projected nested word over $\Sigma$ is a function that maps any prefix of the projected nested word to a configuration. The run must start in some configuration with some initial state and the empty


Figure 9.5: PNwA $\mathbf{A}_{1}$ for the XPath filter [//a/b].


Figure 9.6: A successful run of the PNwa $\mathbf{A}_{1}$ of Figure 9.5 on $p w_{1}$.
stack, i.e., $r(\varepsilon) \in Q_{I} \times\left(\Gamma \uplus \mathbb{N}_{0}\right)^{*}$. Furthermore, for any prefix $w l$ where $l \in P_{\check{\Sigma}}$, the configuration $r(w)$ must be transformed into $r(w l)$ by applying some rule consuming letter $l$. A run on a projected nested word $w$ is called successful if it eventually reaches a configuration with a final state, i.e., if $r\left(w^{\prime}\right) \in Q_{F} \times\left(\Gamma \uplus \mathbb{N}_{0}\right)^{*}$ for some prefix $w^{\prime}$ of $w$. The language $\mathcal{L}(A)$ of a PNwA $A$ is the set of all projected nested words that permit a successful run on $A$.

### 9.3.3 Examples of PNwas and Runs

First Projection. In Figure 9.5 we present PNwa $\mathbf{A}_{1}$ that is a projection of the Nwa in Figure 9.3 for the XPath filter [//a/b]. This automaton accepts the blue projection $p w_{1}$ in Figure 9.4 of the nested word in Figure 9.2. Automaton $\mathbf{A}_{1}$ visits the opening and closing tags of all $a$-nodes with no $a$-parent, and of all non- $a$ children of these $a$-nodes, and jumps over all other nodes. Automaton $\mathbf{A}_{1}$ accepts when the first match of $[/ / \mathrm{a} / \mathrm{b}]$ arrives. In Figure 9.6, we illustrate a successful
run of $\mathbf{A}_{1}$ on $p w_{1}$. The states of configurations are placed below the tags, while the stack consists of the labels on the subedges above the state. Edges between tags indicate their correspondence. Furthermore there are edges for jumps to children and descendants, where the excess is pushed, while jumps to the jump origin close the jump, and rejumps update the excess on the stack. The only exceptions are jumps to the closing tag of self nodes, where no excess is pushed. In general PNwa $\mathbf{A}_{1}$ works as follows. It starts in the initial state $q_{1}$, it opens the root and goes into $q_{2}$, where either the root can be closed to $q_{\text {rej }}$ or where it can jump over $b$ and $c$ nodes to the opening tag of an $a$-descendant and go to $q_{3}$. There are 3 possibilities depending on what happens first: (1) close the $a$-node, and go to $q_{2}\left[q_{2}\right],(2)$ jump down over a sequence of $a$-nodes to the opening tag of a $c$-descendant and go to $q_{2}$, or (3) jump down over a sequence of $a$-nodes to the opening tag of a $b$-descendant and accept in $q_{4}$. In state $q_{2}$ a $c$-node with a sequence of $a$-grand parents can be closed to $q_{3}\left[q_{3}\right]$. The sequence of $a$-grand parents consists of a sequence of jumped $a$-nodes and one not jumped $a$-node $\pi$ at the top. Continuing depending on what comes first, the following can happen in $q_{3}\left[q_{3}\right]$ : (1) jump back to the closing tag of the $a$-grand parent $\pi$ and go to $q_{2}\left[q_{2}\right]$, (2) rejump over a sequence of $a$-nodes, while staying below $\pi$, to the opening tag of a $c$-descendant and go to $q_{2}$, or (3) rejump over a sequence of $a$-nodes, while staying below $\pi$, to the opening tag of a $b$-descendant, and accept in state $q_{4}$. In state $q_{2}\left[q_{2}\right]$ there are 3 possibilities depending on what happens first: (1) rejump over a sequence of $b$ and $c$ nodes to the opening tag of an $a$-descendant and goto $q_{3}$, while staying below a not-jumped $c$-grand parent with a sequence of $a$-grand parents if exists, (2) jump back to the closing tag of a not-jumped $c$-grand parent with the $a$-grand parents sequence if exists, or else (3) close the root to $q_{r e j}$.

Second Projection. A second projection of the Nwa from Figure 9.3 is given by the PNwa $A_{2}$ in Figure 9.7. This one accepts the green projection $p w_{2}$ in Figure 9.4. A successful run of $\underline{A}_{2}$ on $p w_{2}$ from Figure 9.4 is illustrated in Figure 9.8.

Recomputing Stack Symbols. We give an PNwa that contains rules to recompute stack symbols. In Figure 9.9 we give a deterministic Nwa for XPath filter [//a/following-sibling::b]. A PNwA $A_{3}$ for the same query is depicted in Figure 9.13. A successful run of $\mathrm{A}_{3}$ on projected nested word $p w_{3}$ from Figure 9.12 is illustrated in Figure 9.14.

### 9.3.4 Evaluation of Projection Nwas

Next we are interested to evaluate a collection of PNwAS obtained from deterministic Nwas on a single complete nested word. For this, we need to project the nested word with respect to the PNwas, and run the PNwas on the respective projected nested word. Therefore, we have to define how to project a nested word $w$ with respect to a deterministic PNwA. More generally, we define a projection $\pi_{q}(w)$ for


Figure 9.7: PNwa $A_{2}$ for the XPath filter [//a/b].


Figure 9.8: A successful run of the PNwA $A_{2}$ of Figure 9.7 on $p w_{2}$.
any suffix $w$ of some nested word in $P_{\Sigma}^{*}$ and state $q$ of a PNwA $A$ :

$$
\pi_{q}(w)=. i . p @ r \pi_{q^{\prime}}\left(w^{\prime \prime}\right)
$$

such that $w=w^{\prime} p w^{\prime \prime}$ for some $p \in P_{\Sigma}$ and $w^{\prime}, w^{\prime \prime} \in P_{\Sigma}^{*}$, where $w^{\prime}$ is the shortest prefix, so that there exists a rule of $A$ from $q$ to $q^{\prime}$ consuming letter $p @ r$ for some $r \in$ Rels, and $i$ is the excess of $w^{\prime}$.

### 9.4 Irrelevant Labels and Prefixes of Nested Words

In this section, we define properties of Nwa states which allow to skip parenthesis with irrelevant labels and irrelevant prefixes of nested words, that is prefixes of linearizations of subtrees.

Definition 15. An Nwa $E$ can jump over parenthesis with labels in $L$ and incoming state $q$ - in formulas $q \in$ irrel $_{L}$ - if there exists a stack symbol $\gamma$, such that $E$ has all transitions shown in Figure 9.15, no other opening transition pushing $\gamma$, no other $L$-opening transition in $q$, and no other $L$-closing transition with $\gamma$ in $q$.


Figure 9.9: A deterministic NwA over $\Sigma=\{a, b, c\}$ for XPath filter [//a/following-sibling::b].

If $q \in \operatorname{irrel}_{L}$ then any sequence of letters in $P_{L}$ is irrelevant in state $q$, so that it can be removed from the nested word and replaced by a jump symbol. Consider a run of $E$ on a nested word $w$ and assume $q \in \operatorname{irrel}_{L}$. We next argue, that we can replace all letters in $P_{L}$ of $w$ with ingoing state $q$ by jump symbols, while "repairing" the run. The first point is that the state is not changed when reading such letters, so that their removal keeps the states correct. But we must also take care of the stack. If an opening tag $\langle a\rangle$ is removed but not the corresponding closing tag, then we have to repair the run, in order to be able to reproduce the missing stack symbol when needed. The idea is to memoize the state before jumping. Since this state does not change while jumping, one can then recompute the stack symbol that was pushed for any letter that was jumped over. Conversely, it is not possible that a closing tag $\langle/ a\rangle$ was removed but not the corresponding opening tag, since the symbol pushed at $\langle a\rangle$ must be $\gamma$, and by definition of $q \in \operatorname{irrel}_{L}$ there is no other opening transition pushing $\gamma$ than that started in $q$.

Definition 16. An NwA $E$ in state $q$ can jump over prefixes of nested words (subtrees) that start in $\langle L\rangle$, do not contain letters in $P_{L^{\prime}}$, and either end with the closing tag of the subtree's root or with a letter in $L^{\prime}$, if there exist three different stack symbols $\gamma, \gamma^{\prime}, \gamma^{\prime \prime}$ and a state $q^{\prime}$ such that the transitions shown in Figure 9.16 exist, but no further opening transitions with $\gamma$, no further transitions with $\gamma^{\prime}$, and no further opening transitions in $q^{\prime}$ for $L^{\prime}$, and no further closing transition in $q$ for $L$ popping $\gamma$. In this case, we write $q \in i$-tree ${ }_{L \backslash L^{\prime}}$ and call $q$ a state of irrelevant subtrees.

In the easiest case where $q \in i$-tree ${ }_{L \backslash \emptyset}$ one can jump over nested words linearizing subtrees, with incoming state $q$ and labels in $L$ only. When opening the root of the subtree, the state changes to $q^{\prime}$ and stays there until closing the root and going back to $q$. So the removal of the subtree does not change the state globally. In this case, the full nested word of the subtree is read, so the stack difference is zero. In the case where $L^{\prime} \neq \emptyset$ it is more tricky to repair the run, in order to deal with missing stack symbols. But it remains possible, since the state used within the subtree does


Figure 9.10: Another unranked tree.

$$
\langle\mathbf{b}\rangle\langle c\rangle\langle\mathbf{a}\rangle\langle b\rangle\langle c\rangle\langle\mathbf{a}\rangle\langle\mathbf{a}\rangle\langle/ \mathbf{a}\rangle\langle/ \mathbf{a}\rangle\langle/ \mathbf{c}\rangle\langle/ b\rangle\langle/ \mathbf{a}\rangle\langle\mathbf{b}\rangle\langle/ b\rangle\langle/ c\rangle\langle/ b\rangle
$$

Figure 9.11: The nested word that corresponds to the unranked tree in Figure 9.10.

$$
\begin{gathered}
\langle\mathbf{b}\rangle . \frac{1}{.}\langle\mathrm{a}\rangle @ c h^{+} .2 .\langle\mathrm{a}\rangle @ c h^{+} .0 .\langle\mathrm{a}\rangle @ c h^{+} . . .\langle/ \mathrm{a}\rangle @ \text { self } \\
.9 .\langle/ \mathrm{a}\rangle @ c h^{-1}\langle/ \mathrm{c}\rangle .0 .\langle/ \mathrm{a}\rangle @ c h^{-2}\langle\mathrm{~b}\rangle
\end{gathered}
$$

Figure 9.12: Projected nested word $p w_{3}$ describing the nested word in Figure 9.11.
not change, so that it can be memoized and so that missing stack symbols can be recomputed at closing time.

For illustration, we have annotated the state of the Nwa in Figure 9.3 with the properties that they satisfy. It turns out that state $q_{3}$ satisfies both properties $\operatorname{irrel}_{\{a\}}$ and $i$-tree ${ }_{\{c\} \backslash\{a\}}$, but that we cannot perform the two corresponding projections at the same time. When choosing projection with irrel $_{\{a\}}$ we obtain the PNwA $\mathbf{A}_{1}$ from Figure 9.5, and when choosing projection with $i$-tree $\}_{\{c\} \backslash\{a\}}$ we obtain the second projection PNwA $\underline{A}_{2}$ from Figure 9.7.

### 9.5 Projection from Nwas to PNwas

We show how to project deterministic Nwas $E$ to a PNwa $A$. For any state $q$ of $E$, we chose a projection property choice $(p)$, which is either irrel $_{L}$ or $i$-tree ${ }_{L \backslash L^{\prime}}$ for some sets $L, L^{\prime} \subseteq \Sigma$. Note that irrel $_{\emptyset}$ can always be assigned, so that this assumption can always be satisfied, but not always in a unique manner.

Any state of $A$ is either a state of $q$ of $E$ or a pair of states of $E$ that we write as $q\left[q^{\prime}\right]$. Such a pair means that one is in state $q$ and that on the top of the stack is a jump symbol $i$ that was pushed from a jump over $i$ descendants that started in state $q^{\prime}$. Any stack symbol of $A$ is either a stack symbol $\gamma$ of $E$ or a pair written as $\gamma[q]$ of a stack symbol and a state of $E . \gamma$ serves as the stack symbol that was pushed before at opening tags, while $q$ is the state where a previous jump started. Whenever such a pair $\gamma[q]$ is on the stack then the symbol below is always a jump


Figure 9.13: PNwa $\mathrm{A}_{3}$ for the XPath filter [//a/following-sibling::b].


Figure 9.14: A successful run of the PNwA $\mathrm{A}_{3}$ of Figure 9.7 on $p w_{3}$ from Figure 9.12.
symbol $i$ that was pushed by a jump over $i$ descendants that started in state $q$. The sets of initial and final states remain unchanged.

Every transition rule of $E$ gives rise to a possible empty set of transition rules of $A$, according to rules I-VII in Figure 9.17. In PNwa $\mathbf{A}_{1}$ from Figure 9.5 we annotated transitions accordingly. Transitions from an initial state are translated to non-jumping transitions that open the root. If $\operatorname{choice}(q)=\operatorname{irrel}_{L}$, then all looping transitions required by $\mathrm{irrel}_{L}$ are removed. The other opening transitions starting from $q$ are translated to jumping and rejumping transitions to descendants and descendants of grand parents. If $\operatorname{choice}(q)=i$-tree ${ }_{L \backslash \emptyset}$ then the opening and closing $L$ transitions, and looping transitions required by $i$-tree ${ }_{L \backslash \emptyset}$ are removed. The other opening transitions starting from $q$ are translated to jumping and rejumping rules to children and children of grand parents. If choice $(q)=i$-tree $L_{L \rightarrow L^{\prime}}$ then the opening and closing $L$ transitions, and looping transitions required by $i$-tree $L_{L \rightarrow L^{\prime}}$ are


Figure 9.15: $q \in$ irrel $_{L}$.


Figure 9.16: $q \in i$-tree ${ }_{L \backslash L^{\prime}}$.
removed. All other transitions with opening tag $a \in L^{\prime}$ departing $q$ are translated to jumping and rejumping rules for descendants. Closing transitions are translated to six rules: Two rules to close self nodes, two rules to jump back to jump's origins, and two last rules that close parents in a state $q\left[q^{\prime \prime}\right]$ for $q \neq q^{\prime \prime}$. Those states do not allow to rejump, since the previous jump started in a different state $q^{\prime \prime}$ than the current state $q$, and therefore they also do not allow to jump back to the jump's origin. For these states opening and closing transitions are translated as indicated, while recomputing stack symbols, that have not been pushed for jumped grand parents.

Proposition 10 (Soundness). Let $E$ be a deterministic NwA $E$ with initial state $q_{0}$ and $A$ be a PNwA obtained from $E$ by our projection algorithm. It then holds for any nested word $w$ that $w \in \mathcal{L}(E)$ if and only if $\pi_{q_{0}}(w) \in \mathcal{L}(A)$.

### 9.6 Node Selection

Node selection as needed for typical XPath queries requires some extensions to what we have presented so far, which we will discuss in the following.

Let us consider the unranked tree with the corresponding nested word in Figure 9.18. The tree represents an XmL library, in which a single node has a label which is annotated by a fixed variable $x$, meaning that this node is to be tested for selection by an Nwa that answers a given XPath query. Such $x$-annotations can be computed in streaming mode as discussed in Chapter 8.

The Nwa in Figure 9.19 defines the XPath query library/book/title, which selects all title-nodes in a tree, whose parent is a book-node, and whose grand parent is the library-root. It accepts the nested word of Figure 9.18, where the title tag is annotated, and thereby selects the corresponding title node in the library without the $x$ annotation. For sake of completeness, we assume a sink state $q_{r e j}$ in the NwAs, which allows for early rejection: whenever reached by a deterministic NwA

I: q) $\left.\xrightarrow{\langle a\rangle \downarrow \alpha} q^{\prime}\right) \xrightarrow{\left.q \in Q_{I} \quad \text { q) } \xrightarrow{\langle a\rangle \downarrow \alpha} q^{\prime}\right)}$

II: (q) $\xrightarrow{\langle a\rangle \downarrow \alpha}\left(q^{\prime}\right.$

$$
\begin{aligned}
& a \notin L \neq \emptyset, q \notin Q_{I} \\
& \xrightarrow[{(q[q]})]{\text { (q)- }} \underset{\text { reju }\left(\langle a\rangle, c h^{+}, \alpha[q]\right)}{j u\left(\langle a\rangle, c h^{+}, \alpha[q]\right)} \rightarrow q^{\prime}
\end{aligned}
$$

III: (q) $\xrightarrow{\langle a\rangle \downarrow \alpha} q^{\prime}$
$a \notin L \neq \emptyset, q \notin Q_{I}$
$\operatorname{choice}(q)=i$-tree $_{L \backslash \emptyset}$
or choice $(q)=$ irrel $_{\emptyset}$


$\mathrm{V}:$ (q) $\xrightarrow{\langle/ a\rangle \uparrow \alpha} q^{\prime} \xrightarrow{q \neq q^{\prime \prime}}$



Figure 9.17: Rewriting system for rules of a deterministic NwA to rules of the PNwA.
the run will fail on the completed tree. Transitions with annotated labels going to $q_{\text {rej }}$ allow then to reject candidates that will fail early.

Due to the alphabet with annotated labels $\Sigma=\left\{a, a^{x} \mid a \in \Sigma^{n o-v a r}\right\}$, where $\Sigma^{n o-v a r}$ is a signature without variable annotations, we need to adapt Definitions 15 and 16 of Section 9.4.

Definition 15 becomes
Definition 17. An NWA $E$ can jump over parenthesis with labels in $L \subseteq \Sigma^{\text {no-var }}$ and incoming state $q$, if there exists a stack symbol $\gamma$ and a sink state $q_{r e j}$, such that $E$ has all transitions shown in Figure 9.20, no other opening transition pushing $\gamma$, no other L-opening transition in $q$, no other $\left\{a^{x} \mid a \in L\right\}$-opening transition in $q$, and no other $L$-closing transition with $\gamma$ in $q$.

There we require transitions with letters $a^{x}$ with $a \in L$ go to rejection state $q_{r e j}$. This is because since, otherwise if there exists a transition with an annotation that does not go to the rejection, letter $a$ becomes relevant. For these letters candidates are created that may be selected in some future. Similarly Definition 16 requires an


Figure 9.18: An Xml tree library and the corresponding nested word.

$\begin{array}{ll}\Sigma=\left\{a, a^{x} \mid a \in \Sigma^{\prime}\right\}, & \Sigma^{\prime}=\{\text { library, book, author, title, article }\}, \quad \Sigma^{x}=\Sigma \backslash \Sigma^{\prime}, \\ \text { no_book }=\Sigma^{\prime} \backslash\{\text { book }\}, & \text { no_library }=\Sigma^{\prime} \backslash\{\text { library }\}, \quad \text { no_title } \quad=\Sigma^{x} \backslash\left\{\text { title } e^{x}\right\} .\end{array}$

Figure 9.19: An Nwa for XPATH query library/book/title.
adaptation, where transitions with letters $\left\{a^{x} \mid a \in L\right\}$ and $\left\{a^{x} \mid a \in L^{\prime}\right\}$ for $L, L^{\prime}$ of Figure 9.16 must go into the rejection state.

### 9.7 Experiments

We implemented Nwa projection within the QuiXPath system and tested it on the (revised) XPathMark query set of Section 5.11 on queries A1-A8, B1-B7, and B11(1)-B15(1).

As argued in the introduction, it is most natural to measure the efficiency in parsing-free time as presented in Section 8.7.4.

In a first experiment, we start from Fxp and enhance it with projection. The results are presented in Figure 9.21 for a 559 MB XPathMark document. It turns out that projection reduces the parsing-free running time for this query set by a factor of 4.3 , which is a major improvement, in particular when evaluating many XPath queries in parallel as needed for streaming Xslt or XQuery programs. In our second experiment, we compare the overall running time of our PNwA evaluator of XPath queries on Xml streams with Saxon's in-memory evaluator [Kay 2004]. For each of our queries, we compare the full running times including parsing, when evaluating the query $n$-times. The results are given in Figure 9.22. It turns out that QuiXPath with projection for Nwas can answer on average a query up to 12 times in parallel, in no more time than needed by Saxon for the same task.

One observes that running less than 12 queries in parallel with PNwas is a lot quicker than running them with SAXON, mostly due to the expensive in-memory


Figure 9.20: $L \subseteq \Sigma^{n o-v a r}$ and $L^{\prime}=\left\{a^{x} \mid a \in L\right\}$.


Figure 9.21: Improvement by Nwa projection of XPath query evaluation.
tree creation. But when running more than 12 queries on small documents, the advantage of in-memory evaluation takes over. Indeed, without the time for parsing and in-memory tree construction, SAXON in-memory evaluation is still faster by a factor 20 in average than streaming with PNwas. With the improvements of the present paper, it now seems possible that stream processing can become more efficient than in-memory evaluation in practice in the future.


Figure 9.22: Streaming wins vs. in-memory evaluation for up to 12 queries in parallel.

## Part III

## Query Evaluation Algorithms for Full XPath

We present an algorithm for evaluating $\lambda \mathrm{XP}$ queries on data trees that are stored in-memory. When composed with our compiler from XPath 3.0 to $\lambda \mathrm{XP}$, this yields an in-memory evaluator for full XPATH.

In contrast to more standard $\lambda$ calculi, the difficulty for obtaining an in-memory evaluator for $\lambda \mathrm{XP}$ is that it is unclear how to formulate a small-step semantics for this language, given that it also supports first-order logical queries. For instance, for evaluating $\exists x . x \in\{1,2,3\} \wedge x+1 \geq 2$ one has to generate and test all possible values for $x$ and apply the addition function to these values in order to test whether they satisfy $x+1 \geq 2$. Our evaluator will rely on the mode system for $\lambda \mathrm{XP}$, in order to properly split the logical and programming parts of $\lambda \mathrm{XP}$ queries. The logical parts will be evaluated by generating answer sets, while the programming part will be evaluated by executing function applications.

We will then show how to turn our in-memory evaluator into a streaming evaluation algorithm. For this we need to split the navigational from non-navigation aspects of $\lambda \mathrm{XP}$ queries. Purely navigational $\lambda \mathrm{XP}$ queries will be evaluated by running early nested word automata as described earlier. General $\lambda$ XP queries are decomposed into networks of navigational $\lambda$ XP queries. These can be evaluated on XmL streams by running networks of early nested word automata on them.

## In-Memory Evaluation of $\lambda$ XP Queries

## Contents

10.1 Simplification of $\lambda$ XP Queries ..... 173
10.1.1 Simple Queries ..... 174
10.1.2 Decomposition into Networks of Navigational Queries ..... 174
10.1.3 Backward Axes Elimination ..... 175
10.2 Evaluation Algorithm ..... 176
10.2.1 Specification ..... 176
10.2.2 Implementation ..... 184
10.2.3 Examples ..... 184

In this chapter we present how to evaluate in-memory a network of navigational $\lambda \mathrm{XP}$ expressions. The network of navigational $\lambda \mathrm{XP}$ is defined by simple expressions that we introduce. For the evaluation of these formulas we present algorithms that compute their semantics and variable assignments according to the mode system of $\lambda \mathrm{XP}$ that we introduced earlier. We thus evaluate well-moded and well-typed $\lambda \mathrm{XP}$ expressions.

### 10.1 Simplification of $\lambda$ XP Queries

$\lambda \mathrm{XP}$ formulas can be decomposed into a network of navigational formulas, i.e. a $\lambda \mathrm{XP}$ formula where all subexpressions below an axis are navigational. This is a simplication, because the evaluation of these simple kind of $\lambda$ XP formulas can be split into an evaluation of navigational and non-navigational formulas, such that an evaluator for navigational formulas can be lifted to an evaluator for arbitrary $\lambda \mathrm{XP}$ expressions.

Another simplication is the elimination of backward axes. This is neccessary for a streaming evaluator that cannot go back on the stream, but also useful for an in-memory evaluator, for example, since no support for backward axes is required.

### 10.1.1 Simple Queries

We are interested in simple $\lambda$ XP formulas, where all formulas $E$ in axis-expressions $A(E)$ are navigational, where below negations no non-deterministic constructs occur, and where goto-nodes formulas at no non-navigation expression exist.

Definition 18. We call an $\lambda \mathrm{XP}$ formulas $E$ simple, if

1. for all formulas $A\left(E^{\prime}\right)$ in $E$, where $A$ is an axis, $E^{\prime}$ contains no non-navigational formulas,
2. for all navigational formulas $A(F)$ in $E$, where $A$ is an axis, $F$ contains no negations $\neg F^{\prime}$, where $F^{\prime}$ contains disjunctions or non-child axes, and
3. for all formulas $\boldsymbol{a t}\left(E_{1}, E_{2}\right)$ in $E, E_{2}$ is navigational.

For example, for query

$$
\begin{align*}
& \operatorname{at}\left(x_{1},\left\{x \mid c h^{+}\left(\text {tweet } \wedge i s_{x}\right.\right.\right. \\
& \wedge \exists=\left(\text { fn }: \operatorname{data}\left(\operatorname{set} 2 l i s t\left(\left\{x^{\prime} \mid \operatorname{ch}\left(\text { user_name } \wedge i s_{x^{\prime}}\right)\right\}\right)\right)\right. \\
& \operatorname{at}\left(x_{2}, \text { fn }: \operatorname{data}(\operatorname{set} 2 l i s t\right.  \tag{1}\\
&\left.\left.\left.\left.\left.\left.\left.\quad\left\{x^{\prime} \mid c h^{+}\left(\text {students } \wedge c h\left(\text { name } \wedge i s_{x^{\prime}}\right)\right)\right\}\right)\right)\right)\right)\right\}\right)\right)
\end{align*}
$$

discussed already in Section 6.2.10, we give the following equivalent simple query, where all subqueries of axes terms are navigational.

```
\(\left\{x \mid \exists y\left[\operatorname{at}\left(x_{1}, c h^{+}\left(\right.\right.\right.\right.\)tweet \(\left.\left.\wedge i s_{x} \wedge i s_{y}\right)\right)\)
\(\left(Q_{1}^{\prime}\right)\)
    \(\wedge \exists=\left(\mathrm{fn}: \operatorname{data}\left(\operatorname{set} 2 l i s t\left(\left\{x^{\prime} \mid \boldsymbol{a t}\left(y\right.\right.\right.\right.\right.\), ch(user_name \(\left.\left.\left.\left.\left.\wedge i s_{x^{\prime}}\right)\right)\right\}\right)\right)\),
        fn: data(set2list
    \(\left\{x^{\prime} \mid \boldsymbol{a t}\left(x_{2}, c h^{+}\left(\right.\right.\right.\)students \(\wedge \operatorname{ch}\left(\right.\) name \(\left.\left.\left.\left.\left.\left.\left.\left.\wedge i s_{x^{\prime}}\right)\right)\right)\right\}\right)\right)\right]\right\}\)
```


### 10.1.2 Decomposition into Networks of Navigational Queries

We next show that any $\lambda \mathrm{XP}$ formulas can be translated into a simple $\lambda \mathrm{XP}$ formula, i.e. a network of navigational queries. In particular, this allows to lift the streaming evaluator of Chapterchap:enwa for navigational $\lambda$ XP expressions to a general streaming evaluator for $\lambda \mathrm{XP}$ in Chapter 11.

Lemma 11. Any $\lambda \mathrm{XP}$ formula can be transformed into a simple $\lambda \mathrm{XP}$ formula.
Proof. Let $E$ be an $\lambda$ XP formula.
Conditions (1) of definition 18 can be obtained as follows. We identify maximal navigational contexts $C$ in $E$ with formulas $E_{1}, \ldots, E_{n}$ in the holes: $C\left(E_{1}, \ldots, E_{n}\right)$, where all $E_{i}$ are non-navigational and have an axis $A$ above them in $C$ for all $1 \leq$ $i \leq n$. Then we replace such $C\left(E_{1}, \ldots, E_{n}\right)$ in $E$ by $\exists y_{1} \ldots \exists y_{n} .\left[C\left(i s_{y_{1}}, \ldots, i s_{y_{n}}\right) \wedge\right.$ $\left.\boldsymbol{a t}\left(y_{1}, E_{1}\right) \wedge \ldots \wedge \boldsymbol{a t}\left(y_{n}, E_{n}\right)\right]$.

Negations $\neg$ below an axis in navigational formulas of $E$ which contain disjunctions or non-child axes, are eliminated as follows. We identify maximal navigational contexts $C$ in $E$ with formulas $\neg E_{1}, \ldots, \neg E_{n}$ in the holes: $C\left(\neg E_{1}, \ldots, \neg E_{n}\right)$, where
all $E_{i}$ are navigational, containing a disjunction or some non-child axes, and where all $E_{i}$ have an axis $A$ above them in $C$ for all $1 \leq i \leq n$. Then we will replace such $C\left(\neg E_{1}, \ldots, \neg E_{n}\right)$ in $E$ by $\exists y_{1} \ldots \exists y_{n} .\left[C\left(i s_{y_{1}}, \ldots, i s_{y_{n}}\right) \wedge \neg \boldsymbol{a t}\left(y_{1}, E_{1}\right) \wedge \ldots \wedge\right.$ $\left.\neg \boldsymbol{a t}\left(y_{n}, E_{n}\right)\right]$.

Last but not least, we consider formulas at $\left(E_{1}, E_{2}\right)$ in $E$, where $E_{2}$ is not navigational. We rewrite $\mathbf{a t}\left(E_{1}, E_{2}\right)$ as follows: Let $E_{2}=E^{\prime}\left(E_{1}^{\prime}, \ldots, E_{n}^{\prime}\right)$, where $E_{i}^{\prime}$ are navigational formulas and $E^{\prime}$ does not contain any axes or label tests, assuming condition (1) is true. Then $\boldsymbol{a t}\left(E_{1}, E_{2}\right)$ is rewritten to $E^{\prime}\left(\mathbf{a t}\left(E_{1}, E_{1}^{\prime}\right), \ldots, \boldsymbol{a t}\left(E_{1}, E_{n}^{\prime}\right)\right)$. This is correct and can be proven by induction on the structure of non-navigational formulas $E_{2}$. The idea is to push the at formula down to navigational formulas, who depend directly on the evaluation start node, changed by at-formulas.

Simple query $Q_{1}^{\prime}$ can be obtained from $Q_{1}$ following the proof of the lemma.

### 10.1.3 Backward Axes Elimination

We show how to evaluate backward axes in simple navigational queries. Let $F$ be a simple navigational $\lambda$ XP formula, which contains backward axes, such as parent par, ancestor $p a r^{+}$, or preceding-sibling $\mathrm{ps}^{+}$. Since we are considering networks of navigational queries, queries are evaluated from different nodes in general. We are thus considering the more general case of an evaluation of $F$ at some arbitrary node $\pi$, instead of evaluating $F$ from some root node always.

Our backward axes elimination procedure rewrites the query by "pushing up" backward axes in the formula, until they appear at the root position of the formula. This is useful for queries that are evaluated at the root of a tree, since there no parent, no ancestor, and no preceding-sibling exists. Instead of rewriting formulas $F$, which is evaluated at some node $\pi$, we rewrite backward axes in the slightly adapted formulas:

$$
\operatorname{start}(F, z)=\operatorname{def}^{c h^{*}}\left(i s_{z} \wedge F\right)
$$

Evaluating $F$ at node $\pi \in \operatorname{nodes}(s)$ is then equivalent to evaluating $\operatorname{start}(F, z)$ on the root $\operatorname{root}(\pi)$ to which $\pi$ belongs:

$$
\llbracket F \rrbracket_{s, \pi, \mu}=\llbracket \operatorname{start}(F, z) \rrbracket_{s, \operatorname{root}(\pi), \mu \uplus[z / \pi]}
$$

Therefore the elimination process "pushes up" backward axes and disjunctions in $\operatorname{start}(F, z)$, until at the root of the term backward axes can be eliminated, by applying the rewrite rules that we give in Figure 10.1 exhaustively. Notice that since $\operatorname{start}(F, z)$ is simple we can assume that no backward axes appear below a negation, for which reason the set of given rewrite rules suffices.

Backward axes below existential axes:

$$
\begin{array}{ll}
\operatorname{ch}\left(p a r(F) \wedge F^{\prime}\right) & =F \wedge \operatorname{ch}\left(F^{\prime}\right) \\
\operatorname{ch}\left(\operatorname{par}^{+}(F) \wedge F^{\prime}\right) & =\left(F \vee \operatorname{par}^{+}(F)\right) \wedge \operatorname{ch}\left(F^{\prime}\right) \\
\operatorname{ch}\left(p s^{+}(F) \wedge F^{\prime}\right) & =\operatorname{ch}\left(F \wedge n s^{+}\left(F^{\prime}\right)\right) \\
\operatorname{ch}^{+}\left(\operatorname{par}(F) \wedge F^{\prime}\right) & =\left(F \wedge \operatorname{ch}\left(F^{\prime}\right)\right) \vee c h^{+}\left(F \wedge \operatorname{ch}\left(F^{\prime}\right)\right) \\
\operatorname{ch}^{+}\left(\operatorname{par}^{+}(F) \wedge F^{\prime}\right) & =\left(\left(\operatorname{par}^{+}(F) \vee F\right) \wedge c h^{+}\left(F^{\prime}\right)\right) \vee\left(c h^{+}\left(F \wedge c h^{+}\left(F^{\prime}\right)\right)\right) \\
c h^{+}\left(p s^{+}(F) \wedge F^{\prime}\right) & =c h^{+}\left(F \wedge n s^{+}\left(F^{\prime}\right)\right) \\
n s^{+}\left(\operatorname{par}^{+}(F) \wedge F^{\prime}\right) & =\operatorname{par}^{\prime}(F) \wedge n s^{+}\left(F^{\prime}\right) \\
n s^{+}\left(\operatorname{par}^{+}(F) \wedge F^{\prime}\right) & =\operatorname{par}^{+}(F) \wedge n s^{+}\left(F^{\prime}\right) \\
n s^{+}\left(p s^{+}(F) \wedge F^{\prime}\right) & =\left(\left(p s^{+}(F) \vee F\right) \wedge n s^{+}\left(F^{\prime}\right)\right) \vee n s^{+}\left(F \wedge n s^{+}\left(F^{\prime}\right)\right)
\end{array}
$$

Disjunctions where $A$ is an axis, and De Morgan's law:

$$
\begin{array}{ll}
A\left(F \vee F^{\prime}\right) & =A(F) \vee A\left(F^{\prime}\right) \\
\left(F \vee F^{\prime}\right) \wedge F^{\prime \prime} & =\left(F \wedge F^{\prime \prime}\right) \vee\left(F^{\prime} \wedge F^{\prime \prime}\right)
\end{array}
$$

Eliminate backward axes at the root of the term:

$$
\begin{array}{ll}
\operatorname{par}(F) & =\text { false } \\
\operatorname{par}^{+}(F) & =\text { false } \\
p s^{+}(F) & =\text { false }
\end{array}
$$

Figure 10.1: Backward axes rewrite rules.

## Example.

$$
\begin{aligned}
\operatorname{ch}\left(i s_{x} \wedge\left(\operatorname{par}^{+}(a) \vee p s^{+}(b)\right)\right) & =\operatorname{ch}\left(\left(i s_{x} \wedge \operatorname{par}^{+}(a)\right) \vee\left(i s_{x} \wedge p s^{+}(b)\right)\right) \\
& \left.=\operatorname{ch}\left(\left(i s_{x} \wedge \operatorname{par}^{+}(a)\right)\right) \vee \operatorname{ch}\left(i s_{x} \wedge p s^{+}(b)\right)\right) \\
& =\left(\left(a \vee \operatorname{par}^{+}(a)\right) \wedge \operatorname{ch}\left(i s_{x}\right)\right) \vee \operatorname{ch}\left(b \wedge n s^{+}\left(i s_{x}\right)\right) \\
& =\left((a \vee f a l s e) \wedge \operatorname{ch}\left(i s_{x}\right)\right) \vee \operatorname{ch}\left(b \wedge n s^{+}\left(i s_{x}\right)\right) \\
& =\left(a \wedge \operatorname{ch}\left(i s_{x}\right)\right) \vee \operatorname{ch}\left(b \wedge n s^{+}\left(i s_{x}\right)\right)
\end{aligned}
$$

### 10.2 Evaluation Algorithm

What we would like to compute is the semantics $\llbracket E \rrbracket_{s, \pi, \alpha}$ for any expression $E$, sequence of trees $s$, node $\pi$, and variable assignment $\alpha$. We restrict ourselves to expressions $E$ that are well-moded and well-typed. This permits us to separate logical subexpressions, where variables assignments must be enumerated, from program subexpressions, where functions are applied.

### 10.2.1 Specification

In order to deal with set constructions and existential quantifiers, we have to compute variable assignments for well-moded expressions $E \triangleright V_{1} \rightarrow V_{2}$ of type bool.

More precisely, given an assignment of the variables in $V_{1}$ we have to compute an extension to the variables in $V_{1} \cup V_{2}$ so that $E$ becomes true. For well-moded expressions of other types, the set $V_{2}$ will always be empty.

Lemma 12. If $E \triangleright V_{1} \rightarrow V_{2}$ with $V_{2} \neq \emptyset$ and $E: T$ then $T$ : bool.
If $V_{2}=\emptyset$ then we are interested in a program evaluator, which inputs some $V_{1}$ assignment and computes the value of $E$ for it. Otherwise, we have $T=$ bool and are interested in a query evaluator that inputs some $V_{1}$ assignment, and generates the set of all extensions to variables in $V_{2}$ so that $E$ becomes true.

Proposition 11. Let $E$ be an expression with mode $E \triangleright V_{1} \rightarrow V_{2}$ and type $E: T$.
a) There exist a program evaluator $A$ that computes the value of $E$ for any sequence $s$ of trees, $V_{1} \cup V_{2}$ assignments $\alpha$ into s-values, and any node $\pi \in$ nodes(s):

$$
A(s, \alpha, \pi)=\llbracket E \rrbracket_{s, \pi, \alpha}
$$

under the assumption that a program evaluator exists that computes the semantics of expressions $c \in \mathcal{C}$ onst.
b) There exists a query evaluator $B$ that for any sequence $s$ of trees and $V_{1}$ assignment to s-values computes the set of $V_{1} \cup V_{2}$ assignments to s-values that extend $\beta$ and satisfies $E$ :

$$
B(s, \beta, \pi)= \begin{cases}\perp & , \text { if } A(s, \alpha, \pi)=\perp \\ \{\alpha \mid \beta \subseteq \alpha, A(s, \alpha, \pi)=\text { true }\} & , \text { otherwise }\end{cases}
$$

Proof. The construction of $A$ and $B$ is by simultaneous induction on derivations of judgments $E \triangleright V_{1} \rightarrow V_{2}$. We first note that if $V_{2}=\emptyset$ then we can always obtain $B$ from $A$ as follows:

$$
B(s, \pi, \beta)= \begin{cases}\{\beta\} & , A(s, \pi, \beta)=\text { true } \\ \emptyset & , A(s, \pi, \beta)=\text { false } \\ \perp & , A(s, \pi, \beta)=\perp\end{cases}
$$

Submodes. Suppose that the judgement $E \triangleright V_{1} \rightarrow V_{2}$ is derived by the first rule for submodes:

$$
\frac{E \triangleright V \rightarrow V^{\prime}}{E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}}
$$

Let $A^{\prime}, B^{\prime}$ be the program and query evaluators for $E \triangleright V \rightarrow V^{\prime}$, respectively. We then define program and query evaluators for $E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}$ as follows:

$$
\begin{aligned}
A(s, \pi, \alpha) & =A^{\prime}\left(s, \pi, \alpha_{\left.\right|_{V \cup V^{\prime}}}\right) \\
B(s, \pi, \beta) & = \begin{cases}\perp & \text { if } B^{\prime}\left(s, \pi, \beta_{\left.\right|_{V}}\right)=\perp \\
\left\{\beta \uplus \beta^{\prime} \mid \beta^{\prime} \in B^{\prime}\left(s, \pi, \beta_{\left.\right|_{V}}\right)\right\} & , \text { otherwise }\end{cases}
\end{aligned}
$$

Next consider the case, where the judgement was inferred by the second rule for submodes:

$$
\frac{E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}}{E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}}
$$

Let $A^{\prime}, B^{\prime}$ be the evaluators for $E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}$. We define the evaluators $A, B$ for $E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}$ as follows:

$$
\begin{array}{ll}
A(s, \pi, \alpha)=A^{\prime}(s, \pi, \alpha) & , \text { if } B^{\prime}\left(s, \pi, \beta_{\mid V}\right)=\perp \\
B(s, \pi, \beta)= \begin{cases}\stackrel{\perp}{ } & \\
\left\{\beta^{\prime} \mid \beta^{\prime} \in B^{\prime}\left(s, \pi, \beta_{\mid V}\right), \beta \subseteq \beta^{\prime}\right\} & , \text { otherwise }\end{cases}
\end{array}
$$

Conjunction. The mode is inferred by inference rule:

$$
\begin{array}{cc}
E_{1} \triangleright V \rightarrow V^{\prime} & E_{2} \triangleright V \cup V^{\prime} \rightarrow V^{\prime \prime} \quad E=E_{1} \wedge E_{2} \\
E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}
\end{array}
$$

Let $A_{1}, B_{1}$ be evaluators for $E_{1} \triangleright V \rightarrow V^{\prime}$ and $A_{2}$ and $B_{2}$ evaluators for $E_{2} \triangleright V \cup V^{\prime} \rightarrow$ $V^{\prime \prime}$. We define evaluators for $E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}$ by induction:

$$
\begin{aligned}
& A(s, \pi, \alpha)=A_{1}(s, \pi, \alpha) \wedge^{\text {Bool }^{\perp} A_{2}(s, \pi, \alpha)} \\
& B(s, \pi, \beta)= \begin{cases}\perp & , \text { if } B_{1}(s, \pi, \beta)=\perp \text { or } \\
& B_{2}\left(s, \pi, \beta_{1}\right)=\perp \text { for } \\
& \text { some } \beta_{1} \in B_{1}(s, \pi, \beta) \\
\left\{\beta_{2} \mid \beta_{1} \in B_{1}(s, \pi, \beta), \beta_{2} \in B_{2}\left(s, \pi, \beta_{1}\right)\right\} & , \text { otherwise }\end{cases}
\end{aligned}
$$

## Disjunction.

$$
\frac{E_{1} \triangleright V \rightarrow V^{\prime} \quad E_{2} \triangleright V \rightarrow V^{\prime} \quad E=E_{1} \vee E_{2}}{E \triangleright V \rightarrow V^{\prime}}
$$

Let $A_{i}$ and $B_{i}$ be evaluators for $E_{i} \triangleright V \rightarrow V^{\prime}$ for $i \in\{1,2\}$. We define evaluators for $E \triangleright V \rightarrow V^{\prime}$ as:

$$
\begin{aligned}
& A(s, \pi, \alpha)=A_{1}(s, \pi, \alpha) \vee^{\text {Bool }}{ }^{\perp} A_{2}(s, \pi, \alpha) \\
& B(s, \pi, \beta)=B_{1}(s, \pi, \beta) \cup^{\perp} B_{2}(s, \pi, \beta)
\end{aligned}
$$

## Negation.

$$
\frac{E \triangleright V \rightarrow \emptyset}{\neg E \triangleright V \rightarrow \emptyset}
$$

Let $A^{\prime}$ be the program evaluator for $E \triangleright V \rightarrow \emptyset$. We define $A$ and $B$ for $\neg E \triangleright V \rightarrow \emptyset$ as follows:

$$
A(s, \pi, \alpha)=\neg^{\text {Bool }} \perp A^{\prime}(s, \pi, \alpha)
$$

The modes are such that no variables are generated, so that $B(s, \pi, \beta)$ can be defined from $A(s, \pi, \beta)$.
Constants.

$$
\frac{\text { true }}{c \triangleright \emptyset \rightarrow \emptyset}
$$

We define program evaluator $A$ for $c \triangleright \emptyset \rightarrow \emptyset$ as:

$$
A(s, \pi, \alpha)=\llbracket c \rrbracket_{s, \pi}
$$

According to the proposition there exists a program evaluator computing $\llbracket c \rrbracket_{s, \pi}$. Again, no variables are generated, so that $B(s, \pi, \beta)$ can be defined from $A(s, \pi, \beta)$.

## Variables.

$$
\frac{\text { true }}{x \triangleright\{x\} \rightarrow \emptyset}
$$

We define evaluators $A$ and $B$ for $x \triangleright\{x\} \rightarrow \emptyset$ as:

$$
A(s, \pi, \alpha)=\alpha(x)
$$

Due to the modes, no variables are generated, $B(s, \pi, \beta)$ can be defined from $A(s, \pi, \beta)$.

## Existential quantification.

$$
\frac{E \triangleright V \rightarrow V^{\prime} \cup\{x\} \quad x \notin V^{\prime}}{\exists x . E \triangleright V \rightarrow V^{\prime}}
$$

Let $B^{\prime}$ be a query evaluator for $E \triangleright V \rightarrow V^{\prime} \cup\{x\}$. We define evaluators for $\exists x . E \triangleright V \rightarrow V^{\prime}$ as follows:

$$
\begin{aligned}
& A(s, \pi, \alpha)= \begin{cases}\perp & , B^{\prime}\left(s, \pi, \alpha_{\mid V}\right)=\perp \\
\text { true } & , \exists \beta^{\prime} \in B^{\prime}\left(s, \pi, \alpha_{\mid V}\right): \alpha \subset \beta^{\prime} \\
\text { false } & \text { otherwise }\end{cases} \\
& B(s, \pi, \beta)= \begin{cases}\perp & \text { if } B^{\prime}(s, \pi, \beta)=\perp \\
\left\{\left.\beta^{\prime}\right|_{V U V^{\prime}} \mid \beta^{\prime} \in B^{\prime}(s, \pi, \beta)\right\} & \text {, otherwise }\end{cases}
\end{aligned}
$$

Navigation formulas. Consider first the rule for navigation by axes:

$$
\frac{E \triangleright V \rightarrow V^{\prime}}{A(E) \triangleright V \rightarrow V^{\prime}}
$$

Let $A^{\prime}$ and $B^{\prime}$ be evaluators for $E \triangleright V \rightarrow V^{\prime}$. We define evaluators for $A(E) \triangleright V \rightarrow V^{\prime}$ as:

$$
\begin{aligned}
& A(s, \pi, \alpha)=\begin{array}{ll}
\left(\exists \pi^{\prime} \in \operatorname{nodes}(s): A^{s}\left(\pi, \pi^{\prime}\right) \wedge^{\text {Bool }} A^{\prime}\left(s, \pi^{\prime}, \alpha\right)=\text { true }\right) \\
B(s, \pi, \beta) & = \begin{cases}\perp & \text { if } B^{\prime}\left(s, \pi^{\prime}, \beta\right)=\perp \text { for } \\
\left\{\beta^{\prime} \mid A^{s}\left(\pi, \pi^{\prime}\right), \beta^{\prime} \in B^{\prime}\left(s, \pi^{\prime}, \beta\right)\right\} & \text { some } \pi^{\prime} \text { with } A^{s}\left(\pi, \pi^{\prime}\right)\end{cases}
\end{array} \text { otherwise }
\end{aligned}
$$

## Node tests.

$$
\frac{\text { true }}{L \triangleright \emptyset \rightarrow \emptyset}
$$

Since no variables are generated we only need to define the program evaluator $A$ :

$$
A(s, \pi, \alpha)=\left(\pi \in L^{s}\right)
$$

## Negated navigational formulas.

$$
\frac{E \triangleright V \rightarrow V^{\prime} \quad \text { E is navigational }}{\neg E \triangleright V \rightarrow V^{\prime}}
$$

Let $A^{\prime}$ and $B^{\prime}$ be evaluators for $E \triangleright V \rightarrow V^{\prime}$. We define evaluators $A$ and $B$ for $\neg E \triangleright V \rightarrow V^{\prime}$ as:

$$
\begin{array}{ll}
A(s, \pi, \alpha) & =\left(\neg^{\text {Bool }} A(s, \pi, \alpha)\right) \\
B(s, \pi, \beta) & = \begin{cases}\perp & \text { if } B^{\prime}(s, \pi, \beta)=\perp \\
\left\{\beta^{\prime} \mid \beta \subseteq \beta^{\prime}, \beta^{\prime} \notin B^{\prime}(s, \pi, \beta)\right. & \text { otherwise } \\
\left.\beta^{\prime} \text { is } V \cup V^{\prime} \text { assignment to } s\right\}\end{cases}
\end{array}
$$

Notice that $\beta^{\prime}$ in the definition of $B(s, \pi, \beta)$ only permits variables of type node, since $E$ is navigational. Therefore there is only a finite number nodes to try for $\beta^{\prime}$.

## Location.

$$
\begin{array}{cc}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow V^{\prime} \quad E=\operatorname{at}\left(E_{1}, E_{2}\right) \\
E \triangleright V \rightarrow V^{\prime}
\end{array}
$$

Let $A_{1}$ be a program evaluator for $E_{1} \triangleright V \rightarrow \emptyset$, and $A_{2}$ and $B_{2}$ evaluators for $E_{2} \triangleright V \rightarrow V^{\prime}$. We define evaluators for $E \triangleright V \rightarrow V^{\prime}$ as follows:

$$
\begin{aligned}
A(s, \pi, \alpha) & = \begin{cases}A_{2}\left(s, A_{1}(s, \pi, \alpha), \alpha\right) & , A_{1}(s, \pi, \alpha) \neq \perp \\
\perp & , \text { otherwise }\end{cases} \\
B(s, \pi, \beta) & = \begin{cases}B_{2}\left(s, A_{1}(s, \pi, \beta), \beta\right) & , A_{1}(s, \pi, \beta) \neq \perp \\
\perp & , \text { otherwise }\end{cases}
\end{aligned}
$$

## Conditional.

$$
\begin{gathered}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow V^{\prime} \quad E_{3} \triangleright V \rightarrow V^{\prime} \\
E=\text { if } E_{1} \text { then } E_{2} \text { else } E_{3} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{1}$ be a program evaluator for $E_{1} \triangleright V \rightarrow \emptyset$ and $A_{i}$ and $B_{i}$ be evaluators for $E_{i} \triangleright V \rightarrow V^{\prime}$ for $i \in\{2,3\}$. We define evaluators $A$ and $B$ for $E \triangleright V \rightarrow V^{\prime}$ as:

$$
\begin{aligned}
& A(s, \pi, \alpha)= \begin{cases}A_{2}(s, \pi, \alpha) & , A_{1}(s, \pi, \alpha)=\text { true } \\
A_{3}(s, \pi, \alpha) & , A_{1}(s, \pi, \alpha)=\text { false } \\
\perp & , A_{1}(s, \pi, \alpha)=\perp\end{cases} \\
& B(s, \pi, \beta)= \begin{cases}B_{2}(s, \pi, \beta) & , A_{1}(s, \pi, \beta)=\text { true } \\
B_{3}(s, \pi, \beta) & , A_{1}(s, \pi, \beta)=\text { false } \\
\perp & , A_{1}(s, \pi, \beta)=\perp\end{cases}
\end{aligned}
$$

## Recursive definition.

$$
\begin{gathered}
\forall 1 \leq i \leq n . E_{i} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow \emptyset \\
E^{\prime} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime} \\
E=\text { letrec } x_{1}=E_{1}, \ldots, x_{n}=E_{n} \text { in } E^{\prime} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{i}$ be program evaluators for $E_{i} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow \emptyset$ for $1 \leq i \leq n$ and $A^{\prime}$ and $B^{\prime}$ be evaluators for $E^{\prime} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime}$. We define evaluators for $E \triangleright V \rightarrow V^{\prime}$ as follows:

$$
\begin{aligned}
& A(s, \pi, \alpha)= \\
& \quad \text { Letrec } \\
& \quad v_{1}=A_{1}\left(s, \pi, \alpha_{\left.\right|_{V}} \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]\right), \\
& \quad \ldots \\
& \quad v_{n}=A_{n}\left(s, \pi, \alpha_{\left.\right|_{V}} \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]\right) \\
& \text { in } A^{\prime}\left(s, \pi, \alpha \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]\right) \\
& B(s, \pi, \beta)=
\end{aligned}
$$

Letrec

$$
\begin{aligned}
& v_{1}=A_{1}\left(s, \pi, \beta \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]\right), \\
& \quad \ldots \\
& v_{n}=A_{n}\left(s, \pi, \beta \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]\right) \\
& \operatorname{in~} B^{\prime}\left(s, \pi, \beta \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]\right)
\end{aligned}
$$

By Proposition 1, there exist algorithms computing the functions $v_{i}$ for all $1 \leq$ $i \leq n$.

## Tuple constructions.

$$
\frac{\forall 1 \leq i \leq n . E_{i} \triangleright V \rightarrow \emptyset \quad E=\left(E_{1}, \ldots, E_{n}\right)}{E \triangleright V \rightarrow \emptyset}
$$

Let $A_{i}$ be program evaluators for $E_{i} \triangleright V \rightarrow \emptyset$ for $1 \leq i \leq n$. We define the program evaluator $A$ for $E \triangleright V \rightarrow \emptyset$ by:

$$
A(s, \pi, \alpha)= \begin{cases}\perp & , \exists i: A_{i}(s, \pi, \alpha)=\perp \\ \left(A_{1}(s, \pi, \alpha), \ldots, A_{n}(s, \pi, \alpha)\right) & , \text { otherwise }\end{cases}
$$

The query evaluator $B$ can be derived from the program evaluator $A$ since no variables are generated.

Tuple decompositions.

$$
\begin{gathered}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime} \\
E=\operatorname{match} E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{1}$ and be a program evaluator for $E_{1} \triangleright V \rightarrow \emptyset$, and $A_{2}$ and $B_{2}$ evaluators for $E_{2} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime}$. We define evaluators for $E \triangleright V \rightarrow V^{\prime}$ as:

$$
\begin{aligned}
& A(s, \pi, \alpha)=\left\{\begin{array}{cl}
A_{2}\left(s, \pi, \alpha \uplus\left[x_{1} / a_{1}, \ldots, x_{n} / a_{n}\right]\right) & , A_{1}(s, \pi, \alpha) \neq \perp \\
\text { where } A_{1}(s, \pi, \alpha)=\left(a_{1}, \ldots, a_{n}\right) & \\
\perp & , \text { otherwise }
\end{array}\right. \\
& B(s, \pi, \beta)= \\
& \begin{cases}\left\{\beta_{\left.\right|_{V \cup V^{\prime}} ^{\prime} \mid \beta^{\prime} \in B_{2}\left(s, \pi, \beta \uplus\left[x_{1} / a_{1}, \ldots, x_{n} / a_{n}\right]\right)}\right. & , A_{1}(s, \pi, \beta) \neq \perp \\
\left.A_{1}(s, \pi, \beta)=\left(a_{1}, \ldots, a_{n}\right)\right\} & \\
\perp & \end{cases}
\end{aligned}
$$

## Set constructions.

$$
\frac{E \triangleright V \rightarrow\{x\}}{\{x \mid E\} \triangleright V \rightarrow \emptyset}
$$

Let $B_{1}$ be a query evaluator for $E \triangleright V \rightarrow\{x\}$. We define the program evaluator $A$ for $\{x \mid E\} \triangleright V \rightarrow \emptyset$ as follows:

$$
A(s, \pi, \alpha)= \begin{cases}\perp & , \text { if } B_{1}(s, \pi, \alpha)=\perp \\ \left\{\beta^{\prime}(x) \mid \beta^{\prime} \in B_{1}(s, \pi, \alpha)\right\} & , \text { otherwise }\end{cases}
$$

Since no variables are generated, the query evaluator $B$ can be derived from the program evaluator $A$.

## List constructions.

$$
\frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow \emptyset}{E_{1}:: E_{2} \triangleright V \rightarrow \emptyset}
$$

Let $A_{i}$ be program evaluators for $E_{i} \triangleright V \rightarrow \emptyset$ for $i \in\{1,2\}$. We define the $A$ program evaluator for $E_{1}:: E_{2} \triangleright V \rightarrow \emptyset$ as:

$$
A(s, \pi, \alpha)= \begin{cases}\perp & , \exists i: A_{i}(s, \pi, \alpha)=\perp \\ A_{1}(s, \pi, \alpha):: A_{2}(s, \pi, \alpha) & , \text { otherwise }\end{cases}
$$

Since no variables are generated, the $B$ query evaluator can be derived from the $A$ program evaluator.

## List decomposition.

$$
\begin{gathered}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \cup\{x, y\} \rightarrow V^{\prime} \quad E_{3} \triangleright V \rightarrow V^{\prime} \\
E=\text { match } E_{1} \text { with } x:: y \text { then } E_{2} \text { else } E_{3} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{1}$ be a program evaluator for $E_{1} \triangleright V \rightarrow \emptyset, A_{2}$ and $B_{2}$ evaluators for $E_{2} \triangleright V \cup$ $\{x, y\} \rightarrow V^{\prime}$, and $A_{3}$ and $B_{3}$ evaluators for $E_{3} \triangleright V \rightarrow V^{\prime}$. We define evaluators for
$E \triangleright V \rightarrow V^{\prime}$ as follows:

$$
\begin{aligned}
& A(s, \pi, \alpha)= \begin{cases}A_{2}\left(s, \pi, \alpha \uplus\left[x / a, y / a^{\prime}\right]\right) & , A_{1}(s, \pi, \alpha)=a:: a^{\prime} \\
A_{3}(s, \pi, \alpha) & , A_{1}(s, \pi, \alpha)=\text { nil } \\
\perp & , A_{1}(s, \pi, \alpha)=\perp\end{cases} \\
& B(s, \pi, \beta)= \\
& \begin{cases}\left\{\beta^{\prime}{ }_{V \cup V^{\prime}} \mid \beta^{\prime} \in B_{2}\left(s, \pi, \beta \uplus\left[x / a, y / a^{\prime}\right]\right)\right\} & , A_{1}(s, \pi, \beta)=a:: a^{\prime} \\
B_{3}(s, \pi, \beta) & , A_{1}(s, \pi, \beta)=\text { nil } \\
\perp & , A_{1}(s, \pi, \beta)=\perp\end{cases}
\end{aligned}
$$

## Function application.

$$
\frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow \emptyset}{E_{1} E_{2} \triangleright V \rightarrow \emptyset}
$$

Let $A_{i}$ be program evaluators for $E_{i} \triangleright V \rightarrow \emptyset$ for $i \in\{1,2\}$. We define the $A$ program evaluator for $E_{1} E_{2} \triangleright V \rightarrow \emptyset$ as follows:

$$
A(s, \pi, \alpha)= \begin{cases}f\left(A_{2}(s, \pi, \alpha)\right) & , f=A_{1}(s, \pi, \alpha) \neq \perp \\ \perp & , \text { otherwise }\end{cases}
$$

Since no variables are generated, the $B$ query evaluator can be derived from the program evaluator $A$.

## Function definition.

$$
\frac{E \triangleright V \cup\{x\} \rightarrow \emptyset}{\lambda x \cdot E \triangleright V \rightarrow \emptyset}
$$

Let $A^{\prime}$ be a program evaluator for $E \triangleright V \cup\{x\} \rightarrow \emptyset$. We define the $A$ program evaluator for $\lambda x . E \triangleright V \rightarrow \emptyset$ as follows:

$$
A(s, \pi, \alpha)=\left(\Lambda v \in \llbracket \operatorname{TYPE}(x) \rrbracket \cdot A^{\prime}(s, \pi, \alpha \uplus[x / v])\right)^{\perp}
$$

Since no variables are generated, the $B$ query evaluator can be derived from the $A$ program evaluator.

## Variable binding.

$$
\frac{E \triangleright V \rightarrow \emptyset}{x=E \triangleright V \rightarrow\{x\}}
$$

Let $A^{\prime}$ be a program evaluator for $E \triangleright V \rightarrow \emptyset$. We define the evaluators for $x=$ $E \triangleright V \rightarrow\{x\}$ as follows:

$$
\begin{aligned}
& A(s, \pi, \alpha)= \begin{cases}\perp & , \text { if } A^{\prime}\left(s, \pi, \alpha_{\left.\right|_{V}}\right)=\perp \\
\text { true } & , \text { if } \alpha(x)=A^{\prime}\left(s, \pi, \alpha_{\left.\right|_{V}}\right) \\
\text { false } & , \text { otherwise }\end{cases} \\
& B(s, \pi, \beta)= \begin{cases}\perp & \text { if } A^{\prime}(s, \pi, \beta)=\perp \\
\left\{\beta \uplus\left[x / A^{\prime}(s, \pi, \beta)\right]\right\} & , \text { otherwise }\end{cases}
\end{aligned}
$$

## Set Membership.

$$
\frac{E \triangleright V \rightarrow \emptyset}{x \in E \triangleright V \rightarrow\{x\}}
$$

Let $A^{\prime}$ be the program evaluator for $E \triangleright V \rightarrow \emptyset$. We define the evaluators for $x \in E \triangleright V \rightarrow\{x\}$ as follows:

$$
\begin{aligned}
& A(s, \pi, \alpha)= \begin{cases}\perp & , \text { if } A^{\prime}\left(s, \pi, \alpha_{\mid V}\right)=\perp \\
\text { true } & , \text { if } \alpha(x) \in A^{\prime}\left(s, \pi, \alpha_{\mid V}\right) \\
\text { false } & , \text { otherwise }\end{cases} \\
& B(s, \pi, \beta)= \begin{cases}\perp & \text { if } A^{\prime}(s, \pi, \beta)=\perp \\
\left\{\beta \uplus[x / v] \mid v \in A^{\prime}(s, \pi, \beta)\right\} & , \text { otherwise }\end{cases}
\end{aligned}
$$

### 10.2.2 Implementation

Large parts of the implementation of the in-memory evaluator are straightforward given by functional programs. What we have not yet explained is how functions will be represented. Functions may be contained in variable assignments as the input of the evaluator, but may also be produced as output.

In our implementation, we always represent functions by functional programs that compute the functions. For a function $\Lambda v \in I n t . v+3$, one can use the corresponding functional program $\operatorname{fun}(v) v+3$ where $v \in I n t$. For recursive functions Letrec $x_{1}=E_{1}, \ldots, x_{n}=E_{n}$ in $E^{\prime}$ we can assume functional programs for $E_{1}, \ldots$, $E_{n}$ and $E$ and then construct the functional program for the letrec expression as in the proof of Proposition 1.

### 10.2.3 Examples

In the following we give examples for the evaluation of functions, recursive lets, logical formulas, and their combinations.

Functions When applied to the lambda expression $\lambda x . x+5$ where $\operatorname{Type}(x)=$ int the implementation of the program evaluator $A$ returns a functional program computing the total function $\Lambda i \in \operatorname{Int} . i+5$, which when applied to some integer $i \in$ Int returns $i+5$. The implementation of the program evaluator $A$ for the function application

$$
(\lambda x: \text { int. } x+5)(3)
$$

applies this functional program $\operatorname{fun}(v) v+5$ where $v \in I n t$, which when applied to argument 3 returns 8 .

Recursion Let $z$ be a variable of type $\operatorname{Type}(z)=$ int. When applied to the recursive let expression

$$
\text { letrec } x_{f a c}=\lambda z . \text { if } z=0 \text { then } 1 \text { else } z \cdot x_{f a c}(z-1) \text { in } x_{f a c}
$$

the implementation of the program evaluator $A$ returns a functional program computing the faculty function:

$$
f a c=\operatorname{fun}(i) \text { if } i=0 \text { then } 1 \text { else } i \cdot f a c(i-1)
$$

where $i \in$ Int. When applied to a nonnegative integer $i$ this functional program computes $f a c(i)=i!$, and otherwise returns $\perp$. This functional program can be obtained in a systematic manner from the letrec expression, as shown in the proof of Proposition 1.

Mixing Logics and Functions Let $x$ be a variable of type $\operatorname{Type}(x)=$ int. We consider the following logical formula which contains an application of a recursive function:

$$
\exists x . x \in\{1,2,3\} \wedge f a c(x) \geq 5
$$

The query evaluator $B$ for $x \in\{1,2,3\}$ will return the set of variable assignments $\{[x / 1],[x / 2],[x / 3]\}$. From these, the query evaluator $B$ of the conjunction will filter those assignments, for which program evaluator $A$ of $f a c(x) \geq 5$ returns true. This is the set $\{[x / 3]\}$. Since this set is nonempty, the program evaluator $A$ of the existential quantified formula will return true.

## Streaming Evaluation of $\lambda$ XP Queries

## Contents

11.1 Streaming Evaluators ..... 187
11.1.1 Restrictions ..... 188
11.1.2 Linearizing a Sequence of Trees ..... 190
11.1.3 Updates ..... 190
11.1.4 Extended Types ..... 192
11.1.5 Open Values ..... 192
11.1.6 Registrations ..... 193
11.1.7 Program and Query Evaluators ..... 195
11.1.8 Running Evaluators over Streams ..... 196
11.2 Evaluators ..... 198
11.2.1 Generic Functions ..... 198
11.2.2 Inductive Construction of Evaluators ..... 201
11.3 Examples ..... 244
11.3.1 Navigational Queries ..... 244
11.3.2 A Network of Queries ..... 246
11.4 Tuple Sharing ..... 247
11.5 Experiments ..... 249

In this chapter we present a streaming algorithm that evaluates a network of early nested word automata, where navigational expressions are evaluated by eNwas as described in Chapter 8.

### 11.1 Streaming Evaluators

In this section we describe how we evaluate $\lambda$ XP formulas over a stream. We are interested in two evaluators similar to Section 10.2: A program evaluator $A_{s}$ that computes the semantics of a formula, and a query evaluator $B_{s}$ that computes sets of extensions of variable assignment under which $A_{s}$ becomes true. Both evaluators use registrations that store possible open descriptions of values and variable assignments, which can be completed when future values arrive on the stream.

### 11.1.1 Restrictions

For the streaming evaluation we need to impose the following restrictions on conditionals, list decompositions, and two new constants that we introduce. These restrictions are necessary to avoid exponential blow-ups and problems with program termination that arise by speculative execution that is required without the restrictions. For example, the test expression of a conditional may not yet be determined at some event of stream, since it requires more information from the stream for its evaluation. Therefore, one needs to speculatively guess that either the then or the else expression will be taken. A problem is the nontermination of an invalid branch that was a wrong guess. Furthermore, the choices for the guesses must be propagated throughout the network, leading to copies of the choices, which becomes expensive to resolve.

Furthermore, our streaming evaluators will maintain collections, i.e. set or lists, of nodes whose determination may require more information from the future of the stream. Such collections cannot always be decomposed by using list-matches, since list-matches will be strongly restricted to be acceptable for streaming.

Therefore, we add further constants to our language. In particular, we introduce the two mapping constants:

$$
\begin{aligned}
& \text { map-list }_{T, T^{\prime}}:\left(T \rightarrow T^{\prime}\right) \times[T] \rightarrow\left[T^{\prime}\right] \\
& \text { map-set }_{T, T^{\prime}}:\left(T \rightarrow T^{\prime}\right) \times\{T\} \rightarrow\left\{T^{\prime}\right\}
\end{aligned}
$$

which given some function $f$ of type $T \rightarrow T^{\prime}$ and a list or a set of type $T$, applies the function to every element of the list or set, to obtain a new list or set, respectively. This works fine, as long as termination is ensured for all applications of $f$ to some value. We also add constant

$$
\text { string_value }: \text { node } \rightarrow \text { string }
$$

to our language, that can be defined as in Section 7.2.3, but as a constant it can be implemented in any preferable way. It computes the string value of a given node. Then, for example, map-list string_value can convert a list of nodes to the list of their string values, even though the membership of some node to the input list will be decided only lately. In this case, one will apply the function to the candidate nodes in a speculative manner. This is safe, as long as speculative function applications will not lead to nontermination.

Definition 19. We call a $\lambda \mathrm{XP}$ expression $E$ stream-acceptable if $E$ is well-typed and satisfies the following two conditions:
(1) for subexpression of $E$ that is either a conditional

$$
\text { if } E_{0} \text { then } E_{1} \text { else } E_{2}
$$

or a branching match-expression
match $E_{0}$ with $x:: y$ then $E_{1}$ else $E_{2}$
with types $E_{i}: T_{i}$ for $1 \leq i \leq 3$, either of the following holds:
(a) the types $T_{1}$ and $T_{2}$ do not contain the type node as a subterm and the expressions $E_{1}$ and $E_{2}$ do not contain any axis and any constant whose semantics depends on nodes, or
(b) the type $T_{0}$ does not contain the type node as a subterm and the expression $E_{0}$ does not contain any axis and any constants whose semantics depends on nodes.
(2) all occurrences of the constants map-list or map-set in $E$ must be in applications of the form

$$
\text { map-list } E^{\prime} \quad \text { or } \quad \text { map-set } E^{\prime}
$$

where $E^{\prime}$ is some expression that is terminating in that it does neither contain letrec nor any free variables or constants, with the exception of
string_value
(or other constants that may not lead to nontermination).
Restriction (1a) allows for a late evaluation of branches $E_{1}$ and $E_{2}$ of conditionals or branching match expressions. Since neither $T_{1}$ and $T_{2}$ do contain the type node as a subterm and neither $E_{1}$ nor $E_{2}$ contain any axes, the expressions $E_{1}$ and $E_{2}$ do not depend on nodes on the stream, so that can be evaluated at any time point, without any needs of stream buffering. For example, consider the expression

$$
\text { if } c h^{*}(a) \text { then } f a c(\text { string_value(1st-node())) else fac(string_value(2nd-node())) }
$$

that is run on a document which has no $a$-labeled nodes, while the documents first node's string value is -1 and the second node's string value is 3 . 1 st-node and $2 n d$-node are constants that return the first and second node of the root, respectively:

$$
\text { 1st-node }: \text { unit } \rightarrow \text { node } \quad \text { and } \quad \text { 2nd-node }: \text { unit } \rightarrow \text { node }
$$

and fac is the faculty function defined in Section 6.2.7 that is defined for positive integers only. The correct evaluation of the expression on the stream which contains no $a$-labeled node should terminate with 6 , since the evaluation of the test expression of the conditional selects the else branch, but however, before arriving at the end of the stream to determine whether an $a$-labeled descendant exists, when doing all computation speculatively, one would be forced to also evaluate $f a c(-1)$, which would lead to nontermination.

With restriction (1b) the test expression of the conditional and branching match expressions will be determined right at the node when the branches are started, since independent of future nodes on the stream. Then one chooses the respective branch depending on the evaluation of the test expression and whether the list is empty or not, respectively.

Mapping expressions map-list $E$ and map-set $E$ allow to decompose lists and sets containing elements whose membership to the list or set may depend on information from the future of stream. However, we must ensure that the function application of the function by $E$ on elements of the collection does not run into nontermination. Restriction (2) thereby forbids letrec expressions, free variables, and other constants, which may lead to nontermination.

### 11.1.2 Linearizing a Sequence of Trees

Let $s$ be a sequence of trees $s=t_{1}, \ldots, t_{n}$. A streaming evaluator for $s$ consumes the events of linearizations $\operatorname{lin}\left(t_{1}\right), \ldots, \operatorname{lin}\left(t_{n}\right)$. At every time point, i.e. after having consumed already all events of linearizations $\operatorname{lin}\left(t_{i}\right)$ up to and excluding an event $e_{i}$ for all $1 \leq i \leq n$, then the evaluator has the choice to read next any of the events $e_{i}$ for some $1 \leq i \leq n$ :


By $l \leq e$ we denote the prefix of a linearization $l$ that ends with event $e$. A prefix of a linearization of $s$ is thus a tuple $\left(\operatorname{lin}\left(t_{1}\right)^{\leq e_{1}}, \ldots, \operatorname{lin}\left(t_{n}\right)^{\leq e_{n}}\right)$, which we denote by $\operatorname{lin}(s)^{\leq \vec{e}}$ where $\vec{e}=\left(e_{1}, \ldots, e_{n}\right)$. Notice that there are many possible linearizations of a sequence of trees: one for every different shuffle of events of the linearizations of the trees.

### 11.1.3 Updates

In streaming, values are computed over the stream incrementally, such that one needs a facility to modify them in an incremental manner. We define the modifications via update commands Upds listed in Figure 11.1 whose types upds $(T)$ are defined in Figure 11.2. When no update is required, one can make use of the command none. Update commands can be composed via "\&". Atomic future values - can be instantiated with a value $v$ via command instantiate $(v)$. Tuples are updated with an tuple of updates. Sets and lists can be extended and their elements can be updated and resolved, such that the element remains in the collection or is removed. Finally, variable assignments can be extended with a new record and values of variables may be updated.

In Figure 11.3 we present the apply function that given some value $v$ and an update command $c$ returns the by $c$ updated value of $v$.

| $c::=$ | none |  | no update |
| :---: | :---: | :---: | :---: |
| \| | $c_{1} \& c_{2}$ |  | two consecutive updates |
| \| | instantiate ( $v$ ) | $v: T \in \mathcal{T}_{\text {atom }}$ | instantiating - by $v$ |
| \| | $\left(c_{1}, \ldots, c_{n}\right)$ |  | updating tuples |
| \| | extend-set ( $v$ ) | $v:\{T\}$ | extending sets by set $v$ |
| \| | upd-elem-set ( $v, c$ ) | $v: T$ | updating element $v$ of a set |
| 1 | resolve-elem-set ( $\left.e^{?}, b\right)$ | $e^{?}: T, b:$ bool | resolving element $e^{\text {? }}$ by $b$ |
| \| | extend-list (v) | $v:[T]$ | extending lists by list $v$ |
|  | upd-elem-list ( $i, c$ ) | $i$ : int | updating elements at index $i$ in a list |
|  | resolve-elem-list ( $i, b$ ) | $i:$ int, $b$ : bool | resolving element $e^{?}$ at position $i$ by boolean $b$ |
|  | extend-var-ass ( $x, v$ ) | $x: T, v: T$ | extending variable assignment by $[x / v]$ |
| \| | upd-var-ass (x, v, c) | $x: T, v: T$ | updating assignment $x$ to $v$ by $c$ |

Figure 11.1: Update commands $c$.

$$
\begin{aligned}
& \frac{\text { true }}{\text { none }: \operatorname{upds}(T)} \\
& \frac{c_{1}: \operatorname{upds}(T) \quad c_{2}: \operatorname{upds}(T)}{c_{1} \& c_{2}: \operatorname{upds}(T)} \\
& \frac{T \in \mathcal{T}_{\text {atom }} \quad v \in T}{\text { instantiate }(v): \operatorname{upds}(T)} \\
& \frac{c_{1}: \operatorname{upds}\left(T_{1}\right) \quad \ldots \quad c_{n}: \operatorname{upds}\left(T_{n}\right)}{\left(c_{1}, \ldots, c_{n}\right): \mathbf{u p d s}\left(T_{1} \times \ldots \times T_{n}\right)} \\
& \frac{v:\{T\}}{\operatorname{extend}-\operatorname{set}(v): \operatorname{upds}(\{T\})} \quad \frac{v: T \quad c: \operatorname{upds}(T)}{u p d-e l e m-\operatorname{set}(v, c): \operatorname{upds}(\{T\})} \\
& \frac{e^{?}: T \quad b: \text { bool }}{\text { resolve-elem-set }\left(e^{?}, b\right): \operatorname{upds}(\{T\})} \\
& \frac{v:[T]}{\text { extend-list }(v): \mathbf{u p d s}([T])} \quad \frac{i: \text { int } c: \mathbf{u p d s}(T)}{u p d-\text { elem-list }(i, c): \mathbf{u p d s}([T])} \\
& \frac{i: \text { int } b: \text { bool }}{\text { resolve-elem-list }(i, b): \mathbf{u p d s}([T])} \\
& \frac{x: T \quad x \in V \quad v: T}{\text { extend-var-ass }(x, v): \operatorname{upds}\left(\mathbf{a s s}_{V}\right)} \quad \frac{x: T \quad x \in V \quad v: T \quad c: \operatorname{upds}(T)}{\text { extend-var-ass }(x, v): \operatorname{upds}\left(\operatorname{ass}_{V}\right)}
\end{aligned}
$$

Figure 11.2: Update commands and their types upds( $T$ ).

```
letrec
    apply = fun(v,c)
        case c
        of none then none
        of c}\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then apply(apply (v, c1), c⿱亠⿱口小⿺
        of instantiate ( }\mp@subsup{v}{}{\prime}\mathrm{ ) then if v=• then }\mp@subsup{v}{}{\prime}\mathrm{ end
        of (c, (c, c, cn) then
```



```
        of extend-set(v') then v\cup\mp@subsup{v}{}{\prime}
        of upd-elem-set (e, c') then v\{e}\cup{apply(e,\mp@subsup{c}{}{\prime})}
        of resolve-elem-set (e?,b) then if b then v\{e?}\cup{e} else v\{\mp@subsup{e}{}{?}}
        of extend-list( (v') then listconcat (v, v
        of upd-elem-list(i,\mp@subsup{c}{}{\prime}) then list-apply-pos(v,i,\lambdax.apply (x, c'))
        of resolve-elem-list (i,b) then if b then case v[i] of e}\mp@subsup{e}{}{\mathrm{ ? then}
            list-set(v,i,e) end else list-remove(v,i)
        of extend-var-ass(x,\mp@subsup{v}{}{\prime}) then }v\uplus[x/\mp@subsup{v}{}{\prime}
        of upd-var-ass(x, v},\mp@subsup{c}{}{\prime})\mathrm{ then }\mp@subsup{v}{|v.dom()\{x}}{}\uplus[x/\operatorname{apply}(\mp@subsup{v}{}{\prime},\mp@subsup{c}{}{\prime})
    end
in
    apply
end
```

Figure 11．3：Function to apply update commands．

## 11．1．4 Extended Types

We extend the types of $\lambda$ XP by types $\operatorname{ass}_{V}$ for variable assignments，type $\operatorname{proc}(T)$ of procedures that are like functions of type $T \rightarrow$ unit except that they do not produce any output，type $\operatorname{upds}(T)$ for update commands，variable types $\{x\}$ ，and event types event：

$$
\begin{aligned}
T: & :=A\left|T_{1} \times \ldots \times T_{n}\right|[T]|\{T\}| T_{1} \cup T_{2} \mid T_{1} \rightarrow T_{2} \\
& \left|\operatorname{ass}_{V}\right| \operatorname{proc}(T)|\operatorname{upds}(T)|\{x\} \mid \text { event }
\end{aligned}
$$

## 11．1．5 Open Values

For the evaluation of $\lambda \mathrm{XP}$ formulas we have to compute $s$－values incrementally，since the stream is consumed event per event．Given a prefix $\operatorname{lin}(s)^{\leq e}$ of a linearization of $s$ ，we can thus only compute $\operatorname{lin}(s) \leq{ }^{\leq}$－values，that are open values that we define in the following．

Open values are values such as atomic values，tuples，and functions，but where sets are replaced by open sets，lists by open lists，and where the $\bullet$ value is added． The open • value represents a future value that can only be determined once more information from the stream is known．For example，it may be the future value of a filter that requires to read more from the stream for the evaluation to true or false．Sets and lists may also contain uncertain elements $v^{?}$ ，which are atomic values whose selection depends on the future of the stream．It may be that not all the elements of a set are yet known，for which we consider open sets $S \cup \bullet$ where

```
\(\llbracket T \rrbracket_{s}^{\leq \vec{e}} \quad=\llbracket T \rrbracket_{s} \backslash\left\{\pi \mid \pi \notin \operatorname{nodes}\left(\operatorname{lin}(s)^{\leq \vec{e}}\right)\right\} \cup\{\bullet\} \quad T \in \mathcal{T}_{\text {atom }}\)
\(\llbracket T_{1} \times \ldots \times T_{n} \rrbracket \frac{\leq \vec{e}}{s}=\llbracket T_{1} \rrbracket \frac{\leq \vec{e}}{s} \times \ldots \times \llbracket T_{n} \rrbracket \rrbracket_{s}^{\leq \vec{e}}\)
\(\llbracket\{T\} \rrbracket \rrbracket_{s}^{\leq \vec{e}} \quad=\left\{\left\{v_{1}, \ldots, v_{n}\right\} \cup \bullet \mid v_{i}=v_{i}^{\prime}\right.\) or \(\left.v_{i}=v_{i}^{\prime ?}, v_{i}^{\prime} \in \llbracket T \rrbracket \frac{\leq \vec{s}}{s}\right\}\)
\(\llbracket[T] \rrbracket \frac{\leq \vec{e}}{s} \quad=\left\{v_{1}:: \ldots:: v_{n}:: \bullet \mid v_{i}=v_{i}^{\prime}\right.\) or \(\left.v_{i}=v_{i}^{\prime ?}, v_{i}^{\prime} \in \llbracket T \rrbracket \rrbracket_{s}^{\leq \vec{e}}\right\}\)
\(\llbracket T_{1} \cup T_{2} \rrbracket_{s}^{\leq \vec{s}} \quad=\llbracket T_{1} \rrbracket_{s}^{\leq \vec{e}} \cup \llbracket T_{2} \rrbracket_{\vec{s}} \vec{e}\)
\(\llbracket T_{1} \rightarrow T_{2} \rrbracket_{\stackrel{S}{s}}^{\leq \vec{e}}=\llbracket T_{1} \rrbracket \frac{\leq \vec{s}}{s} \rightarrow\left(\llbracket T_{2} \rrbracket_{\stackrel{S}{s}}^{\leq \vec{e}} \cup\{\perp\}\right)\)
\(\llbracket \operatorname{ass}_{V} \rrbracket_{s}^{\leq e} \quad=\) assignments of variables \(x \in V\) of some type \(T\)
    to open values in \(\llbracket T \rrbracket \frac{\leq \vec{e}}{}\)
\(\llbracket \operatorname{proc}(T) \rrbracket \frac{\leq \vec{e}}{}=\llbracket T \rrbracket \frac{\leq}{s} \vec{e} \rightarrow()\)
\(\llbracket \operatorname{upds}(T) \rrbracket_{\bar{s}}^{\leq \vec{e}} \quad=\) as defined in Figure 11.2
\(\llbracket\{x\} \rrbracket_{s}^{\leq \vec{e}} \quad=\{x\}\)
\(\llbracket\) event \(\rrbracket_{s}^{\leq \vec{e}} \quad=\) events \((s)\)
```

Figure 11.4: Open values $\llbracket T \rrbracket_{\frac{S}{s}}^{\leq \vec{e}}$, where $T$ is a type, $s$ a sequence of trees, and $\operatorname{lin}(s)^{\leq \vec{e}}$ is a prefix of $\operatorname{lin}(s)$ that ends with events $\vec{e}$.
only the elements of $S$ are known so far. Similarly open lists can be open to the right, such that the last element in the list is $\bullet$, for example open list $1:: 2:: 3:: \bullet$ • More precisely, we define open values $\llbracket T \rrbracket_{s}^{\leq \vec{e}}$ in Figure 11.4 for any extended type $T$ and prefix $\operatorname{lin}(s)^{\leq e}$ of a linearization of a sequence $s$ of data trees.

For atomic types $T \in \mathcal{T}_{\text {atom }}$ open values must belong to $\operatorname{lin}(s)^{\leq e_{e}}$-values and thus exclude any node that comes in the future of the stream. The selection of uncertain atomic open values $v^{?}$ depends on the future of the stream. They may only appear within sets and lists, and may thus be deleted later on. Open tuples are tuples that contain open values. Open sets are sets that may grow with the stream and contain uncertain elements. Open lists are lists $v_{1}:: \ldots:: v_{n}:: \bullet$ with an open end such that it may still grow with the stream containing possibly uncertain elements. Open functions are functions whose arguments and values are open values.

### 11.1.6 Registrations

We are interested in a program evaluator that computes the semantics of a formula incrementally while consuming the stream, and in a query evaluator that computes incrementally extensions of variable assignments under which some formula becomes true. This requires registrations that store in tables tuples of open values and variable assignments to open variable.

Definition 20. Let $V$ be a finite subset of typed variables, and let $T$ be some type. $A$ registration with these parameters is a tuple

$$
R=(\text { R.dom, R.set-val, R.add-inst, } \text { R.remove, R.upd-ass })
$$

of programs, that operate on a finite table as illustrate in Figure 11.5. This table maps entries of type $T^{\prime}=$ node $\times \mathbf{a s s}_{V}$ to values of type $T$ in a functional manner. The programs are doing the following:


Figure 11.5: A registration table.

- R.dom : unit $\rightarrow T^{\prime}$ is always applied to the empty tuple. It returns the current set of entries of type $T^{\prime}$ to which the registration's table assigns values.
- R.add-inst : $\boldsymbol{p r o c}\left(T^{\prime}\right)$ can be applied to any entry of type $T^{\prime}$ that is new to the table, and then adds it to the table with value $\bullet$.
- R.set-val : $\boldsymbol{\operatorname { p r o c }}\left(T^{\prime} \times T\right)$ is given as arguments an entry of type $T^{\prime}$ in the table and a value of type $T$. It then adds the entry with this value to the table.
- R.get-val : $T^{\prime} \rightarrow T$ is a partial function that can be applied to an entry of type $T^{\prime}$. It then returns the unique value of type $T$ that the table assigns to this entry, while assuming that it is there.
- R.remove : $\boldsymbol{\operatorname { p r o c }}\left(T^{\prime}\right)$ receives an entry of type $T^{\prime}$ as argument and removes it from the table, while assuming that is was there.
- R.upd-ass : $\boldsymbol{p r o c}\left(T^{\prime} \times \mathbf{a s s}_{V}\right)$ receives an entry of type $T^{\prime}$ and a variable assignment of type $\mathbf{a s s}_{V}$ and it assumes that the entry exists in the table. It then replaces the variable assignment of the entry with the given variable assignment, preserving the entrie's value.

Furthermore, we introduce master-registrations that extend registrations with further programs by which to govern a tuple of slave registrations by providing additional functionality.

Definition 21. Let $n$ be a natural number, $R$ is a registration of type $T$ with entries of type $T^{\prime}=$ node $\times \operatorname{ass}_{V}$ for some set of typed variables $V$, and $R_{i}$ are subregistrations of type $T_{i}$ for all $1 \leq i \leq n$. A master-registration is a tuple of programs:

$$
\mathcal{M}\left(R, R_{1}, \ldots, R_{n}\right)=(\mathcal{M} . \text { init-collection, } \mathcal{M} . \text { collect }, \mathcal{M} . \text { get-collection })
$$

These programs are doing the following:

- M.init-collection : $\boldsymbol{p r o c}\left(T^{\prime} \times \mathbf{i n t}\right)$ sets for some entry of type $T^{\prime}$ and some integer $1 \leq i \leq n$ the update command for subregistration $R_{i}$ to none,
- M.collect : proc( $\left.\bigcup T^{\prime} \times \operatorname{upds}\left(T_{i}\right) \times \mathbf{i n t}\right)$ collects update commands for $1 \leq i \leq n$
some entry of type $T^{\prime}$, some update command $c$, and some integer $1 \leq i \leq$ $n$. Update command $c$ is collected, by replacing the already collected update command $c^{\prime}$ of registration $R_{i}$ by $c^{\prime} \& c$, and
- M.get-collection: $\bigcup_{1 \leq i \leq n} T^{\prime} \times \mathbf{i n t} \rightarrow \mathbf{u p d s}\left(T_{i}\right)$ returns for some entry of type $T^{\prime}$ and some integer $1 \leq i \leq n$ the collected update command for registration $R_{i}$.


### 11.1.7 Program and Query Evaluators

In streaming we define program and query evaluators similar to the in-memory case, which however compute semantics of formulas and variable assignments incrementally. Let $E$ be a $\lambda$ XP formula of type $T$ with mode $E \triangleright V_{1} \rightarrow V_{2}$.

Program Evaluators. Program evaluators $A_{s}$ compute a semantic description of type $T$ of $E$ over some linearization $\operatorname{lin}(s)$ for some open node $\pi$ : node and some open variable assignment $\mu: \operatorname{ass}_{V_{1} \cup V_{2}}$. Evaluator $A_{s}$ maintains a registration $R$ with typed variables $V_{1} \cup V_{2}$ and result type $T$. Program evaluators $A_{s}=($ get-val, is-done, remove, add-inst, upd-val) are defined via the following functions, where $T^{\prime}=$ node $\times \operatorname{ass}_{V_{1} \cup V_{2}}$ :

- get-val : $T^{\prime} \rightarrow T$ is a partial function,
- is-done : $T^{\prime} \rightarrow \mathbf{b o o l}$ is a partial function,
- remove : $\operatorname{proc}\left(T^{\prime}\right)$,
- add-inst : $T^{\prime} \rightarrow \mathbf{u p d s}(T)$, and
- upd-val: $\bigcup_{x \in V_{1} \cup V_{2}}$ event $\times 2^{T^{\prime} \times\{x\} \times \operatorname{upds}(T Y P E(x))} \rightarrow 2^{T^{\prime} \times T \times \mathbf{u p d s}(T)}$.

Function get-val $(\pi, \mu)$ returns the value stored in $R$ for $\pi$ and $\mu$ by calling R.get-val $(\pi, \mu)$. Function is-done $(\pi, \mu)$ returns whether the open value computed by $A_{s}$ is determined. Procedure remove $(\pi, \mu)$ removes the entry with respect to $\pi$ and $\mu$ and thereby also calls $R$.remove $(\pi, \mu)$. Function $\operatorname{add-inst}(\pi, \mu)$ created a new entry in $R$ for the computation of the semantic of $E$, but for a new node $\pi$ and variable assignment $\mu$. The function calls $R$.add-inst $(\pi, \mu)$ and returns the update command, by which the initial $\bullet$-value in $R$ for $\pi$ and $\mu$ was updated. Lastly, function upd-val( $e, A s s U p s$ ) updates entries in $R$ with respect to event $e$ and $(\pi, \mu, x, c) \in$ AssUps, where the latter requires to update entry $(\pi, \mu) \in R . \operatorname{dom}()$ by applying $c$ to the value of $x \in \mu \cdot \operatorname{dom}()$. Not all entries may evolve at the new event $e$ however. The update function therefore returns the set of all tuples ( $\pi, \mu, v, c$ ), such that the value $v$ of entry $(\pi, \mu)$ was updated with $c$ to some new value $v^{\prime}$.

The evaluator is executed in an environment which feeds $R$ with instructions to create (add-inst), evolve (upd-val), and remove (remove) entries:


The incoming edge with label $(\pi, \alpha)$ represents that the environment has called $a d d-\operatorname{inst}(\pi, \alpha)$ that created entry $(\pi, \alpha)$ in $R$. The outgoing edge indicates that a call to upd-val(e, AssUps) at some event $e$ with variable assignment update AssUps updated the previous value of the entry with update command $c \in U p d s$ to value $v$. Notice, that the program and query evaluators may compute values for some future node •. In streaming we require such pre-computations for nodes that have not yet been seen on the stream, since the evaluation at nodes may require information from the past of the stream (via backward axes), while a streaming evaluator cannot go back on the stream. However given an environment such pre-computations are thereby not arbitrary. For example, when interested in computing the node labels for ancestor nodes, then the environment is in charge of running the a program evaluator $A_{s}$ for query $\operatorname{lab}_{\text {name }}(y)$ only for ancestor nodes $y$. The environment in this case is then another evaluator for the selection of ancestor nodes, that precomputes nodes that may be ancestors to future nodes and thus runs $A_{s}$ for these precomputed nodes.

Query Evaluators. Query evaluators $B_{s}$ compute extensions of variable assignments under which formula $E$ becomes true. Given some open node $\pi$ : node and some open variable assignment $\mu$ : $\boldsymbol{a s s}_{V_{1}}$ it means to generate all possible extensions $\mu^{\prime}: \boldsymbol{\operatorname { a s s }}_{V_{1} \cup V_{2}}$ of $\mu$. Evaluator $B_{s}$ maintains a registration $R$ with typed variables $V_{1}$ and result type $2^{\text {ass }_{V_{1}} \cup V_{2}}$. Program evaluators $B_{s}=$ (get-val, is-done, remove, add-inst, upd-val) are defined via the following functions, where $T^{\prime}=\operatorname{node} \times \boldsymbol{a s s}_{V_{1}}$ and $T^{\prime \prime}=2^{\operatorname{ass}_{V_{1} \cup V_{2}}}$ :

- get-val : $T^{\prime} \rightarrow T^{\prime \prime}$ is a partial function,
- is-done : $T^{\prime} \rightarrow$ bool is a partial function,
- remove : $\operatorname{proc}\left(T^{\prime}\right)$,
- add-inst : $T^{\prime} \rightarrow \mathbf{u p d s}\left(T^{\prime \prime}\right)$, and
- upd-val: $\bigcup_{x \in V_{1}}$ event $\times 2^{T^{\prime} \times\{x\} \times \operatorname{upds}(\operatorname{TyPE}(x))} \rightarrow 2^{T^{\prime} \times T^{\prime \prime} \times \operatorname{upds}\left(T^{\prime \prime}\right)}$.
similar to program evaluators, but with different signatures.


### 11.1.8 Running Evaluators over Streams

Let $s=t_{1}, \ldots, t_{n}$ be a stream of data trees $t_{1}, \ldots, t_{n}$. Let $E$ be a well-typed and well-moded $\lambda$ XP formula of type $T$ and mode $E \triangleright V_{1} \rightarrow V_{2}$. Let $\mu: \operatorname{ass}_{V_{1} \cup V_{2}}$ be an assignment of input variables in $V_{1} \cup V_{2}$, let $\pi \in\left\{\operatorname{root}\left(t_{i}\right) \mid 1 \leq i \leq n\right\}$, and let $A_{s}$ be a program evaluator for $E \triangleright V_{1} \rightarrow V_{2}$. The program evaluator $A_{s}$ is run over stream $s$ according to the evaluation function eval of Figure 11.6. There, list-of-events(s) computes a stream-merge of linearizations $\operatorname{lin}\left(t_{i}\right)$ of $s$ returning a list of events of $\operatorname{lin}(s)$ in an implementation dependent order. Note that at any time point, open values $\llbracket T \rrbracket \frac{\leq \vec{e}}{}$ are stored in the registration for $A_{s}$

```
//Let As be a program evaluator for E\trianglerightV狽 }->\mp@subsup{V}{2}{
evals}
    fun( }\pi,\mu
        (get-val, is-done, remove, add-inst, upd-val) = As
        {x, ,\ldots, 利}= V V \cupV V
        add-inst(\bullet, \mu)
    in
        letrec
            eval' =
            fun(l)
                case l
                of e::l}\mp@subsup{l}{}{\prime}\mathrm{ then
                                    if e=(op,\pi) then add-inst (\pi,\mu) else skip end
                                    upd-val(e,\emptyset)
                    in
                                    if is-done( }\pi,\mu)\mathrm{ then
                                    get-val(\pi, \mu)
                            else
                                eval'(l')
                            end
                    of nil then
                        get-val(\pi, \mu)
                    end
            end
        in
            eval'(list-of-events(s))
    end
```

Figure 11.6: Evaluation of program evaluators over streams $s$.

```
// for any link function on a registration R with variables W
// link: node }\times\mp@subsup{\boldsymbol{ass}}{W}{}->\mp@subsup{\mathbf{ass}}{\mp@subsup{W}{}{\prime}}{}\mathrm{ for some W
// generate a function computing inverse links to entries of R:
// gen-inv-links(R,link): node }\times\mp@subsup{\boldsymbol{\operatorname{ass}}}{\mp@subsup{W}{}{\prime}}{}->2,\mp@subsup{2}{}{\mathrm{ node }\times\mp@subsup{\mathbf{ass}}{W}{}
gen-inv-links(R,link) =
    fun (\pi : node, }\mp@subsup{\gamma}{}{\prime}:\mp@subsup{\boldsymbol{\operatorname{ass}}}{\mp@subsup{W}{}{\prime}}{}
        {(\pi,\gamma)\inR.dom()|\operatorname{link}(\pi,\gamma)=\mp@subsup{\gamma}{}{\prime}}
    end
```

Figure 11.7: Generator of inverse links function.

### 11.2 Evaluators

In this section we present the streaming algorithms that evaluate a network of simple well-typed and well-moded $\lambda$ XP formulas with eliminated backward axes. For this we need to define program and query evaluators for all $\lambda$ XP formulas. Before defining them inductively with respect to the mode system, we will present and explain commonly used generic functions that will be used by our evaluators.

### 11.2.1 Generic Functions

Since the evaluators are constructed inductively, the registrations have the following form:


There, some evaluator $A_{s}$ updates a registration $R$ with variables in $V$, while subevaluators $A_{i s}$ will update registrations $R_{i}$ for $1 \leq i \leq n$. Evaluator $A_{s}$ maintains link relations link $\boldsymbol{l}_{i}:$ node $\times \boldsymbol{a s s}_{V} \rightarrow \operatorname{ass}_{V_{i}}$ that uniquely link an entry ( $\left.\pi, \alpha\right) \in R$.dom() to entries $\left(\pi, \operatorname{link}_{i}(\pi, \alpha)\right) \in R_{i}$. $\operatorname{dom}()$. However, an entry in a subregistration may be linked to various entries in the parent registration. In Figure 11.7 we present a generator for inverse link function that map to sets of pairs of nodes and variable assignments in the parent registration.

```
// for any link function on a registration
// generate a function gen-ass-com that computes update commands
gen-ass-com(link)=
    fun(AssUps,U)
        AssUps' = set.new()
        for ( }\pi,\gamma,x,c)\inAssUps d
            AssUps'.}.\operatorname{add}(\pi,\operatorname{link}(\pi,\gamma),x,c
        end
        in
        AssUps'.content()
    end
```

Figure 11.8: Generator of functions that update assignment commands.

Registration then exchange update commands that are communicated among linked entries. Given updates $c_{i}$ of values of entries in $R_{i}$ one can then compute update commands for entries in the parent registration $R$ to which is linked with respect to the inverse link function. Update commands are thus computed in a bottom up fashion. However, one must also pass updates of variable assignments top down. This becomes evident, for example, when decomposing tuples. Consider mode rule

$$
\begin{gathered}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime} \\
E=\operatorname{match} E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

When subexpression $E_{1}$ evaluates to some $n$-tuple, then $E_{2}$ is evaluated while assigning to variables $x_{i}$ the value of the $i$-th component of the $n$-tuple. In streaming, the values of the components of the open tuple may not yet be determined. Therefore, whenever some component of the tuple is updated, one also has to update the corresponding variable assignment that $E_{2}$ contains. In Figure 11.8 we define generator gen-ass-com that given some link definition returns a function that starting from some update for variable assignments AssUps, returns a new update for variable assignments to be passed down to subevaluators according to the link definition.

In the beginning before evaluating over the stream we must initialize all registrations with an initial entry of the future node $\bullet$ and some initial variable assignment where every variable is mapped to $\bullet$. This is necessary for the automata registrations that precompute backward axes nodes. Besides the initial entries one can create new entries in some registration $R$ via function add-inst of $R$. Due to our restrictions it holds the following invariant: When calling add-inst $(\pi, \mu)$ at some event of the stream, either the event is the opening event of node $\pi$, or $R$ answers an expression whose type contains not the type node as subterm. The function can be defined for most $\lambda \mathrm{XP}$ constructs by the functions generator of Figure 11.9 that is parameterized by $a d d-i n s t_{i}$ and link $_{i}$ functions of subregistrations and function get-upd-com that computes update commands. The generated function obtains the

```
// R is registration with variables W and type T with streams s
// that has subregistrations }\mp@subsup{R}{i}{}\mathrm{ with the same streams s. For i:
// - function add-insti instantiates entries of registration R
// - function linki converts entries of R to entries of R
// - function get-upd-com returns update commands of R based on the
    update commands of }\mp@subsup{R}{i}{
gen-add-inst(R,add-inst },\ldots,\ldots,add-inst ( , link ( , .., link * , get-upd-com)=
    fun( }\pi:\mathbf{node, }\gamma:\mp@subsup{\boldsymbol{ass}}{W}{}
            R.add-inst( }\pi,\gamma
            c
            c
            c=get-upd-com(\pi,\gamma,\mp@subsup{c}{1}{},\ldots,\mp@subsup{c}{n}{}))
            R.set-val(\pi,\gamma,\operatorname{apply}(R(\pi,\gamma),c))
        in
            c
        end
```

Figure 11.9: Generator of functions that instantiate registration entries.

```
// R is registration with variables W and subregistration R on
// the same streams. For all i:
// - procedure removei removes entries of registration R
// - function link convert entries of R to entries of R
gen-remove( }R,\mp@subsup{\mathrm{ remove }}{1}{},\ldots,\mp@subsup{\mathrm{ remove }}{n}{},\mp@subsup{\operatorname{link}}{1}{},\ldots,\mp@subsup{\operatorname{link}}{n}{})
    proc( }\pi\mathrm{ : node, }\gamma:\mp@subsup{\boldsymbol{ass}}{W}{}
        remove}1(\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\gamma)
        remove}n(\pi,\mp@subsup{\operatorname{link}}{n}{}(\pi,\gamma)
        R.remove( }\pi,\gamma
    end
```

Figure 11.10: Generator of remove procedures.
updates $c_{i}$ by the $a d d$-inst ${ }_{i}$ function applied to entries that are in $\operatorname{link}_{i}$ relation to the input node $\pi$ and variable assignment $\gamma$, then it computes the update commands $c$ for $R$ by calling get-upd-com on the basis of all $c_{i}$. Finally, it sets the value of $R$ for $\pi$ and $\gamma$, applying the result update command $c$ to the initial $\bullet$-value $R(\pi, \gamma)$.

Entries in $R$ may also be removed, which can be defined for most evaluators by procedures of the generator in Figure 11.10. Via the $\operatorname{link}_{i}$ functions and remove ${ }_{i}$ procedure for subregistrations, the remove procedures by the generator removes entries in subregistrations to which entry $(\pi, \gamma) \in R . \operatorname{dom}()$ is linked, and it removes entry $(\pi, \gamma)$ itself.

Last but not least, in Figure 11.11 we present a generator for update functions that implements a rewriting of entries in $R$ that returns a set of tuples ( $\pi, \gamma, v, c$ ) of entries $(\pi, \gamma) \in R . \operatorname{dom}()$ whose value $v$ was updated by $c$ at some event $e$ of
some stream $s$. First, one updates the variable assignments in $R$ with respect to tuples $(\pi, \gamma, x, c) \in$ AssUps: An entry with node $\pi$ and variable assignment $\gamma$ is updated with the value that is obtained by applying command $c$ to the value of $x$ in $\gamma$. Next, one updates entries of subregistrations $R_{i}$ by calling the respective upd-val ${ }_{i}$ functions, while an update $U_{i}$ may cause a change in a variable assignment of a sibling registration, for which get-ass-com is called. Notice that answer tuples in $U_{i}$ concern only those entries in $R_{i}$ whose value changed at event $e$. Similarly for $R$ one wants to return only those answers of entries which value has changed. Therefore, we initialize a new collection, and collect all tuples $(\pi, \gamma, c, i)$ where a linked entry of subregistration $R_{i}$ was updated with command $c$. Then, for all entries in $R$ for which some linked entry of a subregistrations was updated, one calls the get-upd-com function for $R$ to compute the updates for the respective entry. We note that $\mathcal{M}$.get-collection $(\pi, \gamma, i)$ is equal to update command none if the linked entry in $R_{i}$ was not updated. Finally, we set the new value in $R$, applying the newly computed update command to the old value in $R$, and we can safely accumulate tuples in the answer set.

### 11.2.2 Inductive Construction of Evaluators

The construction of $A_{s}$ and $B_{s}$ is by simultaneous induction on derivations of judgements $E \triangleright V_{1} \rightarrow V_{2}$.

## Induction:

Submode rule 1. Suppose that the judgement $E \triangleright V_{1} \rightarrow V_{2}$ is derived by the first rule for submodes:

$$
\frac{E \triangleright V \rightarrow V^{\prime}}{E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}}
$$

Let $A_{s}^{\prime}$ be a program evaluator evaluating $E \triangleright V \rightarrow V^{\prime}$ while assuming values for all variables in $V^{\prime}$. We have to define a program evaluator $A_{s}$ that evaluates $E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}$ given values for $V^{\prime}$. The idea is as follows. Program evaluator $A_{s}$ updates a registration $R$ with variables in $W=V \cup V^{\prime} \cup V^{\prime \prime}$, while program evaluator $A_{s}^{\prime}$ will update a registration $R^{\prime}$ with variables in $W \backslash V^{\prime \prime}$ that contains the corresponding entries projected to $W \backslash V^{\prime \prime}$.

| R | $(\pi, \alpha)$ | node $\mathrm{ass}_{W}$ | TYPE(E) | $\int_{u p d(v)}$ |
| :---: | :---: | :---: | :---: | :---: |
|  |  | $\pi \quad \alpha$ | $v$ |  |
|  | $\left(\pi, \alpha_{\left.\right\|_{W \backslash V^{\prime \prime}}}\right)$ | ... |  | $u p d(v)$ |

```
// \(R\) is registration with variables \(W\) and type \(T\) with streams \(s\)
// that has subregistration \(R_{i}\) with the same streams \(s\). For all \(i\) :
// - function upd-vali updates entries of registration \(R_{i}\)
// - function linki converts entries of \(R\) to entries of \(R_{i}\)
// - function get-upd-com returns update commands of \(R\) based on the
    updated commands of \(R_{i}\)
// - function get-ass-com computes assignment updates \(^{\text {con }}\)
gen-upd-val( \(R\), upd-val \(l_{1}, \ldots\), upd-val \(_{n}\), link \(_{1}, \ldots\), link \(_{n}\), get-upd-com, get-ass-com \({ }_{1}, \ldots\),
    get-ass-com \(\left.{ }_{n}\right)=\)
        let
            \(i n v-\) links \(_{1}=\) gen-inv-links \(\left(R, \operatorname{link}_{1}\right)\)
            inv-links \(_{n}=\) gen-inv-links \(\left(R, \operatorname{link}_{n}\right)\)
            in
            fun( \(e \in \operatorname{events}(s)\), AssUps \()\)
                for \((\pi, \gamma, x, c) \in \operatorname{AssUps}\) do R.upd-ass \(\left(\pi, \gamma, \gamma_{\mid W \backslash\{x\}} \uplus[x / \operatorname{apply}(\gamma(x), c)]\right)\) end
                    \(U_{1}=u p d-v a l_{1}\left(e\right.\), get-ass-com \({ }_{1}(\) AssUps, \(\left.\emptyset)\right)\)
                    \(U_{2}=u p d-v a l_{2}\left(e\right.\), get-ass-com \(\left.{ }_{2}\left(A s s U p s, U_{1}\right)\right)\)
                    \(U_{n}=\operatorname{upd}^{-v a l_{n}}\left(e\right.\), get-ass-com \({ }_{n}\left(\right.\) AssUps \(\left.\left.^{( } U_{n-1}\right)\right)\)
                    \(\mathcal{M}=\) master-registration.new \(\left(R, R_{1}, \ldots, R_{n}\right)\)
                        for \((\pi, \gamma) \in R . \operatorname{dom}()\) do
                    for \(1 \leq i \leq n\) do \(\mathcal{M}\).init-collection \((\pi, \gamma, i)\) end
                    end
                    for \(1 \leq i \leq n\) do
                    for \(\left(\pi, \gamma^{\prime}, v, c\right) \in U_{i}\) do
                        for \((\pi, \gamma) \in \operatorname{inv-links}\left(\pi, \gamma^{\prime}\right)\) do
                                    \(\mathcal{M} . \operatorname{collect}(\pi, \gamma, c, i)\)
                    end
                    end
                    end
                    \(M=\) set.new ()
                        for \((\pi, \gamma) \in R . \operatorname{dom}()\) do
                        \(c=\) get-upd-com \((\pi, \gamma, \mathcal{M}\). get-collection \((\pi, \gamma, 1), \ldots\),
                                M.get-collection \((\pi, \gamma, n)\) )
                    \(v=R(\pi, \gamma)\)
                        R.set-val( \(\pi, \gamma, \operatorname{apply}(v, c))\)
                    in \(\operatorname{M.add}((\pi, \gamma, v, c))\)
                        end
                in M.content()
        end
    end
```

Figure 11.11: Generator of update functions.

```
// Let \(A_{s}^{\prime}\) be a program evaluator for \(E \triangleright V \rightarrow V^{\prime}\)
\(A_{s}=\) let \(/ /\) program evaluator for \(E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}\).
    (get-val', \({ }^{\prime}\) s-done \({ }^{\prime}\), remove \({ }^{\prime}\), add-inst \({ }^{\prime}\), upd-val \(\left.l^{\prime}\right)=A_{s}^{\prime}\)
    \(W=V \cup V^{\prime} \cup V^{\prime \prime}\)
    \(R=\) registration.new( \(W\), \(\operatorname{TYpe}(E))\)
    link \(=\mathbf{f u n}(\pi, \alpha) \quad \alpha_{\left.\right|_{W \backslash V^{\prime \prime}}}\) end
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    get-upd-com \(=\) fun \(\left(\pi, \alpha, c^{\prime}\right) c^{\prime}\) end
    \(i s\)-done \(=\mathbf{f u n}(\pi, \alpha) \quad i s-\operatorname{done}^{\prime}(\pi, \operatorname{link}(\pi, \alpha))\) end
    remove \(=\) gen-remove \((R\), remove', link \()\)
    add-inst \(=\) gen-add-inst ( \(R\), add-inst', link, get-upd-com)
    upd-val \(=\) gen-upd-val( \(R\), upd-val', link, get-upd-com, gen-ass-com(link) \()\)
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.12: A program evaluator for submode rule 1 on streams $s$

Whenever the environment of $A_{s}$ requires to compute the value of $E$ for a new instance, consisting of a possible open start node $\pi$ and some possible open $W$ assignment $\alpha$, then $R$.add- $\operatorname{inst}(\pi, \alpha)$ is called and adds $R . \operatorname{get}-v a l(\pi, \alpha)=\bullet$. Then the subregistration is called with $R^{\prime}$.add-inst $\left(\pi, \alpha_{\left.\right|_{W \backslash V^{\prime \prime}}}\right)$ to add a linked entry $R^{\prime} . \operatorname{get}-v a l\left(\pi, \alpha_{\left.\right|_{W \backslash V^{\prime \prime}}}\right)=\bullet$. We then have to ensure that $R . \operatorname{get}-\operatorname{val}(\pi, \alpha)=R^{\prime} . \operatorname{get}-v a l\left(\pi, \alpha_{\mid W \backslash V^{\prime \prime}}\right)$ how so ever the open value will be instantiated by $R^{\prime}$ later on: When calling $A_{s}$.upd-val the updates to values in $R^{\prime}$ by $A_{s}^{\prime}$ are also carried out to corresponding values of $R$. This idea can be implemented by the following program evaluator $A_{s}$ based on algorithm $A^{\prime}$ in Figure 11.12. There, function get-upd-com performs updates $c^{\prime}$ to values in $R$, when $A_{s}^{\prime}$ performs updates $c^{\prime}$ to corresponding values in $R^{\prime}$.

Let $B_{s}^{\prime}$ be a query evaluator that evaluates $E \triangleright V \rightarrow V^{\prime}$ on streams while generating values for $V^{\prime}$. We have to define a streaming query evaluator $B_{s}$ for $E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}$ that generates values for $V^{\prime}$. The idea is similar to that of $A_{s}$ but now the registrations updated by $B_{s}$ and $B^{\prime}{ }_{s}$ have the following forms.


For computing the value of $R . \operatorname{get}-\mathrm{val}(\pi, \beta)$ by $B_{s}$ a corresponding entry $R . \operatorname{get}$-val $\left(\pi, \beta_{\mid V}\right)$

```
// Let B
Bs}=\mathrm{ let // query evaluator for E}\trianglerightV\cup\mp@subsup{V}{}{\prime\prime}->\mp@subsup{V}{}{\prime}
    (get-val', is-done', remove}\mp@subsup{}{}{\prime},\mathrm{ add-inst', upd-val')}=\mp@subsup{B}{s}{\prime
    W=V\cup\mp@subsup{V}{}{\prime}\cup\mp@subsup{V}{}{\prime\prime}
    R= registration.new (W\\mp@subsup{V}{}{\prime},\operatorname{TYPE}(E))
    link}=\mathbf{fun}(\pi,\beta)\quad\mp@subsup{\beta}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    get-val = fun (\pi,\beta) R(\pi,\beta) end
    letrec
        get-upd-com=
        fun (\pi, \beta, c)
            case c
            of none then none
            of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then get-upd-com( }\pi,\beta,\mp@subsup{c}{1}{})&get-upd-com(\pi,\beta,\mp@subsup{c}{2}{}
            of extend-set(v) then extend-set ({\mp@subsup{\beta}{}{\prime}\uplus\beta\mp@subsup{|}{\mp@subsup{V}{}{\prime\prime}}{}|\mp@subsup{\beta}{}{\prime}\inv})
            of upd-elem-set (e, c') then upd-elem-set (e\uplus 
            of resolve-elem-set (e,b) then resolve-elem-set (e\uplus 
        end
    in
    is-done = fun( }\pi,\beta) is-\mp@subsup{done}{}{\prime}(\pi,\operatorname{link}(\pi,\beta))\mathrm{ end
    remove = gen-remove( }R\mathrm{ , remove',link)
    add-inst = gen-add-inst(R, add-inst',link,get-upd-com)
    upd-val = gen-upd-val(R,upd-val',link,get-upd-com,gen-ass-com(link))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.13: A query evaluator for submode rule 1 on streams $s$.
is added to the registration of $B_{s}^{\prime}$. Whenever some variables assignment $\beta^{\prime}$ is added to $R^{\prime}$.get-val $\left(\pi, \beta_{\left.\right|_{V}}\right)$, the corresponding variable assignment $\beta^{\prime} \uplus \beta_{\mid V^{\prime \prime}}$ is added to R.get-val $(\pi, \beta)$. When an existing element $e$ in $R^{\prime}$.get-val $\left(\pi, \beta_{\left.\right|_{V}}\right)$ is updated, the corresponding element $e \uplus \beta_{\left.\right|^{\prime \prime}}$ in $R . \operatorname{get}-\operatorname{val}(\pi, \beta)$ is updated as well, and similar for resolving elements, as described by function get-upd-com of the streaming query evaluator given in Figure 11.13.

Submode rule 2. Next consider the case, where the judgement was inferred by the second rule for submodes:

$$
\frac{E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}}{E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}}
$$

Let $A^{\prime}{ }_{s}$ be a program evaluator for $E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}$. We define the program evaluator $A_{s}$ for $E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}$ in Figure 11.14. The registrations $R$ and $R^{\prime}$ have the following forms where $W=V \cup V^{\prime} \cup V^{\prime \prime}$.


Updates to values in $R^{\prime}$ are also carried out to corresponding values in $R$, see definition of the get-upd-com function. Let $B^{\prime}{ }_{s}$ be a query evaluator for $E \triangleright V \rightarrow$ $V^{\prime} \cup V^{\prime \prime}$. We define the query evaluator $B_{s}$ for $E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}$ in Figure 11.15, with registrations:


Whenever a new variable assignment $\beta^{\prime}$ is added to $R^{\prime}$.get-val $\left(\pi, \beta_{\left.\right|_{V}}\right)$, then one adds it also $R$.get-val $(\pi, \beta)$, but only if $\beta \subseteq \beta^{\prime}$. Function get-upd-com also describes,

```
\(/ /\) Let \(A_{s}^{\prime}\) be a program evaluator for \(E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}\)
\(A_{s}=\) let \(/ /\) program evaluator for \(E \triangleright V \cup V^{\prime \prime} \rightarrow V^{\prime}\)
    (get-val', is-done \({ }^{\prime}\), remove \(^{\prime}\), add-inst \({ }^{\prime}\), upd-val' \()=A_{s}^{\prime}\)
    \(W=V \cup V^{\prime} \cup V^{\prime \prime}\)
    \(R=\) registration.new \((W, \operatorname{TYPE}(E))\)
    link \(=\mathbf{f u n}(\pi, \alpha) \quad \alpha\) end
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    get-upd-com \(=\mathbf{f u n}\left(\pi, \alpha, c^{\prime}\right) \quad c^{\prime}\) end
    \(i s\)-done \(=\) fun \((\pi, \alpha)\) is-done \({ }^{\prime}(\pi, \alpha)\) end
    remove \(=\) gen-remove \((R\), remove', link \()\)
    add-inst \(=\) gen-add-inst \(\left(R\right.\), add-inst' \({ }^{\prime}\), link, get-upd-com \()\)
    \(u p d-v a l=\) gen-upd-val \((R\), upd-val', link, get-upd-com, gen-ass-com(link))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.14: A program evaluator for submode rule 2 on streams $s$.
that updating or resolving the value of an element in $R^{\prime} . \operatorname{get}$-val $\left(\pi, \beta_{\left.\right|_{V}}\right)$ results in a update of the respective element in $R . \operatorname{get}-v a l(\pi, \beta)$ if it exists.

Conjunction. The mode is inferred by inference rule:

$$
\frac{E_{1} \triangleright V \rightarrow V^{\prime} \quad E_{2} \triangleright V \cup V^{\prime} \rightarrow V^{\prime \prime} \quad E=E_{1} \wedge E_{2}}{E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}}
$$

Let $A_{1 s}$ be a program evaluator for $E_{1} \triangleright V \rightarrow V^{\prime}$ and $A_{2 s}$ be a program evaluator for $E_{2} \triangleright V \cup V^{\prime} \rightarrow V^{\prime \prime}$. We define a program evaluator $A_{s}$ for $E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}$ in Figure 11.16, while registration have the following form where $W=V \cup V^{\prime} \cup V^{\prime \prime}$ :

| R |  | node | $s_{W}$ | bool |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\pi$ |  | $v_{1} \wedge^{\text {Bool }}{ }^{\perp} v_{2}$ | $u p d$ (v |  |
|  | $\left(\pi, \alpha_{\left.\right\|_{V \cup V^{\prime}}}\right) / / \operatorname{upd}\left(v_{1}\right)$ <br> node $\operatorname{ass}_{V \cup V^{\prime}} \mid$ bool |  | $\begin{array}{r} (\pi, \alpha) \ u p d\left(v_{2}\right) \\ \underline{\text { node } \operatorname{ass}_{W}} \mid \text { bool } \\ \hline \end{array}$ |  |  |  |
|  |  |  |  |
| $R_{1}$ | $\pi \quad \alpha_{\left.\right\|_{V \cup V^{\prime}}}$ | $v_{1}$ |  |  |  |  | $\pi \stackrel{ }{\cdots}$ | $v_{2}$ | $R_{2}$ |
|  |  |  |  |  |  |  |

Given some entry $(\pi, \alpha) \in R . \operatorname{dom}()$ one waits until entries $\left(\pi, \alpha_{\left.\right|_{V \cup V^{\prime}}}\right) \in R_{1} . \operatorname{dom}()$ and $(\pi, \alpha) \in R_{2} \cdot \operatorname{dom}()$ have determined values $v_{1}$ and $v_{2}$, respectively, such that the conjunction $v_{1} \wedge^{\text {Bool }} v_{2}$ can be computed. The get-upd-com function implements this by returning none until at some event $e$ it holds that is-done $(\pi, \alpha)$ is true and

```
// Let B
B}=\mathrm{ let // query evaluator for E}\trianglerightV\cup\mp@subsup{V}{}{\prime\prime}->\mp@subsup{V}{}{\prime
    (get-val', is-done', remove}\mp@subsup{}{}{\prime},\mathrm{ add-inst', upd-val')}=\mp@subsup{B}{s}{\prime
    W=V\cupV'\cupV''
    R= registration.new(W\V',
    link}=\mathbf{fun}(\pi,\beta)\quad\mp@subsup{\beta}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    get-val = fun(\pi,\beta) R(\pi,\beta) end
    letrec
        get-upd-com =
        fun ( }\pi,\beta,c
            case c
            of none then none
            of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then get-upd-com( }\pi,\beta,\mp@subsup{c}{1}{})&get-upd-com(\pi,\beta,\mp@subsup{c}{2}{}
            of extend-set (v) then extend-set ({\mp@subsup{\beta}{}{\prime}|\mp@subsup{\beta}{}{\prime}\inv,\beta\subseteq\mp@subsup{\beta}{}{\prime}})
            of upd-elem-set (e, c') then if e\inget-val(\pi,\beta) then upd-elem-set (e, c') else
                none
            of resolve-elem-set (e,b) then if e\inget-val( }\pi,\beta)\mathrm{ then resolve-elem-set (e,b)
                else none
        end
    in
    is-done = fun( }\pi,\beta) is-done'(\pi,\operatorname{link}(\pi,\beta))\mathrm{ end
    remove = gen-remove( }R,\mathrm{ remove',link)
    add-inst = gen-add-inst(R,add-inst',link, get-upd-com)
    upd-val = gen-upd-val(R,upd-val',link,get-upd-com,gen-ass-com(link))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.15: A query evaluator for submode rule 2 on streams $s$.

```
// let A As a program evaluator for E E \triangleright 
// let }\mp@subsup{A}{2s}{}\mathrm{ a program evaluator for E E D V U VV' }->\mp@subsup{V}{}{\prime\prime
As}=\mathrm{ let // program evaluator for E = E 左^ E D }\trianglerightV->\mp@subsup{V}{}{\prime}\cup\mp@subsup{V}{}{\prime\prime
    (get-val },\mp@subsup{\mathrm{ is-done }}{1}{},\mp@subsup{\mathrm{ remove }}{1}{},\mathrm{ add-inst }\mp@subsup{\mp@code{I}}{1}{},\mp@subsup{\mathrm{ upd-val }}{1}{})=\mp@subsup{A}{1s}{
    (get-val },\mp@subsup{\mathrm{ is-done }}{2}{},\mp@subsup{\mathrm{ remove }}{2}{},\mathrm{ add-inst }\mp@subsup{\mp@code{N}}{2}{},\mp@subsup{\mathrm{ upd-val }}{2}{})=\mp@subsup{A}{2s}{
    W=V\cup\mp@subsup{V}{}{\prime}\cup\mp@subsup{V}{}{\prime\prime}
    R= registration.new(W,TYPE (E))
    link}\mp@subsup{k}{1}{}=\mathbf{fun}(\pi,\alpha)\quad\mp@subsup{\alpha}{\mp@subsup{|}{V\cup\mp@subsup{V}{}{\prime}}{\prime}}{}\mathrm{ end
    link}\mp@subsup{k}{2}{}=\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
```



```
        instantiate (get-val ( }\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha))\mp@subsup{\wedge}{}{\mathrm{ Bool }
    is-done = fun (\pi,\alpha) is-done 
    remove = gen-remove (R, remove}1,\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = gen-add-inst(R,add-inst 
    upd-val = gen-upd-val(R,upd-val },\mathrm{ upd-val }\mp@subsup{\mp@code{vink}}{1}{},\mp@subsup{\mathrm{ link }}{2}{},\mathrm{ get-upd-com,
                                    gen-ass-com(link}\mp@subsup{1}{1}{}),\mathrm{ gen-ass-com(link }2\mathrm{ ))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.16: A program evaluator for conjunctions on streams $s$.
such that either $v_{1}$ in $R_{1}$ was updated by some update command $c_{1} \neq$ none or $v_{2}$ was updated by some update command $c_{2} \neq$ none.

Let $B_{1 s}$ be a query evaluator for $E_{1} \triangleright V \rightarrow V^{\prime}$ and $B_{2 s}$ be a query evaluator for $E_{2} \triangleright V \cup V^{\prime} \rightarrow V^{\prime \prime}$. A query evaluator $B_{s}$ for $E \triangleright V \rightarrow V^{\prime} \cup V^{\prime \prime}$ is given in Figure 11.17 and Figure 11.18. Its registration have the following form:


The idea is the following. For every entry $(\pi, \beta) \in R . \operatorname{dom}()$ there exists a corresponding entry in $(\pi, \beta) \in R_{1} \cdot \operatorname{dom}()$, which computes variable extensions $\left\{\beta_{1}, \ldots, \beta_{n}\right\}$. According to the mode rule $E_{2} \triangleright V \cup V^{\prime} \rightarrow V^{\prime \prime}$ the evaluator $B_{2 s}$
must receive as input values for variables in $V$ and $V^{\prime}$. Therefore, for every $\beta_{i}$ where $1 \leq i \leq n$ an entry $\left(\pi, \beta_{i}\right)$ is created in $R_{2}$, while the union of their answers $v_{1}$ until $v_{n}$ becomes the final answer for $B_{s}$. Since the link definition link ${ }_{2}$ links one entry of $R$ to many entries in $R_{2}$, unlike all other evaluators presented here, the query evaluator presented in Figure 11.17 and Figure 11.18 cannot use the common functions that are generated by the function generators in Section 11.2.1. The add-inst function of Figure 11.17 therefore starts add-inst ${ }_{1}$ for some open node $\pi$ and open variable assignment $\beta$, and calls function create-entries that creates for every new answer $v_{i}$ of $R_{1}$ with respect to $\pi$ and $\beta$ an entry in $R_{2}$, while the result update command is a conjunction $a d d-$ inst $_{2}\left(\pi, v_{1}\right) \& \ldots \& a d d-$ inst $_{2}\left(\pi, v_{n}\right)$. Function upd-val presented in Figure 11.18 updates at some event $e \in \operatorname{events}(s)$ with variable assignment updates $A s s U p s$ the entries of $R$ as follows. Variable assignment update in AssUps are carried out to $R$ via function upd-ass. Next, before calling function upd-val ${ }_{1}$, one starts to compute the new variable assignment updates $A s s U p s^{\prime}$ needed for the evaluation of upd-val ${ }_{2}$. Hence every existing entries in AssUps are changed according to link definition $\operatorname{link}_{2}$. Next, we obtain updates $U_{1}=u p d-v a l_{1}(e, A s s U p s)$, that allows to add to $A s s U p s^{\prime}$ those assignment updates for variables in $V^{\prime}$ that $B_{2 s}$ generated and for which $R_{2}$ contains corresponding entries. This is done by function add-ups which in case that $B_{1 s}$ performed an update $c^{\prime}$ to some variable assignment $\beta^{\prime}$ in upd-elem-set $\left(\beta^{\prime}, c^{\prime}\right)$ calls function add-var-ass-ups which in turn adds a respective variable assignment update to AssUps ${ }^{\prime}$, when $c^{\prime}$ was an update to some variable in assignment $\beta^{\prime}$. Otherwise, function add-ups in the case that $B_{1 s}$ removed some element $\beta^{\prime}$ in resolve-elem-set $\left(\beta^{\prime ?}\right.$, false $)$ then the corresponding entry in $R_{2}$ is removed, while $B_{s}$ has to remove the elements of $\operatorname{get}-v a l_{2}(\pi, b)$ in $\operatorname{get}-v a l(\pi)$. Finally, we have compute the variable assignment updates $A s s U p s^{\prime}$ and function upd-val proceeds to call upd-val ${ }_{2}$ with $e$ and $A s s U p s^{\prime}$ to obtain $U_{2}$. Next we need to add missing updates to $M$. Similar to function add-inst one creates new entries in $R_{2}$ for those new variable assignments found by $B_{1 s}$ in $U_{1}$ by calling function create-entries of before. Lastly, we add to $M$ all updates in $U_{2}$ by $B_{2 s}$ which are also updates for $B_{s}$ and the function returns $M$.

## Disjunction.

$$
\frac{E_{1} \triangleright V \rightarrow V^{\prime} \quad E_{2} \triangleright V \rightarrow V^{\prime} \quad E=E_{1} \vee E_{2}}{E \triangleright V \rightarrow V^{\prime}}
$$

Let $A_{i s}$ be program evaluators for $E_{i} \triangleright V \rightarrow V^{\prime}$ for $i \in\{1,2\}$. The program evaluator $A_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ is given in Figure 11.19 and registrations have the following form where $W=V \cup V^{\prime}$ :

```
// Let }\mp@subsup{B}{1s}{}\mathrm{ query evaluator for E E }\trianglerightV->\mp@subsup{V}{}{\prime
// Let }\mp@subsup{B}{2s}{}\mathrm{ query evaluator for E E }\trianglerightV\cup\mp@subsup{V}{}{\prime}->\mp@subsup{V}{}{\prime\prime
Bs}=\mathrm{ let // define Bs query evaluator E = E E }\wedge\wedge\mp@subsup{E}{2}{}\trianglerightV->\mp@subsup{V}{}{\prime}\cup\mp@subsup{V}{}{\prime\prime
    (get-val }\mp@subsup{|}{1}{},\mp@subsup{\mathrm{ is-done }}{1}{},\mp@subsup{\mathrm{ remove }}{1}{},\mathrm{ ,add-inst }\mp@subsup{}{1}{},\mp@subsup{\mathrm{ upd-val }}{1}{})=\mp@subsup{B}{1s}{
```



```
    W=V\cupV'\cupV'
    R= registration.new(V,TYPE (E))
    link}\mp@subsup{1}{1}{}=\mathbf{fun}(\pi,\beta) \beta en
    link}\mp@subsup{\mp@code{2}}{2}{=}\mathbf{fun(\pi,\beta) get-val
    get-val = fun(\pi,\beta) R(\pi,\beta) end
    is-done = fun (\pi,\beta) is-done}1(\pi,\beta)\wedge\forall\mp@subsup{\beta}{1}{\prime}\in\mp@subsup{\operatorname{get-val}}{1}{(\pi,\beta):is-done}\mp@subsup{\mp@code{D}}{2}{(\pi,\mp@subsup{\beta}{1}{\prime})}\mathrm{ end
    remove = \boldsymbol{proc}(\pi,\beta)
        remove }\mp@subsup{}{1}{
        for }\mp@subsup{\beta}{}{\prime}\in\mp@subsup{\operatorname{link}}{2}{}(\pi,\beta) d
            remove}\mp@subsup{2}{2}{(\pi,\mp@subsup{\beta}{}{\prime})
        R.remove( }\pi,\beta\mathrm{ )
    end
    letrec
    create-entries =
        fun (\pi, },\mp@code{c
            case c
            of none then none
            of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then get-upd-com( }\pi,\beta,\mp@subsup{c}{1}{})&get-upd-com(\pi,\beta,\mp@subsup{c}{2}{}
            of extend-set(v) then
                {v, ,\ldots,v,v}}=
            in
                add-inst2}(\pi,\mp@subsup{v}{1}{})&\ldots&add-inst 2 ( |, ven
            else none
        end
    in
    add-inst = fun (\pi,\beta)
        R.add-inst(\pi, }\beta\mathrm{ )
        c
        c=create-entries( }\pi,\beta,\mp@subsup{c}{1}{}
        R.set-val(\pi, \beta, apply(R(\pi,\beta),c))
    in
        c
    end
```

Figure 11.17: Part 1 of a query evaluator for conjunction on streams $s$.

```
    letrec
    add-var-ass-ups \(=\boldsymbol{p r o c}\left(\pi, \beta^{\prime}, c^{\prime}, A s s U p s^{\prime}\right)\)
        case \(c^{\prime}\)
        of \(c_{1} \& c_{2}\) then
                add-var-ass-ups \(\left(\pi, \beta^{\prime}, c_{1}, A s s U p s^{\prime}\right) \& a d d-v a r-a s s-u p s\left(\pi, \beta^{\prime}, c_{2}, A s s U p s^{\prime}\right)\)
            of upd-var-ass \((x, v, c)\) then \(A s s U p s^{\prime} \cdot a d d\left(\pi, \beta^{\prime}, x, c\right)\)
            else return
        end
    \(a d d-u p s=\operatorname{proc}\left(\pi, \beta, c, A s s U p s^{\prime}, M\right)\)
        case \(c\)
        of \(c_{1} \& c_{2}\) then \(\operatorname{add}\)-ups \(\left(\pi, \beta, c_{1}, x\right) \& \operatorname{add}-u p s\left(\pi, \beta, c_{2}, x\right)\)
        of upd-elem-set \(\left(\beta^{\prime}, c^{\prime}\right)\) then add-var-ass-ups \(\left(\pi, \beta^{\prime}, c^{\prime}, A s s U p s^{\prime}\right)\)
        of resolve-elem-set \(\left(\beta^{\prime}\right.\), false) then
                \(\left\{\beta_{1}^{\prime \prime}, \ldots, \beta_{n}^{\prime \prime}\right\}=\) get-val \({ }_{2}\left(\pi, \beta^{\prime}\right)\)
                remove \(_{2}\left(\pi, \beta^{\prime}\right)\)
                \(M . \operatorname{add}(\pi, \beta, \operatorname{get}-\operatorname{val}(\pi, \beta)\),
                                    resolve-elem-set \(\left(\beta_{1}^{\prime \prime}\right.\), false \() \& \ldots\). . \&resolve-elem-set \(\left(\beta_{n}^{\prime \prime}\right.\), false \(\left.)\right)\)
            else return
        end
    in
    upd-val \(=\mathbf{f u n}(e \in \operatorname{events}(s)\), AssUps \()\)
        for \((\pi, \beta, x, c) \in A s s U p s\) do \(R . u p d-a s s\left(\pi, \beta, \beta_{\left.\right|_{W \backslash\{x\}}} \uplus[x / \operatorname{apply}(\beta(x), c)]\right)\) end
        AssUps' \(=\) set.new()
        for \((\pi, \beta, x, c) \in A s s U p s\) do
            for \(\beta^{\prime} \in \operatorname{link}_{2}(\pi, \beta)\) do \(\operatorname{AssUps} s^{\prime} \cdot a d d\left(\pi, \beta^{\prime}, x, c\right)\) end
        end
        \(U_{1}=u p d-v a l_{1}(e, A s s U p s)\)
        \(M=\) set.new()
        for \((\pi, \beta, v, c) \in U_{1}\) do \(\operatorname{add-ups}\left(\pi, \beta, c, A s s U p s^{\prime}, M\right)\) end
        \(U_{2}=u p d-v a l_{2}\left(e, A s s U p s^{\prime} . \operatorname{content}()\right)\)
        for \((\pi, \beta, v, c) \in U_{1}\) do
            \(c^{\prime}=\) create-entries \((\pi, \beta, c)\)
            \(M . a d d\left(\left(\pi, \beta, \operatorname{get}-\operatorname{val}(\pi, \beta), c^{\prime}\right)\right)\)
        end
        for \(\left(\pi, \beta^{\prime}, v, c\right) \in U_{2}\) do
            if \(\exists\left(\pi, \beta_{\left.\right|_{V}}^{\prime}, v, c^{\prime}\right) \in M\) then M.replace \(\left(\left(\pi, \beta_{\left.\right|_{V}}^{\prime}, v, c^{\prime}\right),\left(\pi, \beta_{\left.\right|_{V}}^{\prime}, v, c^{\prime} \& c\right)\right)\)
            else \(\left.M . a d d\left(\pi, \beta_{\left.\right|_{V}}^{\prime}, v, c\right)\right)\)
        end
    in M.content()
    end
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.18: Part 2 of a query evaluator for conjunction on streams $s$.

```
// Let }\mp@subsup{A}{is}{}\mathrm{ be a program evaluator for }\mp@subsup{E}{i}{}\trianglerightV->\mp@subsup{V}{}{\prime},1\leqi\leq
As}=|\mathrm{ let // A program evaluator for }E=\mp@subsup{E}{1}{}\vee\mp@subsup{E}{2}{}\trianglerightV->\mp@subsup{V}{}{\prime
    (get-val },\mp@subsup{\mathrm{ is-done }}{i}{},\mp@subsup{\mathrm{ remove }}{i}{},\mathrm{ add-inst }\mp@subsup{\mp@code{N}}{i}{},\mp@subsup{\mathrm{ upd-val }}{i}{})=\mp@subsup{A}{is}{},\quad1\leqi\leq
    W=V\cupV'
    R= registration.new(W,TYPE (E))
    link}\mp@subsup{k}{1}{}=\mathbf{fun}(\pi,\alpha) \alpha end
    link}\mp@subsup{k}{2}{}=\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun (\pi,\alpha) R(\pi,\alpha) end
```



```
        instantiate(get-val ( }\pi,\alpha)\mp@subsup{\vee}{}{\mathrm{ Bool }}\mp@subsup{}{}{\perp}\mathrm{ get-val 
    is-done = fun (\pi,\alpha) is-done}\mp@subsup{1}{1}{(\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha))\wedgeis-done}\mp@subsup{2}{2}{(\pi,\alpha) end
    remove = gen-remove(R, remove}\mp@subsup{}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = gen-add-inst(R,add-inst 
    upd-val =gen-upd-val(R,upd-val },\mathrm{ ,upd-val },\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{},\mathrm{ get-upd-com
                                    gen-ass-com(link (), gen-ass-com(link }\mp@subsup{\mp@code{L}}{1}{})
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.19: A program evaluator for disjunctions on streams $s$.


Similar to the program evaluator for conjunction, the program evaluator for the disjunction waits until the event at which both $A_{1 s}$ and $A_{2 s}$ have finished computing their boolean values, such that function get-upd-com can compute the disjunction for the respective entries.

Let $B_{i s}$ be query evaluators for $E_{i} \triangleright V \rightarrow V^{\prime}$ for $i \in\{1,2\}$. The query evaluator $B_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ is given in Figure 11.20. Registrations have the following form where $W=V \cup V^{\prime}$ :

```
// Let Bis query evaluator for }\mp@subsup{E}{i}{}\trianglerightV->\mp@subsup{V}{}{\prime},1\leqi\leq
```




```
    W=V\cupV'
    R= registration.new(V,TYPE (E))
    link}\mp@subsup{k}{1}{}=\mathbf{fun}(\pi,\beta) \beta en
    link}\mp@subsup{k}{2}{}=\mathbf{fun}(\pi,\beta)\beta\mathrm{ end
    get-val = fun (\pi,\beta) R(\pi,\beta) end
    get-upd-com = fun( }\pi,\beta,\mp@subsup{c}{1}{},\mp@subsup{c}{2}{})\quad\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ end
    is-done = fun(\pi,\beta) is-done 
    remove = gen-remove(R, remove}\mp@subsup{}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = gen-add-inst(R,add-inst 
    upd-val = gen-upd-val(R,upd-val , upd-val2, link 
        gen-ass-com(link 1), gen-ass-com(link }2)
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.20: A query evaluator for disjunctions on streams $s$.


Given some open node $\pi$ and variable assignment $\beta$, evaluator $B_{s}$ is in charge of computing the union of variables assignments $v_{1}$ and $v_{2}$ by evaluators $B_{1 s}$ and $B_{2 s}$, respectively, for the linked entries. Therefore, as one sees in function get-upd-com, any update to $v_{1}$ by $c_{1}$ and any update to $v_{2}$ by $c_{2}$ becomes an update $c_{1} \& c_{2}$ to the union $v_{1} \cup v_{2}$.

## Negation.

$$
\frac{E^{\prime} \triangleright V \rightarrow \emptyset \quad E=\neg E^{\prime}}{E \triangleright V \rightarrow \emptyset}
$$

Let $A_{s}^{\prime}$ be a program evaluator for $E^{\prime} \triangleright V \rightarrow \emptyset$. We define a program evaluator $A_{s}$ for $E \triangleright V \rightarrow \emptyset$ in Figure 11.21. Registrations have the following form:

```
// Let }\mp@subsup{A}{s}{\prime}\mathrm{ be a program evaluator for E}\mp@subsup{E}{}{\prime}\trianglerightV->
As}=|\mathbf{let // program evaluator for }E=\neg\mp@subsup{E}{}{\prime}\trianglerightV->\emptyset
    (get-val', is-done', remove}\mp@subsup{}{}{\prime},\mathrm{ add-inst', upd-val')}=\mp@subsup{A}{s}{\prime
    R= registration.new(V,TYPE (E))
    link = fun ( }\pi,\alpha) \alpha en
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
    get-upd-com= fun (\pi,\alpha,c) if c\not= none }\wedgeis-done(\pi,\alpha)) the
        instantiate( }\mp@subsup{\neg}{}{\mathrm{ Bool }}\mp@subsup{}{}{\perp}\mathrm{ get-val'}(\pi,\operatorname{link}(\alpha))) else none end
    is-done = fun (\pi,\alpha) is-done }\mp@subsup{}{}{\prime}(\pi,\alpha) end
    remove = gen-remove( }R,\mp@subsup{\mathrm{ remove'}}{}{\prime},link
    add-inst = gen-add-inst(R,add-inst',link,get-upd-com)
    upd-val = gen-upd-val(R,upd-val',link,get-upd-com,gen-ass-com(link))
in (get-val,is-done,remove, add-inst,upd-val)
```

Figure 11.21: A program evaluator for negation on streams $s$.


Since the program evaluator computes the negation of the boolean value computed by $A_{s}^{\prime}$, we wait until $A_{s}^{\prime}$ has finished computing the boolean value: For some entry $(\pi, \alpha) \in R \cdot \operatorname{dom}()$ function get-upd-com tests whether the respective update $c$ by $A_{s}^{\prime}$ was not empty and whether its computation finished. In this case, one returns the update command instantiate $\left(\neg^{\text {Bool }}{ }^{\perp}\right.$ get-val $\left.l^{\prime}(\pi, \operatorname{link}(\alpha))\right)$, which is used in upd-val to compute the result value. Since no variables are generated, a query evaluator $B_{s}$ can be defined from $A_{s}$.

## Constants.

$$
\frac{\text { true }}{c \triangleright \emptyset \rightarrow \emptyset}
$$

We define in Figure 11.22 a program evaluator $A_{s}$ for $c \triangleright \emptyset \rightarrow \emptyset$ where $c$ is an atomic value, the empty set $\emptyset$ or empty list nil. Registration $R$ has the following form:


```
// define \(A_{s}\) a program evaluator for \(E=c \triangleright \emptyset \rightarrow \emptyset\).
\(A_{s}=\mathbf{l e t}\)
    \(R=\) registration.new \((\emptyset, \operatorname{TYPE}(E))\)
    get-val \(=\mathbf{f u n}(\pi, \emptyset) \quad R(\pi, \emptyset)\) end
    is-done \(=\) fun \((\pi, \emptyset)\) True end
    remove \(=\) gen-remove \((R)\)
    add-inst \(=\mathbf{f u n}(\pi, \emptyset)\)
        R.add-inst( \(\pi, \emptyset)\)
        R.set-val \(\left(\pi, \emptyset, \llbracket c \rrbracket_{s}^{\leq \vec{e}}\right)\)
        in
        instantiate \(\left(\llbracket c \rrbracket_{s}^{\leq \vec{s}}\right)\)
    end
    upd-val \(=\mathbf{f u n}(e \in \operatorname{events}(s)\), AssUps \() \emptyset\) end
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.22: A program evaluator for constants on streams $s$.

The $a d d$-inst function sets directly the final answer, for which for all entries $i s$-done $(\pi, \emptyset)=$ true. The update function therefore returns always the empty set of updates. Since, no variables are generated, a query evaluator $B_{s}$ can be defined from $A_{s}$. We assume the existence of streaming evaluators for all other constants $c \in \mathcal{C}$ onst of $\lambda$ XP. For example, a program evaluator for function constant set2list receives entries ( $\pi, \alpha$ ) where $\alpha: \boldsymbol{a s s}_{\{\arg \}}$, which contain the argument set to be transformed into a list, which may possibly contain candidates which are to be decided later. As the argument set is updated, one updates the result list. This requires to store a mapping from elements of the input set to indices in the result list, such that updates to elements of the set can be mapped to updates that change the element at a certain position in the result list.

Variables.

$$
\frac{\text { true }}{x \triangleright\{x\} \rightarrow \emptyset}
$$

We define a program evaluator $A_{s}$ for $x \triangleright\{x\} \rightarrow \emptyset$ in Figure 11.23, while the registrations has the following form:

| $R$ | $(\pi, \alpha)$ |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\pi$ |  |  | $\alpha(x)$ |  |

Similar to the program evaluator for constants, the add-inst functions can directly set the answer $\alpha(x)$ of the query for any instance $\pi$ and variable assignment $\alpha$. However, the update function that inputs an event $e \in e v e n t s(s)$ and a set of variable assignment updates AssUps may contain a tuple ( $\pi, \alpha, x, c$ ) which instructs that the value for $x$ with respect to entry $(\pi, \alpha) \in R . \operatorname{dom}()$ needs to be updated by $c$ (as the

```
\(A_{s}=\) let // program evaluator for \(E=x \triangleright\{x\} \rightarrow \emptyset\).
    \(R=\) registration.new \((\{x\}, \operatorname{TyPE}(E))\)
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    is-done \(=\mathbf{f u n}(\pi, \alpha)\) True end
    remove \(=\) gen-remove \((R)\)
    \(a d d\)-inst \(=\mathbf{f u n}(\pi, \alpha)\)
        R.add-inst( \(\pi, \alpha\) )
        R.set-val( \(\pi, \alpha, \alpha(x))\)
        in
            instantiate \((\alpha(x))\)
    end
    upd-val \(=\mathbf{f u n}(e \in \operatorname{events}(s)\), AssUps \()\)
        \(M=\) set.new()
        for \((\pi, \alpha, y, c) \in\) AssUps do
            if \(y=x\) then
                \(\alpha^{\prime}=[x / \operatorname{apply}(R(\pi, \alpha), c)]\)
                R.add-inst ( \(\pi, \alpha^{\prime}\) )
                R.set-val \(\left(\pi, \alpha^{\prime}, \alpha^{\prime}(x)\right)\)
                \(M . \operatorname{add}\left(\left(\pi, \alpha^{\prime}, R(\pi, \alpha), c\right)\right)\)
            end
        in
        M.content()
    end
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.23: A program evaluator for variables on streams $s$.
program evaluator for tuple decompositions requires, see function get-ass-com of Figure 11.35). Since many parent registration entries may be linked with an entry $(\pi, \alpha) \in R . \operatorname{dom}()$, while the variable assignment update may only concern some of the parent registration entries, see generator gen-ass-com (link) in Section 11.2.1, one creates a new entry $\left(\pi, \alpha^{\prime}\right) \in R . \operatorname{dom}()$, where $\alpha^{\prime}$ is the variable assignment where $x$ is assigned the by $c$ updated value of $\alpha(x)$. Since, no variables are generated, a query evaluator $B_{s}$ can be defined from $A_{s}$.

## Existential quantification.

$$
\frac{E^{\prime} \triangleright V \rightarrow V^{\prime} \cup\{x\} \quad x \notin V^{\prime} \quad E=\exists x . E^{\prime}}{E \triangleright V \rightarrow V^{\prime}}
$$

Let $B_{s}^{\prime}$ be a query evaluator for $E^{\prime} \triangleright V \rightarrow V^{\prime} \cup\{x\}$. We define a program evaluator $A_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ in Figure 11.24. Registrations have the following form where $W=V \cup V^{\prime}$ :

```
\(/ /\) Let \(B_{s}^{\prime}\) a query evaluator for \(E^{\prime} \triangleright V \rightarrow V^{\prime} \cup\{x\}\)
\(A_{s}=\) let \(/ /\) program evaluator for \(E=\exists x . E^{\prime} \triangleright V \rightarrow V^{\prime}\).
    (get-val', is-done \({ }^{\prime}\), remove \(^{\prime}\), add-inst \({ }^{\prime}\), upd-val \(\left.{ }^{\prime}\right)=B_{s}^{\prime}\)
    \(W=V \cup V^{\prime}\)
    \(R=\) registration.new \((W, \operatorname{TYPE}(E))\)
    \(\operatorname{link}=\mathbf{f u n}(\pi, \alpha) \quad \alpha_{\left.\right|_{V}}\) end
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    get-upd-com \(=\mathbf{f u n}(\pi, \alpha, c)\)
        if \(c \neq\) none \(\wedge i s\) - \(\operatorname{done}(\pi, \alpha)\) then
                if \(\exists \beta^{\prime} \in \operatorname{get}^{\operatorname{val}} \mathrm{l}^{\prime}(\pi, \operatorname{link}(\pi, \alpha)): \alpha \subset \beta^{\prime}\) then
                    instantiate(true)
                else
                instantiate(false)
        else
            none
    end
    is-done \(=\) fun \((\pi, \alpha)\) get-val \((\pi, \alpha)=\) true \(\vee i s-\operatorname{done}{ }^{\prime}(\pi, \operatorname{link}(\alpha))\) end
    remove \(=\) gen-remove \(\left(R\right.\), remove \(\left.{ }^{\prime}, \operatorname{link}\right)\)
    \(a d d-\) inst \(=\) gen-add-inst \(\left(R\right.\), add-inst' \({ }^{\prime}\), link, get-upd-com \()\)
    upd-val \(=\) gen-upd-val( \(R\), upd-val', link, get-upd-com,gen-ass-com(link) \()\)
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.24: A program evaluator for existential quantifiers on streams $s$.


Given some entry $(\pi, \alpha) \in R . \operatorname{dom}()$ the evaluator $A_{s}$ aims to find some variable extensions $\beta^{\prime} \supset \alpha$ within the set $v$ that is computed by query evaluator $B_{s}^{\prime}$ for the linked entry $\left(\pi, \alpha_{\left.\right|_{V}}\right)$ in $R^{\prime}$. Function then get-upd-com waits until the set $v$ by $B_{s}^{\prime}$ has been determined, such that the existence of some $\beta^{\prime} \in v$ with $\alpha \subset \beta^{\prime}$ implies that there exists a value for $x$, which is $\beta^{\prime}(x)$, for which the formula becomes true.

Let $B_{s}^{\prime}$ be a query evaluator for $E^{\prime} \triangleright V \rightarrow V^{\prime} \cup\{x\}$. We define a query evaluator $B_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ in Figure 11.25. Registrations have the following form where $W=V \cup V^{\prime}:$

| R | $(\pi, \beta)$ | $\frac{{\text { node } \text { ass }_{l}}_{\pi^{\cdots} \beta}}{\pi^{\prime}}$ | $2^{\mathrm{ass}_{W}}$ <br> $v^{\prime}$ | $\begin{aligned} & \text { upd }\left(v^{\prime}\right) \\ & v^{\prime}=\left\{\beta_{\left.\right\|_{W}}^{\prime} \mid \beta^{\prime} \in v\right\} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| $R^{\prime}$ | $(\pi, \beta)$ | $\frac{\text { node } \mathbf{a s s}_{V}}{\pi^{\cdots} \beta}$ | $2^{\boldsymbol{a s s}_{W \cup\{x\}}}$ <br> $v$ |  |

The idea is that query evaluator $B_{s}^{\prime}$ computes a set of variable assignment extension $v$ for some $\beta$ and some node $\pi$, which also assigns values for variable $x$. Query evaluator $B_{s}$ then computes the set $v^{\prime}=\left\{\beta_{\left.\right|_{W}}^{\prime} \mid \beta^{\prime} \in v\right\}$ that restricts assignments $\beta^{\prime}$ to variables in $W$ without $x$. The challenge is, given an update command $c$ to variable extensions $v$ from $B_{s}^{\prime}$, how to compute update commands $c^{\prime}$ by $B_{s}$ that update $v^{\prime}$ accordingly. For this, we refer to function get-upd-com, which tests the various possible case for update command $c$. When extending the set with new elements $\beta^{\prime}$, then one extends simply the set $v^{\prime}$ by elements $\beta_{\left.\right|_{W}}^{\prime}$. When resolving an element in $v$, then one resolves the corresponding element in $v^{\prime}$. However, when updating some element $e \in v$ by $\bar{c}$, then $\bar{c}$ may contain updates for values for $x$ in $e$, which do not concern corresponding values in $v^{\prime}$. In this case, we rely on some function get-upd-var-ass-elem, which returns the proper adapted update commands, regardless of updates $\bar{c}$ that do not concern elements of $v^{\prime}$.

## Navigational formulas.

Let $E$ be a simple navigational query with mode $E \triangleright V \rightarrow V^{\prime}$. For navigational queries we will apply our streaming algorithm of Chapter 8 that runs eNwas. They require however to be evaluated from the root of any tree, for which we consider the slightly adapted formula

$$
\operatorname{start}(E, z)=_{\operatorname{def}} c h^{*}\left(i s_{z} \wedge E\right) .
$$

When evaluating $E$ at some node $\pi \in \operatorname{nodes}(s)$ with variable assignment $\alpha$ then this is equivalent to evaluate $\operatorname{start}(E, z)$ on the root $\operatorname{root}(\pi)$ to which $\pi$ belongs while setting variable $z$ to $\pi$ :

$$
\llbracket E \rrbracket_{s, \pi, \alpha}=\llbracket \operatorname{start}(E, z) \rrbracket_{s, \operatorname{root}(\pi), \alpha \uplus[z / \pi]}
$$

In streaming we next eliminate backward axes in $\operatorname{start}(F, z)$ as described in Section 10.1.3. Finally we translate the backward axes free and simple query into an early nested word automata $\mathcal{E}=\left(\Sigma, \Delta, Q, Q_{I}, Q_{F}, \Gamma, \delta, Q_{S}, Q_{R}\right)$. We present a program evaluator $A_{t}$ for some tree $t$ within the sequence of trees $s$ in Figure 11.26 and Figure 11.27 that runs $\mathcal{E}$ for every event of the stream that belong to $t$ and whose registration stores besides variable assignments for variables in $V \cup V^{\prime}$ also values for start variable $z$ and configurations of the automata for variable conf. Since a

```
// Let B}\mp@subsup{B}{s}{\prime} query evaluator for E'\trianglerightV -> V V'\cup{x
// define Bs query evaluator for }E=\existsx.\mp@subsup{E}{}{\prime}\trianglerightV->\mp@subsup{V}{}{\prime}
Bs}=|le
    (get-val', is-done', remove}\mp@subsup{}{}{\prime},add-inst', upd-val') = Bs'
    W=V\cupV'
    R= registration.new(W\\mp@subsup{V}{}{\prime},\operatorname{TYPE}(E))
    link}=\mathbf{fun}(\pi,\beta) \beta en
    get-val = fun (\pi,\beta) R(\pi,\beta) end
    letrec
        get-upd-var-ass-elem=
            fun (e,c)
            case c
            of none then none
            of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then get-upd-var-ass-elem(e, c
            of extend-var-ass}(y,v) then if [y/v]\subseteq\mp@subsup{e}{\mp@subsup{|}{W}{}}{}\mathrm{ then
                upd-elem-set( (e\mp@subsup{|}{W}{}}\mathrm{ , extend-var-ass (y,v)) else none
            of upd-var-ass (y,v,\overline{c}) then if [y/v]\subseteq\mp@subsup{e}{\mp@subsup{|}{W}{}}{}\mathrm{ then}
                upd-elem-set (e\mp@subsup{|}{W}{}},\mathrm{ upd-var-ass(y,v,的) else none
        end
        get-upd-com =
            fun (\pi, \beta,c)
                case c
                of none then none
                of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then get-upd-com( }\pi,\beta,\mp@subsup{c}{1}{})&get-upd-com(\pi,\beta,\mp@subsup{c}{2}{}
                of extend-set (v) then extend-set ({\mp@subsup{\beta}{\mp@subsup{|}{W}{\prime}}{\prime}|\mp@subsup{\beta}{}{\prime}\inv})
                of upd-elem-set (e,\overline{c}) then get-upd-var-ass-elem(e,\overline{c})
                of resolve-elem-set (e,b) then resolve-elem-set ( }\mp@subsup{e}{\mp@subsup{|}{W}{}}{}
        end
    in
    is-done = fun( }\pi,\beta) is-\mp@subsup{done}{}{\prime}(\pi,\operatorname{link}(\beta))\mathrm{ end
    remove = gen-remove( }R,\mathrm{ remove',link)
    add-inst = gen-add-inst(R, add-inst',link,get-upd-com)
    upd-val = gen-upd-val(R,upd-val',link,get-upd-com,gen-ass-com(link))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.25: A query evaluator for existential quantifiers on streams $s$.

ENWA runs on one tree only, we maintain program and query evaluators for every tree $t$ in $s$. However, not all navigational formulas must be run on all trees of the input sequence $s$. We leave it to static analysis to reduce the number of program and query evaluators for navigational formulas, and otherwise run one evaluator per tree $t$ in $s$. We refer to Chapter 8 for a more detailed explanation of running automata over streams, while in the following we only explain the essentials. The registration has the following form:


Function add-inst that is run for some open node $\pi$ and variable assignment $\alpha \in$ $\operatorname{ass}_{V \cup V^{\prime}}$ is called at the opening event of $\pi$. The automaton $\mathcal{E}$ guides the creation of entry in $R$, by testing all variable annotations $v$ that do not lead to some rejection state for the opening event at $\pi$. If $z \in v$ then an entry in $R$ is created by calling $R$.add-inst, which sets the new configuration and which sets start variable $z$ to $\pi$. When no entry was created in $R$ for $\pi$ and $\alpha$, then the navigational formula evaluates to false, otherwise one analyses the state $q$ for the entry that contains $\pi$ and $\alpha$ and returns true if $q \in Q_{S}$ is a selection state, one returns false if $q \in Q_{R}$ is a rejection states, and otherwise the $\bullet$ - value is stored in $R$ as intermediate answer. In the later case, it is the update function in Figure 11.27 that runs the automaton for these entries at later events. It uses function test-new-state that computes updates for those entries whose configuration's state reached a selection or a rejection state.

We present a query evaluator $B_{t}$ for $E \triangleright V \rightarrow V^{\prime}$ in Figure 11.28 and Figure 11.29 that runs $\mathcal{E}$ that we obtain as explained for the program evaluator. The registration has the following form:


One can see that the registration for the query evaluator contains several entries for one instance $(\pi, \beta) \in R$. $\operatorname{dom}()$. The reason is that the automaton generates all variable assignments for variables in $V^{\prime}$. The result for such an instance is

```
// define At program evaluator for F}F\trianglerightV->\mp@subsup{V}{}{\prime
// where conf is a global variable for configurations of ENwA \mathcal{E}
At}=|\textrm{let
    \mathcal{E}=(\Sigma,\Delta,Q,\mp@subsup{Q}{I}{},\mp@subsup{Q}{F}{},\Gamma,\delta,\mp@subsup{Q}{S}{},\mp@subsup{Q}{R}{})
    W={z,conf}\cupV\cup\mp@subsup{V}{}{\prime}
    R= registration.new(W,TyPE(E))
    get-val = fun(\pi,\alpha) R(\pi,\alpha) end
    is-done = fun( }\pi,\alpha:\mp@subsup{\boldsymbol{ass}}{V\cup\mp@subsup{V}{}{\prime}}{\prime}
        \forall\pi,q,\rho,\sigma,\mp@subsup{\alpha}{}{\prime}.([conf/(q,\rho,\sigma),z/\pi]\uplus\alpha\inR.dom()) -> q\in QS \cup Q Q 
    end
    remove = gen-remove( }R\mathrm{ )
    add-inst = fun(\pi,\alpha:\mp@subsup{\boldsymbol{~ss}}{V\cup\mp@subsup{V}{}{\prime}}{\prime})}///call at opening event of 
        a=lab(\pi)
        for (\bullet, \alpha') \inR.dom():}\forallx\in\alpha.\operatorname{dom}():\mp@subsup{\alpha}{}{\prime}(x)=\bullet\vee\mp@subsup{\alpha}{}{\prime}(x)=\alpha(x) d
            (q,\rho,\sigma)=\mp@subsup{\alpha}{}{\prime}(conf)
            for }q\xrightarrow{}{\langle(a,v)\rangle:\gamma}\mp@subsup{q}{}{\prime}\in\delta:v\not=\emptyset,\mp@subsup{q}{}{\prime}\not\in\mp@subsup{Q}{R}{}\mathrm{ do
                    if z\inv then
                        R.add-inst (\pi,[conf/(\mp@subsup{q}{}{\prime},\rhov,\sigma\gamma)\uplus\mp@subsup{\alpha}{\mp@subsup{|}{(V\cup\mp@subsup{V}{}{\prime})\v}{\prime}}{\prime}{[x/\pi]|x\inv})
            end
        end
        M={(\pi,\mp@subsup{\alpha}{}{\prime})\inR.dom() | \alpha\subseteq\mp@subsup{\alpha}{}{\prime}}
        b= if M=\emptyset then false
            else //#M=1
                (\pi,\mp@subsup{\alpha}{}{\prime})\inM
                (q,\rho,\sigma)=\mp@subsup{\alpha}{}{\prime}(conf)
                if q\in\mp@subsup{Q}{S}{}}\mathrm{ then true else if q}\in\mp@subsup{Q}{R}{}\mathrm{ then false else -
        c= if b=\bullet then none else instantiate(b)
        R.set-val( }\pi,\alpha,b
        in c
    end
```

Figure 11.26: Part 1 of a program evaluator for navigational formulas on streams $s$.

```
    test-new-state \(=\mathbf{f u n}(q, \alpha, M)\)
        if \(q \in Q_{S} \cup Q_{R}\) then
                if \(q \in Q_{R}\) then \(R\).remove \((\alpha(z), \alpha)\)
            \(c=\) if \(q \in Q_{S}\) then instantiate(true) else instantiate(false)
            \(\pi=\alpha(z)\)
            \(\alpha^{\prime}=\alpha_{\left.\right|_{V \cup V^{\prime}}}\)
            \(v=R\left(\pi, \alpha^{\prime}\right)\)
            R.set-val \(\left(\pi, \alpha^{\prime}, \operatorname{apply}(v, c)\right)\)
            M.add \(\left(\left(\pi, \alpha^{\prime}, v, c\right)\right)\)
        in \(M\)
end
upd-val \(=\)
    fun ( \(e \in\) events(s), AssUps)
                \((\pi, c)=e\)
                if \(\pi \notin \operatorname{nodes}(t)\) then
                    for \((\pi, \alpha, x, c) \in\) AssUps do
                    \(R . \operatorname{upd-ass}\left(\pi, \alpha, \alpha_{\left.\right|_{W \backslash\{x\}}} \uplus[x / \operatorname{apply}(\alpha(x), c)]\right)\) end
                    \(a=\operatorname{lab}(\pi)\)
                        for \(\left(\pi^{\prime}, \alpha\right) \in R . \operatorname{dom}()\) do
                    if \(c=o p\) then
                        \((q, \rho, \sigma)=\alpha(\) conf \()\)
                        for \(q \xrightarrow{\langle(a, v)\rangle: \gamma} q^{\prime} \in \delta: \quad v \neq \emptyset, q^{\prime} \notin Q_{R}\) do
                        if \(z \notin v\) then
                        alpha' \(=\left[c o n f /\left(q^{\prime}, \rho v, \sigma \gamma\right) \uplus \alpha_{\left(V \cup V^{\prime}\right) \backslash v} \uplus\{[x / \pi] \mid x \in v\}\right)\)
                            R.add-inst ( \(\pi^{\prime}, \alpha^{\prime}\) )
                            test-new-state ( \(\left.q^{\prime}, \alpha^{\prime}, M\right)\)
                        end
                        if \(q \notin Q_{S}\) then
                            \(q \xrightarrow{\langle(a, \varnothing)\rangle: \gamma} q^{\prime} \in \delta\)
                            \(\alpha^{\prime}=R . u p d-\operatorname{ass}\left(\pi^{\prime}, \alpha, \alpha_{\left.\right|_{V \cup V^{\prime} \cup\{z\}}} \uplus\left[\operatorname{conf} /\left(q^{\prime}, \rho \emptyset, \sigma \gamma\right)\right]\right)\)
                        test-new-state \(\left(q^{\prime}, \alpha^{\prime}, M\right)\)
            else
                        if \(q \notin Q_{S}\) then
                            \((q, \rho v, \sigma \gamma)=\alpha(\) conf \()\)
                            \(q \xrightarrow{\langle/(a, v)\rangle: \gamma} q^{\prime} \in \delta\)
                            \(\alpha^{\prime}=R . \operatorname{upd}-\operatorname{ass}\left(\pi^{\prime}, \alpha, \alpha_{\left.\right|_{V \cup V^{\prime} \cup\{z\}}} \uplus\left[\operatorname{conf} /\left(q^{\prime}, \rho, \sigma\right)\right]\right)\)
                            test-new-state \(\left(q^{\prime}, \alpha^{\prime}, M\right)\)
            end
            in
                    M.content()
            else Ø
    end
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.27: Part 2 of a program evaluator for navigational formulas on streams $s$.
then the set of extended variable assignments that is accumulated from all entries that carry $\pi$ and $\beta$. Similar to the program evaluator, function add-inst creates entries for some open node $\pi$ and variable assignment $\beta$ under the guidance of the automaton. The result set then contains all non-rejecting variable extensions, where variable extensions with a non-selecting and non-rejecting configuration are candidates whose selection is to be determined later on. Function upd-val runs the automaton for all entries, possible creating new entries or candidates belonging to some previously created instance. Function test-new-state removes and resolves answer elements for previous entries whose state became selecting or rejecting at the respective event. Function test-new-candidate adds new answer elements to the final set, which are possibly candidates whose selection must yet be determined. Finally function add-com-and-set-val keeps track that $R$ contains the updated values for created instances, while it adds update commands to answer set $M$.

## Location.

$$
\frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow V^{\prime} \quad E=\mathbf{a t}\left(E_{1}, E_{2}\right)}{E \triangleright V \rightarrow V^{\prime}}
$$

The semantics of formula $\mathbf{a t}\left(E_{1}, E_{2}\right)$ at some open $\pi$ and variable assignment $\alpha$ in $V \cup V^{\prime}$, is equal to the semantics of $E_{2}$ with the same variable assignment $\alpha$, but at the node selected by $E_{1}$ for $\pi$ and $\alpha$. Let $A_{1 s}$ be a program evaluator for $E_{1} \triangleright V \rightarrow \emptyset$ and $A_{2 s}$ be a program evaluator for $E_{2} \triangleright V \rightarrow V^{\prime}$. The program evaluator $A_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ is given in Figure 11.30 and Figure 11.31. The registrations have the following form:

| , | $\begin{aligned} & (\pi, \alpha) \\ & (\pi, \alpha) \end{aligned}$ |  | $\operatorname{Type}\left(E_{2}\right)$ <br> $v$ $\left(\pi^{\prime}, \alpha\right)$ <br> node ass $_{W}$ | $\operatorname{upd}(v)$ $\mid \operatorname{Type}\left(E_{2}\right)$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $R_{1}$ |  | $\pi^{\prime}$ | $\pi^{\prime}{ }^{\cdots}{ }^{\prime}{ }^{\alpha}$ | $v$ | $R_{2}$ |

Given an instance $(\pi, \alpha) \in R . \operatorname{dom}()$ one observes that an answer node $\pi^{\prime}$ of the linked instance in $R_{1}$ is used as new start node to create an instance $\left(\pi^{\prime}, \alpha\right) \in$ $R_{2} \cdot \operatorname{dom}()$. Since the node of linked entries changes, unlike to all other registrations, the program evaluator for location cannot make use of the function generators gen-ass-com, gen-add-inst, gen-remove, and gen-upd-val presented in Section 11.2.1, but it mimics the functions that are being generated while taking care of proper linkage with respect to the semantics. A query evaluator for $E$ works just as the program evaluator, but it assumes a query evaluator $B_{s}$ for $E_{2} \triangleright V \rightarrow V^{\prime}$.

```
\(/ /\) define \(B_{t}\) query evaluator for \(F \triangleright V \rightarrow V^{\prime}\).
// where conf is a global variable for configurations of ENWA \(\mathcal{E}\)
\(B_{t}=1 e t\)
    \(\mathcal{E}=\left(\Sigma, \Delta, Q, Q_{I}, Q_{F}, \Gamma, \delta, Q_{S}, Q_{R}\right)\)
    \(W=\{z\), conf \(\} \cup V \cup V^{\prime}\)
    \(R=\) registration.new \((W, \operatorname{TyPE}(E))\)
    get-val \(=\mathbf{f u n}(\pi, \beta) \quad R(\pi, \beta)\) end
    is-done \(=\mathbf{f u n}\left(\pi, \beta: \boldsymbol{a s s}_{V}\right)\)
        \(\forall \pi, q, \rho, \sigma, \beta^{\prime} .\left([\operatorname{conf} /(q, \rho, \sigma), z / \pi] \uplus \beta^{\prime} \in R . \operatorname{dom}() \wedge \beta \subseteq \beta^{\prime}\right) \rightarrow q \in Q_{S} \cup Q_{R}\)
    end
    remove \(=\) gen-remove \((R)\)
    add-inst \(=\)
        fun \(\left(\pi, \beta: \boldsymbol{a s s}_{V}\right) / /\) call at the opening event of \(\pi\)
            \(a=\operatorname{lab}(\pi)\)
            for \(\left(\bullet, \beta^{\prime}\right) \in R \cdot \operatorname{dom}(): \beta^{\prime}(z)=\bullet \wedge \forall x \in \beta \cdot \operatorname{dom}(): \beta^{\prime}(x)=\bullet \vee \beta^{\prime}(x)=\beta(x)\) do
                \((q, \rho, \sigma)=\beta^{\prime}(\) conf \()\)
                        for \(q \xrightarrow{\langle(a, v)\rangle: \gamma} q^{\prime} \in \delta: \quad v \neq \emptyset, q^{\prime} \notin Q_{R}\) do
                        if \(z \in v\) then
                        R.add-inst \(\left(\pi,\left[\operatorname{conf} /\left(q^{\prime}, \rho v, \sigma \gamma\right)\right] \uplus \beta_{\left(V \cup V^{\prime}\right) \backslash v}^{\prime} \uplus\{[x / \pi] \mid x \in v\}\right)\)
                    end
            end
            \(M=\) set.new()
            for \(\left(\pi, \beta^{\prime}\right) \in R . \operatorname{dom}(): \beta \subseteq \beta^{\prime}\) do
                        \((q, \rho, \sigma)=\beta^{\prime}(\) conf \()\)
                            case \(q\)
                    of \(q \in Q_{S}\) then \(\operatorname{M.add}\left(\beta_{\left.\right|_{V U V^{\prime}} ^{\prime}}^{\prime}\right)\)
                    of \(q \notin Q_{S} \cup Q_{R}\) then \(\operatorname{Madd}\left(\beta_{\left.\right|_{V \cup V^{\prime}} ^{\prime}}^{?}\right)\)
                    of \(q \in Q_{R}\) then \(\perp\)
            end
            \(c=\operatorname{extend}-\operatorname{set}(M . \operatorname{content}())\)
            \(R . \operatorname{set}-v a l(\pi, \beta, \operatorname{apply}(R(\pi, \beta), c))\)
        in \(c\)
        end
    add-com-and-set-val \(=\boldsymbol{p r o c}(\pi, \beta, M, c)\)
        \(v=R(\pi, \beta)\)
        R.set-val( \(\pi, \beta, \operatorname{apply}(v, c))\)
        if \(\exists\left(\pi, \beta, v, c^{\prime}\right) \in M\) then M.replace \(\left(\left(\pi, \beta, v, c^{\prime}\right),\left(\pi, \beta, v, c^{\prime} \& c\right)\right)\)
        else \(\operatorname{M.add}((\pi, \beta, v, c))\)
    end
```

Figure 11.28: Part 1 of a query evaluator for navigational formulas on streams $s$.

```
    test-new-state \(=\mathbf{f u n}(q, \beta, M)\)
    if \(q \in Q_{S} \cup Q_{R}\) then
                if \(q \in Q_{R}\) then \(R\).remove \((\beta(z), \beta)\)
        \(c=\) if \(q \in Q_{S}\) then resolve-elem-set \(\left(\beta_{\left.\right|_{V \cup V^{\prime}}}^{?}\right.\), true \()\)
            else resolve-elem-set \(\left(\beta_{\left.\right|_{V \cup V^{\prime}}}^{?}\right.\), false \()\)
        add-com-and-set-val \(\left(\beta(z), \beta_{\left.\right|_{V}}, M, c\right)\)
    in \(M\)
end
test-new-candidate \(=\mathbf{f u n}(q, \beta, M) / / q \notin Q_{R}\)
        \(c=\mathbf{i f} \quad q \in Q_{S}\) then extend-set \(\left(\left\{\beta_{\left.\right|_{V \cup V^{\prime}}}\right\}\right)\)
            else \(\operatorname{extend}-\operatorname{set}\left(\left\{\beta_{\left.\right|_{V \cup V^{\prime}}}\right\}\right)\)
        add-com-and-set-val \(\left(\beta(z), \beta_{\mid V}, M, c\right)\)
    in \(M\)
end
upd-val \(=\mathbf{f u n}(e \in \operatorname{events}(s)\), AssUps \()\)
        \((\pi, c)=e\)
        if \(\pi \notin \operatorname{nodes}(t)\) then
            for \((\pi, \beta, x, c) \in A s s U p s\) do \(R . u p d-a s s\left(\pi, \beta, \beta_{\left.\right|_{W \backslash\{x\}}} \uplus[x / \operatorname{apply}(\beta(x), c)]\right)\) end
            \(a=\operatorname{lab}(\pi)\)
            \(M=\) set.new()
            for \(\left(\pi^{\prime}, \beta\right) \in R . \operatorname{dom}()\) do
            if \(c=o p\) then
                    \((q, \rho, \sigma)=\beta(\) conf \()\)
                        for \(q \xrightarrow{\langle(a, v)\rangle: \gamma} q^{\prime} \in \delta: \quad v \neq \emptyset, \quad q^{\prime} \notin Q_{R}\) do
                            if \(z \notin v\) then
                                    \(\left.\beta^{\prime}=\left[\operatorname{conf} /\left(q^{\prime}, \rho v, \sigma \gamma\right)\right] \uplus \beta_{\left(V \cup V^{\prime}\right) \backslash v} \uplus\{[x / \pi] \mid x \in v\}\right)\)
                                    R.add-inst \(\left(\pi^{\prime}, \beta^{\prime}\right)\)
                                    test-new-candidate \(\left(q^{\prime}, \beta^{\prime}, M\right)\)
                    end
                    if \(q \notin Q_{S}\) then
                            \(q \xrightarrow{\langle(a, \emptyset)\rangle: \gamma} q^{\prime} \in \delta\)
                        \(\beta^{\prime}=R . u p d-\operatorname{ass}\left(\pi^{\prime}, \beta, \beta_{\left.\right|_{V \cup V^{\prime} \cup\{z\}}} \uplus\left[\operatorname{conf} /\left(q^{\prime}, \rho \emptyset, \sigma \gamma\right)\right]\right)\)
                        test-new-state \(\left(q^{\prime}, \beta^{\prime}, M\right)\)
                else
                    if \(q \notin Q_{S}\) then
                                    \((q, \rho v, \sigma \gamma)=\beta(\) conf \()\)
                                    \(q \xrightarrow{\langle/(a, v)\rangle: \gamma} q^{\prime} \in \delta\)
                                    \(\beta^{\prime}=R . u p d-\operatorname{ass}\left(\pi^{\prime}, \beta, \beta_{\left.\right|_{V \cup V^{\prime} \cup\{z\}}} \uplus\left[\operatorname{conf} /\left(q^{\prime}, \rho, \sigma\right)\right]\right)\)
                                    test-new-state \(\left(q^{\prime}, \beta^{\prime}, M\right)\)
            end
        in M.content()
        else \(\emptyset\)
    end
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.29: Part 2 of a query evaluator for navigational formulas on streams $s$.

```
// let }\mp@subsup{A}{1s}{}\mathrm{ a program evaluator for E E }\trianglerightV->
// let A As a program evaluator for E E \trianglerightV 
As}=\mathrm{ let // program evaluator for E= at (E1, E2 )}\V->\mp@subsup{V}{}{\prime
    (get-val }\mp@subsup{}{1}{},\mp@subsup{\mathrm{ is-done }}{1}{},\mp@subsup{\mathrm{ remove }}{1}{},\mp@subsup{\mathrm{ add-inst }}{1}{},\mp@subsup{\mathrm{ upd-val }}{1}{})=\mp@subsup{A}{1}{
```



```
    W=V\cup\mp@subsup{V}{}{\prime}
    R= registration.new(W,TyPE (E))
    link}\mp@subsup{k}{1}{}=\mathrm{ fun ( }\pi,\alpha)\quad\mp@subsup{\alpha}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    link}\mp@subsup{\mp@code{2}}{2}{=}\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun(\pi,\alpha) R(\pi,\alpha) end
    is-done = fun( }\pi,\alpha\mathrm{ )
        is-done 
    remove = proc(\pi,\alpha)
        remove}1(\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha)
        remove}2(get-val ( ( , ,link ( ( \pi,\alpha)), ,ink 2 (\pi,\alpha)
        R.remove(\pi,\alpha)
    end
    add-inst = fun( }\pi,\alpha
        R.add-inst(\pi, \alpha)
        c}=add-inst1 (\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha)
        c}=\mp@code{add-inst2}(get-val ( (\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha)),\mp@subsup{\operatorname{link}}{2}{}(\pi,\alpha)
        R.set-val(\pi, \alpha, apply(R(\pi,\alpha),\mp@subsup{c}{2}{}))
    in
        c
    end
    get-ass-com}\mp@subsup{2}{2}{= fun(AssUps)
        AssUps' = set.new()
        for (\pi,\alpha,x,c)\inAssUps do
            AssUps'.add(get-val ( }\pi,\mp@subsup{\operatorname{link}}{1}{(}(\pi,\alpha)),\mp@subsup{\operatorname{link}}{2}{(}(\pi,\alpha),x,c
        end
        in
        AssUps'.content()
    end
```

Figure 11.30: Part 1 of a program evaluator for locations on streams $s$.

```
    letrec
    get-upd-com \(=\)
        fun \(\left(\pi, \alpha, c_{1}, c_{2}\right)\)
            case \(c_{1}\)
            of none then \(c_{2}\)
            of instantiate \((v)\) then \(a d d-\) inst \(_{2}\left(v, \operatorname{link}_{2}(\pi, \alpha)\right)\)
            end
in
upd-val \(=\mathbf{f u n}(e \in \operatorname{events}(s)\), AssUps \()\)
    for \((\pi, \alpha, x, c) \in\) AssUps do R.upd-ass \(\left(\pi, \alpha, \alpha_{\left.\right|_{W \backslash\{x\}}} \uplus[x / \operatorname{apply}(\alpha(x), c)]\right)\)
    \(U_{2}=u p d-\) val \(_{2}\left(e\right.\), get-ass-com \(\left.{ }_{2}(A s s U p s)\right)\)
    \(\mathcal{M}=\) master-registration.new \(\left(R, R_{1}, R_{2}\right)\)
    for \((\pi, \alpha) \in R . \operatorname{dom}()\) do
        \(\mathcal{M}\).init-collection \((\pi, \alpha, 1)\)
        \(\mathcal{M}\).init-collection \((\pi, \alpha, 2)\)
    end
    for \(\left(\pi^{\prime}, \alpha^{\prime}, v, c\right) \in U_{2}\) do
        for \((\pi, \alpha) \in\left\{(\pi, \alpha) \mid \operatorname{get}-\operatorname{val}_{1}\left(\pi, \operatorname{link}_{1}(\pi, \alpha)\right)=\pi^{\prime}, \operatorname{link}_{2}(\pi, \alpha)=\alpha^{\prime}\right\}\) do
                \(\mathcal{M} . \operatorname{collect}(\pi, \alpha, c, 2)\)
            end
    end
    get-ass-com \({ }_{1}=\) gen-ass-com \(\left(\right.\) link \(\left._{1}\right)\)
    \(U_{1}=u p d-v a l_{1}\left(e\right.\), get-ass-com \({ }_{1}(\) AssUps,\(\left.\emptyset)\right)\)
    for \(\left(\pi, \alpha^{\prime}, v, c\right) \in U_{1}\) do
        for \((\pi, \alpha) \in\left\{(\pi, \alpha) \mid \operatorname{link}_{1}(\pi, \alpha)=\alpha^{\prime}\right\}\) do
            \(\mathcal{M} . \operatorname{collect}(\pi, \alpha, c, 1)\)
        end
    end
    \(M=\) set.new()
    for \((\pi, \alpha) \in R . \operatorname{dom}()\) do
        \(c=\) get-upd-com \((\pi, \alpha, \mathcal{M}\). get-collection \((\pi, \alpha, 1), \mathcal{M} . \operatorname{get}-\operatorname{collection}(\pi, \alpha, 2))\)
        \(v=R(\pi, \alpha)\)
        R.set-val \((\pi, \alpha, \operatorname{apply}(v, c))\)
        in
        \(M . \operatorname{add}((\pi, \alpha, v, c))\)
    end
in
    M.content()
    end
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.31: Part 2 of a program evaluator for locations on streams $s$.

## Conditionals.

$$
\begin{gathered}
E_{0} \triangleright V \rightarrow \emptyset \quad E_{1} \triangleright V \rightarrow V^{\prime} \quad E_{2} \triangleright V \rightarrow V^{\prime} \\
E=\text { if } E_{0} \text { then } E_{1} \text { else } E_{2} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{0 s}$ be a program evaluator for $E_{0}:$ bool $\triangleright V \rightarrow \emptyset$ and $A_{i s}$ be program evaluators for $E_{i}: T \triangleright V \rightarrow V^{\prime}$ for $i \in\{1,2\}$. We define a program evaluator $A_{s}$ for $E: T \triangleright V \rightarrow$ $V^{\prime}$ in Figure 11.32. Registrations have the following form:


For algorithm $A_{s}$ in the beginning it is not known whether $A_{0 s}$ evaluates to true, for which the result by $A_{1 s}$ is the answer, or whether $A_{0 s}$ evaluates to False, for which the result by $A_{2 s}$ is needed. Therefore we wait until $A_{0 s}$ has determined its answer, at which event we start $A_{1}$ or $A_{2}$, respectively. Therefore in the example we consider three entries $\left(\pi_{1}, \alpha_{1}\right),\left(\pi_{2}, \alpha_{2}\right),\left(\pi_{3}, \alpha_{3}\right) \in R . \operatorname{dom}()$. For entries where $A_{0 s}$ returns true, as with entry $\left(\pi_{1}, \alpha_{1}\right) \in R . \operatorname{dom}()$, registration $R_{1}$ is started, while when $A_{0 s}$ returns false, then $R_{2}$ is started. Due to our restrictions on conditionals from Section 11.1.1 the possible late launch of either $A_{1}$ or $A_{2}$ does not require information from the past of the stream. The get-upd-com function of the program evaluator tests the update $c_{0}$ of $A_{0 s}$ at some event. If it is none, then maybe because it has already determined its answer get-val $0\left(\pi, \operatorname{link}_{0}(\pi, \alpha)\right)$ for some entry $(\pi, \alpha) \in R . \operatorname{dom}()$. If it was true, then the value of $R$ for the entry requires the same update $c_{1}$ with which the corresponding value in $R_{1}$ was updated with. If the answer was false then one takes update $c_{2}$ from $R_{2}$, or the answer is not yet known $(\bullet)$, such that neither $R_{1}$ nor $R_{2}$ has been started for the entry, for which update command none is returned. If update $c_{0}$ was instantiate $(v)$, meaning that $R_{0}$ determined its answer, one starts either $R_{1}$ or $R_{2}$ depending on $v$. This is a possible late start, e.g. a start at some event $e=\left(o p, \pi^{\prime}\right)$ that was input to the upd-val function, of a node $\pi^{\prime}$ that came after $\pi$. The query evaluator $B_{s}$ works similarly and only differs in link definitions.

```
// Let }\mp@subsup{A}{1s}{}\mathrm{ be a program evaluator for E E DV }->
// Let }\mp@subsup{A}{is}{}\mathrm{ be a program evaluator for }\mp@subsup{E}{i}{}\trianglerightV->\mp@subsup{V}{}{\prime}\mathrm{ for 1}\leqi\leq
As}=\mathrm{ let // program evaluator for }E=\mathrm{ if }\mp@subsup{E}{0}{}\mathrm{ then }\mp@subsup{E}{1}{}\mathrm{ else }\mp@subsup{E}{2}{}\trianglerightV->\mp@subsup{V}{}{\prime
    (get-val i, is-done i, remove i, add-inst i,upd-vali) = A Ais, for all 0 \leqi\leq2
    R= registration.new(V\cupV',}\operatorname{TYPE}(E)
    link}\mp@subsup{|}{0}{}=\mathrm{ fun ( }\pi,\alpha)\quad\mp@subsup{\alpha}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    link}\mp@subsup{k}{1}{}=\mathbf{fun}(\pi,\alpha) \alpha en
    link}\mp@subsup{k}{2}{}=\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun (\pi,\alpha) R(\pi,\alpha) end
    get-upd-com = fun (\pi,\alpha,\mp@subsup{c}{0}{},\mp@subsup{c}{1}{},\mp@subsup{c}{2}{})
        case co
        of none then
            case get-val ( }\pi,\mp@subsup{\operatorname{link}}{0}{}(\pi,\alpha)
            of true then c
            of false then c}\mp@subsup{c}{2}{
            of - then none
            end
        of instantiate(v) then //starts }\mp@subsup{A}{1s}{}\mathrm{ or }\mp@subsup{A}{2s}{}\mathrm{ possibly late
            if v}\mathrm{ then add-inst
            else add-inst}\mp@subsup{2}{2}{(\pi,\mp@subsup{\operatorname{link}}{2}{(}(\pi,\alpha))
        end
    end
    is-done = fun (\pi,\alpha) (get-val ( }\pi,\mp@subsup{\alpha}{\mp@subsup{|}{V}{}}{})=\mathrm{ true ^is-done 
```



```
    remove = gen-remove(R, remove}0,\mp@subsup{\mathrm{ remove }}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{0}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = fun( }\pi,\alpha
        R.add-inst( }\pi,\alpha
        coloadd-inst
        c=get-upd-com( }\pi,\alpha,\mp@subsup{c}{0}{},\mathrm{ none, none )
        in
        c
    end
    upd-val = gen-upd-val(R,upd-val },\mathrm{ ,upd-val },\mathrm{ ,upd-val },\mp@subsup{\mathrm{ link }}{0}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{},\mathrm{ get-upd-com,
                gen-ass-com(link 
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.32: A program evaluator for conditionals on streams $s$.

## Recursions.

$$
\begin{gathered}
\forall 1 \leq i \leq n . E_{i} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow \emptyset \\
E^{\prime} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime} \\
E=\text { letrec } x_{1}=E_{1}, \ldots, x_{n}=E_{n} \text { in } E^{\prime} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{i s}$ be a program evaluator for $E_{i} \triangleright V \cup\left\{x_{1}, \ldots, x_{n} \rightarrow \emptyset, 1 \leq i \leq n\right.$. and $A_{s}^{\prime}$ be a program evaluator for $E^{\prime} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime}$. The program evaluator $A_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ is given in Figure 11.33. The registrations have the following form where $W=V \cup V^{\prime} \cup\left\{x_{1}, \ldots, x_{n}\right\}$ :


For some instance $(\pi, \alpha) \in R$. $\operatorname{dom}()$ the respective entry in $R^{\prime}$ is $\alpha^{\prime}=\alpha \uplus\left[x_{1} / A_{1}{ }_{s}^{\prime \prime}, \ldots, x_{n} / A_{n_{s}}^{\prime \prime}\right]$ where the $A_{i s}^{\prime \prime}$ are recursively defined by program evaluators $A_{i s}$. The subevaluators for variables $x_{i}$ in $A_{s}^{\prime}$ that are assigned to $A_{i_{s}^{\prime \prime}}^{\prime \prime}$ are then the evaluators $A_{i s}^{\prime \prime}$ themselves. The query evaluator $B_{s}$ is similar to the program evaluator. It differs only in link definitions.

## Tuple constructions.

$$
\frac{\forall 1 \leq i \leq n . E_{i} \triangleright V \rightarrow \emptyset \quad E=\left(E_{1}, \ldots, E_{n}\right)}{E \triangleright V \rightarrow \emptyset}
$$

Let $A_{i s}$ be program evaluator for $E_{i}: T_{i} \triangleright V \rightarrow \emptyset$ for $1 \leq i \leq n$. We define a program evaluator $A_{s}$ for $E \triangleright V \rightarrow \emptyset$ in Figure 11.34. Registrations have the following form:

```
// Let }\mp@subsup{A}{is}{}\mathrm{ be a program evaluator for Ei}\trianglerightV\cup{\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{}}->\emptyset,1\leqi\leq
// Let }\mp@subsup{A}{s}{\prime}\mathrm{ be a program evaluator for }\mp@subsup{E}{}{\prime}\trianglerightV\cup{\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{}}->\mp@subsup{V}{}{\prime
As}=\mathrm{ let // program evaluator for
    E= letrec }\mp@subsup{x}{1}{}=\mp@subsup{E}{1}{},\ldots,\mp@subsup{x}{n}{}=\mp@subsup{E}{n}{}\mathrm{ in }\mp@subsup{E}{}{\prime}\trianglerightV->\mp@subsup{V}{}{\prime
```



```
    (get-val', is-done', remove', add-inst', upd-val') = A's
    letrec
        A1s}\mp@subsup{|}{s}{\prime\prime}=(\mathrm{ get-val 
        R
        link}\mp@subsup{k}{1}{\prime}=\mathbf{fun}(\pi,\alpha) \alpha\uplus[\mp@subsup{x}{1}{}/\mp@subsup{A}{1}{\prime\prime},\ldots,\mp@subsup{x}{n}{\prime}/\mp@subsup{A}{n}{\prime\prime}\mp@subsup{}{s}{\prime\prime}]\mathrm{ end
        get-val l}=\mathrm{ fun( }\pi,\alpha:\mp@subsup{\boldsymbol{ass}}{V\cup{\operatorname{arg}}) get-val}{1}(\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha))\mathrm{ end
        get-upd-com'\prime}=\mathbf{fun}(\pi,\alpha,\mp@subsup{c}{1}{\prime})\quad\mp@subsup{c}{1}{}\mathrm{ end
```



```
        remove",}=\mathrm{ gen-remove ( }\mp@subsup{R}{1}{\prime\prime},\mp@subsup{\mathrm{ remove }}{1}{},\mp@subsup{\mathrm{ link }}{1}{}
        add-inst1
        upd-vall
        A}\mp@subsup{n}{s}{\prime\prime}=(\mathrm{ get-val 
        R
```



```
        get-val首}=\mathbf{fun(}(\pi,\alpha:\mp@subsup{\mathbf{ass}}{V\cup{\operatorname{arg}}}{)}\mathrm{ ) get-val 
        get-upd-com'\prime}=\mathbf{fun}(\pi,\alpha,\mp@subsup{c}{n}{\prime})\mp@subsup{c}{n}{}\mathrm{ end
```



```
        remove=
```



```
        upd-vall
    in
    W=V\cup\mp@subsup{V}{}{\prime}\cup{\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{}}
    R= registration.new(V\cupV',}\operatorname{TYPE}(E)
    link}=\mathbf{fun}(\pi,\alpha) \alpha\uplus[\mp@subsup{x}{1}{}/\mp@subsup{A}{1}{\prime\prime},\ldots,\mp@subsup{x}{n}{\prime}/\mp@subsup{A}{n}{\prime\prime}] ] end
    get-val = fun (\pi,\alpha) R(\pi,\alpha) end
    get-upd-com}=\mathbf{fun}(\pi,\alpha,\mp@subsup{c}{}{\prime})\quad\mp@subsup{c}{}{\prime}\mathrm{ end
    is-done = fun( }\pi,\alpha) is-done' ( \pi, link (\pi,\alpha)) end
    remove = gen-remove( }R,\mathrm{ remove',link)
    add-inst = gen-add-inst(R,add-inst',link, get-upd-com)
    upd-val = gen-upd-val(R,upd-val',link,get-upd-com,gen-ass-com(link))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.33: A program evaluator for recursive lets on streams $s$.

```
// Let }\mp@subsup{A}{is}{}\mathrm{ be a program evaluator for }\mp@subsup{E}{i}{}\trianglerightV->\emptyset,1\leqi\leq
As}=\mathrm{ let // program evaluator for E= (E E , .., E E ) }\downarrowV->
```



```
    R= registration.new(V,TYPE (E))
    link}\mp@subsup{k}{i}{}=\mathbf{fun}(\pi,\alpha) \alpha end for all 1\leqi\leqn
    get-val = fun(\pi,\alpha) R(\pi,\alpha) end
    get-upd-com = fun (\pi,\alpha,\mp@subsup{c}{1}{},\ldots,\mp@subsup{c}{n}{})(\mp@subsup{c}{1}{},\ldots,\mp@subsup{c}{n}{})\mathrm{ end}
    is-done = fun (\pi,\alpha) is-done 
```





```
                gen-ass-com(link}\mp@subsup{1}{1}{}),\ldots,\mathrm{ gen-ass-com(link}\mp@subsup{|}{n}{})
```

in (get-val,is-done, remove, add-inst, upd-val)

Figure 11.34: A program evaluator for tuple constructions on streams $s$.

| R | $(\pi, \alpha)$ |  | node $\operatorname{ass}_{V} \mid T_{1} \times \ldots \times T_{n}$ |  |  |  | $\operatorname{upd}\left(\left(v_{1}, \ldots, v_{n}\right)\right)$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | $\pi$ | $\alpha$ | (v | $\left.v_{n}\right)$ |  |  |  |
|  | $\left.(\pi, \alpha) / \int \operatorname{upd}\left(v_{1}\right) \quad \cdots \quad(\pi, \alpha)\right\rangle\left\langle u p d\left(v_{n}\right)\right.$ |  |  |  |  |  |  |  |  |
|  | nod | ass | $T_{1}$ |  |  | nod | $\mathbf{s s}_{V}$ | $T_{n}$ |  |
| $R_{1}$ | $\pi \quad \alpha$ |  | $v_{1}$ |  |  | $\pi$ | $\alpha$ | $v_{n}$ | $R_{n}$ |

Tuples are constructed by program evaluator $A_{s}$, whereas program evaluator $A_{i s}$ computes the $i$-th component of the tuples. Therefore, at some event, the get-upd-com function of $A_{s}$ combines the updates $c_{i}$ to the $i$-th component into an update $\left(c_{1}, \ldots, c_{n}\right)$ of the tuple.

## Tuple decompositions.

$$
\begin{gathered}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime} \\
E=\text { match } E_{1} \text { with }\left(x_{1}, \ldots, x_{n}\right) \text { in } E_{2} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{1 s}$ be a program evaluator for $E_{1}: T_{1} \times \ldots \times T_{n} \triangleright V \rightarrow \emptyset$, and $A_{2 s}$ be a program evaluator for $E_{2}: T \triangleright V \cup\left\{x_{1}, \ldots, x_{n}\right\} \rightarrow V^{\prime}$. We define a program evaluator $A_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ in Figure 11.35. Registrations have the following form where $W=V \cup V^{\prime} \cup\left\{x_{1}, \ldots, x_{n}\right\}:$


Program evaluator $A_{s}$ decomposes tuples by $A_{1 s}$ in $R_{1}$ into their components $v_{i}$, which are passed to evaluator $A_{2 s}$ via assignments $\alpha^{\prime}=\alpha \uplus\left[x_{1} / v_{1}, \ldots, x_{n} / v_{n}\right]$ with respect to the entries given for the registrations. Any updates of tuples in $R_{1}$ must therefore be forwarded as variable assignment update to $A_{2 s}$. This is done by function get-ass-com 2 , which given the updates $U_{1}$ by $A_{1 s}$ and given some variable assignment update AssUps, computes a new variable assignment update such that the upd-val of $A_{2 s}$ has knowledge of these updates. The function first converts the updates in AssUps to fit linked entries in $R_{2}$ and next adds for any update $c$ of tuples $\left(v_{1}, \ldots, v_{n}\right)$ and any variable $x_{i}$ a new variable assignment update that indicates that the value of variable $x_{i}$ has been updated with the update to the $i$-th component of $v_{i}$. This update is computed via function $i$-th-com that decomposes the tuple update $c$ into updates $c_{i}$ for component $i$. The query evaluator $B_{s}$ for $E \triangleright V \rightarrow V^{\prime}$ differs with respect to the program evaluator $A_{s}$ only in the link definition.

Set constructions.

$$
\frac{E^{\prime} \triangleright V \rightarrow\{x\} \quad E=\left\{x \mid E^{\prime}\right\}}{E \triangleright V \rightarrow \emptyset}
$$

Let $B_{s}^{\prime}$ be a query evaluator for $E^{\prime} \triangleright V \rightarrow\{x\}$. We define program evaluator $A_{s}$ for $E:\{T\} \triangleright V \rightarrow \emptyset$ in Figure 11.36. The registrations have the following form:

| , | $(\pi, \alpha)$ | node $^{\text {ass }}$ $\pi^{\cdots} \quad \alpha$ $\cdots$ | $\begin{array}{l\|l}  & \{T\} \\ v^{\prime} \end{array}$ | $\begin{aligned} & \text { upd }\left(v^{\prime}\right) \\ & v^{\prime}=\left\{\beta^{\prime}(x) \mid \beta^{\prime} \in v\right\} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| R' | $(\pi, \alpha) /$ | $\begin{gathered} \text { node } \operatorname{ass}_{V} \\ \hline \left.\begin{array}{c} \cdots \\ \\ \pi \end{array} \right\rvert\, \\ \cdots \end{gathered}$ | $2^{\boldsymbol{a s s}_{V \cup\{x\}}}$ <br> $v$ |  |

```
// Let }\mp@subsup{A}{1s}{}\mathrm{ be a program evaluator for E E D V }->
// Let }\mp@subsup{A}{2s}{}\mathrm{ be a program evaluator for E E D V }\cup{\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{}}->\mp@subsup{V}{}{\prime
// Let E = match E E with ( }\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{})\mathrm{ in }\mp@subsup{E}{2}{
As}=\mathrm{ let // program evaluator for }E\trianglerightV->\mp@subsup{V}{}{\prime
    (get-val },\mp@subsup{\mathrm{ is-done }}{1}{},\mp@subsup{\mathrm{ remove }}{1}{},\mathrm{ add-inst }\mp@subsup{}{1}{},\mp@subsup{\mathrm{ upd-val }}{1}{})=\mp@subsup{A}{1s}{
    (get-val },\mp@subsup{\mathrm{ is-done }}{2}{},\mp@subsup{\mathrm{ remove }}{2}{},\mathrm{ add-inst }\mp@subsup{\mp@code{N}}{2}{},\mathrm{ upd-val }2)=\mp@subsup{A}{2s}{
    W=V\cup\mp@subsup{V}{}{\prime}\cup{\mp@subsup{x}{1}{},\ldots,\mp@subsup{x}{n}{}}
    R= registration.new (V\cupV',}\operatorname{TYPE}(E)
    link}\mp@subsup{|}{1}{}=\mathbf{fun}(\pi,\alpha)\quad\mp@subsup{\alpha}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    link}\mp@subsup{k}{2}{}=\mathbf{fun}(\pi,\alpha
        case get-val ( }\pi,\mp@subsup{\operatorname{link}}{1}{}(\pi,\alpha)
        of \bullet then \alpha}\uplus[\mp@subsup{x}{1}{}/\bullet,\ldots,\mp@subsup{x}{n}{}/\bullet
        of (v},\mp@code{,., v
        end
    end
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
    get-upd-com = fun( }\pi,\alpha,\mp@subsup{c}{1}{},\mp@subsup{c}{2}{})\quad\mp@subsup{c}{2}{}\mathrm{ end
    letrec
        i-th-com = fun(c,i)
            case c
            of none then none
            of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then }i\mathrm{ -th-com (col,i)&i-th-com (con},i
            of (c
        end
    in
    get-ass-com}\mp@subsup{2}{2}{=}\mathbf{fun(AssUps,U}\mp@subsup{U}{1}{}
        M=set.new()
        get-ass-com',}=\mathrm{ gen-ass-com(link }\mp@subsup{)}{2}{}
        M.union(get-ass-com'
        inv-links }\mp@subsup{1}{1}{=gen-inv-links(R, link}\mp@subsup{1}{1}{}
        for }(\pi,\mp@subsup{\alpha}{1}{},(\mp@subsup{v}{1}{},\ldots,\mp@subsup{v}{n}{}),c)\in\mp@subsup{U}{1}{}\mathrm{ do
```



```
                M.add(\pi,\alpha\uplus[x}/\mp@subsup{x}{1}{}/\mp@subsup{v}{1}{},\ldots,\mp@subsup{x}{n}{}/\mp@subsup{v}{n}{}],\mp@subsup{x}{1}{},i\mathrm{ -th-com(c,1))
                    M.add( }\pi,\alpha\uplus[\mp@subsup{x}{1}{}/\mp@subsup{v}{1}{},\ldots,\mp@subsup{x}{n}{}/\mp@subsup{v}{n}{}],\mp@subsup{x}{n}{},i-th-com(c,n)
        in M.content()
    end
```



```
    remove = gen-remove( }R,\mp@subsup{\mathrm{ remove }}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = gen-add-inst(R,add-inst 
    upd-val = gen-upd-val(R,upd-val 
        gen-ass-com(link }\mp@subsup{1}{1}{}),\mathrm{ get-ass-com}2
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.35: A program evaluator for tuple decompositions on streams $s$.

```
\(/ /\) Let \(B_{s}^{\prime}\) be a query evaluator for \(E^{\prime} \triangleright V \rightarrow\{x\}\)
\(A_{s}=\) let \(/ /\) program evaluator for \(E=\left\{x \mid E^{\prime}\right\} \triangleright V \rightarrow \emptyset\)
    (get-val', is-done \({ }^{\prime}\), remove \({ }^{\prime}\), add-inst \({ }^{\prime}\), upd-val') \(=B_{s}^{\prime}\)
    \(R=\) registration.new \((V, \operatorname{TYPE}(E))\)
    \(\operatorname{link}=\mathbf{f u n}(\pi, \alpha) \quad \alpha\) end
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    letrec
        get-upd-var-ass-elem =
            fun \((e, c)\)
            case \(c\)
            of none then none
            of \(c_{1} \& c_{2}\) then get-upd-var-ass-elem \(\left(e, c_{1}\right) \&\) get-upd-var-ass-elem \(\left(e, c_{2}\right)\)
            of extend-var-ass \((y, v)\) then if \(y=x\) then extend-set \((\{v\})\) else none
            of upd-var-ass \((y, v, c)\) ) then if \(y=x\) then \(u p d\)-elem-set \((v, c)\) else none
        end
    get-upd-com \(=\)
        fun \((\pi, \alpha, c)\)
            case \(c\)
            of none then none
            of \(c_{1} \& c_{2}\) then get-upd-com \(\left(\pi, \alpha, c_{1}\right) \& g e t-u p d-c o m\left(\pi, \alpha, c_{2}\right)\)
            of extend-set \((v)\) then extend-set \(\left(\left\{\beta^{\prime}(x) \mid \beta^{\prime} \in v, x \in \beta^{\prime} . \operatorname{dom}()\right\}\right)\)
            of upd-elem-set \(\left(e, c^{\prime}\right)\) then get-upd-var-ass-elem \(\left(e, c^{\prime}\right)\)
            of resolve-elem-set \((e, b)\) then if \(x \in \operatorname{edom}()\) then resolve-elem-set \((e(x), b)\)
                else none
        end
    in
    is-done \(=\) fun \((\pi, \alpha)\) is-done \({ }^{\prime}(\pi, \alpha)\) end
    remove \(=\) gen-remove \(\left(R\right.\), remove \({ }^{\prime}\), link \()\)
    \(a d d-\) inst \(=\) gen-add-inst ( \(R\), add-inst', link, get-upd-com)
    upd-val \(=\) gen-upd-val(R,upd-val', link, get-upd-com,gen-ass-com(link))
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.36: A program evaluator for set constructions on streams $s$.

The set of all elements of values for $x$ is constructed via query evaluator $B_{s}^{\prime}$ that generates all possible values for $x$, by computing variable assignment extensions. Given an entry $(\pi, \alpha) \in R . \operatorname{dom}()$ the value $v$ of the linked entry $(\pi, \alpha) \in R^{\prime} . \operatorname{dom}()$ contains variable assignment that extend $\alpha$ by assigning values to $x$. The result set by $A_{s}$ is thus $v^{\prime}=\left\{\beta^{\prime}(x) \mid \beta^{\prime} \in v\right\}$. The challenge for the program evaluator $A_{s}$ is thus to compute updates to $v^{\prime}$ given updates to $v$. The get-upd-com function therefore decomposes updates $c$ to $v$. When $v$ is extended by a set of variables assignments, then one simply extends $v^{\prime}$ by the set of values of $x$ of these variable assignments. Whenever a variable assignment $e$ of $v$ that assigns some value to $x$ is resolved by boolean $b$ then one resolves element $e(x)$ in $v^{\prime}$ by $b$. Finally when a variable assignment $e$ is updated via some variable assignment update $c^{\prime}$, then one calls function get-upd-var-ass-elem that returns an update to $v$ that corresponds to $c^{\prime}$ when $c^{\prime}$ involves updates to values of $x$.

## List constructions.

$$
\frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow \emptyset \quad E=E_{1}:: E_{2}}{E \triangleright V \rightarrow \emptyset}
$$

Let $A_{1 s}$ be program evaluator for $E_{1}: T \triangleright V \rightarrow \emptyset$ and $A_{2_{s}}$ be program evaluator for $E_{2}:\left[T^{\prime}\right] \triangleright V \rightarrow \emptyset$ We define program evaluator $A_{s}$ for $E_{1}:: E_{2}:\left[T \cup T^{\prime}\right] \triangleright V \rightarrow \emptyset$ in Figure 11.37. Registrations have the following form:


Lists are constructed by joining some head element that is computed by program evaluator $A_{1 s}$, with a tail that is the list, that is computed by program evaluator $A_{2 s}$. In function get-upd-com one translates updates $c_{1}$ to the head and updates $c_{2}$ to the tail to updates for the result list as follows. Updates $c_{1}$ become updates to the result list that update the first element in the list. Updates $c_{2}$ to the tail must be altered to updates to the result list, that contains a new head element, which is done via function add-index that converts updates to the $i$-th element of the tail, to updates to the $i+1$-st element of the result list.

## List decompositions.

$$
\begin{gathered}
E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \cup\{x, y\} \rightarrow V^{\prime} \quad E_{3} \triangleright V \rightarrow V^{\prime} \\
E=\text { match } E_{0} \text { with } x:: y \text { then } E_{1} \text { else } E_{2} \\
E \triangleright V \rightarrow V^{\prime}
\end{gathered}
$$

Let $A_{0 s}$ be a program evaluator for $E_{0}:[T] \triangleright V \rightarrow \emptyset, A_{1 s}$ a program evaluator for $E_{1}: T^{\prime} \triangleright V \cup\{x, y\} \rightarrow V^{\prime}$, and $A_{2 s}$ a program evaluator for $E_{2}: T^{\prime} \triangleright V \rightarrow V^{\prime}$. We define program evaluator $A_{s}$ for $E: T^{\prime} \triangleright V \rightarrow V^{\prime}$ in Figure 11.38. Registrations have the following form, where $W=V \cup V^{\prime} \cup\{x, y\}$ :

```
// Let }\mp@subsup{A}{is}{}\mathrm{ be program evaluators for }\mp@subsup{E}{i}{}\trianglerightV->\emptyset\mathrm{ and all 1 
As}=\mathrm{ let // program evaluator for E= E 泣: E E D V 
```



```
    R= registration.new (V, TYPE (E))
    link}\mp@subsup{\mp@code{1}}{}{=}\mathbf{fun}(\pi,\alpha) \alpha en
    link}\mp@subsup{2}{2}{}=\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
    letrec add-index = fun (\pi,\alpha,c)
            case c
            of none then none
            of }\mp@subsup{c}{1}{}&\mp@subsup{c}{2}{}\mathrm{ then add-index ( }\pi,\alpha,\mp@subsup{c}{1}{})&add-index (\pi,\alpha,\mp@subsup{c}{2}{}
            of extend-list(v) then extend-list(v)
            of upd-elem-list( }i,\mp@subsup{c}{}{\prime})\mathrm{ then upd-elem-list ( }i+1,\mp@subsup{c}{}{\prime}
            of resolve-elem-list (i,b) then resolve-elem-list (i+1,b)
        end
    in
    get-upd-com = fun( }\pi,\alpha,\mp@subsup{c}{1}{},\mp@subsup{c}{2}{})\mathrm{ upd-elem-list(1, c
```



```
    remove = gen-remove(R, remove}\mp@subsup{}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = gen-add-inst(R,add-inst 
    upd-val = gen-upd-val(R,upd-val },\mathrm{ ,upd-val2, link }\mp@subsup{1}{1}{},\mp@subsup{\mathrm{ link }}{2}{},\mathrm{ ,get-upd-com,gen-ass-com(link 
                gen-ass-com(link }\mp@subsup{\mp@code{L}}{2}{)}
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.37: A program evaluator for list constructions on streams $s$.


For algorithm $A$ in the beginning it is not known a priori whether $A_{0 s}$ evaluates to the empty list, for which the result by $A_{2 s}$ is the answer, or whether $A_{0 s}$ evaluates to a non-empty list, for which the result by $A_{1 s}$ is needed. One therefore waits until the computation of the list by $A_{0 s}$ has finished, at which event we launch $A_{1 s}$ or $A_{2 s}$, respectively. This is done by function get-upd-com, similar to conditionals. Due to our restrictions on list decompositions the possible late launch of either
$A_{1 s}$ or $A_{2 s}$ does not require information from the past of the stream. The query evaluator $B_{s}$ is similar and differs only slightly in link definitions.

## Function applications.

$$
\frac{E_{1} \triangleright V \rightarrow \emptyset \quad E_{2} \triangleright V \rightarrow \emptyset \quad E=E_{1} E_{2}}{E \triangleright V \rightarrow \emptyset}
$$

Let $A_{1 s}$ be a program evaluator for $E_{1}: T \rightarrow T^{\prime} \triangleright V \rightarrow \emptyset$ and $A_{2 s}$ be a program evaluator for $E_{2}: T \triangleright V \rightarrow \emptyset$. We define a program evaluator $A_{s}$ for $E_{1} E_{2}: T^{\prime} \triangleright V \rightarrow \emptyset$ in Figure 11.39. Registrations have the following form:


The argument $v_{2}$ that is computed by $A_{2 s}$ is passed via variable assignment $\left[\arg / v_{2}\right]$ to $A_{1 s}$. Any update $c_{1}$ to the result by $v_{1}$ by $A_{1 s}$ is therefore an update to the result $v_{1}$ of $A_{s}$ of the function application, see function get-upd-com. However, similar to tuple decompositions, one requires to pass updates to argument $v_{2}$ as variable assignment updates to $A_{2 s}$, computed by function get-ass-com ${ }_{1}$. Then after the registration $R_{2}$ has been updated, one can update $R_{1}$, as one sees in the order of the parameters for the function generator gen-upd-val.

## Function definitions.

$$
\frac{E^{\prime} \triangleright V \cup\{x\} \rightarrow \emptyset \quad E=\lambda x . E^{\prime}}{E \triangleright V \rightarrow \emptyset}
$$

Let $A_{s}^{\prime}$ be a program evaluator for $E^{\prime}: T^{\prime} \triangleright V \cup\{x\} \rightarrow \emptyset$. We define a program evaluator $A_{s}$ for applying function definitions $\lambda x . E^{\prime}: T \rightarrow T^{\prime} \triangleright V \rightarrow \emptyset$ in Figure 11.40. Registrations have the following form:

```
// Let }\mp@subsup{A}{0s}{}\mathrm{ be a program evaluator for E E D V }->
// Let }\mp@subsup{A}{1s}{}\mathrm{ be a program evaluator for E E D V }\cup{x,y}->\mp@subsup{V}{}{\prime
// Let }\mp@subsup{A}{2s}{}\mathrm{ be a program evaluator for E E D }\downarrow->\mp@subsup{V}{}{\prime
// Let E = match E E with }x::y\mathrm{ then }\mp@subsup{E}{1}{}\mathrm{ else }\mp@subsup{E}{2}{
As}=\mathrm{ let // program evaluator for }E\trianglerightV->\mp@subsup{V}{}{\prime
```



```
    W=V\cup\mp@subsup{V}{}{\prime}\cup{x,y}
    R= registration.new(V\cupV',
    link}\mp@subsup{k}{0}{}=\mathbf{fun}(\pi,\alpha)\quad\mp@subsup{\alpha}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    link}\mp@subsup{k}{1}{}=\mathbf{fun}(\pi,\alpha
        case get-val ( }\pi,\mp@subsup{\operatorname{link}}{0}{}(\pi,\alpha)
        of \bullet then \alpha}\uplus[x/\bullet,y/\bullet
        of v:: v' then \alpha}[x/v,y/\mp@subsup{v}{}{\prime}
        end
    end
    link}\mp@subsup{k}{2}{}=\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
    get-upd-com = fun( }\pi,\alpha,\mp@subsup{c}{0}{},\mp@subsup{c}{1}{},\mp@subsup{c}{2}{}
        if colonone ^is-done ( 
            if get-val ( 
            else add-inst
            else
            if none then
                if is-done }(\pi,\mp@subsup{\operatorname{link}}{0}{}(\pi,\alpha)) the
                        case get-val ( }\pi,\mp@subsup{\operatorname{link}}{0}{}(\pi,\alpha)
                        of nil then c}\mp@subsup{c}{2}{
                        of v:: v
                        end
                    else none
            else none
    end
```




```
    remove = gen-remove(R, remove}0,\mp@subsup{\mathrm{ remove }}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{0}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = fun( }\pi,\alpha
            R.add-inst( }\pi,\alpha
            co =add-inst 
            c = get-upd-com( }\pi,\alpha,\mp@subsup{c}{0}{},\mathrm{ none, none)
        in c
    end
    upd-val = gen-upd-val(R,upd-val },\mathrm{ ,upd-val },\mathrm{ ,upd-val },\mp@subsup{\mathrm{ link }}{0}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{},\mathrm{ get-upd-com,
        gen-ass-com(link })\mathrm{ ), gen-ass-com(link }\mp@subsup{1}{1}{}),\mathrm{ gen-ass-com(link 2 ))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.38: A program evaluator for list decompositions on streams $s$.

```
// Let }\mp@subsup{A}{is}{}\mathrm{ be a program evaluator for Ei
// Let arg be a fixed variable used to pass arguments
As}=\mathrm{ let // program evaluator for E = E E E E DV }->
    (get-val }\mp@subsup{,}{is-done }{i},\mp@subsup{\mathrm{ remove }}{i}{},\mp@subsup{\mathrm{ add-inst }}{i}{},\mp@subsup{\mathrm{ upd-val }}{i}{})=\mp@subsup{A}{is}{},\quad1\leqi\leq
    R= registration.new(V,TYPE (E))
    link}\mp@subsup{\mp@code{1}}{1}{=}\mathbf{fun}(\pi,\alpha) \alpha\uplus[\operatorname{arg}/get-val ( (\pi,\alpha)] en
    link}\mp@subsup{\mp@code{2}}{2}{=}\mathbf{fun}(\pi,\alpha) \alpha en
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
    get-upd-com = fun( }\pi,\alpha,\mp@subsup{c}{1}{},\mp@subsup{c}{2}{})\quad\mp@subsup{c}{1}{}\mathrm{ end
    get-ass-com}\mp@subsup{1}{1}{}=\mathbf{fun}(\mathrm{ AssUps, U U )
        M = set.new()
        get-ass-com'_}=\mathrm{ gen-ass-com(link }\mp@subsup{1}{1}{}
        M.union(get-ass-com'(AssUps, U2))
        inv-links}\mp@subsup{2}{2}{=gen-inv-links(R, link 2 )
        for }(\pi,\mp@subsup{\alpha}{2}{},v,c)\in\mp@subsup{U}{2}{}\mathrm{ do
            for (\pi,\alpha)\ininv-links}2(\pi,\mp@subsup{\alpha}{2}{})\mathrm{ do
            M.add(\pi,\alpha\uplus[\operatorname{arg}/v], arg,c)
        in
        M.content()
    end
```



```
    remove = gen-remove( }R,\mp@subsup{\mathrm{ remove }}{1}{},\mp@subsup{\mathrm{ remove }}{2}{},\mp@subsup{\mathrm{ link }}{1}{},\mp@subsup{\mathrm{ link }}{2}{}
    add-inst = gen-add-inst(R,add-inst 
    upd-val = gen-upd-val(R,upd-val ( ,upd-val 
        gen-ass-com(link 2), get-ass-com
in (get-val,is-done,remove, add-inst,upd-val)
```

Figure 11.39: A program evaluator for function applications for streams $s$.

```
// Let \(A_{s}^{\prime}\) be a program evaluator for \(E^{\prime} \triangleright V \cup\{x\} \rightarrow \emptyset\)
\(A_{s}=\) let // program evaluator for \(E=\lambda x \cdot E^{\prime} \triangleright V \rightarrow \emptyset\)
    (get-val', is-done \({ }^{\prime}\), remove \({ }^{\prime}\), add-inst \({ }^{\prime}\), upd-val \(\left.{ }^{\prime}\right)=A_{s}^{\prime}\)
    \(R=\) registration.new \(\left(V \cup\{\arg \}, T^{\prime}\right)\)
    link \(=\mathbf{f u n}(\pi, \alpha) \quad \alpha_{\left.\right|_{V}} \uplus[x / \alpha(\arg )]\) end
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    get-upd-com \(=\mathbf{f u n}(\pi, \alpha, c) \quad c\) end
    is-done \(=\mathbf{f u n}(\pi, \alpha)\) is-done \((\pi, \operatorname{link}(\pi, \alpha))\) end
    remove \(=\) gen-remove \(\left(R\right.\), remove \({ }^{\prime}\), link \()\)
    add-inst \(=\) gen-add-inst \((R\), add-inst', link, get-upd-com \()\)
    upd-val \(=\) gen-upd-val( \(R\), upd-val', link, get-upd-com, gen-ass-com(link) \()\)
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.40: Program evaluator for function definitions for streams $s$.

$A_{s}$ only applies the function definition to some argument. The evaluation of the function body by $A_{s}^{\prime}$ therefore computes the required result.

## Variable Bindings.

$$
\frac{E^{\prime} \triangleright V \rightarrow \emptyset \quad E=\left(x=E^{\prime}\right)}{E \triangleright V \rightarrow\{x\}}
$$

Let $A_{s}^{\prime}$ be a program evaluator for $E^{\prime} \triangleright V \rightarrow \emptyset$. We define program evaluator $A_{s}$ for $x=E^{\prime} \triangleright V \rightarrow\{x\}$ in Figure 11.41. Registrations have the following form:


```
// Let }\mp@subsup{A}{s}{\prime}\mathrm{ be a program evaluator for E}\mp@subsup{E}{}{\prime}\trianglerightV->
As}=\mathrm{ let // program evaluator for E = (x= E'})\trianglerightV->{x
    (get-val', is-done', remove}\mp@subsup{}{}{\prime},\mathrm{ add-inst', upd-val')}=\mp@subsup{A}{s}{\prime
    R= registration.new (V\cup{x}, TYPE (E))
    link = fun ( }\pi,\alpha)\quad\mp@subsup{\alpha}{\mp@subsup{|}{V}{}}{}\mathrm{ end
    get-val = fun( }\pi,\alpha)\quadR(\pi,\alpha) en
    get-upd-com = fun (\pi,\alpha,c) if c\not= none ^is-done (\pi,\alpha) then
        instantiate (\alpha(x)=get-val'(}\pi,\operatorname{link}(\pi,\alpha))) else none en
    is-done = fun (\pi,\alpha) is-done' (\pi,\alpha) end
    remove = gen-remove( }R,\mp@subsup{\mathrm{ remove'}}{}{\prime},\mathrm{ link )
    add-inst = gen-add-inst(R, add-inst',link,get-upd-com)
    upd-val = gen-upd-val(R,upd-val',link,get-upd-com,gen-ass-com(link))
in (get-val,is-done, remove, add-inst,upd-val)
```

Figure 11.41: A program evaluator for variable bindings on streams $s$.

Since a boolean is computed by $A_{s}$, one waits until the answer by $A_{s}^{\prime}$ for some linked entry is determined. The get-upd-com function then returns the update of the truth value of whether the answer $v$ by $A_{s}^{\prime}$ is equal to value of $x$ in the variable assignment $\alpha$ of the respective input entry.

Let $A_{s}^{\prime}$ be a program evaluator for $E^{\prime} \triangleright V \rightarrow \emptyset$. We define query evaluator $B_{s}$ for $x=E^{\prime} \triangleright V \rightarrow\{x\}$ in Figure 11.42. Registrations have the following form:


Query evaluator $B_{s}$ must generate the value $v$ for $x$ that $A_{s}$ computes, and must thus return the set that contains the variable assignment of any input entry extended by $[x / v]$. Given some update $c$ to some result value $v$ by $A_{s}$, the get-upd-com function returns an update to the value that is assigned to variable $x$ in the variable assignment of the answer set.

## Set Membership.

$$
\frac{E^{\prime} \triangleright V \rightarrow \emptyset \quad E=\left(x \in E^{\prime}\right)}{E \triangleright V \rightarrow\{x\}}
$$

```
\(/ /\) Let \(A_{s}^{\prime}\) be a program evaluator for \(E^{\prime} \triangleright V \rightarrow \emptyset\)
\(B_{s}=\) let \(/ /\) query evaluator for \(E=\left(x=E^{\prime}\right) \triangleright V \rightarrow\{x\}\)
    (get-val', is-done \({ }^{\prime}\), remove \({ }^{\prime}\), add-inst \({ }^{\prime}\), upd-val \(\left.{ }^{\prime}\right)=A_{s}^{\prime}\)
    \(R=\) registration.new \((V, \operatorname{TYPE}(E))\)
    link \(=\mathbf{f u n}(\pi, \beta) \beta\) end
    get-val \(=\mathbf{f u n}(\pi, \beta) \quad R(\pi, \beta)\) end
    get-upd-com \(=\mathbf{f u n}(\pi, \beta, c)\)
        \(\{v\}=\operatorname{get}-v a l(\pi, \beta)\)
        upd-elem-set \((v\), upd-var-ass \((x, v(x), c)\)
    end
    \(i s\)-done \(=\mathbf{f u n}(\pi, \beta) \quad i s\) - \(\operatorname{done}^{\prime}(\pi, \beta)\) end
    remove \(=\) gen-remove \(\left(R\right.\), remove \(\left.^{\prime}, \operatorname{link}\right)\)
    \(a d d\)-inst \(=\mathbf{f u n}(\pi, \beta)\)
        R.add-inst \((\pi, \beta)\)
        \(c^{\prime}=a d d-\operatorname{inst}(\pi, \operatorname{link}(\pi, \beta))\)
        \(v=\left\{\beta \uplus\left[x / \operatorname{get}-\operatorname{val}^{\prime}(\pi, \operatorname{link}(\pi, \beta))\right]\right\}\)
        R.set-val \((\pi, \beta, v)\)
        in
            extend-set \((v)\)
    end
    upd-val \(=\) gen-upd-val(R,upd-val', link, get-upd-com,gen-ass-com(link) )
in (get-val, is-done, remove, add-inst, upd-val)
```

Figure 11.42: A query evaluator for variable bindings for streams $s$.

Let $A_{s}^{\prime}$ be a program evaluator for $E^{\prime} \triangleright V \rightarrow \emptyset$. We define program evaluator $A_{s}$ for $x \in E^{\prime} \triangleright V \rightarrow\{x\}$ in Figure 11.43. Registration have the following form:


Similar to the program evaluator for variable bindings, the program evaluator $A_{s}$ for the set membership waits until the set $v$ by $A_{s}^{\prime}$ is determined, such that get-upd-com returns the update that instantiates to the respective membership test.

Let $A_{s}^{\prime}$ be a program evaluator for $E^{\prime} \triangleright V \rightarrow \emptyset$. We define query evaluator $B_{s}$ for $x \in E^{\prime} \triangleright V \rightarrow\{x\}$ in Figure 11.44. Registrations have the following form:

```
\(/ /\) Let \(A_{s}^{\prime}\) be a program evaluator for \(E^{\prime} \triangleright V \rightarrow \emptyset\)
\(A_{s}=\) let \(/ /\) program evaluator for \(E=\left(x \in E^{\prime}\right) \triangleright V \rightarrow\{x\}\)
    (get-val', is-done \({ }^{\prime}\), remove \({ }^{\prime}\), add-inst \({ }^{\prime}\), upd-val' \()=A_{s}^{\prime}\)
    \(R=\) registration.new \((V \cup\{x\}, \operatorname{TYPE}(E))\)
    link \(=\) fun \((\pi, \alpha) \quad \alpha_{\left.\right|_{V}}\) end
    get-val \(=\mathbf{f u n}(\pi, \alpha) \quad R(\pi, \alpha)\) end
    get-upd-com \(=\mathbf{f u n}(\pi, \alpha, c) \quad \mathbf{i f} c \neq\) none \(\wedge i s\)-done \((\pi, \alpha)\) then
        instantiate \(\left(\alpha(x) \in\right.\) get-val \(\left.^{\prime}(\pi, \operatorname{link}(\pi, \alpha))\right)\) else none end
    \(i s\)-done \(=\) fun \((\pi, \alpha)\) is-done \({ }^{\prime}(\pi, \alpha)\) end
    remove \(=\) gen-remove \(\left(R\right.\), remove \(^{\prime}\), link \()\)
    add-inst \(=\) gen-add-inst \((R\), add-inst', link, get-upd-com \()\)
    upd-val \(=\) gen-upd-val( \(R\), upd-val', link, get-upd-com,gen-ass-com(link \())\)
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.43: A program evaluator for set membership testing on streams $s$.

| R | $(\pi, \beta)$ | $\frac{{\text { node } \operatorname{ass}_{V}}_{\pi^{\cdots}}}{}$ | $\begin{gathered} 2^{\boldsymbol{\operatorname { a s s }}_{V \cup\{x\}}} \\ v^{\prime \prime} \end{gathered}$ | $\begin{aligned} & \text { upd }\left(v^{\prime \prime}\right) \\ & v^{\prime \prime}=\left\{\beta \uplus\left[x / v^{\prime}\right] \mid v^{\prime} \in v\right\} \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: |
| $R^{\prime}$ |  | $\frac{\text { node }_{\text {ass }}^{V}}{}$ | $\operatorname{Type}\left(E^{\prime}\right)$ <br> $v$ | $\operatorname{upd}(v)$ |

Query evaluator $B_{s}$ must generate all values for $x$ that arise from the set $v$ that $A_{s}^{\prime}$ computes. Given some entry $(\pi, \beta) \in R . \operatorname{dom}()$ and some set $v$ by $A_{s}^{\prime}$ for some linked entry, $B_{s}$ computes the set of variable assignments $\left\{\beta \uplus\left[x / v^{\prime}\right] \mid v^{\prime} \in v\right\}$. The get-upd-com function thus turns an update $c$ to $v$ into a corresponding update for the result by $B_{s}$.

### 11.3 Examples

### 11.3.1 Navigational Queries

In the following we present the evaluation of a forward and a backward query, to show the control of tuple generation and the interaction with registration tables that may select nodes from the past.

A Forward Query. Let $F=c h^{*}\left(a \wedge i s_{x}\right)$ be a forward query of interest with mode $F \triangleright \emptyset \rightarrow\{x\}$ that selects all $a$-descendants. We thus consider

$$
\operatorname{start}(F, z)=c h^{*}\left(i s_{z} \wedge c h^{*}\left(a \wedge i s_{x}\right)\right) .
$$

```
\(/ /\) Let \(A_{s}^{\prime}\) be a, program evaluator for \(E^{\prime} \triangleright V \rightarrow \emptyset\)
\(B_{s}=\) let \(/ /\) query evaluator for \(E=\left(x \in E^{\prime}\right) \triangleright V \rightarrow\{x\}\)
    (get-val', is-done \({ }^{\prime}\), remove \(^{\prime}\), add-inst \({ }^{\prime}\), upd-val \(\left.{ }^{\prime}\right)=A_{s}^{\prime}\)
    \(R=\) registration.new \((V, \operatorname{TYPE}(E))\)
    link \(=\mathbf{f u n}(\pi, \beta) \beta\) end
    get-val \(=\mathbf{f u n}(\pi, \beta) \quad R(\pi, \beta)\) end
    letrec
        get-upd-com =
            fun \((\pi, \beta, c)\)
            case \(c\)
            of none then none
            of \(c_{1} \& c_{2}\) then get-upd-com \(\left(\pi, \beta, c_{1}\right) \& \operatorname{get}-u p d-\operatorname{com}\left(\pi, \beta, c_{2}\right)\)
            of extend-set \((v)\) then extend-set \(\left(\left\{\beta \uplus\left[x / v^{\prime}\right] \mid v^{\prime} \in v\right\}\right)\)
            of upd-elem-set \(\left(e, c^{\prime}\right)\) then upd-elem-set \(\left(\beta \uplus[x / e]\right.\),upd-var-ass \(\left.\left.\left(x, e, c^{\prime}\right)\right)\right\}\)
            of resolve-elem-set \((e, b)\) then resolve-elem-set \((\beta \uplus[x / e], b)\)
        end
    in
    \(i s\)-done \(=\mathbf{f u n}(\pi, \beta) \quad i s\)-done \({ }^{\prime}(\pi, \beta)\) end
    remove \(=\) gen-remove \((R\), remove', link \()\)
    \(a d d-\) inst \(=\) gen-add-inst \((R\), add-inst', link, get-upd-com \()\)
    upd-val \(=\) gen-upd-val( \(R\), upd-val', link, get-upd-com,gen-ass-com(link))
in (get-val,is-done, remove, add-inst, upd-val)
```

Figure 11.44: A query evaluator for set membership testing on streams $s$.

The query contains no backward axes, such that we can directly translate it to an ENwA $A$. The alphabet of $A$ is annotated by subsets of $\mathcal{V}(\operatorname{start}(F, z))=\{z, x\}$, i.e. the variables contained in $\operatorname{start}(F, z)$, and thus we are generating pairs of nodes. Our example in Figure 11.45 evaluates $A$ over a prefix of the linearization of tree $t=a(b(a))$. The registration contains variables $z, x$, and conf for configurations of $A$. We surrounded the second event by a rectangle to indicate that we want to evaluated $F$ at the second node $\pi_{2}$ of the tree. Before evaluation starts, there is an initial entry contained in the registration where $c_{0}$ is the initial configuration of $A$ in an initial state with the empty stack, and for variables $z$ and $x$ there is a $\bullet$ entry, for future nodes. The automaton will try to instantiate future $\bullet$ values by the node of open events, for which it does not reject. However, it may only instantiate the - for variable $z$ if we instruct it to do so, thus at the second event. After reading event ( $o p, \pi_{1}$ ) of the first node $\pi_{1}$, the configuration of the automaton for the begincandidates changes to $c_{1}$, since the stack is updated. The intuitive meaning of a pair ( $v_{1}, v_{2}$ ) of values for variables $z$ and $x$, respectively, with respect to the query, is that $v_{2}$ must be an $a$-descendant of $v_{1}$. At the first event we did not instantiate the $z-\bullet$ value with $\pi_{1}$, since we did not start the evaluation of $F$ at that node, and the automaton could not instantiate the $\bullet$-value for $x$, since a pair $\left(\bullet, \pi_{1}\right)$ would intuitively mean that $\pi_{1}$ is an $a$-descendant of some future node, which is forbidden according to the automaton. At the next event $\left(o p, \pi_{2}\right)$ we want to evaluate $F$, and thus instruct the automaton to instantiate node $\pi_{2}$ for variable $z$. At the next event


Figure 11.45: Content of the registration table for the evaluation of query $c h^{*}\left(i s_{z} \wedge\right.$ $\left.c h^{*}\left(a \wedge i s_{x}\right)\right)$ over the linearization of tree $a(b(a))$ until event $\langle/ b\rangle$.
$\left(o p, \pi_{3}\right)$ the automaton instantiates the $x-\bullet$ value of pair $\left(\pi_{2}, \bullet\right)$ with $\pi_{3}$ and moves into a selecting configuration $c_{6}$ with a selection state. Pair $\left(\pi_{2}, \pi_{3}\right)$ is an answer: node $\pi_{3}$ is an $a$-descendant of node $\pi_{2}$. At event $\left(c l, \pi_{2}\right)$ where we close node $\pi_{2}$, notice that the automaton removes pair $\left(\pi_{2}, \bullet\right)$ : indeed it is not possible that node $\pi_{2}$ finds further $a$-descendants.

A Backward Query. Queries that contain backward axes are evaluated just as similar. Consider query $F=\operatorname{par}^{+}\left(i s_{x}\right)$ with mode $F \triangleright \rightarrow\{x\}$ that selects all ancestors $x$ of a given start node. Backward axes are eliminated in $\operatorname{start}(F, z)=$ $c h^{*}\left(i s_{z} \wedge \operatorname{par}^{+}\left(i s_{x}\right)\right)$. The backward axes free query is

$$
i s_{x} \wedge c h^{+}\left(i s_{z}\right) \vee c h^{+}\left(i s_{x} \wedge c h^{+}\left(i s_{z}\right)\right)
$$

which translates to some ENwA. The evaluation of this query over the same tree $t=$ $a(b(a))$ as before is shown in Figure 11.46. There at the first event the registration contains the pair $\left(\bullet, \pi_{1}\right)$, which means that node $\pi_{1}$ is an ancestor of any future node to come. In general, our algorithm pre-computes all nodes selected by some query that may contain backward axes when started at future nodes. Also notice, that we precompute only those nodes that are candidates according to our ENwA: The speculative computation therefore correlates to the earliest-ness of our automaton. Finishing with the example, one sees at the next event $\left(o p, \pi_{2}\right)$ that node $\pi_{2}$ is another ancestor of future nodes, and also since we instructed an evaluation of the query at this node, we instantiated the $\bullet$ in pair $\left(\bullet, \pi_{1}\right)$ with node $\pi_{2}$ and obtain an answer pair $\left(\pi_{2}, \pi_{1}\right)$ that is stored: Node $\pi_{2}$ has node $\pi_{1}$ as ancestor.

### 11.3.2 A Network of Queries

We consider query

$$
F=\left\{x \mid \operatorname{par}^{+}\left(i s_{x}\right) \wedge l a b_{\text {name }}(x)=" \mathrm{a} "\right\}
$$

that may be evaluated relatively to some node $\pi$. It returns the set of $a$-ancestor nodes of $\pi$. In particular, we are interested in subformula

$$
\operatorname{lab}_{\text {name }}(x)=" \mathrm{a} "
$$

|  | $\langle a\rangle:\left(o p, \pi_{1}\right)$ | $\langle b\rangle:\left(o p, \pi_{2}\right)$ | $\langle a\rangle:\left(o p, \pi_{3}\right)$ | $\langle/ a\rangle:\left(c l, \pi_{3}\right)$ | $\langle/ b\rangle:\left(c l, \pi_{2}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $z x$ conf | $z x$ conf | $z x$ conf | $z x$ conf | $z x$ conf | $z x$ conf |
| - - $c_{0}$ | - - $c_{1}$ | - - $c_{3}$ | - - $c_{7}$ | - - $c_{12}$ | - - $c_{16}$ |
|  | - $\pi_{1} \quad c_{2}$ | - $\pi_{1} \quad c_{4}$ | - $\pi_{1} \quad c_{8}$ | - $\pi_{1} c_{13}$ | - $\pi_{1} c_{17}$ |
|  |  | - $\pi_{2} \quad c_{5}$ | - $\pi_{2} \quad c_{9}$ | - $\pi_{2} \quad c_{14}$ | $\pi_{2} \pi_{1} c_{18}$ |
|  |  | $\pi_{2} \pi_{1} \quad c_{6}$ | - $\pi_{3} \quad c_{10}$ | $\pi_{2} \pi_{1} c_{15}$ |  |
|  |  |  | $\pi_{2} \pi_{1} c_{11}$ |  |  |

Figure 11.46: Content of the registration table for the evaluation of query $c h^{*}\left(i s_{z} \wedge\right.$ $\operatorname{par}^{+}\left(i s_{x}\right)$ ) over the linearization of tree $a(b(a))$ until event $\langle/ b\rangle$.
of $F$ that has one free variable $x$, whose value may be a node that comes before a node for which the query is evaluated. We give in Figure 11.47 a decomposition of $F$ and display the contents of registration table for program and query evaluators in the network that evaluate the query. We evaluate $F$ on the linearization of tree $a(b(a(c)))$, while on the left in the figure we showcase the buffers after event $\left(o p, \pi_{3}\right)$ has arrived (indicated by an arrow pointing to the node in the tree in the upper left corner of the figure), while on the right in the figure we showcase buffers after processing event $\left(o p, \pi_{4}\right)$ at which we start an evaluation. At event ( $o p, \pi_{3}$ ), notice, similar to as we seen before, that the registration $R_{2}$ for par $^{+}\left(i s_{x}\right)$ finds ancestors $\pi_{1}, \pi_{2}$, and $\pi_{3}$ for any future node to come. The registration $R_{1}$ for the conjunction according to the mode system instruct for every tuple $\tau \in R_{2}$ an evaluation of the algorithm for query $l a b_{\text {name }}(x)=$ "a" as we see in registration $R_{3}$. The label test, however, is satisfied for nodes $\pi_{1}$ and $\pi_{3}$ only, for which only those corresponding tuples remain in $R_{3}$. The algorithm for the conjunction combines the answers and synchronizes the tuples of $R_{3}$ with its registration table $R_{1}$. The algorithm that computes the set of all $x$ such that the conjunction holds, now has precomputed the open set of nodes $\pi_{1}$ and $\pi_{3}$ as an answer for any future node. At the next event, in the figure on the right, one instructs an evaluation at node $\pi_{4}$, for which • values for variable $z$ are instantiated by $\pi_{4}$. One observes that in registration table $R_{3}$ there is an entry ( $\pi_{4},\left[x / \pi_{1}\right]$ ) and an entry $\left(\pi_{4},\left[x / \pi_{3}\right]\right)$ of a start node $\pi_{4}$ with values for variable $x$ from the past. However, since we pre-computed the answers of the label test for past nodes, the answer is already computed, and one just takes it over, but leaves entries $\left(\bullet,\left[x / \pi_{1}\right]\right)$ and $\left(\bullet,\left[x / \pi_{3}\right]\right)$ within the registration table, for further future nodes.

### 11.4 Tuple Sharing

Tuple sharing lifts the stack-and-state sharing algorithm of Section 8.6.3 to tuple sharing in networks of early nested word automata. The need for tuple sharing arises when the number of candidates grows linearly with the size of the document. For example, XPath query //a/fn:data(following: :b) that computes for every


Figure 11.47: A network.
a -descendant the typed value of all following b -nodes. On a document whose root contains a list of a-children followed by a list of b-children, without tuple sharing, the typed value for every b-node will be computed, but this for every buffered a-node.

The idea is that when the automaton evaluator with stack-and-state sharing reaches for several candidates the same state and the same stack representative (of which there are no more than states as shown by Proposition 9), then these candidates can be shared in the tables, so that the work for them will be shared from that event on. This happens in the above example, where for every a-node there is an entry in the registration table that computes subquery following: :b, all of which have the same configuration. At the arrival of the first b-node, the registration that computes the typed value of the b-node only does it once thanks

```
FJ: //people/person[not(@id = following::bidder/personref/@person)]
BJ: //open_auction
    [not(@id = preceding::people/person/watches/watch/@open_auction)]
AFJ: //people/person[not(@id = //bidder/personref/@person)]
ABJ: //open_auction[not(@id = //people/person/watches/watch/@open_auction)]
```

Figure 11.48: Additional data comparison queries.


Figure 11.49: Parsing-free time of $\lambda$ XP for the queries of Figure 11.48.
to tuple sharing, instead of computing the same result for every a-node.

### 11.5 Experiments

The design of the $\lambda \mathrm{XP}$ language is ahead of our current implementation in our QuiXPath tool. QuiXPath however implements besides navigational XPath, a large subset of the XPath functions, arithmetic, aggregation, and data comparisons in streaming. This implementation is based on the semantics and data model of XPath 1.0 and supports practically all XPath 1.0 expressions. The implementation enjoys linear runtime behavior for most aggregation and data comparison queries, thanks to tuple sharing.

In Figure 11.49 we showcase that QuiXPath runs indeed linearly for a collection of data comparison queries, that we list in Figure 11.48. They perform joins with forward and backward axes both with relative and absolute subqueries. There list of tables of data values grow largely over the stream of XPathMark documents, in contrast to the data comparison queries of the benchmark in Section A.3. A second experiment for the aggregation queries of Section A. 4 of the XPathMark benchmark is done in Figure 11.50 scaling documents in size.


Figure 11.50: Parsing-free time of $\lambda \mathrm{XP}$ for aggregation queries of Section A.4.

## Chapter 12

## Conclusion and Outlook

In this thesis, we have developed streaming algorithms for XPATH with high time efficiency, low latency, low memory consumption, and large coverage.

The core of our algorithms maps navigational XPATH queries to early nested word automata. The first idea here was to approximate earliest query answering by introducing selection and rejection states during the compilation, in order to avoid the need to decide accessibility problems for nested word automata. The second idea was to introduce a stack-and-state sharing algorithm. This was essential to avoid quadratic or higher blow-ups in the processing time for documents, in cases where the number of candidates is large. Rather than depending on the number of candidates, the time for processing a single event is reduced to depend only on the number states of the ENwA. We improved these algorithms further in time efficiency by developing projection algorithms for early nested word automata that permit to project large parts of the XmL streams away that the automata thereby does not have to process. We therefore obtained a streaming algorithm for answering navigational XPATH queries with close to optimal low latency and memory consumption, whose implementation outperforms all other available tools in time efficiency.

Next, we worked on finding streaming algorithms that answer to general XPATH 3.0 queries. For this purpose, we proposed $\lambda \mathrm{XP}$, a typed first-order logical language with higher order functions based on first principles for querying data trees. We then show that it is sufficiently expressive to capture all of XPATH 3.0 by presenting a compiler from XPATH 3.0 to $\lambda$ XP. This compiler provides a formal semantics to XPath 3.0 - for the first time to the best of our knowledge - i.e., it formalizes the W3C standard for XPath 3.0. We then propose a restriction of $\lambda \mathrm{XP}$ that is accessible to streaming. The problem is to avoid exhaustive speculative computation. For instance, one might want to rule out cases, where some navigational queries are computed dynamically from the input document, and then applied to the same input document. Furthermore, exhaustive speculative computation bears the risk of running incorrectly into nontermination, when wrongly speculating that the result of a computation may be needed which is nonterminating. Finally, we developed streaming algorithms for $\lambda \mathrm{XP}$ queries that are accessible to streaming. Our idea was to decompose general queries into network of simpler subqueries, so that our streaming algorithms for navigational subqueries can be lifted to the general case. To this purpose we proposed to decompose general queries into networks of registrations with ENWAs. In order to avoid quadratic or higher blow-ups on the
network level, we propose to lift the stack-and-state sharing algorithm on the level of ENWAs to a tuple sharing algorithm on the level of registration networks. We implemented our algorithm to a large extend, and show that it covers very large fragments of XPATH 3.0 in streaming mode. While mild extensions are still possible, it does not seem reasonable to us to try to process non-streaming-accessible queries of XPath 3.0 in streaming mode.

In the following, we envisage to complete our implementation of the presented streaming algorithms for the supported fragment of $\lambda \mathrm{XP}$. Then, they can serve as a streaming XPath motor for streaming implementations of Xslt, XQuery, and finally XProc. In [Labath 2015] the authors proposed a uniform programming language, similar to that of $\lambda \mathrm{XP}$, that allows to implement the W3C standards. This language extends on $\lambda \mathrm{XP}$ by facilities to create and process data trees on the fly as one requires for transformation languages like XsLT and XQUERY.

For the future, it will be relevant to develop streaming algorithms for NoSQL databases. These rely on the Json format, whose data trees are then linearized to complex Json events. The challenge is to find streaming algorithms that can be combined with the algorithms of classical databases and that run in distributed settings and may thereby profit from parallelism.

## Appendix A

## XPathMark Benchmark

## Contents

A. 1 Downward Queries ..... 253
A. 2 Axis Queries ..... 254
A. 3 Comparison Queries ..... 254
A. 4 Aggregation Queries ..... 255
A. 5 Position Queries ..... 255
A. 6 Closure Queries ..... 256

A common XPath benchmark is the XPathMark benchmark ${ }^{1}$ which is the revised version in contrast to the benchmark of the original paper [Franceschet 2005]. It contains queries about XMARK documents that contain a table of bids and a table of bidders. Some of the queries are parameterized by an integer $i \geq 1$, so that these queries can be scaled in size. Notice that the XPathMark bechmark was designed to test XPATh 1.0 queries only, which are valid XPath 3.0 queries however. We state all of the queries of the benchmark, while we do not test against all of the queries in our experiments.

## A. 1 Downward Queries

Downward queries use forward axes child and descendant, path compositions, and filters.

```
A1: /site/closed_auctions/closed_auction/annotation/description/text
    /keyword
A2: //closed_auction//keyword
A3: /site/closed_auctions/closed_auction//keyword
A4:/site/closed_auctions/closed_auction
    [annotation/description/text/keyword]/date
A5:/site/closed_auctions/closed_auction[descendant::keyword]/date
A6:/site/people/person[profile/gender and profile/age]/name
A7: /site/people/person[phone or homepage]/name
A8: /site/people/person
    [address and (phone or homepage) and (creditcard or profile)]
    /name
```

[^20]
## A. 2 Axis Queries

The axis queries in the benchmark use in addition to the downward axes, also backward axes, attribute axes and other forward axes. Some of the queries are parametric.

B1: /site/regions/*/item[parent::namerica or parent::samerica] /name
B2: //keyword/ancestor::listitem/text/keyword
B3: /site/open_auctions/open_auction/bidder [following-sibling::bidder]
B4: /site/open_auctions/open_auction/bidder
[preceding-sibling::bidder]
/site/regions/*/item[following::item]/name
B5: /site/regions/*/item[following::item]/name
B7: //person[profile/@income]/name
B8: /site/open_auctions/open_auction
[bidder and not(bidder/preceding-sibling::bidder)]/interval
B9: /site/open_auctions/open_auction
[(not(bidder/following::bidder) or
not(bidder/preceding::bidder)) or
(bidder/following::bidder and bidder/preceding::bidder)]
/interval
B10: /site/open_auctions/open_auction
[(not(bidder/following::bidder) or
not(bidder/preceding::bidder)) and
(bidder/following::bidder and bidder/preceding::bidder)]
/interval
B11(i): //open_auction(/bidder/. . $)^{i} /$ interval
B12(i): //item(/@id/..) ${ }^{i} /$ name
B13(i): //keyword(/ancestor::parlist/descendant::keyword) ${ }^{i}$
B14(i): //bidder
(/following-sibling::bidder/preceding-sibling::bidder) ${ }^{i}$
B15(i)://keyword(/following::keyword/preceding::keyword) ${ }^{i}$

## A. 3 Comparison Queries

The queries in this section perform data comparisons, some of which use the id function, that return all element nodes with an ID value that matche the values of the argument to the id function.

```
C1: /site/people/person
    [profile/age >= 18 and profile/@income < 10000
```

```
    and address/city != "Dallas"]/name
C2: /site/open_auctions/open_auction[bidder/increase = current]
    /interval
C3: /site/people/person
    [profile/@income = /site/open_auctions/open_auction/current]
    /name
C4: /site/people/person
    [watches/watch/id(@open_auction)/seller/@person = @id]/name
C5: id("person0")/name
C6: /site/people/person/watches/watch/id(@open_auction)/interval
C7: /site/people/person[watches/watch/id(@open_auction)/itemref
    /id(@item)/parent::australian]/name
C8(i): Y(i)/id(.)/name
    where Y(1) = /site/catgraph/edge[@from = "category0"]/@to
        Y(i) = /site/catgraph/edge[@from = Y(i-1)]/@to for i\geq2
C9(i): /site/open_auctions/open_auction
    (/seller/id(@person)/watches/watch/id(@open_auction))i/interval
C10(i):/site/people/person
    (/watches/watch/id(@open_auction)/bidder/personref
    /id(@person))}\mp@subsup{}{}{i}/nam
```


## A. 4 Aggregation Queries

Aggregation queries perform arithmetic operations and count and sum up values.
D1: /site/open_auctions/open_auction[(count(bidder) mod 2) = 0] /interval
D2: count(//text) + count(//bold) + count(//emph) + count(//keyword)
D3: /site/open_auctions/open_auction [sum(bidder/increase) > 10 * initial]/interval
D4: /site/open_auctions/open_auction
[sum(bidder/increase) != (current - initial)]/interval
D5: /site/open_auctions/open_auction
[bidder and
(sum(bidder/increase) div count(bidder)) > 2 * initial]/interval

## A. 5 Position Queries

Position queries use positions, see Section 5.3.
E1: site/open_auctions/open_auction
[bidder[1]/number(increase) < bidder[floor((last() + 1) div 2)]
/number(increase) and bidder[floor((last() + 1) div 2)]
/number(increase) < bidder[last()]/number(increase)]/interval

E2: /site/regions/europe/item/description/descendant::keyword[last()]
E3: //keyword/ancestor: :listitem[1]/text/keyword
E4: site/open_auctions/open_auction/bidder
[preceding-sibling: :bidder[1]/number(increase)
<= number (increase) and number (increase)
<= following-sibling::bidder[1]/number(increase)]
E5: /site/regions/*/item
[preceding::item[100] and following::item[100]]/name
E6: /site/regions/*/item[contains(description, name)]/name
E7: /site/regions/*/item
[contains(substring-before(description, "eros"), "passion") and contains(substring-after(description, "eros"), "dangerous")]
/name
E8: /site/regions/*/item
[string-length(translate(normalize-space(description)," ","")) > 10000]/name

## A. 6 Closure Queries

Closure queries perform the closure from nodes in \$input and XPATH query following-sibling: : bidder [position()=1 and number(increase) <= 10] according to the function closure below, where

```
Bigger \(={ }_{\mathrm{df}}\)
    following-sibling::bidder[position()=1 and number(increase) > 10]
```


## Smaller $={ }_{\text {df }}$

    following-sibling::bidder[position()=1 and number(increase) <= 10]
    and

```
closure = }\mp@subsup{}{\textrm{df}}{
function closure($input as node()*, $result as node()*) as node()*
{
    let $current := $input/following-sibling::bidder
                                    [position()=1 and number(increase) <= 10]
    let $new := $current except $result
    let $all := ($result,$new)
    return
            if(exists($new))
            then ($new, closure($new,$all))
            else ()
}
```

F1: //bidder
[number(increase) <= 10 and (Bigger or closure(.,Smaller)/Bigger)]
F2: //bidder
[number(increase) <= 10 and (Bigger or closure(.,Smaller)/Bigger)]
F3: //listitem[text/keyword or
closure(., parlist/listitem/parlist/listitem)/text/keyword] /text/keyword
F4: /site/open_auctions/open_auction[position() <= 5] /closure(.,seller/id(@person)/watches/watch/id(@open_auction)) /interval
F5: /site/people/person[position() <= 5]/closure(.,/watches/watch /id(@open_auction)/bidder/personref/id(@person))/name
F6: /site/people/person[1]/idref(@id)/..
F7: //category[@id="category0"]/@id
/closure (.,let \$i = . return (\$i | //edge[@from = \$i]/@to)) /id(.)/name
F8: //category[@id="category0"]/@id
/closure(.,idref(.)[name() = "from"]/../@to)/id(.)/name

Appendix B XPath to $\lambda$ XP Compiler

## Contents

B. 1 Basic Expressions ..... 261
B.1.1 XPath expressions ..... 261
B.1.2 Nonterminals to define inline function expressions ..... 261
B.1.3 Sequence constructions ..... 261
B.1.4 Single expressions ..... 261
B.1.5 Sequence decompositions ..... 261
B.1.6 Let expressions ..... 262
B.1.7 Quantified expressions ..... 262
B.1.8 First-Order expressions ..... 263
B.1.9 Comparisons ..... 264
B.1.10 Concatenation of strings ..... 266
B.1.11 Range expressions ..... 267
B.1.12 Arithmetic Expressions ..... 267
B.1.13 Ordered Sets ..... 268
B.1.14 Type checks and casts ..... 269
B.1.15 Unary Expressions ..... 270
B.1.16 Value expressions ..... 270
B.1.17 Comparison operators ..... 271
B.1.18 Simple Map expressions ..... 271
B. 2 Navigational Expressions ..... 272
B.2.1 Absolute path expressions ..... 272
B.2.2 Relative path expressions ..... 272
B.2.3 Steps ..... 272
B.2.4 Axis steps and Filters ..... 273
B.2.5 Axis Steps ..... 274
B.2.6 Node Tests, Name Tests, and Wildcards ..... 275
B. 3 Postfix expressions ..... 276
B.3.1 Postfix expressions ..... 276
B.3.2 Argument Lists and Predicates ..... 276
B.3.3 Primary expressions ..... 276
B.3.4 Literals ..... 276
B.3.5 Variables ..... 277
B.3.6 Parenthesized expressions and the empty list ..... 277
B.3.7 Context Item, Position, and Size ..... 277
B.3.8 Function Calls ..... 277
B.3.9 Functions ..... 278
B.3.10 Simple Types ..... 279
B. 4 Sequence Type Expressions ..... 279
B.4.1 Top level Sequence Type Matching ..... 279
B.4.2 Item types ..... 280
B.4.3 Atomic and union types ..... 280
B.4.4 Kind Tests ..... 280
B.4.5 Node and Type Names ..... 283
B.4.6 Function Tests ..... 284
B.4.7 EQNames ..... 284
B. 5 Terminal Expressions ..... 284

We translate XPath 3.0 queries to $\lambda$ XP expressions along its grammar in Ebnf given in Section 5.1 for basic, navigational, postfix, and terminal expressions, and for sequence types whose production rules are given in Section 4.1.
$\triangle$ The following translations were done to the best of our understanding of the informally described XPath 3.0 specification ${ }^{1}$.

The translation follows the specification where the XPATH 1.0 compatibility mode is set to false, and where its type system is based on Xml Schema 1.0. Notice that we can also translate XPath 3.0 expressions where the XPath 1.0 compatibility mode is set to true, which then implements different specifications. We use some constant mode which is equal to the sort function sort if the ordering mode of XQuery is set to ordered, while it is the identity function $i d$, when the ordering mode is set to unordered:

$$
\text { mode }= \begin{cases}\text { sort } & , \text { ordering mode of XQuery is ordered } \\ \text { id } & \text {, ordering mode of XQUERY is unordered }\end{cases}
$$

We assume that XPath expressions are not abbreviated, i.e. we only translate the unabbreviated XPath syntax. Notice that we raise an error for expressions that depend on the unsupported namespace axis (see the Xml data model in Section 2.3.1).

[^21]
## B. 1 Basic Expressions

## B.1.1 XPath expressions

Nonterminal XPath expands to nonterminal Expr.
(1) $\llbracket \mathrm{XPath}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$
$\llbracket \operatorname{Expr}(P) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

## B.1.2 Nonterminals to define inline function expressions

The next four nonterminals in the grammar are used to define function declarations by expressions InlineFunctionExpr (64), and thus translated as a whole there.
(2) ParamList : := Param (", " Param)*
(3) Param ::= "\$" EQName TypeDeclaration?
(4) FunctionBody ::= EnclosedExpr
(5) EnclosedExpr ::= "\{" Expr "\}"

## B.1.3 Sequence constructions

(6) $\llbracket \operatorname{Expr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
[ExprSingle (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
Sequences in XPATH are constructed using the comma seperator and they are flattened according to Section 4.3 for which we append the result lists.

$$
\begin{aligned}
& \llbracket \operatorname{Expr}\left(\mathrm{P}_{1}, \ldots, \mathrm{P}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\frac{n \geq 2}{\mathrm{df}} \\
& \quad \text { listconcat }\left(\llbracket \operatorname{ExprSingle}\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}, \ldots, \llbracket \operatorname{ExprSingle}\left(\mathrm{P}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)
\end{aligned}
$$

## B.1.4 Single expressions

There exist various single expressions.
(7) $\llbracket \operatorname{ExprSingle}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$

$$
\begin{cases}\llbracket \text { ForExpr }(\mathrm{P}) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z} & \mathrm{P} \in \text { ForExpr } \\ \llbracket \operatorname{LetExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \operatorname{LetExpr} \\ \llbracket \text { QuantifiedExpr }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { QuantifiedExpr } \\ \llbracket \operatorname{IfExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \operatorname{IfExpr} \\ \llbracket \operatorname{OrExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \operatorname{OrExpr}\end{cases}
$$

## B.1.5 Sequence decompositions

For expressions using multiple variables are first expanded to a set of nested for expressions:

```
ForExpr(for $VarName(y ( ) in ExprSingle( }\mp@subsup{P}{1}{}\mathrm{ ),...,
    $VarName(y }\mp@subsup{y}{n}{}\mathrm{ ) in ExprSingle(P}\mp@subsup{\textrm{P}}{n}{}) return ExprSingle(P))
=ForExpr(for $VarName(y ( ) in ExprSingle(P
    for $VarName( }\mp@subsup{\textrm{y}}{n}{}\mathrm{ ) in ExprSingle( (P}n) return ExprSingle(P))
single-variable for expressions concatenate sequences by the return expression P' in
```

the order of the items in the binding sequence $P$ :
(8) 『ForExpr (for \$VarName (y) in ExprSingle (P)

```
                                    return ExprSingle( \(\left.\left.\mathrm{P}^{\prime}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
```

listconcat
(map $\left.\left.\left(\lambda \llbracket \operatorname{VarName}(\mathrm{y}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z} \cdot \llbracket \operatorname{ExprSingle}(\mathrm{P}}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \llbracket \operatorname{ExprSingle}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$
The following two nonterminals are used to define for expressions ForExpr, translated above.
(9) SimpleForClause : := "for" SimpleForBinding (", " SimpleForBinding)*
(10) SimpleForBinding ::= "\$" VarName "in" ExprSingle

## B.1.6 Let expressions

Similar to for expression, also let expressions using multiple variables are first expanded to a set of nested let expressions:

```
LetExpr(let $VarName(y1) := ExprSingle(P
    $VarName(y }\mp@subsup{y}{n}{}\mathrm{ ) := ExprSingle( }\mp@subsup{\textrm{P}}{n}{}\mathrm{ ) return ExprSingle(P))
=LetExpr(let $VarName(y1) := ExprSingle(P}\mp@subsup{\textrm{P}}{1}{})\mathrm{ return ...
    let $VarName(y }\mp@subsup{\textrm{y}}{n}{}\mathrm{ ) := ExprSingle(P}\mp@subsup{\textrm{P}}{n}{})\mathrm{ return ExprSingle(P))
variable let expressions translate to let definitions in \lambdaXP:
(11) \llbracketLetExpr(let $VarName(y):= ExprSingle(P)
                            return ExprSingle(P'))}\mp@subsup{|}{\overline{z},\hat{z},\tilde{z}}{}=\mp@subsup{}{\textrm{df}}{
    let \llbracketVarName(y)}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{}=\llbracket\operatorname{ExprSingle(P)}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{}\mathrm{ in }\llbracket\operatorname{ExprSingle(P')}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{
```

The following two nonterminals are used to define let expressions LetExpr, translated above.
(12) SimpleLetClause : := "let" SinleLetBinding (", " SimpleLetBinding)*
(13) SimpleLetBinding ::= "\$" VarName ":=" ExprSingle

## B.1.7 Quantified expressions

Quantified expressions that we mentioned briefly in Section 5.2.2 can bind several variables in general. Expression $P$ below that follows the satisfies keyword may be tested for any such variable binding from variables $\mathrm{y}_{i}$ to items of sequences $\mathrm{P}_{i}$. The translation to $\lambda \mathrm{XP}$ expressions is therefore a little tedious. It obtains $n$ lists of elements from expressions $\mathrm{P}_{i}$, which must be decomposed, such that all needed variable bindings are obtained. This requires to re-iterate through certain lists in general, which is done by the functions in the following translations. When function $f_{i}$ will be called, variables $\mathrm{y}_{1}$ until $\mathrm{y}_{i-1}$ have been bound by previous calls to functions $f_{j}$ for $j<i$ via the let definition for those variables. Function $f_{i}$ then iterates through the list by $\mathrm{P}_{i}$ while binding variable $\mathrm{y}_{i}$ and which evaluates $f_{i+1}$ if $i<n$, or if $i=n$ it evaluates P , since all appearing variables are bound. When one of these evaluations return true, the function returns true and stops the iteration.
(14) 【QuantifiedExpr (some
\$VarName ( $\mathrm{y}_{1}$ ) in ExprSingle $\left(\mathrm{P}_{1}\right)$, ...,
$\$ \operatorname{VarName}\left(\mathrm{y}_{n}\right)$ in ExprSingle $\left(\mathrm{P}_{n}\right)$ satisfies ExprSingle $\left.(\mathrm{P})\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
let $f_{n}=\lambda z_{n}$. match $z_{n}$ with $x:: y$ then
let $\llbracket \operatorname{VarName}\left(\mathrm{y}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=x$ in
if $\llbracket \mathrm{fn}$ : boolean $\rrbracket\left(\llbracket\right.$ ExprSingle $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z})}$ then true else $f_{n}(y)$ else false
in let $f_{n-1}=\lambda\left(z_{n-1}, z_{n}\right)$.match $z_{n-1}$ with $x:: y$ then
let $\llbracket \operatorname{VarName}\left(\mathrm{y}_{n-1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=x$ in
if $f_{n}\left(z_{n}\right)$ then true else $f_{n-1}\left(y, z_{n}\right)$
else false
in ...
in let $f_{1}=\lambda\left(z_{1}, \ldots, z_{n}\right)$.match $z_{1}$ with $x:: y$ then
let $\llbracket \operatorname{VarName}\left(\mathrm{y}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=x$ in
if $f_{2}\left(z_{2}, \ldots, z_{n}\right)$ then true else $f_{1}\left(y, z_{2}, \ldots, z_{n}\right)$
else false
in $f_{1}\left(\llbracket \operatorname{ExprSingle}\left(\mathrm{P}_{1}\right), \ldots\right.$, ExprSingle $\left.\left.\left(\mathrm{P}_{n}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$
In contrast to test for the existence of a variable binding for which expressions P becomes true as above, the quantification with keyword every tests whether P becomes true for all variables bindings:

## 【QuantifiedExpr (every

$\$ \operatorname{VarName}\left(\mathrm{y}_{1}\right)$ in ExprSingle $\left(\mathrm{P}_{1}\right)$, ...,
$\$ \operatorname{VarName}\left(\mathrm{y}_{n}\right)$ in ExprSingle $\left(\mathrm{P}_{n}\right)$ satisfies ExprSingle $\left.(\mathrm{P})\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$ let $f_{n}=\lambda z_{n}$. match $z_{n}$ with $x:: y$ then
let $\llbracket \operatorname{VarName}\left(\mathrm{y}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=x$ in
if $\llbracket$ fn: boolean $\rrbracket\left(\llbracket\right.$ ExprSingle $\left.(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$ then $f_{n}(y)$ else false else true
in let $f_{n-1}=\lambda\left(z_{n-1}, z_{n}\right)$. match $z_{n-1}$ with $x:: y$ then
let $\llbracket \operatorname{VarName}\left(\mathrm{y}_{n-1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=x$ in
if $f_{n}\left(z_{n}\right)$ then $f_{n-1}\left(y, z_{n}\right)$ else false
else true
in ...
in let $f_{1}=\lambda\left(z_{1}, \ldots, z_{n}\right)$.match $z_{1}$ with $x:: y$ then
let $\llbracket \operatorname{VarName}\left(\mathrm{y}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=x$ in
if $f_{2}\left(z_{2}, \ldots, z_{n}\right)$ then $f_{1}\left(y, z_{2}, \ldots, z_{n}\right)$ else false
else true
in $f_{1}\left(\llbracket \operatorname{ExprSingle}\left(\mathrm{P}_{1}\right), \ldots\right.$, ExprSingle $\left.\left.\left(\mathrm{P}_{n}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$

## B.1.8 First-Order expressions

Conditionals, disjunctions, and conjunctions of XPATH are translated to conditionals, disjunctions, and conjunctions in $\lambda \mathrm{XP}$, respectively.
(15) $\llbracket I f E x p r(i f(E x p r(P))$ then ExprSingle(P')

$$
\text { else ExprSingle } \left.\left(\mathrm{P}^{\prime}{ }^{\prime}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}
$$

if $\llbracket \mathrm{fn}$ : boolean $\rrbracket\left(\llbracket \operatorname{Expr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z})}\right.$
then $\llbracket \operatorname{ExprSingle}\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ else $\left.\llbracket \operatorname{ExprSingle}\left(\mathrm{P}^{\prime}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
(16) $\llbracket \operatorname{OrExpr}(\operatorname{AndExpr}(\mathrm{P})) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$ $\llbracket \operatorname{AndExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket \operatorname{OrExpr}\left(\operatorname{AndExpr}\left(\mathrm{P}_{1}\right)\right.$ or $\ldots$ or $\left.\operatorname{AndExpr}\left(\mathrm{P}_{n}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{d \mathrm{f}}^{n \geq 2}$
$\llbracket \mathrm{fn}$ : boolean $\rrbracket\left(\llbracket \operatorname{AndExpr}\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \vee \ldots \vee \llbracket \mathrm{fn}$ : boolean $\rrbracket\left(\llbracket \operatorname{AndExpr}\left(\mathrm{P}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$
(17) $\llbracket \operatorname{AndExpr}$ (ComparisonExpr (P)) $\rrbracket_{\bar{z}}, \hat{z}, \tilde{z}={ }_{\mathrm{df}}$

【ComparisonExpr (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket \operatorname{AndExpr}$ (ComparisonExpr $\left(\mathrm{P}_{1}\right)$ and $\ldots$ and ComparisonExpr $\left.\left(\mathrm{P}_{n}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{d} f}^{n \geq 2}$ $\llbracket \mathrm{fn}$ : boolean $\rrbracket\left(\llbracket\right.$ ComparisonExpr $\left.\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$
$\wedge \ldots \wedge \llbracket \mathrm{fn}$ : boolean $\rrbracket\left(\llbracket\right.$ ComparisonExpr $\left.\left(\mathrm{P}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$

## B.1.9 Comparisons

Comparison expressions may expand to string concatenation expressions.
(18) $\llbracket$ ComparisonExpr ( P ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$

【StringConcatExpr (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

Otherwise we translate comparison expression to $\lambda$ XP expressions as follows. It spells out the details of the XPath 3.0 specifications, whose essence we described in Section 5.6. The translation assumes a function lct that computes the least common type of two types in XPATH. It also assumes a function validComb that tests whether the transformed operands are of valid type with respect to the operator according to the specification ${ }^{2}$.

[^22]```
【ComparisonExpr (
StringConcatExpr(P) ValueComp(vc) StringConcatExpr(P')) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let right \(=\llbracket \mathrm{fn}:\) data \(\rrbracket\left(\llbracket\right.\) StringConcatExpr \(\left.\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\) in
    match \(\llbracket \mathrm{fn}:\) data \(\rrbracket\left(\llbracket\right.\) StringConcatExpr \(\left.(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{\tilde{z}}}\right)\) with \(x_{1}:: y_{1}\) then
        if right \(=\) nil then nil else
            if \(y_{1}=n i l\) then
                match right with \(x_{2}:: y_{2}\) then
                    if \(y_{2}=\) nil then
                            let \(x_{1}^{\prime}=\) if type \({\operatorname{TYPE}\left(x_{1}\right), \text { xs:untypedAtomic }}\left(x_{1}\right)\)
                            then \(\operatorname{cast}_{\mathrm{xs}: \text { untypedAtomic,string }}\left(x_{1}\right)\) else \(x_{1}\) in
                            let \(x_{2}^{\prime}=\) if type \(e_{\text {TYPE }\left(x_{2}\right), \text { xs:untypedAtomic }}\left(x_{2}\right)\)
                            then cast \(_{\text {xs:untypedAtomic,string }}\left(x_{2}\right)\) else \(x_{2}\) in
                            let \(x_{1}^{\prime \prime}=\operatorname{cast}_{\operatorname{TYPE}\left(x_{1}^{\prime}\right), \operatorname{lct}\left(\operatorname{TYPE}\left(x_{1}^{\prime}\right), \operatorname{TYPE}\left(x_{2}^{\prime}\right)\right)}\left(x_{1}^{\prime}\right)\) in
                            let \(x_{2}^{\prime \prime}=\operatorname{cast}_{\operatorname{TYPE}\left(x_{2}^{\prime}\right), \operatorname{lct}\left(\operatorname{TYPE}\left(x_{1}^{\prime}\right), \operatorname{TYPE}\left(x_{2}^{\prime}\right)\right)\left(x_{2}^{\prime}\right) \text { in }, ~}^{\text {and }}\)
                                    let \(o p=\llbracket \mathrm{ValueComp}\) (vc) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\) in
                                    if validComb \(\left(\operatorname{TyPe}\left(x_{1}^{\prime \prime}\right), \operatorname{Type}\left(x_{2}^{\prime \prime}\right), o p\right)\)
                                    then \(x_{1}^{\prime \prime}\) op \(x_{2}^{\prime \prime}\) else raise error(err:XPTY0004)
                    else raise \(\operatorname{error}\) (err:XPTY0004)
                else nil
            else raise \(\operatorname{error}(\) err:XPTY0004)
    else nil
```

```
【ComparisonExpr(
StringConcatExpr (P) GeneralComp(gc) StringConcatExpr ( \(\mathrm{P}^{\prime}\) )) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let \(x_{1}=\llbracket \mathrm{fn}:\) data \(\rrbracket\left(\llbracket\right.\) StringConcatExpr \(\left.(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\),
        \(o p=\llbracket\) GeneralComp (gc) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\),
        \(x_{2}=\llbracket\) fn:data \(\rrbracket\left(\llbracket\right.\) StringConcatExpr \(\left.\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\) in
    \(\exists x .\left[x \in \operatorname{list} 2 \operatorname{set}\left(x_{1}\right) \wedge \exists y .\left[y \in \operatorname{list} 2 \operatorname{set}\left(x_{2}\right) \wedge\right.\right.\)
        let \(x^{\prime}=\) if type \(_{\text {TYPE }(x), \mathbf{x s}: \text { untypedAtomic }}(x) \wedge\) type \(_{\text {TYPE }(y), \mathbf{x s}: \text { untypedAtomic }}(y)\)
                then cast \(_{\mathrm{xs}: \text { untypedAtomic,string }}(x)\) else \(x\) in
        let \(y^{\prime}=\) if type \(_{\text {TYPE }(x), \mathbf{x s}: \text { untypedAtomic }}(x) \wedge\) type \(_{\text {TYPE }(y), \mathbf{x s}: \text { untypedAtomic }}(y)\)
                then cast \(_{\text {xs:untypedAtomic,string }}(y)\) else \(y\) in
        if type \({\operatorname{TYPE}\left(x^{\prime}\right), \mathbf{x s}: \text { untypedAtomic }}\left(x^{\prime}\right) \vee\) type \(_{\text {TYPE }\left(y^{\prime}\right), \text { xs:untypedAtomic }}\left(y^{\prime}\right) \vee\) then
            let left \(=\) if type \(_{\text {TYPE }\left(x^{\prime}\right), \text { xs:untypedAtomic }}\left(x^{\prime}\right)\) then \(x^{\prime}\) else \(y^{\prime}\) in
            let right \(=\) if type \(e_{\operatorname{TYPE}\left(x^{\prime}\right), \mathrm{xs}: \text { untypedAtomic }}\left(x^{\prime}\right)\) then \(y^{\prime}\) else \(x^{\prime}\) in
            let left \(=\)
                        if type \({ }_{\text {TYPE }(l e f t), \text { num }}(l e f t)\) then cast \(_{\text {TYPE }(l e f t), \text { xs:double }}(l e f t)\)
                        else if type Type \((l e f t)\), xs:day TimeDuration \((l e f t)\) then
                            cast \(_{\text {TYPE }}\) left), xs:dayTimeDuration \((\) left \()\)
                else if type \({ }_{\text {TYPE (left), xs:yearMonthDuration }}(l e f t)\) then
                    cast \(_{\text {TYPE }(l e f t), \mathrm{xs}: \text { yearMonthDuration }}(l e f t)\)
                    else cast \(_{\text {TYPE }(\text { left }), \operatorname{TYPE}(\text { right })}(\) left \()\)
            in if validComb(TyPe(left'), Type(right),op)
                                    then left' op right else raise error
        else if validComb \(\left(\operatorname{TyPE}\left(x^{\prime}\right), \operatorname{TyPE}\left(y^{\prime}\right), o p\right)\) then \(x^{\prime}\) op \(y^{\prime}\) else raise error
【ComparisonExpr (
    StringConcatExpr(P) NodeComp(nc) StringConcatExpr(P')) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
        let left \(=\llbracket\) StringConcatExpr \((\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\),
        right \(=\llbracket\) StringConcatExpr \(\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\) in
    if left \(=\) nil \(\vee\) right \(=n i l\) then nil else
        match left with \(x_{1}:: y_{1}\) then
            if \(y_{1}=n i l \wedge\) type \(_{\text {TYPE }\left(x_{1}\right), \text { node },\left(x_{1}\right)}\) then
                match right with \(x_{2}:: y_{2}\) then
                    if \(y_{2}=\) nil \(\wedge\) type \(_{\text {TYPE }\left(x_{2}\right), \text { node }}\left(x_{2}\right)\) then
                                \(x_{1} \llbracket \operatorname{NodeComp}(\mathrm{nc}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} x_{2}\)
                    else raise error(//err:XPTY0004)
                else nil
            else raise error(//err:XPTY0004)
        else nil
```


## B.1.10 Concatenation of strings

(19) $\llbracket$ StringConcatExpr (RangeExpr (P) ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$ $\llbracket$ RangeExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
String concatenation expressions are translated by XPath 3.0 function fn : concat,
i.e. $\$ \mathrm{a} \| \mid \mathrm{b}=\mathrm{fn}$ : concat $(\$ \mathrm{a}, \$ \mathrm{~b})$.

$$
\begin{aligned}
& \llbracket \text { StringConcatExpr }\left(\operatorname{RangeExpr}\left(\mathrm{P}_{1}\right) \quad||\ldots|| \operatorname{RangeExpr}\left(\mathrm{P}_{n}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}^{n \geq 2} \\
& \llbracket \mathrm{fn}: \operatorname{concat} \rrbracket\left(\llbracket \operatorname{RangeExpr}\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}, \ldots, \llbracket \operatorname{RangeExpr}\left(\mathrm{P}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)
\end{aligned}
$$

## B.1.11 Range expressions

We would like to refer to Section 5.3 for an example of a range expression, who evaluate to sequence of consecutive integers.
(20) $\llbracket \operatorname{RangeExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$

【AdditiveExpr (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket R a n g e E x p r(A d d i t i v e E x p r(P) ~ t o ~ A d d i t i v e E x p r(P ')) ~ \rrbracket \bar{z}, \hat{z}, \tilde{z}={ }_{\mathrm{df}}$ match $\llbracket$ AdditiveExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ with $x_{1}:: y_{1}$ then
match $\llbracket$ AdditiveExpr $\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ with $x_{2}:: y_{2}$ then
let left $=\llbracket \mathrm{fn}:$ number $\rrbracket\left(x_{1}\right)$, right $=\llbracket \mathrm{fn}:$ number $\rrbracket\left(x_{2}\right)$ in if left > right then nil else left :: . . .: right :: nil else nil else nil

## B.1.12 Arithmetic Expressions

Operands of arithmetic expressions undergo atomization, see Section 5.5.1. The translation for additive and multiplicate expressions tests whether all operands and operators are pairwise valid combinations (validComb $\left.\left(z_{1}, \ldots, z_{n+1}, \mathrm{op}_{1}, \ldots, \mathrm{op}_{n}\right)\right)$. For additive expressions AdditiveExpr operators are $\mathrm{op}_{i} \in\{+,-\}$ for all $1 \leq i \leq n$ :
(21) $\llbracket$ AdditiveExpr (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket$ MultiplicativeExpr (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

```
【AdditiveExpr(
MultiplicativeExpr \(\left(\mathrm{P}_{1}\right)\) op 1 MultiplicativeExpr \(\left(\mathrm{P}_{2}\right)\)...
MultiplicativeExpr \(\left(\mathrm{P}_{n}\right) \operatorname{op}_{n}\) MultiplicativeExpr \(\left.\left(\mathrm{P}_{n+1}\right)\right) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}={ }_{\mathrm{df}}\)
    let \(x_{1}=\llbracket \mathrm{fn}\) : data \(\rrbracket\left(\llbracket \operatorname{MultiplicativeExpr}\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right), \ldots\),
        \(x_{n+1}=\llbracket \mathrm{fn}:\) data \(\rrbracket\left(\llbracket \operatorname{MultiplicativeExpr}\left(\mathrm{P}_{n+1}\right) \rrbracket \bar{z}, \hat{z}, \tilde{z}\right)\) in
    if \(x_{1}=n i l \vee \ldots \vee x_{n+1}=n i l\) then \(n i l\) else
    let \(z_{1}=\) match \(x_{1}\) with \(x:: y\) then
                        if type \(\operatorname{TYPE}(x), \mathrm{xs}:\) untypedAtomic \((x)\) then
                            try \(\operatorname{cast}_{\text {TyPe }}(x), \mathbf{x s}:\) double \((x) \mathbf{c a t c h}(e)\) raise \(\operatorname{error}(\) err:FORG0001)
            else \(x\)
            else raise \(\operatorname{error}(\mathrm{err}: X P T Y 0004)\) in ...
        let \(z_{n+1}=\operatorname{match} x_{n+1}\) with \(x:: y\) then
                            if type \(\operatorname{TYPE}(x), \mathbf{x s}:\) untypedAtomic \((x)\) then
                            try \(\operatorname{cast}_{\text {TyPE }(x), \text { xs:double }}(x) \mathbf{c a t c h}(e)\) raise \(\operatorname{error}(\) err:FORG0001)
                    else \(x\)
            else raise error(err:XPTY0004) in ...
    if validComb \(\left(z_{1}, \ldots, z_{n+1}, \mathrm{op}_{1}, \ldots, \mathrm{op}_{n}\right)\) then
        \(\operatorname{try} z_{1} \mathrm{op}_{1} z_{2} \mathrm{op}_{2} \ldots z_{n} \mathrm{op}_{n} z_{n+1}\) catch \((e)\) raise \(\operatorname{error}(e)\)
    else raise error(err:XPTY0004)
```

We assume that the operators belong to the built－in contansts $\mathcal{C}$ onst in $\lambda \mathrm{XP}$ ． Similar to additive expressions we translate multiplicative expressions MultiplicativeExpr， but where $\mathrm{op}_{i} \in\{*$ ，div，idiv，mod $\}$ for all $1 \leq i \leq n$ ：
（22）【MultiplicativeExpr（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【UnionExpr（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
【MultiplicativeExpr
UnionExpr $\left(\mathrm{P}_{1}\right)$ op 1 UnionExpr $\left(\mathrm{P}_{2}\right)$ ．．．
UnionExpr $\left.\left(\mathrm{P}_{n}\right) \operatorname{op}_{n} \operatorname{UnionExpr}\left(\mathrm{P}_{n+1}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
same translation as for Additive $\operatorname{Expr}((21))$ ，but where
$x_{i}=\llbracket \mathrm{fn}:$ data $\rrbracket\left(\llbracket \operatorname{UnionExpr}\left(\mathrm{P}_{i}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$ for all $1 \leq i \leq n+1$

## B．1．13 Ordered Sets

The following two nonterminals UnionExpr and IntersectExceptExpr produce operators union，intersect，and except，which operate on sequences of nodes only，see Section 5．7．1．Notice that according to the specification，if one of the items in the sequences is not a node，a type error is raised，which is treated in shortcut nodelist2set．Furthermore the result list may be sorted in document order according to constant mode．
（23）$\llbracket U n i o n E x p r\left(\right.$ IntersectExceptExpr（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【IntersectExceptExpr（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
For the following union operator union，in XPATH also \｜may be written，which has the same semantics．

【UnionExpr（IntersectExceptExpr（ $\mathrm{P}_{1}$ ）union ．．．
union IntersectExceptExpr $\left.\left(\mathrm{P}_{n}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}^{n \geq 2}$
mode（set2list（nodelist2set（ $\llbracket$ IntersectExceptExpr $\left.\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \cup \ldots$
$\cup$ nodelist2set $\left(\llbracket\right.$ IntersectExceptExpr $\left.\left.\left.\left(\mathrm{P}_{n}\right) \rrbracket \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)\right)$
（24）$\llbracket$ IntersectExceptExpr（InstanceofExpr（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【InstanceofExpr（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
For expressions IntersectExceptExpr we have $\mathrm{op}_{i} \in\{$ intersect，except $\}$ for all $1 \leq i \leq n$ ：

【IntersectExceptExpr（
InstanceofExpr（ $\mathrm{P}_{1}$ ）op $\mathrm{p}_{1}$ InstanceofExpr $\left(\mathrm{P}_{2}\right)$ ．．．
InstanceofExpr $\left(\mathrm{P}_{n}\right) \operatorname{op}_{n}$ InstanceofExpr $\left.\left(\mathrm{P}_{n+1}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}^{n \geq 2}$
mode（set2list（
nodelist2set（ $\llbracket$ InstanceofExpr $\left.\left(\mathrm{P}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \mathrm{op}_{1}$ nodelist2set $\left(\llbracket\right.$ Instanceof $\left.\operatorname{Expr}\left(\mathrm{P}_{2}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \mathrm{op}_{2}$
$\ldots \mathrm{op}_{n} \operatorname{nodelist2set}\left(\llbracket\right.$ InstanceofExpr $\left.\left.\left.\left(\mathrm{P}_{n+1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)\right)$

## B．1．14 Type checks and casts

We refer to Section 4.4 for some examples．
The instance－of expression $P$ instance of $P$＇tests whether the type of the result by $P$ matches the type by $P^{\prime}$ ，for which it is reduced to sequence type matching in Section B．4．
（25）$\llbracket$ InstanceofExpr（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket$ TreatExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket$ InstanceofExpr（TreatExpr（P）instance of SequenceType（ $\mathrm{P}^{\prime}$ ））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$ $\llbracket$ SequenceType（ $\mathrm{P}^{\prime}$ ）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{\llbracket \operatorname{TreatExpr}}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
Treat expressions in XPATH varify whether an expressions is of a certain type． If the value of the expression matches the type，then it is returned，otherwise an error is raised．
（26）$\llbracket \operatorname{TreatExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket$ CastableExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
【TreatExpr（CastableExpr（P）treat as SequenceType（ $\mathrm{P}^{\prime}$ ））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$ if 【InstanceofExpr（CastableExpr（P）
instance of SequenceType（ $\left.\mathrm{P}^{\prime}\right)$ ）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
then $\llbracket C a s t a b l e E x p r ~(P) ~ \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ else raise error（err：XPDY0050）
As mentioned in Section 5.8 the expressions that varify whether some value is castable into a certain type，requires a facility to try and catch errors．
（27）$\llbracket$ CastableExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【CastExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket$ CastableExpr（CastExpr $(P)$ castable as SingleType（ ${ }^{\prime}$＇））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{d f}$
try
let $z=\llbracket$ CastExpr $\left(\mathrm{P}\right.$ cast as SingleType（ $\left.\left.\mathrm{P}^{\prime}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ in true catch $(e)$ false
Cast expressions in XPATH are modeled with constant cast functions cast $_{S, T} \in$
$\mathcal{C o n s t}$ in $\lambda \mathrm{XP}$ that are defined for every combination of source types $S$ and target types $T$ according to the specification ${ }^{3}$ ．

```
(28) \(\llbracket \operatorname{CastExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}\)
    \(\llbracket \operatorname{UnaryExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\)
    \(\llbracket\) CastExpr (UnaryExpr (P) cast as SimpleTypeName (P')) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let \(z=\llbracket \mathrm{fn}:\) data \(\rrbracket\left(\llbracket \operatorname{UnaryExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\) in
    match \(z\) with \(x:: y\) then
        if \(y=\) nil then \(\operatorname{cast}_{\operatorname{TYPE}(x), \operatorname{TYPE}\left(\left[\operatorname{SimpleTypeName} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right.}(x)\)
        else raise error(err:XPTY0004)
    else raise error
【CastExpr (UnaryExpr (P) cast as SimpleTypeName (P')?) \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{d f}\)
    let \(z=\llbracket \mathrm{fn}:\) data \(\rrbracket\left(\llbracket \operatorname{UnaryExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\) in
    match \(z\) with \(x:: y\) then
        if \(y=\) nil then cast \(_{\operatorname{TYPE}(x), \operatorname{TYPE}\left(\llbracket \operatorname{SimpleTypeName} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)}(x)\)
        else raise \(\operatorname{error}(\mathrm{err}: \mathrm{XPTY0004)}\)
    else nil
```


## B．1．15 Unary Expressions

（29）$\llbracket \operatorname{UnaryExpr}(\operatorname{ValueExpr}(\mathrm{P})) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket \operatorname{ValueExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
Any sequence of unary operators + and - is reduced to one unary operator in the obvious way．The translation is similar to the translation of arithmetic expressions as above．op $\in\{+,-\}$ ．

【UnaryExpr（op ValueExpr（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{d f}$
match $\llbracket \mathrm{fn}:$ data $\rrbracket\left(\llbracket \operatorname{ValueExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$ with $x:: y$ then
if $y=n i l$ then
let $x^{\prime}=$ if type $_{\text {TYPE }(x), \text { xs：untypedAtomic }}(x)$
then try $\operatorname{cast}_{\text {TyPe }(x), \mathbf{x s} \text { ：double }}(x) \mathbf{c a t c h}(e)$ raise $\operatorname{error}(\mathrm{err}: F O R G 0001)$ else $x$
in
if validComb $\left(x^{\prime}, \mathrm{op}\right)$ then op 【fn：number】（ $x^{\prime}$ ）else raise error（err：XPTY0004）
else raise $\operatorname{error}(\mathrm{err}: X P T Y 0004)$
else nil

## B．1．16 Value expressions

Value expressions are simple map expressions．
（30）$\llbracket \operatorname{ValueExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【SimpleMapExpr（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

[^23]
## B．1．17 Comparison operators

The translation of general comparison，value comparison，and node comparison operators is straight forward．
（31）$\llbracket$ GeneralComp（ $=$ ）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}=$
$\llbracket$ GeneralComp（！$=\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=$ df $\neq$
［GeneralComp（＜）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}<$
$\llbracket$ GeneralComp（＜＝）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}=\mathrm{df} \leq$
$\llbracket$ GeneralComp（＞）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}>$
【GeneralComp（＞＝）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \geq$
（32）【ValueComp（eq）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}=$
$\llbracket$ ValueComp（ne）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=$ df $\neq$
［ValueComp（lt）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}<$
［ValueComp（le）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \leq$
［ValueComp（gt）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\text {df }}>$
【ValueComp（ge）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df} \geq$
（33）$\llbracket$ NodeComp（is）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}=$
$\llbracket \operatorname{NodeComp}(\ll) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}<$
$\llbracket \operatorname{NodeComp}(\gg) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}>$

## B．1．18 Simple Map expressions

（34）$\llbracket \operatorname{SimpleMapExpr}(\operatorname{PathExpr}(P)) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket \operatorname{PathExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
The translation of the simple map operator（！）from Section 3．3．6 makes the treatment of context nodes $c i$ ，context positions $c p$ ，and context size $c s$ explicite using nested data structures，as we discussed in Section 7．3．2．
［SimpleMapExpr（PathExpr（P）！PathExpr（ ${ }^{\prime}$ ））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$ let apply $=\lambda z$ ．match $z$ with $x:: y$ then match $x$ with $(c i, c p, c s)$ in if type TYPE（ci），node $(c i)$ then $\operatorname{at}\left(c i,\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) . \llbracket \operatorname{PathExpr}\left(\mathrm{P}^{\prime}\right) \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\right):: \operatorname{apply}(y)$ else
$\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \operatorname{PathExpr}\left(\mathrm{P}^{\prime}\right) \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s):: \operatorname{apply}(y)$
else nil in
listconcatapply（addPositionAndSize $\left(\left[\operatorname{PathExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)$
However for reverse axis，the assignment of context positions is in reverse doc－ ument order：

```
【ReverseAxis(P): :NodeTest(P') ! PathExpr ( \(\mathrm{P}^{\prime}\) ') \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let apply \(=\lambda z\). match \(z\) with \(x:: y\) then
        match \(x\) with \((c i, c p, c s)\) in
            \(\left.\mathbf{a t}\left(c i,\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \operatorname{PathExpr}\left(\mathrm{P}{ }^{\prime}\right)\right) \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\right):: \operatorname{apply}(y)\)
        else nil
    in listconcat apply (
        addReversePositionAndSize( \(\left.\left.\llbracket \operatorname{ReverseAxis}(\mathrm{P}):: \operatorname{NodeTest}\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)\)
```


## B． 2 Navigational Expressions

## B．2．1 Absolute path expressions

A＂／＂at the beginning of a path expression is an abbreviation for the root node of the tree to which the context node self：：node（）belongs．
（35）$\llbracket \operatorname{PathExpr}(/) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【PathExpr（（fn：root（self：：node（））treat as document－node（）））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
【PathExpr（／RelativePathExpr（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket \operatorname{PathExpr}((f n: r o o t(s e l f:: n o d e())$ treat as document－node（））
／RelativePathExpr（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket \operatorname{PathExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【RelativePathExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

## B．2．2 Relative path expressions

（36）$\llbracket$ RelativePathExpr（StepExpr（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket$ StepExpr $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \bar{z}}$
Each occurence of／／in relative path expressions RelativePathExpr is an ab－ breviation for／descendant－or－self：：node（）／．
$\llbracket$ RelativePathExpr $\left(\mathrm{P} / / \mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【RelativePathExpr（P／descendant－or－self：：node（）／P＇）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
The path operator／that we describe in Section 3．3．6 can be expressed using the simple map operator ！：
$\llbracket R e l a t i v e P a t h E x p r\left(P / P^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【RelativePathExpr
let \＄R：＝P！P＇return
if（every \＄r in \＄R satisfies \＄r instance of node（））then （\＄R union（））
else if（every $\$ \mathrm{r}$ in $\$ \mathrm{R}$ satisfies not（\＄r instance of node（）））
then \＄R
else error（）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

## B．2．3 Steps

Steps in XPath 3.0 are expressions that produce a sequence of items that may be filtered．A step is either an axis step or a postfix expression．
(37) $\llbracket$ StepExpr $(P) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\text {df }}$
$\begin{cases}\llbracket \operatorname{PostfixExpr}(\mathrm{P}) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z} & \mathrm{P} \in \text { PostfixExpr } \\ \llbracket \text { AxisStep }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { AxisStep }\end{cases}$

## B.2.4 Axis steps and Filters

An axis step, described in Section 3.3.1, is either a forward or a backward step.
(38) $\llbracket$ AxisStep(ForwardStep (P)) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
[ForwardStep(P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
$\llbracket$ AxisStep (ReverseStep (P) ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket$ ReverseStep (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
An axis steps with predicates or postfix expressions PostfixExpr (48) are translated as follows. The expression $P$ below is some expression $\bar{P}$ of either a forward step AxisStep (ForwardStep ( $\overline{\mathrm{P}}$ )), a backward step AxisStep (ReverseStep $(\overline{\mathrm{P}}$ )), or a primary expression PostfixExpr (PrimaryExpr( $\overline{\mathrm{P}})$ ). More details on filters can be found in Section 3.3.5. Similarly to the translation of the simple map operator, it must take care of context nodes and positions explicitely.

```
\(\llbracket \mathrm{P}\left[\mathrm{P}^{\prime}\right] \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let eval \(=\lambda z\).match \(z\) with \(x:: y\) then
        match \(x\) with ( \(c i, c p, c s\) ) in
            let filter \(=\) if type \(_{\text {TYPE }(c i), \text { node }}(c i)\) then
                    \(\operatorname{at}\left(c i,\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \mathrm{P}^{\prime} \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\right)\)
                    else
                        \(\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \mathbb{P}^{\prime} \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\)
            in
            if type \(_{\text {TYPE }}\) filter \()\),num \((f i l t e r) \wedge c a s t_{\operatorname{TYPE}(f i l t e r), \text { int }}(\) filter \()=c p\) then
                    ci :: eval(y)
            else if 【fn:boolean】(filter) then
                ci :: eval(y)
            else \(\operatorname{eval}(y)\)
        else nil
    in \(\operatorname{eval}\left(\right.\) addPositionAndSize \(\left.\left(\llbracket \mathrm{P} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)\)
```

Notice that context positions are assigned in reverse document order for testing predicated on nodes selected by reverse axes:

```
\(\llbracket \operatorname{ReverseAxis}(\mathrm{P}):: \operatorname{NodeTest}\left(\mathrm{P}^{\prime}\right)\left[\operatorname{Expr}\left(\mathrm{P}{ }^{\prime}\right)\right] \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}\)
    let eval \(=\lambda z\). match \(z\) with \(x:: y\) then
        match \(x\) with \((c i, c p, c s)\) in
            let filter \(\left.=\mathbf{a t}\left(c i,\left(\lambda\left(z^{i}, z^{p}, z^{s}\right) \cdot \llbracket \operatorname{Expr}\left(\mathrm{P}^{\prime}\right)\right) \rrbracket_{z^{i}, z^{p}, z^{s}}\right)(c i, c p, c s)\right)\) in
                if type TYPE(filter),num \((\) filter \() \wedge \operatorname{cast}_{\text {TYPE }}\) filter),int \((\) filter \()=c p\) then
                    ci :: \(\operatorname{eval}(y)\)
            else if 【fn:boolean】(filter) then
            \(c i:: \operatorname{eval}(y)\)
                else \(\operatorname{eval}(y)\)
        else nil
    in eval(addReversePositionAndSize(
                        【ReverseAxis(P): :NodeTest(P') \(\rrbracket_{\bar{z}, \hat{z}, \tilde{z}))}\)
```


## B．2．5 Axis Steps

The following translations concern axis steps，as discussed in Section 3．3．1．Node label and type tests are reduced to sequence type matching as in Section B．4．
（39）$\llbracket$ ForwardStep（ForwardAxis（P）NodeTest（ $\mathrm{P}^{\prime}$ ））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\operatorname{mode}\left(\operatorname{set} 2 l i s t\left(\left\{x \mid x \in \llbracket\right.\right.\right.$ ForwardAxis $\left.\left.\left.(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} \wedge \llbracket \operatorname{NodeTest}\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{x}\right\}\right)\right)$
Attribute nodes of XmL data trees are considered to be children of their parents， in contrast to what the XmL data model specifies．Thus the following translation has to take this into account．
（40）$\llbracket$ ForwardAxis（child：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\left\{x \mid \operatorname{ch}\left(i s_{x}\right) \wedge \neg\right.$ type $\left._{\text {TYPE }(x), \text { attribute }}(x)\right\}$
$\llbracket$ ForwardAxis（descendant：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\left\{x \mid c h^{+}\left(i s_{x}\right) \wedge \neg\right.$ type $\left._{\text {TYPE }(x), \text { attribute }}(x)\right\}$
［ForwardAxis（attribute：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\left\{x \mid \operatorname{ch}\left(i s_{x}\right) \wedge \operatorname{type}_{\operatorname{TYPE}(x), \text { attribute }}(x)\right\}$
$\llbracket$ ForwardAxis（self：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\left\{x \mid i s_{x}\right\}$
［ForwardAxis（descendant－or－self：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\left\{x \mid c h^{*}\left(i s_{x}\right) \wedge \neg\right.$ type $\left._{\text {TYPE }(x), \text { attribute }}(x)\right\}$
［ForwardAxis（following－sibling：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\left\{x \mid n s^{+}\left(i s_{x}\right) \wedge \neg\right.$ type $\left._{\text {TYPE }(x), \text { attribute }}(x)\right\}$
［ForwardAxis（following：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$ $\left\{x \mid \operatorname{par}^{*}\left(n s^{+}\left(\operatorname{ch}^{*}\left(i s_{x}\right)\right)\right) \wedge \neg\right.$ type $\left._{\text {TYPE }(x), \text { attribute }}(x)\right\}$
［ForwardAxis（namespace：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$ raise error
We do not consider abbreviated XPath queries．＂＠＂is an abbreviation for ＂attribute：：＂．
（41）AbbrevForwardStep ：：＝＂＠＂？NodeTest
The nonterminal for abbreviated forward steps AbbrevForwardStep is not con－ sidered．
（42）$\llbracket \operatorname{ReverseStep}\left(R e v e r s e A x i s(P) \operatorname{NodeTest}\left(\mathrm{P}^{\prime}\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$ $\operatorname{mode}\left(\operatorname{set} 2 l i s t\left(\left\{x \mid x \in \llbracket \operatorname{ReverseAxis}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} \wedge \llbracket \operatorname{NodeTest}\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{x}\right\}\right)\right)$
（43）$\llbracket$ ReverseAxis（parent：：）$\rrbracket_{\bar{z}}, \hat{z}, \tilde{z}={ }_{\mathrm{df}}$

$$
\left\{x \mid \operatorname{par}\left(i s_{x}\right) \wedge \neg \text { type }_{\operatorname{TYPE}(x), \text { attribute }}(x)\right\}
$$

$$
\llbracket \text { ReverseAxis (ancestor: : ) } \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}
$$

$$
\left\{x \mid \operatorname{par}^{+}\left(i s_{x}\right) \wedge \neg \operatorname{type}_{\operatorname{TYPE}(x), \text { attribute }}(x)\right\}
$$

$$
\llbracket \text { ReverseAxis (preceding-sibling: :) } \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}
$$

$$
\left\{x \mid p s^{+}\left(i s_{x}\right) \wedge \neg \text { type }_{\operatorname{TYPE}(x), \text { attribute }}(x)\right\}
$$

【ReverseAxis（preceding：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$
$\left\{x \mid \operatorname{par}^{*}\left(p s^{+}\left(c h^{*}\left(i s_{x}\right)\right)\right) \wedge \neg\right.$ type $\left._{\text {TYPE }(x), \text { attribute }}(x)\right\}$
$\llbracket$ ReverseAxis（ancestor－or－self：：）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$

$$
\left\{x \mid \operatorname{par}^{*}\left(i s_{x}\right) \wedge \neg \text { type }_{\text {TYPE }(x), \text { attribute }}(x)\right\}
$$

We do not consider abbreviated XPATH queries．＂．．＂is an abbreviation for ＂parent：：node（）＂．
（44）AbbrevReverseStep ：：＝＂．．＂

## B．2．6 Node Tests，Name Tests，and Wildcards

Translation for node tests NodeTest，name tests NameTest，and wildcards Wildcard are parametrized by the node $v$ ，for which the test is to be performed．It reduces to sequence type matching in Section B．4．
（45）$\llbracket \operatorname{NodeTest}(\mathrm{P}) \rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$

$$
\begin{cases}\llbracket \text { KindTest }(\mathrm{P}) \rrbracket_{\tilde{z}, \hat{,}, \tilde{z}}^{v} & \mathrm{P} \in \text { KindTest } \\ \llbracket \text { NameTest }(\mathrm{P}) \rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v} & \mathrm{P} \in \text { NameTest }\end{cases}
$$

The following translation for name tests NameTest uses shortcut testEQName．
（46）$\llbracket$ NameTest（P）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$

```
\(\begin{cases}\text { let } z=\llbracket \operatorname{EQName}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} \text { in } & \mathrm{P} \in \text { EQName } \\ \text { testEQName }(v, z) & \mathrm{P} \in \text { Wildcard } \\ \llbracket \text { Wildcard }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v} & \end{cases}\)
```

（47）$\llbracket$ Wildcard（＊）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
labtype $(v)=e l \vee$ labtype $(v)=a t t$
【Wildcard（NCName（P）：＊）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
$\llbracket \mathrm{fn}: \operatorname{prefix}-\mathrm{from-QName} \rrbracket\left(\operatorname{lab} b_{\text {name }}(v)\right)=\llbracket \operatorname{NCName}(\mathrm{P}) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}$
【Wildcard（＊：NCName（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$

【Wildcard（BracedURILiteral（P）＊）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$
$\llbracket \mathrm{fn}: \operatorname{prefix}-\mathrm{from-QName} \rrbracket\left(\operatorname{lab_{name}}(v)\right)=\operatorname{prefix}\left(\llbracket \operatorname{BracedURILiteral}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$

## B. 3 Postfix expressions

## B.3.1 Postfix expressions

(48) $\llbracket \operatorname{PostfixExpr}(\operatorname{PrimaryExpr}(\mathrm{P})) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket \operatorname{PrimaryExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
Expressions PostfixExpr (PrimaryExpr (P) [Expr (P')]) are translated as presented before for filters, see AxisStep (38).

Argument expressions PostfixExpr (PrimaryExpr (P) (Argument $\left.\left(\mathrm{P}_{1}\right), \ldots, \operatorname{Argument}\left(\mathrm{P}_{n}\right)\right)$ ) are translated as function calls FunctionCall (59).

## B.3.2 Argument Lists and Predicates

Argument lists are used to define function calls, see FunctionCall (59) and thus not translated.
(49) ArgumentList : := "(" (Argument ("," Argument)*)? ")"

Predicates are translated as filters, that may appear with expressions AxisStep and PostfixExpr, and thus also not translated.
(50) PredicateList : := Predicate*
(51) Predicate ::= "[" Expr "]"

## B.3.3 Primary expressions

There are the following primary expressions in XPATH.
(52) $\llbracket \operatorname{PrimaryExpr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$

$$
\begin{array}{ll}
\llbracket \text { Literal }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { Literal } \\
\llbracket \operatorname{VarRef}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { VarRef } \\
\llbracket \text { ParenthesizedExpr }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { ParenthesizedExpr } \\
\llbracket \text { ContextItemExpr }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { ContextItemExpr } \\
\llbracket \text { FunctionCall }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { FunctionCall } \\
\llbracket \text { FunctionItemExpr }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { FunctionItemExpr }
\end{array}
$$

## B.3.4 Literals

Literals translate to constants in $\lambda \mathrm{XP}$, see Section B.5.
(53) $\llbracket$ Literal (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{d f}$

$$
\begin{cases}\llbracket \text { NumericLiteral }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}} & \mathrm{P} \in \text { NumericLiteral } \\ \llbracket \text { StringLiteral }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { StringLiteral }\end{cases}
$$

(54) $\llbracket$ NumericLiteral ( P ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$


## B.3.5 Variables

Variables translate to corresponding variables in $\lambda \mathrm{XP}$.
(55) $\llbracket \$ \operatorname{VarRef}(\operatorname{VarName}(P)) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket \operatorname{VarName}(P) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
(56) $\llbracket \operatorname{VarName}$ (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$

【EQName (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

## B.3.6 Parenthesized expressions and the empty list

Expressions with surrounding parenthesis translate to the expressions without the parenthesis.
(57) $\llbracket(\operatorname{Expr}(\mathrm{P})) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$
$\llbracket \operatorname{Expr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
The expression () translates to the empty list in $\lambda \mathrm{XP}$.
$\llbracket() \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
nil

## B.3.7 Context Item, Position, and Size

Whenever an XPath query makes reference to the context item, position, or size in filters or path expressions, then we translate as explained in Section 7.3.2. It evaluates these expressions using some function whose argument will be a triple of context item, position, and size that arrive during runtime. These arguments will substitute the function's parameters $\bar{z}, \hat{z}$, and $\tilde{z}$, to which we translate the context item expression, function $f n$ :position, and function $f n$ :last(), respectively.

```
(58) \llbracketContextItemExpr(.)}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{}=\mp@subsup{}{\textrm{df}}{}\overline{z
    |n:position() \}\mp@subsup{|}{\overline{z},\hat{z},\tilde{z}}{}=\mp@subsup{}{\textrm{df}}{\hat{z}
    |n:last() \\tilde{z},\hat{z},\tilde{z}}=\mp@subsup{}{\textrm{df}}{}\tilde{z
```


## B.3.8 Function Calls

Function calls rely on rules for function conversion and coercion, as mentioned in Section 5.2.3. We use a function convert-arg ${ }^{S T}(x)$ that converts arguments according to the function conversion rules. It converts arguments $x$ with respect to a target sequence type $S T$. When $S T$ is a TypedFunctionTest (92), then function coercion is applied. Otherwise if $S T$ is a generalized atomic type $A T$, for example, the function converts $x$ as follows:
convert-arg ${ }^{A T}={ }_{\mathrm{df}}$

```
\(\lambda(x)\).let \(x^{\prime}=\llbracket \mathrm{fn}\) : data \(\rrbracket(x)\) in
    letrec fun \(=\lambda z\).
    match \(z\) with \(y:: y^{\prime}\) then
            if type \(\operatorname{TYPE}(y), \mathbf{x s}:\) untypedAtomic \((y)\) then
                if type TYPE \((A T)\), num \((y)\) then
                        \(\operatorname{cast}_{\mathrm{TYPE}(y), \mathrm{xs}: \text { double }}(y)::\) fun \(\left(y^{\prime}\right)\)
            else if type \(\operatorname{TYPE}(y), \mathrm{xs}: \mathbf{Q N a m e}(y) \vee\) type \(_{\operatorname{TyPE}(y), \mathrm{xs}: \operatorname{Notation}(y) \text { then }}\)
                            raise error
                    else
                        \(\operatorname{cast}_{\operatorname{Type}(y), \operatorname{Type}(A T)}(y)::\) fun \(\left(y^{\prime}\right)\)
            else
                \(\operatorname{cast}_{\operatorname{TyPe}(y), \operatorname{Type}(A T)}(y)::\) fun \(\left(y^{\prime}\right)\)
    else nil
in fun \(\left(x^{\prime}\right)\)
```

The following translation for function call expressions FunctionCall maps to function applications in $\lambda$ XP in the absence of place holders ?, and otherwise returns a new function that is obtained via currying. The result of the function call is the value of a function $f$ that matches $\llbracket E Q N a m e(P) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ when applied to the converted arguments, of which none is a place holder ?. Otherwise the result is a new function which has as many arguments as place holders:
(59) $\llbracket$ FunctionCall (EQName $\left.(\mathrm{P})\left(\operatorname{Argument}\left(\mathrm{P}_{1}\right), \ldots, \operatorname{Argument}\left(\mathrm{P}_{n}\right)\right)\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}_{\mathrm{df}}$ $\lambda\left(z_{k_{1}}, \ldots, z_{k_{n^{\prime}}}\right) \cdot f\left(m_{1}, \ldots, m_{n}\right)$
where $f: S T_{1} \times \ldots \times S T_{n} \rightarrow S T$ is function matching $\llbracket E Q N a m e(\mathrm{P}) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}$,

$$
\left(m_{i}\right)= \begin{cases}\text { convert-arg } & \\ z_{i} & \left\lfloor\text { ExprSingle }\left(\mathrm{P}_{i}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right) \\ \mathrm{P}_{i} \neq ? \\ \mathrm{P}_{i}=?\end{cases}
$$

$\left(k_{i}\right)$ is the sequence of indices $j$ for which $\mathrm{P}_{j}=$ ?
Function arguments Argument and place holders ArgumentPlaceholder are translated in FunctionCall (59).
(60) Argument ::= ExprSingle | ArgumentPlaceholder
(61) ArgumentPlaceholder ::= "?"

## B.3.9 Functions

Functions may be referenced by EQNames, as with function calls. Otherwise they are referenced via their name and arity or they are constructed inline.
(62) $\llbracket$ FunctionItemExpr (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\begin{cases}\llbracket \text { NamedFunctionRef }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { NamedFunctionRef } \\ \llbracket \text { InlineFunctionExpr }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { InlineFunctionExpr }\end{cases}$
Named function references NamedFunctionRef identify functions by its name and arity.
(63) $\llbracket$ NamedFunctionRef (EQName (P) \#IntegerLiteral (P) ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$x \quad$ where $x \in \mathcal{C}$ onst is the function that matches $\llbracket E Q N a m e(\mathrm{P}) \rrbracket_{\bar{z}}, \hat{z}, \tilde{z}$ and $\llbracket$ IntegerLiteral ( $\mathrm{P}^{\prime}$ ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
(64) 【InlineFunctionExpr (function (\$EQName ( $\mathrm{x}_{1}$ ) , . . , \$EQName $\left(\mathrm{x}_{n}\right)$ )
$\{\operatorname{Expr}(\mathrm{P})\}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\lambda z$. match $z$ with $\left(\llbracket \operatorname{EQName}\left(\mathrm{x}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}, \ldots, \llbracket \operatorname{EQName}\left(\mathrm{x}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$ in $\llbracket \operatorname{Expr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
【InlineFunctionExpr (function (\$EQName ( $\mathrm{x}_{1}$ ) as SequenceType ( $\mathrm{P}_{1}$ ), ..., \$EQName ( $\mathrm{x}_{n}$ ) as SequenceType ( $\mathrm{P}_{n}$ )) (as SequenceType ( $\mathrm{P}^{\prime}$ ))
$\{\operatorname{Expr}(\mathrm{P})\}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\lambda z$. match $z$ with $\left(y_{1}, \ldots, y_{n}\right)$ in
let $\llbracket E Q N a m e\left(\mathrm{x}_{1}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=$ convert- $\arg ^{\mathrm{P}_{1}}\left(y_{1}\right)$,
$\llbracket E Q N a m e\left(\mathrm{x}_{n}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=$ convert- $\arg ^{\mathrm{P}_{n}}\left(y_{n}\right)$
in $\llbracket \operatorname{Expr}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

## B.3.10 Simple Types

Simple types are atomic, list, and union types, into which nonterminal SingleType expands. Cast expressions require such simple types which however must directly translate nonterminal SimpleTypeName (88), such that nonterminal SingleType does not require a translation.
(65) SingleType ::= SimpleTypeName "?"?

TypeClaration are used when defining functions and function tests.
(66) TypeDeclaration ::= "as" SequenceType

## B. 4 Sequence Type Expressions

For matchings of some values $v$ against sequence type expressions P , described in more detail in Section 4.5, the translation $\llbracket \mathrm{P} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ is further parametrized by some value $v$. The translation returns a boolean value depending on whether $v$ matches a certain sequence type using the rules for sequence type matching ${ }^{4}$.

## B.4.1 Top level Sequence Type Matching

Sequence type matching is reduced to matching of item types. The empty sequence type matches the empty sequence.
(67) $\llbracket$ SequenceType (empty-sequence()) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$
if $v=$ nil then true else false
An item type without an occurence indicator matches a sequence that contains exactly one item, if the item type matches that item.
$\llbracket$ SequenceType (ItemType (P)) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
match $v$ with $x:: y$ then
if $y=n i l$ then $\llbracket$ ItemType (P) $\rrbracket \frac{x}{z, \tilde{z}, \tilde{z}}$ else false else false
Item types with an occurence indicator ?, $*$, or + match a sequence, if the number of items in that sequence match the occurence indicator and the item types

[^24]match the items in the sequence．
【SequenceType（ItemType（P）？）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$
match $v$ with $x:: y$ then
if $y=$ nil then $\llbracket$ ItemType（ P$) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{x}$ else false
else true
【SequenceType（ItemType（P）＊）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
let $r e c=\lambda z$. match $z$ with $x:: y$ then
if $\llbracket$ ItemType（ P$) \rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{x}=$ true then $\operatorname{rec}(y)$ else false
else true
in $\operatorname{rec}(v)$
【SequenceType（ItemType（P）＋）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
let $r e c=\lambda z$. match $z$ with $x:: y$ then
if 【ItemType（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{x}=$ true then $\operatorname{rec}(y)$ else false
else true
in if $v=n i l$ then false else $\operatorname{rec}(v)$
The OccurrenceIndicator is treated within the translation for sequence types SequenceType．
（68）OccurrenceIndicator ：：＝＂？＂｜＂＊＂｜＂＋＂

## B．4．2 Item types

The matching against item types splits into the following tests．Notice that item type item（）matches any item．
（69）$\llbracket$ ItemType（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$

$$
\begin{cases}\llbracket \text { KindTest }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v} & \mathrm{P} \in \text { KindTest } \\ \text { true } & \mathrm{P}=\text { item }() \\ \llbracket \text { FunctionTest }(\mathrm{P}) \rrbracket \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v} & \mathrm{P} \in \text { FunctionTest } \\ \llbracket \text { AtomicOrUnionType }(\mathrm{P}) \rrbracket_{\bar{z}}^{v}, \hat{z}, \tilde{z} & \mathrm{P} \in \text { AtomicOrUnionType } \\ \llbracket \text { ParenthesizedItemType }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v} & \mathrm{P} \in \text { ParenthesizedItemType }\end{cases}
$$

## B．4．3 Atomic and union types

Matching against atomic or union types reduces to testing whether the value is of the respective type．
（70）【AtomicOrUnionType（EQName（P））$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$

$$
\operatorname{type}_{\operatorname{TYPE}(v), \operatorname{TYPE}\left(\left[\operatorname{EQName}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right.}(v)
$$

## B．4．4 Kind Tests

Kind tests match nodes of XmL data trees against their type，name，and other properties．
（71）$\llbracket$ KindTest（P）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$

| ［DocumentTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ DocumentTest |
| :---: | :---: |
| 【ElementTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ ElementTest |
| ［AttributeTest（P）$]_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ AttributeTest |
| 【SchemaElementTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ SchemaElementTest |
| 【SchemaAttributeTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ SchemaAttributeTest |
| $\llbracket \mathrm{PITest}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ PITtest |
| 【CommentTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ CommentTest |
| 【TextTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ TextTest |
| $\llbracket$ NamespaceNodeTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ NamespaceNodeTest |
| 【AnyKindTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ | $\mathrm{P} \in$ AnyKindTest |

Type node（）matches any node．
（72）$\llbracket$ AnyKindTest（node（））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ type $_{\text {TyPE }(v), \text { node }}(v)$
Type document－node（）matches any document node．
（73）$\llbracket$ DocumentTest（document－node（））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
type $_{\text {TYPE }(v) \text { ，documentnode }}(v)$
The following two kind tests against document nodes，require the existence of exactly one element node child，that matches against a test for elements or a test for element with schema information，respectively．
$\llbracket$ DocumentTest（document－node（ElementTest（P）））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
if type TYPE $(v)$ documentnode $(v)$ then
match $\operatorname{set} 2 l i s t\left\{v^{\prime} \mid \boldsymbol{a t}\left(v, \operatorname{ch}\left(i s_{v^{\prime}} \wedge \operatorname{labtype}\left(v^{\prime}\right)=e l\right)\right)\right\}$ with $x:: y$
then if $y=n i l$ then
$\llbracket$ ElementTest（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v^{\prime}}$
else false
else false
else false
$\llbracket$ DocumentTest（document－node（SchemaElementTest（P）））$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
if type TYPE $(v)$ ，documentnode $(v)$ then
match $\operatorname{set} 2 l i s t\left\{v^{\prime} \mid \boldsymbol{a t}\left(v, \operatorname{ch}\left(i s_{v^{\prime}} \wedge \operatorname{labtype}\left(v^{\prime}\right)=e l\right)\right)\right\}$ with $x:: y$
then if $y=n i l$ then
$\llbracket$ SchemaElementTest（P）$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v^{\prime}}$
else false
else false
else false
Type text（）matches any text node．
（74）$\llbracket$ TextTest（text（））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
type $_{\text {TYPE }(v), \text { textnode }}(v)$
Type comment（）matches any comment node．
（75）$\llbracket$ CommentTest（comment（））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
type $_{\text {TYPE }(v) \text { ，commentnode }}(v)$
We do not support namespaces nodes and axes．However type namespace－node（）
matches namespace nodes.
(76) $\llbracket$ NamespaceNodeTest (namespace-node()) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$
raise error
Type processing-instruction() matches any processing-instruction node.
(77) $\llbracket$ PITest (processing-instruction()) $\rrbracket \bar{z}, \hat{z}, \tilde{z}={ }_{\mathrm{df}}^{v}$

## $t_{\text {type }}$ TYPE $(v)$, pinode $(v)$

Tests against processing-instruction nodes that specify an NCName, match any processing-instruction node whose target is equal to the NCName up to whitespace normalization.
$\llbracket$ PITest (processing-instruction(NCName(P))) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
let $x=\llbracket \operatorname{NCName}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ in
let $y=\llbracket$ fn: normalize-space $\rrbracket(x)$ in
if $\neg$ type $_{\text {TYPE }(y), \mathrm{xs}: \mathbf{Q N a m e}}(y)$ then raise $\operatorname{error}($ err:XPTY0004)
else type $_{\text {TYPE }(v), \text { pinode }}(v) \wedge \operatorname{lab}_{\text {target }}(v)=y$
If the XPATH 1.0 compatibility mode were set to true, one would have to allow the specification of the processing-instruction target as string literal.
$\llbracket$ PITest (processing-instruction(StringLiteral (P))) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
let $x=\llbracket$ StringLiteral (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ in
if $\neg$ type $_{\text {TYPE }(x), \mathbf{x s}: \mathbf{Q N a m e}}(x)$ then raise error(err:XPTY0004)
else type $_{\text {TYPE }(v) \text {,pinode }}(v) \wedge \operatorname{lab}_{\text {target }}(v)=x$
Type attribute() matches any attribute node.
(78) $\llbracket$ AttributeTest(attribute()) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
type $_{\text {TYPE }(v), \text { attribute }}(v)$
Attribute tests that specify an attribute name match attribute nodes with the respective node-name.
$\llbracket$ AttributeTest (attribute (AttribNameOrWildcard(P))) $\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$ type $_{\text {TYPE }(v), \text { attribute }}(v) \wedge \llbracket \operatorname{AttribNameOrWildcard(P)~} \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$
Attribute tests that besides an attribute name also specify a type, require in addition that the type annotation of the attribute node under consideration derives from the given type.
$\llbracket$ AttributeTest (attribute (AttribNameOrWildcard(P), TypeName(P'))) $\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ $\operatorname{type}_{\operatorname{TYPE}(v), \text { attribute }}(v) \wedge \llbracket \operatorname{AttribNameOrWildcard}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$
$\wedge$ derives-from (lab schema-type $\left.(v), \operatorname{TYPE}\left(\llbracket \operatorname{TypeName}(\mathrm{P} ') \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)$

```
AttribNameOrWildcard(AttributeName(P)) \}\mp@subsup{|}{\tilde{z},\hat{z},\tilde{z}}{v}=\mp@subsup{}{\textrm{df}}{
    let z=\llbracketAttributeName(P)}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{}\mathrm{ in
    testEQName(v,z)
|AttribNameOrWildcard(*)}\mp@subsup{\rrbracket}{\overline{z},\hat{z},\tilde{z}}{v}=\mp@subsup{\textrm{df}}{}{\prime
    true
```

Schema attribute tests match attribute nodes, with a certain attribute declaration.
(80) $\llbracket$ SchemaAttributeTest (schema-attribute (AttributeDeclaration(P))) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ type $_{\operatorname{TYPE}(v), \text { attribute }}(v) \wedge \llbracket \operatorname{AttributeDeclaration~}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$
The type $\operatorname{TyPE}(s)$ for an attribute $s$ denotes the schema type declared for $s$ within the attribute declarations in $\mathcal{C}$ onst.
（81）$\llbracket$ AttributeDeclaration（AttributeName（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
let $z=\llbracket$ AttributeName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ in
testEQName $(v, z) \wedge$ derives－from $\left(\right.$ lab $\left._{\text {schema－type }}(v), \operatorname{TYPE}(z)\right)$
Tests against element node，behave similar to tests for attribute nodes．
（82）$\llbracket$ ElementTest（element（））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
type $_{\text {TyPE }(v), \text { elementnode }}(v)$
【ElementTest（element（ElementNameOrWildcard（P）））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ type $\operatorname{TYPE}(v)$, elementnode $(v) \wedge \llbracket E l e m e n t N a m e O r W i l d c a r d(P) \rrbracket \bar{z}, \hat{z}, \tilde{z}$
【ElementTest（element（ElementNameOrWildcard（P），TypeName（P＇）））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ type $_{\text {TYPE }(v), \text { elementnode }}(v) \wedge \llbracket E l e m e n t N a m e O r W i l d c a r d(P) \rrbracket \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$ $\wedge$ derives－from $\left(\operatorname{lab}_{\text {schema－type }}(v), \operatorname{TYPE}\left(\llbracket \operatorname{TypeName}\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)\right)$ $\wedge l a b_{\text {nilled }}(v)=" f a l s e "$
$\llbracket$ ElementTest（element（ElementNameOrWildcard（P），TypeName（P＇）？））$\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ type $_{\text {TYPE }(v), \text { elementnode }}(v) \wedge \llbracket E l e m e n t N a m e O r W i l d c a r d(P) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$
$\wedge$ derives－from $\left(\right.$ lab $\left._{\text {schema－type }}(v), \operatorname{TYPE}(\llbracket \operatorname{TypeName}(\mathrm{P} ') \rrbracket \bar{z}, \hat{z}, \tilde{z})\right)$
（83）$\llbracket$ ElementNameOrWildcard（ElementName（P））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
let $z=\llbracket$ ElementName $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$ in
testEQName $(v, z)$
【ElementNameOrWildcard（＊）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$
true
In order to correctly translate schema element tests SchemaElementTest，we require a formalism that allows to talk about the various properties of schema el－ ement declarations and substitution groups．We leave this translation open for future work．
（84）$\llbracket$ SchemaElementTest（schema－element（ElementDeclaration $(\mathrm{P})$ ））$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}=\mathrm{df}$ raise error

## B．4．5 Node and Type Names

Not matching occurs for the following five nonterminals，who return simply names of elements and attributes，or names of types．
（85）$\llbracket$ ElementDeclaration（P）$\rrbracket_{\bar{z}}, \hat{z}, \tilde{z}={ }_{\mathrm{df}}$
［ElementName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
（86）$\llbracket$ AttributeName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【EQName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
（87）$\llbracket$ ElementName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【EQName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
（88）$\llbracket$ SimpleTypeName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
$\llbracket$ TypeName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$
（89）$\llbracket$ TypeName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$
【EQName（P）$\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}$

## B.4.6 Function Tests

There are the following two types of function tests.
(90) $\llbracket$ FunctionTest (P) $\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\text {df }}$

$$
\begin{cases}\llbracket \text { AnyFunctionTest }(\mathrm{P}) \rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v} & \mathrm{P} \in \text { AnyFunctionTest } \\ \llbracket \text { TypedFunctionTest }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v} & \mathrm{P} \in \text { TypedFunctionTest }\end{cases}
$$

Test function(*) matches any function.
(91) $\llbracket$ AnyFunctionTest (function (*)) $\rrbracket_{\tilde{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$ type $_{\text {TYPE }(v), f u n c t i o n ~}(v)$
The specification for a typed function test verifies whether the sequence type of the signature of a given function is a subtype of the sequence type of an expected signature. This requires an extension in $\lambda$ XP that translates XPATH functions to pairs of $\lambda \mathrm{XP}$ function and XPath sequence type. Then the typed function test checks whether the corresponding XPath sequence type is a subtype of the expected sequence type. For checking of the subtype relation for sequence types of XPath we assume a function that does this.

TypedFunctionTest ::= "function"
"(" (SequenceType ("," SequenceType)*)? ")" "as" SequenceType
Parenthesized item types match an item if and only it the item matches the item type within the parenthesis.
(93) $\llbracket$ ParenthesizedItemType ( (ItemType (P)) ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}={ }_{\mathrm{df}}$【ItemType (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}^{v}$

## B.4.7 EQNames

EQNames are made up of either QNames or URIQualifiedNames.
(94) $\llbracket E Q N a m e(P) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}}$

$$
\begin{cases}\llbracket \text { QName }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { QName } \\ \llbracket \text { URIQualifiedName }(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}} & \mathrm{P} \in \text { URIQualifiedName }\end{cases}
$$

## B. 5 Terminal Expressions

Terminal symbols IntegerLieral, DecimalLiteral, and DoubleLiteral translate to some numeric value of a respective type. Terminal symbols StringLiteral, URIQualifiedName, Comment, QName, NCName, and Char translate to a corresponding value. Note that non-numeric values which are no characters, are identified with a list of characters, such that they can be composed and decomposed.
(95) $\llbracket$ IntegerLiteral ( P ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(96) $\llbracket$ DecimalLiteral $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(97) $\llbracket$ DoubleLiteral (P) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(98) $\llbracket$ StringLiteral ( P ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(99) 【URIQualifiedName (BracedURILiteral (P) NCName ( $\mathrm{P}^{\prime}$ )) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}=\mathrm{df}$ $\operatorname{append}\left(\llbracket \operatorname{BracedURILiteral}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}, \llbracket \operatorname{NCName}\left(\mathrm{P}^{\prime}\right) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}\right)$
(100) $\llbracket$ BracedURILiteral ( P ) $\rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\text {df }} \mathrm{P}$
(101) $\llbracket$ EscapeQuot $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(102) $\llbracket$ EscapeApos $(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(103) $\llbracket \operatorname{Comment}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(104) $\llbracket \mathrm{QName}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(105) $\llbracket \operatorname{NCName}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$
(106) $\llbracket \operatorname{Char}(\mathrm{P}) \rrbracket_{\bar{z}, \hat{z}, \tilde{z}}={ }_{\mathrm{df}} \mathrm{P}$

## Bibliography

[Alur 2004] Rajeev Alur and P. Madhusudan. Visibly pushdown languages. In Proceedings of the 36th Annual ACM Symposium on Theory of Computing, Chicago, IL, USA, June 13-16, 2004, pages 202-211, 2004. (Cited on pages 10 and 14.)
[Alur 2009] Rajeev Alur and P. Madhusudan. Adding nesting structure to words. J. ACM, vol. 56, no. 3, 2009. (Cited on pages 10, 24, 29, 30 and 121.)
[Arenas 2007] Marcelo Arenas, Pablo Barceló and Leonid Libkin. Combining Temporal Logics for Querying XML Documents. In Database Theory - ICDT 2007, 11th International Conference, Barcelona, Spain, January 10-12, 2007, Proceedings, pages 359-373, 2007. (Cited on page 6.)
[Arroyuelo 2015] Diego Arroyuelo, Francisco Claude, Sebastian Maneth, Veli Mäkinen, Gonzalo Navarro, Kim Nguyen, Jouni Sirén and Niko Välimäki. Fast in-memory XPath search using compressed indexes. Softw., Pract. Exper., vol. 45, no. 3, pages 399-434, 2015. (Cited on page 9.)
[Atserias 2013] Albert Atserias, Martin Grohe and Dániel Marx. Size Bounds and Query Plans for Relational Joins. SIAM J. Comput., vol. 42, no. 4, pages 1737-1767, 2013. (Cited on page 2.)
[Barbieri 2010] Davide Francesco Barbieri, Daniele Braga, Stefano Ceri, Emanuele Della Valle and Michael Grossniklaus. C-SPARQL: a Continuous Query Language for RDF Data Streams. Int. J. Semantic Computing, vol. 4, no. 1, pages 3-25, 2010. (Cited on page 10.)
[Beame 2013] Paul Beame, Paraschos Koutris and Dan Suciu. Communication steps for parallel query processing. In Proceedings of the 32nd ACM SIGMOD-SIGACT-SIGART Symposium on Principles of Database Systems, PODS 2013, New York, NY, USA - June 22-27, 2013, pages 273-284, 2013. (Cited on page 2.)
[Beame 2014] Paul Beame, Paraschos Koutris and Dan Suciu. Skew in parallel query processing. In Proceedings of the 33rd ACM SIGMOD-SIGACTSIGART Symposium on Principles of Database Systems, PODS'14, Snowbird, UT, USA, June 22-27, 2014, pages 212-223, 2014. (Cited on page 2.)
[Benedikt 2007] Michael Benedikt and Alan Jeffrey. Efficient and Expressive Tree Filters. In FSTTCS 2007: Foundations of Software Technology and Theoretical Computer Science, 27th International Conference, New Delhi, India, December 12-14, 2007, Proceedings, pages 461-472, 2007. (Cited on pages 10 and 11.)
[Benedikt 2008a] Michael Benedikt, Wenfei Fan and Floris Geerts. XPath satisfiability in the presence of DTDs. J. ACM, vol. 55, no. 2, 2008. (Cited on page 10.)
[Benedikt 2008b] Michael Benedikt, Alan Jeffrey and Ruy Ley-Wild. Stream firewalling of $x m l$ constraints. In Proceedings of the ACM SIGMOD International Conference on Management of Data, SIGMOD 2008, Vancouver, BC, Canada, June 10-12, 2008, pages 487-498, 2008. (Cited on pages 10 and 13.)
[Benedikt 2009] Michael Benedikt and Christoph Koch. From XQuery to relational logics. ACM Trans. Database Syst., vol. 34, no. 4, 2009. (Cited on page 4.)
[Benedikt 2015] Michael Benedikt, Gabriele Puppis and Huy Vu. The complexity of higher-order queries. Inf. Comput., vol. 244, pages 172-202, 2015. (Cited on page 14.)
[Berglund 2010] Anders Berglund, Scott Boag, Don Chamberlin, Mary F. FernÃjndez, Michael Kay, Jonathan Robie and Jérôme Siméon. XML Path Language (XPath) 2.0, W3C recommendation, 2010. http://www.w3.org/TR/xpath20/. (Cited on pages 5 and 6.)
[Beyer 2011] Kevin S. Beyer, Vuk Ercegovac, Rainer Gemulla, Andrey Balmin, Mohamed Y. Eltabakh, Carl-Christian Kanne, Fatma Özcan and Eugene J. Shekita. Jaql: A Scripting Language for Large Scale Semistructured Data Analysis. PVLDB, vol. 4, no. 12, pages 1272-1283, 2011. (Cited on page 2.)
[Bloom 2001] Gary Bloom and Christopher Lindblad. MarkLogic, 2001. http://www.marklogic.com/. (Cited on page 1.)
[Boag 2007] Scott Boag, Don Chamberlin, Mary F. FernÃjndez, Daniela Florescu, Jonathan Robie and JÃ@rã'me SimÃ@on. XQuery 1.0: An XML query language, W3C recommendation, 2007. http://www.w3.org/TR/2007/REC-xquery-20070123/. (Cited on page 4.)
[Bojańczyk 2011] Mikołaj Bojańczyk and Pawel Parys. XPath evaluation in linear time. J. ACM, vol. 58, no. 4, page 17, 2011. (Cited on page 8.)
[Bray 2008] Tim Bray, Jean Paoli, C. M. Sperberg-McQueen, Eve Maler and FranÃ§ois Yergeau. Extensible Markup Language (XML) 1.0 (Fifth Edition), 2008. https://www.w3.org/TR/xml/. (Cited on pages 1 and 3.)
[Brenna 2009] Lars Brenna, Johannes Gehrke, Mingsheng Hong and Dag Johansen. Distributed event stream processing with non-deterministic finite automata. In Proceedings of the Third ACM International Conference on Distributed Event-Based Systems, DEBS 2009, Nashville, Tennessee, USA, July 6-9, 2009, 2009. (Cited on page 10.)
[Clark 1999a] James Clark. XSL Transformations (XSLT) version 1.0, W3C recommendation, 1999. https://www.w3.org/TR/xslt. (Cited on page 4.)
[Clark 1999b] James Clark and Steve DeRose. XML Path Language (XPath) Version 1.0, W3C recommendation, 1999. hrefhttp://www.w3.org/TR/xpath/http://www.w3.org/TR/xpath/. (Cited on pages 4 and 5.)
[Comon 2007] Hubert Comon, Max Dauchet, Remi Gilleron, Christof Löding, Florent Jacquemard, Denis Lugiez, Sophie Tison and Marc Tommasi. Tree Automata Techniques and Applications., 2007. http://www.grappa.univ-lille3.fr/tata. (Cited on page 4.)
[Crockford 2001] Douglas Crockford. JSON (JavaScript Object Notation), 2001. http://json.org/, RFC 7159 and ECMA-404. (Cited on pages 2 and 23.)
[Debarbieux 2013] Denis Debarbieux, Olivier Gauwin, Joachim Niehren, Tom Sebastian and Mohamed Zergaoui. Early Nested Word Automata for XPath Query Answering on XML Streams. In Implementation and Application of Automata - 18th International Conference, CIAA 2013, Halifax, NS, Canada, July 16-19, 2013. Proceedings, pages 292-305, 2013. (Cited on page 17.)
[Debarbieux 2015] Denis Debarbieux, Olivier Gauwin, Joachim Niehren, Tom Sebastian and Mohamed Zergaoui. Early nested word automata for XPath query answering on XML streams. Theor. Comput. Sci., vol. 578, pages 100-125, 2015. (Cited on page 17.)
[Eich 2015] Brendan Eich. JavaScript, 2015. Standard ECMA-262. (Cited on page 2.)
[Engelfriet 2000] Joost Engelfriet and Sebastian Maneth. Characterizing and Deciding MSO-Definability of Macro Tree Transductions. In STACS 2000, 17th Annual Symposium on Theoretical Aspects of Computer Science, Lille, France, February 2000, Proceedings, pages 542-554, 2000. (Cited on page 4.)
[Fernández 2007] Mary F. Fernández, Philippe Michiels, Jérôme Siméon and Michael Stark. XQuery Streaming à la Carte. In Proceedings of the 23rd International Conference on Data Engineering, ICDE 2007, The Marmara Hotel, Istanbul, Turkey, April 15-20, 2007, pages 256-265, 2007. (Cited on page 10.)
[Franceschet 2005] Massimo Franceschet. XPathMark: An XPath Benchmark for the XMark Generated Data. In Database and XML Technologies, Third International XML Database Symposium, XSym 2005, Trondheim, Norway, August 28-29, 2005, Proceedings, pages 129-143, 2005. revised version: http://sole.dimi.uniud.it/~massimo.franceschet/xpathmark/PTbench.html. (Cited on pages 12, 72, 143 and 253.)
[Friedgut 2004] Ehud Friedgut. Hypergraphs, Entropy, and Inequalities. The American Mathematical Monthly, vol. 111, no. 9, pages 749-760, 2004. (Cited on page 2.)
[Frisch 2004] Alain Frisch. Regular Tree Language Recognition with Static Information. In Exploring New Frontiers of Theoretical Informatics, IFIP 18th World Computer Congress, TC1 3rd International Conference on Theoretical Computer Science (TCS2004), 22-27 August 2004, Toulouse, France, pages 661-674, 2004. (Cited on page 154.)
[Gauwin 2009a] Olivier Gauwin. Streaming Tree Automata and XPath. PhD thesis, Université Lille 1, 2009. (Cited on page 128.)
[Gauwin 2009b] Olivier Gauwin, Joachim Niehren and Sophie Tison. Earliest Query Answering for Deterministic Nested Word Automata. In Fundamentals of Computation Theory, 17th International Symposium, FCT 2009, Wroclaw, Poland, September 2-4, 2009. Proceedings, pages 121-132, 2009. (Cited on pages 10, 14, 116, 121 and 127.)
[Gauwin 2011a] Olivier Gauwin and Joachim Niehren. Streamable Fragments of Forward XPath. In Implementation and Application of Automata - 16th International Conference, CIAA 2011, Blois, France, July 13-16, 2011. Proceedings, pages $3-15,2011$. (Cited on pages 10, 117, 121 and 148.)
[Gauwin 2011b] Olivier Gauwin, Joachim Niehren and Sophie Tison. Queries on Xml streams with bounded delay and concurrency. Inf. Comput., vol. 209, no. 3, pages 409-442, 2011. (Cited on page 11.)
[Goldfarb 1986] Charles Goldfarb, Edward Mosher and Raymond Lorie. The Standard Generalized Markup Language (SGML), 1986. ISO 8879:1986. (Cited on page 1.)
[Gottlob 2002] Georg Gottlob and Christoph Koch. Monadic Queries over TreeStructured Data. In 17th IEEE Symposium on Logic in Computer Science (LICS 2002), 22-25 July 2002, Copenhagen, Denmark, Proceedings, pages 189-202, 2002. (Cited on pages 4 and 5.)
[Gottlob 2003] Georg Gottlob, Christoph Koch and Reinhard Pichler. The complexity of XPath query evaluation. In Proceedings of the Twenty-Second ACM SIGACT-SIGMOD-SIGART Symposium on Principles of Database Systems, June 9-12, 2003, San Diego, CA, USA, pages 179-190, 2003. (Cited on page 5.)
[Gottlob 2005] Georg Gottlob, Christoph Koch and Reinhard Pichler. Efficient algorithms for processing XPath queries. ACM Trans. Database Syst., vol. 30, no. 2, pages 444-491, 2005. (Cited on page 8.)
[Green 2004] Todd J. Green, Ashish Gupta, Gerome Miklau, Makoto Onizuka and Dan Suciu. Processing XML streams with deterministic automata and stream indexes. ACM Trans. Database Syst., vol. 29, no. 4, pages 752-788, 2004. (Cited on page 144.)
[Groz 2012] Benoit Groz. XML Security Views: Queries, Updates, and Schemas. PhD thesis, Université Lille 1, 2012. (Cited on page 8.)
[Grün 1983] C. Grün. BaseX. The XML Database, 1983. http://basex.org/. (Cited on page 1.)
[Grust 2007] Torsten Grust, Jan Rittinger and Jens Teubner. eXrQuy: Order Indifference in XQuery. In Proceedings of the 23rd International Conference on Data Engineering, ICDE 2007, The Marmara Hotel, Istanbul, Turkey, April 15-20, 2007, pages 226-235, 2007. (Cited on page 69.)
[Gupta 2003] Ashish Kumar Gupta and Dan Suciu. Stream Processing of XPath Queries with Predicates. In Proceedings of the 2003 ACM SIGMOD International Conference on Management of Data, San Diego, California, USA, June 9-12, 2003, pages 419-430, 2003. (Cited on page 10.)
[Hickson 2014] Ian Hickson, Robin Berjon, Steve Faulkner, Travis Leithead, Erika Doyle Navara, Edward O'Connor and Silvia Pfeiffer. HTML5, 2014. http://www.w3.org/TR/html5/. (Cited on page 1.)
[Jelliffe 2006] Rick Jelliffe. Schematron, 2006. ISO/IEC 19757-3. (Cited on page 3.)
[Kay 2004] Michael Kay. The saxon XSLT and XQuery processor, 2004. https://www.saxonica.com. (Cited on pages 9, 153 and 166.)
[Kay 2010] Michael Kay. A streaming XSLT processor. In Proceedings of Balisage: The Markup Conference 2010. Balisage Series on Markup Technologies, volume 5, Montrã ©al, Canada, August 3-6, 2010, 2010. (Cited on pages 10, 11 and 144.)
[Kay 2014] Michael Kay. XPath and XQuery Functions and Operators 3.0, W3C recommendation, 2014. https://www.w3.org/TR/xpath-functions-30/. (Cited on pages 13 and 63.)
[Kupferman 2001] Orna Kupferman and Moshe Y. Vardi. Model Checking of Safety Properties. Formal Methods in System Design, vol. 19, no. 3, pages 291-314, 2001. (Cited on page 10.)
[Labath 2015] Pavel Labath and Joachim Niehren. A Uniform Programming Language for Implementing XML Standards. In SOFSEM 2015: Theory and Practice of Computer Science - 41st International Conference on Current Trends in Theory and Practice of Computer Science, Pec pod Sněžkou, Czech Republic, January 24-29, 2015. Proceedings, pages 543-554, 2015. (Cited on page 252.)
[Ley 2009] Clemens Ley and Michael Benedikt. How big must complete XML query languages be? In Database Theory - ICDT 2009, 12th International Conference, St. Petersburg, Russia, March 23-25, 2009, Proceedings, pages 183200, 2009. (Cited on pages 143 and 145.)
[Lick 2013] Anthony Lick and Joachim Niehren. Early = Earliest? Rapport technique, INRIA Lille, 2013. http://hal.inria.fr/hal-00873742. (Cited on pages $15,117,126$ and 148.)
[Madhusudan 2009] P. Madhusudan and Mahesh Viswanathan. Query Automata for Nested Words. In Mathematical Foundations of Computer Science 2009, 34th International Symposium, MFCS 2009, Novy Smokovec, High Tatras, Slovakia, August 24-28, 2009. Proceedings, pages 561-573, 2009. (Cited on pages $10,14,116,118$ and 127.)
[Maneth 2005] Sebastian Maneth, Alexandru Berlea, Thomas Perst and Helmut Seidl. XML type checking with macro tree transducers. In Proceedings of the Twenty-fourth ACM SIGACT-SIGMOD-SIGART Symposium on Principles of Database Systems, June 13-15, 2005, Baltimore, Maryland, USA, pages 283-294, 2005. (Cited on page 4.)
[Maneth 2010] Sebastian Maneth and Kim Nguyen. XPath Whole Query Optimization. PVLDB, vol. 3, no. 1, pages 882-893, 2010. (Cited on pages 9, 153 and 154.)
[Marian 2003] Amélie Marian and Jérôme Siméon. Projecting XML Documents. In VLDB, pages 213-224, 2003. (Cited on pages 9 and 153.)
[Martens 2006a] Wim Martens. Static Analysis of Xml Transformation and Schema Languages. PhD thesis, Universiteit Antwerpen (Belgium), 2006. (Cited on page 3.)
[Martens 2006b] Wim Martens, Frank Neven, Thomas Schwentick and Geert Jan Bex. Expressiveness and complexity of XML Schema. ACM Trans. Database Syst., vol. 31, no. 3, pages 770-813, 2006. (Cited on page 3.)
[Marx 2004a] Maarten Marx. XPath with Conditional Axis Relations. In Advances in Database Technology - EDBT 2004, 9th International Conference on Extending Database Technology, Heraklion, Crete, Greece, March 14-18, 2004, Proceedings, pages 477-494, 2004. (Cited on page 6.)
[Marx 2004b] Maarten Marx and Maarten de Rijke. Semantic Characterization of Navigational XPath. In First Twente Data Management Workshop (TDM 2004) on XML Databases and Information Retrieval, Enschede, The Netherlands, June 21, 2004, pages $73-79$, 2004. (Cited on page 6.)
[Meier 2000] Wolfgang Meier. eXist, 2000. http://exist-db.org/. (Cited on page 1.)
[Mozafari 2012] Barzan Mozafari, Kai Zeng and Carlo Zaniolo. High-performance complex event processing over XML streams. In Proceedings of the ACM SIGMOD International Conference on Management of Data, SIGMOD 2012, Scottsdale, AZ, USA, May 20-24, 2012, pages 253-264, 2012. (Cited on pages 10, 11, 13 and 144.)
[Ngo 2013] Hung Q. Ngo, Christopher Ré and Atri Rudra. Skew strikes back: new developments in the theory of join algorithms. SIGMOD Record, vol. 42, no. 4, pages 5-16, 2013. (Cited on page 2.)
[Olteanu 2007] Dan Olteanu. SPEX: Streamed and Progressive Evaluation of XPath. IEEE Trans. Knowl. Data Eng., vol. 19, no. 7, pages 934-949, 2007. (Cited on pages 10, 11, 12, 116 and 144.)
[Onizuka 2010] Makoto Onizuka. Processing XPath queries with forward and downward axes over XML streams. In EDBT 2010, 13th International Conference on Extending Database Technology, Lausanne, Switzerland, March 22-26, 2010, Proceedings, pages 27-38, 2010. (Cited on page 144.)
[Parys 2011] Pawel Parys. Application of automata theory to processing of XML documents. PhD thesis, Warsaw University, 2011. (Cited on pages 8 and 9.)
[Pemberton 2002] Steven Pemberton and ... XHTML 1.0 The Extensible HyperText Markup Language (Second Edition), 2002. http://www.w3.org/TR/xhtml1/. (Cited on page 1.)
[Peng 2005] Feng Peng and Sudarshan S. Chawathe. XSQ: A streaming XPath engine. ACM Trans. Database Syst., vol. 30, no. 2, pages 577-623, 2005. (Cited on page 144.)
[Phuoc 2011] Danh Le Phuoc, Minh Dao-Tran, Josiane Xavier Parreira and Manfred Hauswirth. A Native and Adaptive Approach for Unified Processing of Linked Streams and Linked Data. In The Semantic Web - ISWC 2011-10th International Semantic Web Conference, Bonn, Germany, October 23-27, 2011, Proceedings, Part I, pages 370-388, 2011. (Cited on page 10.)
[Robie 2014a] Jonathan Robie, Don Chamberlin, Michael Dyck and John Snelson. XML Path Language (XPath) 3.0, W3C recommendation, 2014. http://www.w3.org/TR/xpath-30/. (Cited on page 5.)
[Robie 2014b] Jonathan Robie, Don Chamberlin, Michael Dyck and John Snelson. XPath 3.0 Grammar, W3C recommendation, 2014. https://www.w3.org/TR/xpath-30/\#nt-bnf. (Cited on pages 13, 26, 41, 42, 47 and 102.)
[Robie 2014c] Jonathan Robie, Don Chamberlin, Michael Dyck and John Snelson. XQuery 3.0: An XML Query Language, W3C recommendation, 2014. https://www.w3.org/TR/xquery-30/. (Cited on page 5.)
[Robinson 2015] Ian Robinson, Jim Webber and Emil Eifrem. Graph databases. new opportunities for connected data. O'Reilly Media, 2015. (Cited on page 2.)
[Schmidt 2007] Michael Schmidt, Stefanie Scherzinger and Christoph Koch. Combined Static and Dynamic Analysis for Effective Buffer Minimization in Streaming XQuery Evaluation. In Proceedings of the 23rd International Conference on Data Engineering, ICDE 2007, The Marmara Hotel, Istanbul, Turkey, April 15-20, 2007, pages 236-245, 2007. (Cited on pages 10, 11, 12 and 144.)
[Sebastian 2016] Tom Sebastian and Joachim Niehren. Projection for Nested Word Automata Speeds up XPath Evaluation on XML Streams. In SOFSEM 2016: Theory and Practice of Computer Science - 42nd International Conference on Current Trends in Theory and Practice of Computer Science, Harrachov, Czech Republic, January 23-28, 2016, Proceedings, pages 602-614, 2016. (Cited on page 17.)
[ten Cate 2007] Balder ten Cate and Maarten Marx. Navigational XPath: calculus and algebra. SIGMOD Record, vol. 36, no. 2, pages 19-26, 2007. (Cited on page 8.)
[Thatcher 1968] James W. Thatcher and Jesse B. Wright. Generalized Finite Automata Theory with an Application to a Decision Problem of Second-Order Logic. Mathematical Systems Theory, vol. 2, no. 1, pages 57-81, 1968. (Cited on page 4.)
[Thompson 2004] Henry S. Thompson, David Beech, Murray Maloney and Noah Mendelsohn. XML Schema Part 1: Structures Second Edition, 2004. http://www.w3.org/TR/xmlschema-1/. (Cited on page 3.)
[van der Vlist 2003] Eric van der Vlist. Relax ng. O’Reilly Media, 2003. (Cited on page 3.)
[Walsh 2010a] Norman Walsh. Docbook: The definitive guide. O'Reilly Media, 2010. (Cited on page 1.)
[Walsh 2010b] Norman Walsh, Alex Milowski and Henry S. Thompson. XProc: An XML Pipeline Language, W3C Recommendation, 2010. https://www.w3.org/TR/xproc/. (Cited on page 4.)
[Wu 2006] Eugene Wu, Yanlei Diao and Shariq Rizvi. High-performance complex event processing over streams. In Proceedings of the ACM SIGMOD International Conference on Management of Data, Chicago, Illinois, USA, June $27-29,2006$, pages 407-418, 2006. (Cited on page 10.)


[^0]:    ${ }^{1}$ XPATH function fn :local-name returns the label of the current node. Note that filter [not (b)] is short for [not(child::b)] and thus not a valid substitution.

[^1]:    ${ }^{1}$ http://www.w3.org/TR/xpath-datamodel-30/

[^2]:    ${ }^{2}$ Notice that we do not treat namespace nodes which are contained in the data model. This is because the namespace axis, which selects namespace nodes, is deprecated as of XPATH 2.0, and is thus not supported by us, which in turn does not require to treat namespace nodes. It is also not supported in XQuery.
    ${ }^{3}$ https://www.w3.org/TR/xpath-functions-30/

[^3]:    ${ }^{1}$ https://www.w3.org/TR/xpath-30/\#EBNFNotation

[^4]:    (71) KindTest::= DocumentTest | ElementTest | AttributeTest | SchemaElementTest | SchemaAttributeTest | PITest | CommentTest | TextTest | NamespaceNodeTest | AnyKindTest

[^5]:    ${ }^{1}$ http://www.w3.org/TR/xpath-30/\#id-sequencetype-subtype
    ${ }^{2}$ http://www.w3.org/TR/xpath-30/\#id-sequencetype-matching

[^6]:    ${ }^{1}$ http://www.w3.org/TR/xpath-30/\#id-function-conversion-rules
    ${ }^{2}$ http://www.w3.org/TR/xpath-30/\#id-function-coercion

[^7]:    ${ }^{3}$ http://www.w3.org/TR/xpath-30/ \#id-cast

[^8]:    ${ }^{4}$ http://www.w3.org/TR/xpath-30/\#mapping

[^9]:    ${ }^{5}$ http://sole.dimi.uniud.it/ ${ }^{\text {massimo.franceschet/xpathmark/PTbench.html }}$

[^10]:    ${ }^{1}$ https://www.w3.org/TR/xpath-30/\#mapping
    ${ }^{2}$ https://www.w3.org/TR/xpath-functions-30/\#casting
    ${ }^{3}$ https://www.w3.org/TR/xmlschema-2/
    ${ }^{4}$ https://www.w3.org/TR/xpath-30/\#mapping

[^11]:    ${ }^{5}$ http://www.w3.org/TR/xpath-functions-30/\#func-string

[^12]:    ${ }^{6}$ http://www.w3.org/TR/xpath-functions/\#func-data

[^13]:    ${ }^{7}$ http：／／www．w3．org／TR／xpath－functions－30／\＃func－number
    ${ }^{8}$ http：／／www．w3．org／TR／xpath－functions－30／\＃func－count
    ${ }^{9}$ http：／／www．w3．org／TR／xpath－functions－30／\＃func－boolean

[^14]:    ${ }^{10}$ https://www.w3.org/TR/xpath-functions-30/\#func-concat
    ${ }^{11}$ http://www.w3.org/TR/xpath-functions-30/\#string-value-functions

[^15]:    ${ }^{12}$ http://www.w3.org/TR/xpath-functions-30/\#func-root

[^16]:    ${ }^{1}$ The semantics of our selection states is identical with the semantics of final states in the acceptance condition for NWAs in [Alur 2009], but should not be confused in general.

[^17]:    ${ }^{2}$ See Figure 8.3 and also the expressions $P_{n}$ in the introduction.

[^18]:    ${ }^{3}$ http://sole.dimi.uniud.it/ ${ }^{\sim}$ massimo.franceschet/xpathmark/PTbench.html

[^19]:    ${ }^{4}$ In the general case, backwards axes elimination may need to introduce regular axes[Ley 2009], but not for the XPathMark queries considered here.

[^20]:    ${ }^{1}$ http://sole.dimi.uniud.it/ ${ }^{\sim}$ massimo.franceschet/xpathmark/PTbench.html

[^21]:    ${ }^{1}$ https://www.w3.org/TR/xpath-30/

[^22]:    ${ }^{2}$ http://www.w3.org/TR/xpath-30/\#mapping

[^23]:    ${ }^{3}$ http：／／www．w3．org／TR／xpath－functions－30／\＃casting

[^24]:    ${ }^{4}$ http://www.w3.org/TR/xpath-30/\#id-sequencetype-matching

